

Homework 4

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1 Exercise 17.3

Here we have a Hidden Markov Model (HMM) with a Gaussian Mixture observation model. Assuming we have a discrete $Z \in \{1 \dots K\}$ latent states in the HMM model and an observation model comprised of $M = 1, 2, \dots$ mixture of Gaussians. Let i, k be the indexers for Z , and m be the indexer for M , and we define the transition matrix $A = [A_{jk}]$ be a square matrix that is in $R^{K \times K}$ with each row $A_j = \sum_k A_{jk} = 1$. A is time-invariant because of a homogeneous Markov assumption. Now, we also have a set of realization sequences $X_{obs} = (X_1, X_2, \dots, X_N)$ and each sequence $X_i = (X_{i1}, X_{i2}, \dots, X_{iT_i})$. Along with the observations, we have the latent variable Z_{it} and M_{it} corresponding to each sequence, and each time, $X_{hid} = (Z, M)$. Therefore, if we have full information about the latent variables, we have the following complete data log-likelihood.

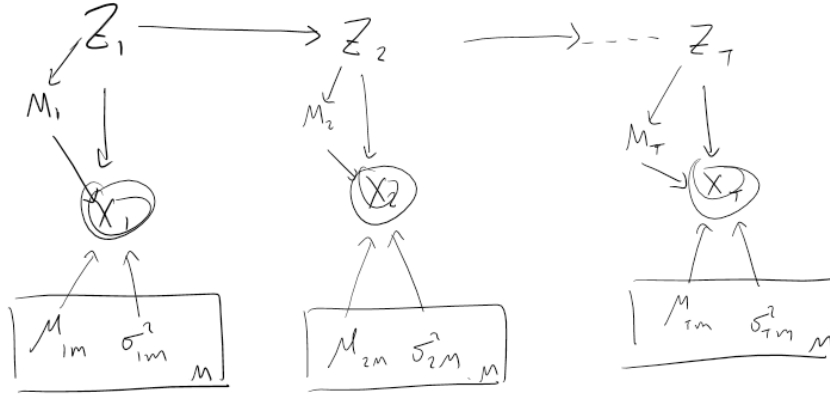


Figure 1: HMM with Gaussian Mixture per Latent State

$$\begin{aligned}
p(X_t|Z_t = j, \theta) &= \sum_m w_{jm} \mathcal{N}(X_t|\mu_{jm}, \Sigma_{jm}) \\
p(X_{1:T}, Z_{1:T}, M_{1:T}) &= p(Z_{1:T})p(X_{1:T}, M_{1:T}|Z_{1:T}) \\
&= p(Z_1) \prod_{t=2}^T p(Z_t|Z_{t-1}) \prod_{t=1}^T p(X_t, M_t|Z_t) \\
&= \prod_{j=1}^K \pi_j^{\mathbb{I}(Z_1=j)} \prod_{t=2}^T \prod_{j=1}^K \prod_{k=1}^K A_{jk}^{\mathbb{I}(Z_t=j, Z_{t-1}=k)} \prod_{t=1}^T \prod_{j=1}^K \prod_{m=1}^M p(X_t, M_t|Z_t = j)^{\mathbb{I}(Z_t=j, M_t=m)} \\
\ell_c(\theta) &= \sum_{j=1}^K N_j^1 \ln \pi_j + \sum_{j=1}^K \sum_{k=1}^K N_{jk} \ln A_{jk} + \sum_{j=1}^K \sum_{m=1}^M N_{jm} \ln w_{jm} \\
&\quad + \sum_{i=1}^N \sum_{t=1}^T \sum_{j=1}^K \sum_{m=1}^M \mathbb{I}(Z_{i,t} = j) \mathbb{I}(M_{i,t} = m) \ln \mathcal{N}(X_{i,t}|\mu_{jm}, \Sigma_{jm}) \\
N_j^1 &= \sum_{i=1}^N \mathbb{I}(Z_{i,1} = j) \\
N_{jk} &= \sum_{i=1}^N \sum_{t=2}^T \mathbb{I}(Z_{i,t} = j, Z_{i,t-1} = k) \\
N_{jm} &= \sum_{i=1}^N \sum_{t=1}^T \mathbb{I}(Z_{i,t} = j, M_{i,t} = m)
\end{aligned}$$

