1. (a).

$$f(\theta) = \frac{1}{m} \sum_{i=1}^{m} \left(\sum_{k=1}^{K} y_{ik} x_{i}^{T} \theta_{k} - log(\sum_{k=1}^{K} exp(x_{i}^{T} \theta_{k})) \right)$$

$$\frac{d(f(\theta))}{d\theta_{k}} = \frac{1}{m} \sum_{i=1}^{m} \left(\frac{d(\sum_{k=1}^{K} y_{ik} x_{i}^{T} \theta_{k})}{d\theta_{k}} - \frac{d(log(\sum_{k=1}^{K} exp(x_{i}^{T} \theta_{k})))}{d\theta_{k}} \right)$$

$$= \frac{1}{m} \sum_{i=1}^{m} \left(y_{ik} x_{i} - \frac{1}{\sum_{j=1}^{K} exp(x_{i}^{T} \theta_{j})} \cdot \frac{d(\sum_{k=1}^{K} exp(x_{i}^{T} \theta_{k}))}{d\theta_{k}} \right)$$

$$= \frac{1}{m} \sum_{i=1}^{m} \left(y_{ik} x_{i} - \frac{1}{\sum_{j=1}^{K} exp(x_{i}^{T} \theta_{j})} \cdot exp(x_{i}^{T} \theta_{k}) \cdot \frac{d(x_{i}^{T} \theta_{k})}{d\theta_{k}} \right)$$

$$= \frac{1}{m} \sum_{i=1}^{m} \left(y_{ik} x_{i} - \frac{1}{\sum_{j=1}^{K} exp(x_{i}^{T} \theta_{j})} \cdot exp(x_{i}^{T} \theta_{k}) \cdot x_{i} \right)$$

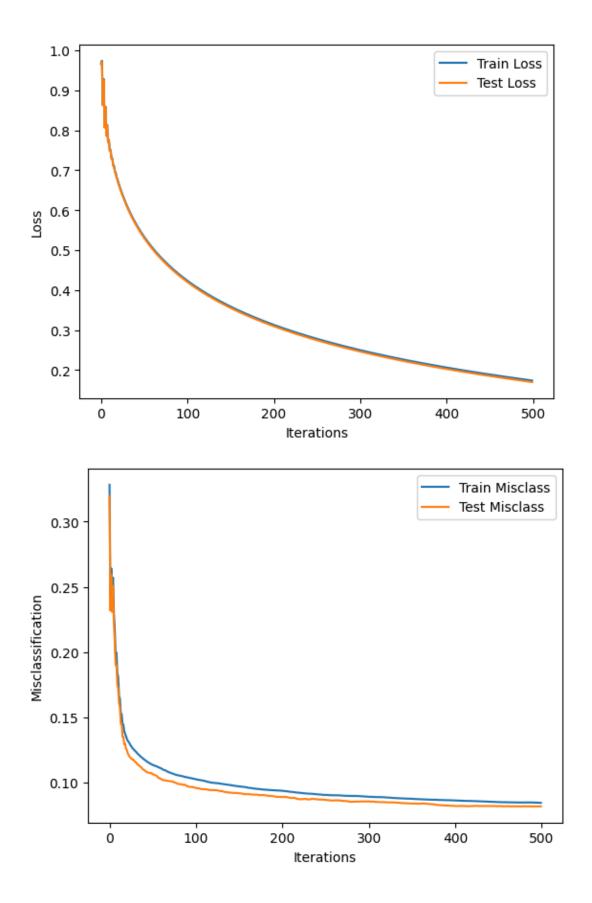
$$= \frac{1}{m} \sum_{i=1}^{m} \left(y_{ik} - \frac{exp(x_{i}^{T} \theta_{k})}{\sum_{j=1}^{K} exp(x_{i}^{T} \theta_{j})} \right) x_{i}$$

(b).

- 1. Use D = max θ i, θ i D <= 0. This makes $\exp(\theta$ i D) <= 1, which prevents $\exp(\theta$ i) from becoming very large due to very large values in θ i, thus preventing overflow.
- 2. Use D = min θ i, θ i D >= 0. This makes $\exp(\theta$ i D) >= 1, which prevents $\exp(\theta$ i) from becoming very close to zero due to very negative values in θ i, thus preventing underflow.