E-step Due to the latent variables, we need to use EM or Baum-Welch algorithm. Here we derive the solutions for those determined by Z and M for the E-step. γ and ξ are the solutions from the forward-backward algorithm smoothing. And the responsibility $r_{i,t,j,m}$ decompose because it has

no time dependency, which results in a usual EM solution conditional on $Z_{i,t} = j$.

$$\begin{aligned}
Q(\theta, \theta^{t-1}) &= \mathbb{E}[\ell_c(\theta)|X, \theta^{t-1}] \\
&= \sum_{j=1}^K \mathbb{E}[N_j^1] \ln \pi_j + \sum_{j=1}^K \sum_{k=1}^K \mathbb{E}[N_{jk}] \ln A_{jk} + \sum_{j=1}^K \sum_{m=1}^M \mathbb{E}[N_{jm}] \ln w_{jm} \\
&\quad + \sum_{i=1}^N \sum_{t=1}^T \sum_{j=1}^K \sum_{m=1}^M p(Z_{i,t} = j, M_{i,t} = m | X, \theta^{t-1}) \ln \mathcal{N}(X_{i,t} | \mu_{jm}, \Sigma_{jm}) \\
\mathbb{E}[N_j^1] &= \sum_{i=1}^N p(Z_{i,1} = j | X_i, \theta^{t-1}) = \sum_{i=1}^N \gamma_{i,1}(j) \\
\mathbb{E}[N_{jk}] &= \sum_{i=1}^N \sum_{t=2}^{T_i} p(Z_{t-1} = j, Z_t = k | X_i, \theta^{t-1}) = \sum_{i=1}^N \sum_{t=2}^{T_i} \xi_{i,t}(j, k) \\
\mathbb{E}[N_j] &= \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{m=1}^M p(M_{i,t} = m | Z_{i,t} = j, X_i, \theta^{t-1}) p(Z_{i,t} = j | X_i, \theta^{t-1}) \\
&= \sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j) \sum_{m=1}^M r_{i,t,j,m} \\
\gamma_{i,t}(j) &= p(Z_t = j | X_i, \theta) \\
\xi_{i,t}(j, k) &= p(Z_{t-1} = j, Z_t = k | X_i, \theta) \\
r_{i,t,j,m} | Z_{i,t} &= \frac{w_{jm} \mathcal{N}(X_{it} | \mu_{jm}, \Sigma_{jm})}{\sum_{m'=1}^M w_{jm'} \mathcal{N}(X_{it} | \mu_{jm'}, \Sigma_{jm'})}
\end{aligned}$$

M-step The M-step solutions follow the Baum-Welch results with a sprinkle of GMM results.

$$\begin{aligned}
\hat{A}_{jk} &= \frac{\mathbb{E}[N_{jk}]}{\sum_{k'} \mathbb{E}[N_{jk'}]} \\
\hat{\pi}_k &= \frac{\mathbb{E}[N_k^1]}{N} \\
\hat{w}_{jm} &= \frac{\mathbb{E}[N_{jm}]}{\mathbb{E}[N_j]} \\
\hat{\mu}_{jm} &= \frac{\mathbb{E}[\bar{X}_{jm}]}{\mathbb{E}[N_{jm}]} \\
\mathbb{E}[\bar{X}_{jm}] &= \sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j) r_{i,t,j,m} X_{i,t} \\
\hat{\Sigma}_{jm} &= \frac{\mathbb{E}[(X\bar{X})_{jm}^\top] - \mathbb{E}[N_{jm}] \hat{\mu}_{jm} \hat{\mu}_{jm}^\top}{\mathbb{E}[N_{jm}]} \\
\mathbb{E}[(X\bar{X})_{jm}^\top] &= \sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j) r_{i,t,j,m} X_{i,t} X_{i,t}^\top
\end{aligned}$$

2 Exercise 17.4

Here in this question, instead of having KM different Gaussians, we assume that we only have M Gaussians. The latent variable Z only affects the mixture weights w_{jm} .

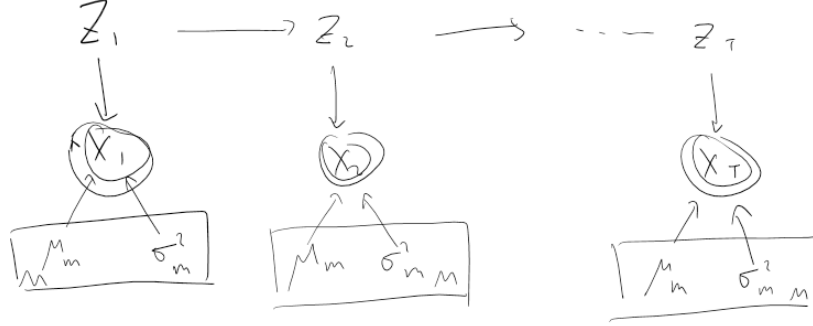


Figure 2: Semi-Continuous HMM with a Tied Gaussian Mixtures

The E-Step Hence, the new observation model and the expected complete data log-likelihood are below, which is very similar to the previous exercise.

$$\begin{aligned}
 p(X_t|Z_t = j, \theta) &= \sum_m w_{jm} \mathcal{N}(X_t|\mu_m, \Sigma_m) \\
 Q(\theta, \theta^{t-1}) &= \mathbb{E}[\ell_c(\theta)|X, \theta^{t-1}] \\
 &= \sum_{j=1}^K \mathbb{E}[N_j^1] \ln \pi_j + \sum_{j=1}^K \sum_{k=1}^K \mathbb{E}[N_{jk}] \ln A_{jk} + \sum_{j=1}^K \sum_{m=1}^M \mathbb{E}[N_{jm}] \ln w_{jm} \\
 &\quad + \sum_{i=1}^N \sum_{t=1}^T \sum_{j=1}^K p(Z_{i,t} = j|X, \theta^{t-1}) \sum_{m=1}^M p(M_{i,t} = m|X, \theta^{t-1}) \ln \mathcal{N}(X_{i,t}|\mu_m, \Sigma_m)
 \end{aligned}$$

$$\begin{aligned}
 \mathbb{E}[N_j^1] &= \sum_{i=1}^N p(Z_{i,1} = j|X_i, \theta^{t-1}) = \sum_{i=1}^N \gamma_{i,1}(j) \\
 \mathbb{E}[N_{jk}] &= \sum_{i=1}^N \sum_{t=2}^{T_i} p(Z_{t-1} = j, Z_t = k|X_i, \theta^{t-1}) = \sum_{i=1}^N \sum_{t=2}^{T_i} \xi_{i,t}(j, k) \\
 \mathbb{E}[N_{jm}] &= \sum_{i=1}^N \sum_{t=1}^{T_i} p(M_{i,t} = m|Z_{i,t} = j, X_i, \theta^{t-1}) p(Z_{i,t} = j|X_i, \theta^{t-1}) \\
 &= \sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j) r_{i,t,j,m}
 \end{aligned}$$

$$\gamma_{i,t}(j) = p(Z_t = j|X_i, \theta)$$

$$\xi_{i,t}(j, k) = p(Z_{t-1} = j, Z_t = k|X_i, \theta)$$

$$r_{i,t,j,m}|Z_{i,t} = \frac{w_{jm} \mathcal{N}(X_{it}|\mu_m, \Sigma_m)}{\sum_{m'}^M w_{jm'} \mathcal{N}(X_{it}|\mu_{m'}, \Sigma_{m'})}$$

The M-Step Similarly, the maximization step is also lookalike. Just the new μ and Σ MLE solutions now incorporate all data no matter the latent state were.