(c).

```
import numpy as np
    import matplotlib.pyplot as plt
    import scipy.io as sio
    from sklearn.preprocessing import OneHotEncoder
   data = sio.loadmat('mnist.mat')
   Xtrain, Xtest = data['trainX'].astype(float), data['testX'].astype(float)
   ytrain, ytest = data['trainY'][0], data['testY'][0]
   ytrain_onehot = OneHotEncoder(categories='auto').fit_transform(ytrain.reshape(-1, 1))
   m, n = Xtrain.shape
   def compute_gradient(X, y, theta):
       s = np.dot(X, theta)
       exp_s = np_exp(s)
       gradient = exp_s.T / np.sum(exp_s, axis=1)
        return np.dot(X.T, (gradient.T - y)) / m
   def compute_loss(X, y, theta):
       s = np.dot(X, theta)
       exp_s = np.exp(s)
       gradient = exp_s.T / np.sum(exp_s, axis=1)
        return np.mean(np.log(np.abs(gradient - y)))
    def accuracy(X, y, theta):
       preds = np.argmax(np.dot(X,theta), axis=1)
        return np.mean(preds == y)
    stepsize = 1e-5
   Theta = np.zeros((n, 10))
    train_loss, test_loss, train_misclass, test_misclass = [], [], [], []
    for _ in range(500):
        Theta -= stepsize * compute_gradient(Xtrain, ytrain_onehot, Theta)
        train_loss.append(compute_loss(Xtrain, ytrain, Theta))
        test_loss.append(compute_loss(Xtest, ytest, Theta))
        train_misclass.append(1 - accuracy(Xtrain, ytrain, Theta))
        test_misclass.append(1 - accuracy(Xtest, ytest, Theta))
    train_loss, test_loss = np.array(train_loss), np.array(test_loss)
    train_misclass, test_misclass = np.array(train_misclass), np.array(test_misclass)
    plt.plot(train_loss, label="Train Loss")
   plt.plot(test_loss, label="Test Loss")
    plt.xlabel('Iterations')
    plt.ylabel('Loss')
    plt.legend()
   plt.show()
    plt.plot(train_misclass, label="Train Misclass")
    plt.plot(test_misclass, label="Test Misclass")
    plt.xlabel('Iterations')
   plt.ylabel('Misclassification')
    plt.legend()
    plt.show()
```



2, (a),	Total = 5+100+30+3+2=140
	HW=- (1/40 log, 1/40 + 1/40 log, 1/40 + 30 log, 30 + 3 log, 1/40 + 1/40 log, 1/40 + 1/40 log, 1/40 + 1/40 log, 1/40 + 1/40 log, 1/40)
	≈-(-21717-23467-24762-21188-0,0876)
	≈1,2
(6)	Top draver = noils + zipties = 100 + 30 = 130
	Bottom dearer = rest = $5+3+2=10$
	1928(X=X Y=botter)
	H(X Y) = -[P(top) · (\$ P(X=X Y=top) b32P(X=X Y=top) + P(botton) = P(X=X Y=botton)
	=- [25 (100 log 150 + 10 log 70) + 25 (5652 5 + 76 log 76 + 76 log 76)]
103	₩ - [25. (-278) + R5. (-1.48)]
	2 L13
(c)	T(X;Y) = 2- .13 = QPT
67-2011	L(X;)/= Z- X) - X
(d)	Topdraver = Phillips + Hathand + 'z' halls = 2+3+ ±-1== >5
Ca/	Bettern drawer = re/t = 5+30+ ±400 = 85
	50 29 29 29 29 29 29 29 29 29 29 29 29 29
	H(X/Y)=-Tor(景的是+景的是+景的最)+の(影片等的是+
	2-[05(-0174-0229-0125)+05(-024-053-045)]
	≈-[05·(-1.148)]
	≈ c874
	[T(xx)] 1 = 221
	I(x,y) = 1.2 - 0.874 = 0.326
-12	
	This one is give the largete information gain.

3 (a) i	$\frac{1}{1} = x + 2i = x + N(e_1)$
7 3711	N(31)= Y-X
	$P(Y_1 X) = \frac{1}{\pi} \cdot e^{x} P(-(Y_1 X_1)^2 - 1$
	P(X, XM) x = = = = = = = = = = = = = = = = = =
	109 P(Y, -1/2) = 109 (# 1/2) + # (-(Y/-X)2)
	= \(\log \left((\int \frac{1}{2} \right) \frac{1}{2} \frac{1}{2} \left(\frac{1}{2} \right) \frac{1}{2} \right) \frac{1}{2} \frac{1}{2} \right) \frac{1}{2} \frac{1}{2} \right) \frac{1}{2} \frac{1}{2} \right) \frac{1}{2} \frac{1}{2} \frac{1}{2} \right) \frac{1}{2} \right) \frac{1}{2} \frac{1}{2} \right) \frac{1}{2} \right) \frac{1}{2} \frac{1}{2} \right) \fr
	= - = 102(27) - = = (1/2-x)2
	MLE Jorx: dosp(x,-xmlx) = m (y,-x)
	$O = \frac{m}{k_{\rm Pl}}(\gamma_{\rm L} - \chi)$
	$O = \frac{m}{2} \gamma_i - m \chi$
	X = 1 = 1/2
ii	BO: E[对=E[前置X]=前至E[X]=X, BN=E[到-X=O
enter to the sters of the sters	Variance: VarOD = Var(m = 1/2) = m = Var(x)
	Since Yz=x+N(9), XER, Z~N(9), Var(1)=
	Var(30) = m2 = 1 = m
lii.	Bios: Big (50) is unbing, so Bir (50 = 0 as m7+00)
	Variable: Var (30) = m -70 as m-7+00

(b) i	-d(六是(x-x)+p(x-x))=0
, , , ,	
	- TO (1-x) + 2p(x-x) =0
	- = 型+2x+2px-2px=0
	$(2+2p)\chi = \frac{2}{m}\sum_{i=1}^{m}/2+2p\bar{\chi}$
	(2+2p)(= m in/2+4)
	2(MAP = 1+P · (m = 1/2+PX)
ìi.	Bin: E[XMAP] = E[T+p. (m = /2+PX)]
	= tp·(E[th=3/1+Px)
	= T+P · (FIXI + P)
	$=\frac{1}{149}\cdot(\chi+P\bar{\chi})$
	Birs (Xnap) = F[XMAP] - X = X+PX X+PX P(X-X)
	VARTURE: Var (XMAP) = Var (+p. (+ = 1/2+PX))
	= (HP)2 · Var (m = Y2)
	= (1+p)2 · Var (St)
	= (1+p)2· m
	$= m(1+p)^2$
	$=$ $m(Hp)^2$
iii.	Big: Big (Xmap) + IC, It's blaston, the board
	Bir (1mmp) = P(5-x) as m-7+00
	Variance: Var ()(MAY) = m(4)+ 70 as m+ too

Cc)	MSE = E[(x-x)2] = 132+V	
	$= \frac{(P(\overline{C-X})^2 + \overline{m(1+p)^2}}{(1+p)^2}$	
	B= itp P= 13-1	
	$MSE = (\frac{1}{13}, \frac{1}{1+\frac{1}{6}}, (x-x))^2 + \frac{1}{m(1+\frac{1}{6}+1)^2}$	
	$= ((1-B)\cdot(\overline{x}-y))^2 + B^2(x)$	
	$= (1-B)^2 \Delta^2 + \frac{B^2}{M}$	
	Minimize the NSF:	
	d (M)E)	
	OB = -2(1-B)4+ #	
	$\frac{2}{10} = -2(1-1)8^2 + \frac{218}{10}$	
	$0 = -2\lambda^2 + 2 X ^2 + \frac{2k}{m}$	
	$28^2 = 2\beta(\Delta^2 + m)$	
	$B = \frac{2\Delta^2}{2(\Delta^2 + \frac{1}{m})} = \frac{\Delta^2}{\Delta^2 + \frac{1}{m}}$	
	P= 1 = 52+15 = 52 = ms2	
	D D D D D D D D D D D D D D D D D D D	