$$\begin{aligned}
\hat{A}_{jk} &= \frac{\mathbb{E}[N_{jk}]}{\sum_{k'} \mathbb{E}[N_{jk'}]} \\
\hat{\pi}_k &= \frac{\mathbb{E}[N_k^1]}{N} \\
\hat{w}_{jm} &= \frac{\mathbb{E}[N_{jm}]}{\mathbb{E}[N_j]} \\
\hat{\mu}_m &= \frac{\mathbb{E}[\bar{X}_m]}{\mathbb{E}[N_m]} \\
\mathbb{E}[\bar{X}_m] &= \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{j=1}^K \gamma_{i,t}(j) r_{i,t,j,m} X_{i,t} \\
\hat{\Sigma}_m &= \frac{\mathbb{E}[(X\bar{X})_m^T] - \mathbb{E}[N_m] \hat{\mu}_m \hat{\mu}_m^T}{\mathbb{E}[N_m]} \\
\mathbb{E}[(X\bar{X})_m^T] &= \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{j=1}^K \gamma_{i,t}(j) r_{i,t,j,m} X_{i,t} X_{i,t}^T
\end{aligned}$$

3 AQ 1

Given the transition matrix A with 5 states $\{A, B, C, D, E\}$, it has the following properties.

Communicating class

1. $c_1 = \{A, E\}$
2. $c_2 = \{B, D\}$
3. $c_3 = \{C\}$

Recurrent Transient

1. Recurrent: $\{A, E, C\}$
2. Transient: $\{B, D\}$

Stationary Distribution

$$\begin{bmatrix} \frac{1}{2} & 0 & 0 & 0 & \frac{1}{2} \\ \frac{1}{4} & 0 & \frac{1}{2} & 0 & \frac{1}{4} \\ 0 & 0 & 1 & 0 & 0 \\ \frac{1}{4} & 0 & \frac{1}{2} & 0 & \frac{1}{4} \\ \frac{1}{2} & 0 & 0 & 0 & \frac{1}{2} \end{bmatrix}$$

4 AQ 2

Under a time-invariant homogeneous Markov Chain, the transition matrix A is time-invariant. Therefore, we have the Chapman-Kolmogorov property.

$$\begin{aligned} A_{ij}(n) &= p(X_{t+n} = j | X_t = i) \\ A(m+n) &= A(m)A(n) \\ A(n) &= AA(n-1) = AAA(n-2) = \dots = A^n \end{aligned}$$

Hence, if we have a X_0, X_1, X_2, \dots Markov Chain with a transition matrix P and a initial state π_o . Then a new chain $Y_t = X_{kt}$ that every step moves k steps equivalently in X has a transition matrix P^k

$$\begin{aligned} X_{kt-k+1} &= X_{kt-k}P \\ X_{kt-k+2} &= X_{kt-k}P^2 \\ &\dots \\ X_{kt} &= X_{kt-k}P^k \\ Y_t &= X_{kt-k}P^k \\ Y_t &= \pi_o P^{kt} \end{aligned}$$

5 AQ 3

We can just brutal force it by constructing the transition matrix A with 6 finite states because we have $3!$ possible ordering given 3 books. The probability of choosing each book $i \in \{1, 2, 3\}$ is given by $a_i > 0$.

$$\begin{bmatrix} a_1 & 0 & a_2 & 0 & a_3 & 0 \\ 0 & a_1 & a_2 & 0 & a_3 & 0 \\ a_1 & 0 & a_2 & 0 & 0 & a_3 \\ a_1 & 0 & 0 & a_2 & 0 & a_3 \\ 0 & a_1 & 0 & a_2 & a_3 & 0 \\ 0 & a_1 & 0 & a_2 & 0 & a_3 \end{bmatrix}$$

The chain is finite and is certainly irreducible and aperiodic. Aperiodicity can be proven easily based on that each state has a self loop, the diagonals; hence, $\gcd\{t : A_{ii}(t) > 0\} = 1$. And we can certainly see the chain is strongly connected because the $P_{ij}(t) > 0, \forall i, j \in K, t > 0$.