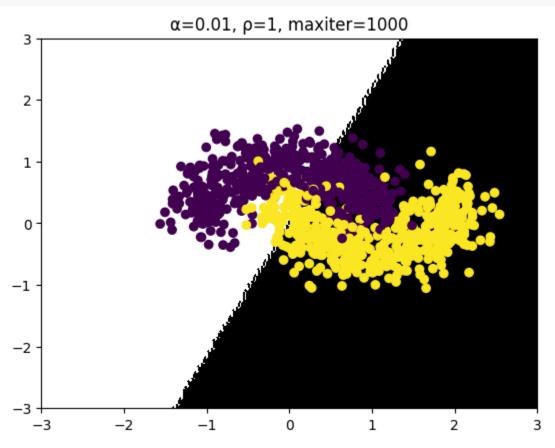
4. (a).	min 11xa-y112+ p119112
	TV
	$\frac{d(x \alpha + y ^2 + p \alpha ^2)}{d\alpha} = 2x^7(x\alpha - y) + (2p\alpha)$
	$0 = 2x^{\dagger}(xQ-y) + 2PQ$
	$0 = 2X^{T}XQ - 2X^{T}Y + 2PQ$
	$Q(2x^{T}x+2p) = 2x^{T}y$
	$Q = (2x^{\dagger}x + 2p)^{-1}2x^{\top}y$
	$\Theta = (x^T x + P y)^{-1} x^T y$
Cb),	Y2=X1 Q + Z1, Z1~N(0,1)
	ELQI= E[(X'X+PZ)'X">]
	= E[(xTx+PZ)-TxT(xTQ+Z)]
	$= FL(x^{T}x+PZ)^{-1}x^{T}xQ + (x^{T}x+PZ)^{-1}x^{T}Z$
	$= (x^{T}x+pz)^{-1}x^{T}x\overline{Q} + (x^{T}x+pz)^{-1}x^{T}EZ$
	Since ZXN(O), IZJ=0
	$TEGI = (x^T x + PI)^{-1} x^T x G$
(c)	13ins (a) = E[a] - a
	$=((x^{T}x+PI)^{-1}x^{T}x-I)\overline{\Theta}$
c 11	**1
(d)	$\Xi = Cov(Q) = E[(Q-E[Q])(Q-E[Q])^{T}]$
	= E[((xTx+PI)-(xTx+PI
	$= E \left[\left(x^{T} x + P^{T} \right)^{-1} x^{T} z^{T} x \left(x^{T} x + P^{T} \right)^{-1} \right]$
	$= (x^{T}x+PI)^{-1}x^{T}EIZZ^{T}Ix(x^{T}x+PI)^{-1}$
	Since $Z_i \sim N(s_i)$, $EI=Z^TI=$ $Z = (x^T x + PI)^{-1} x^T x (x^T x + PI)^{-1}$
	$Z = (X \times YYZ) \times X \times (X \times YYZ)$
(e)	Bins: β ins(Q)=((X^TX+P^Z)- $^{I}X^TX-I$)Q
9	11 (1) - (1) - (1) - (1) - (1)
	As $9 \rightarrow \infty$: Bin (a) $\approx (2-1)\vec{a} \approx 0$ Bin (b) reduce
	MM-70: Bin (a) ~ (I-1) 0 > Bin (a) reduce
	[1] Bias (Q) , = O (P+m)
	$\Xi : \Xi = (X^TX + PI)^{-1}X^TX(X^TX + PI)^{-1}$
	A1P70; ZZ(XX) A1P70; ZZO 3 Z reduce
	A) n72: E (XTX) T & O } 12 reduce
	[I] Ell ₂ = O(P+m)

5 (a), i	L(a,s;a,u)=== a 2+P==s:-== W2(y:o(x:)7a-1+si)-== V2si
	=== = = = = = = = = = = = = = = = = =
ii.	dL(a,s,a,w) = Q - = Niyi p(Xi)
	$0 = \Omega - \frac{m}{2} V_i Y_i \phi(V_i)$
	$0 = \sum_{i=1}^{n} u_i y_i \phi(x_i)$
	2(のルノ)= 主川芸ルンタ(な)に一芸ルンタ(な)だいりの(な)十芸儿
	= 主型を以りメングタ(XJP(X))- 言いりソングタ(XJP(X))+ こいし
	ニーナララルルメソトのは、アカは、アカは、アカは、ナルナー
	$-11 \leq u \times \phi(x_1) ^2 + u^{\dagger} $
	dL(Q) = p - = 1 1/2 - = 1/2
	0= P-U-V
	P=UtV
	Since Was and Vao and P=U+V, get JOENEP
	Maximin 1 11 M 11 11 (12 11 17 1
	DUNL: Maximize = = = = = = = = = = = = = = = = = = =
	Subject to 0 < U < P
1	Dual: maximize -主芸芸 NzNiYiX Kiji
îii	
	Subject to 0 < U < P
÷./	Value = \$15/75K/1
IV.	Visit Area Control of the Control of
	$\nabla_{u} bu = \left(-\frac{\pi}{2} \frac{y_{i} y_{i}}{y_{i} k_{i}} + 1\right) = 1$
	3-11/1/2

(b).

```
def fit data(X,y,Kfun,rho,maxiter=1000):
  K = Kfun(X, X)
   def get grad(u):
       return np.ones_like(u) - (y * np.dot(u * y, K))
  u = np.ones(X.shape[0])
  for in range(maxiter):
       u = np.clip(u - 0.01 * get_grad(u), 0, rho)
   def inference(x):
       Kt = Kfun(x, X)
       return np.sign(np.dot(y * u, Kt.T))
   return inference
def LinearKfun(X1,X2):
  return np.dot(X1, X2.T)
rhos = [0.01, 0.1, 1, 10]
for rho in rhos:
   inference = fit data(X, y, LinearKfun, rho)
   print(f"rho = {rho}, Train error: {np.mean(inference(X) != y):.4f},
Test error: {np.mean(inference(Xt) != yt):.4f}")
rho = 0.01, Train error: 0.2580, Test error: 0.2900
rho = 0.1, Train error: 0.2540, Test error: 0.2900
rho = 1, Train error: 0.2530, Test error: 0.2900
rho = 10, Train error: 0.2530, Test error: 0.2900
```

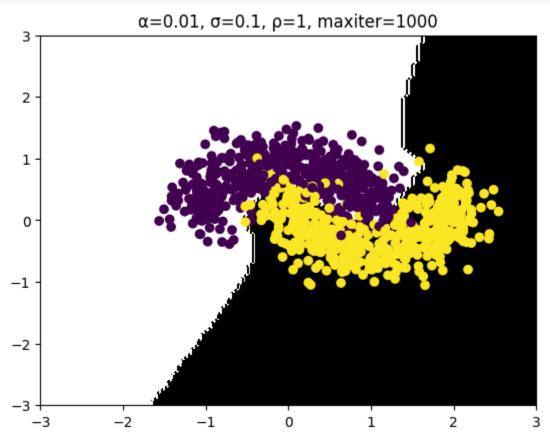
```
(c).
inference = fit_data(X, y, LinearKfun, 1)
Xp, Yp, Zp = plot_model_contour(inference)
plt.contourf(Xp, Yp, Zp, colors=['#FFFFFF', '#000000'])
plt.scatter(*X.T, c=y)
plt.title("α=0.01, ρ=1, maxiter=1000")
plt.show()
```



(d).

```
def fit data(X, y, Kfun, sigma, rho, maxiter=1000):
  K = Kfun(X, X, sigma)
  def get grad(u):
       return np.ones_like(u) - (y * np.dot(u * y, K))
  u = np.ones(X.shape[0])
  for in range(maxiter):
       u = np.clip(u - 0.01 * get_grad(u), 0, rho)
   def inference(x):
       Kt = Kfun(x, X, sigma)
      return np.sign(np.dot(y * u, Kt.T))
  return inference
def RBFKfun(X1,X2,sigma):
   sq = np.sum(X1**2, axis=1).reshape(-1, 1) - 2 * np.dot(X1, X2.T) +
np.sum(X2**2, axis=1)
  return np.exp(- sq / (2 * sigma**2))
sigmas = [1, 0.1, 0.001, 0.0001]
for sigma in sigmas:
   inference = fit data(X, y, RBFKfun, sigma, 1)
  print(f"Sigma: {sigma}, Train error: {np.mean(inference(X) != y):.4f},
Test error: {np.mean(inference(Xt) != yt):.4f}")
Sigma: 1, Train error: 0.1990, Test error: 0.2200
Sigma: 0.1, Train error: 0.0520, Test error: 0.0400
Sigma: 0.001, Train error: 0.0020, Test error: 0.5200
Sigma: 0.0001, Train error: 0.0000, Test error: 0.9700
```

```
(e).
inference = fit_data(X, y, RBFKfun, 0.1, 1)
Xp, Yp, Zp = plot_model_contour(inference)
plt.contourf(Xp, Yp, Zp, colors=['#FFFFFF', '#000000'])
plt.scatter(*X.T, c=y)
plt.title("α=0.01, σ=0.1, ρ=1, maxiter=1000")
plt.show()
```



(f). When $\sigma \to 0$, SVM is too sensitive to a single data point, causing the model to fit the training data very closely but lose generalization ability, leading to overfitting. This is why although Train error -> 0, the Test error is getting bigger and bigger.