

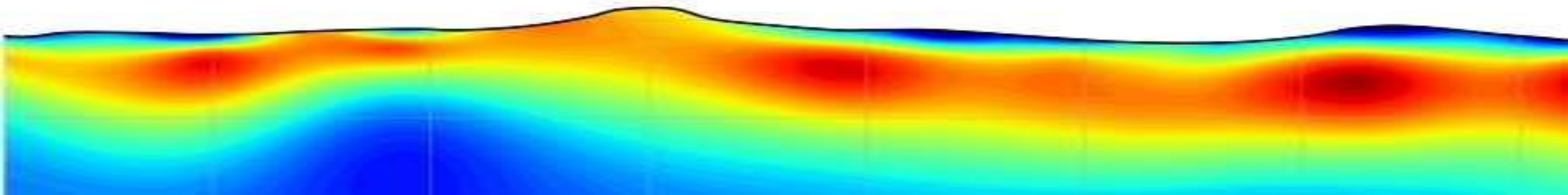
ESS302 Applied Geophysics II

Gravity, Magnetic, Electrical, Electromagnetic and Well Logging

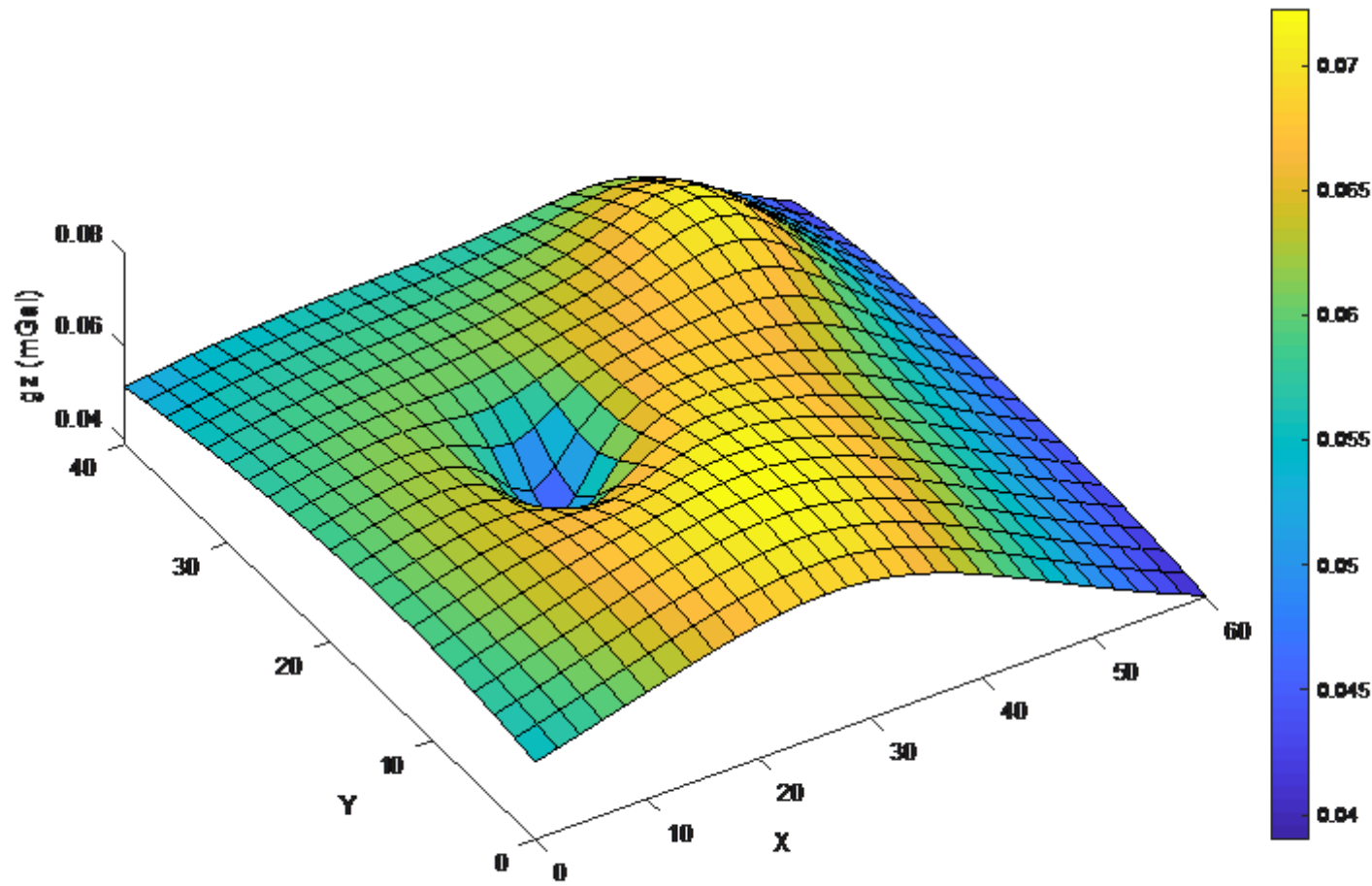
Gravity 3: Applications

Instructor: Dikun Yang

Feb – May, 2019



From the Last Lecture



Inherent ambiguity

- How many objects?
- How big/dense?
- Where are they?

Contents

- Upward and downward continuation
- Gravity gradiometry
 - Horizontal and vertical derivatives
 - Full tensor gravity gradient
- Gravity inversion
 - Geometric inversion
 - Pixel/voxel inversion
- Gravity applications
 - Planetary science
 - Environmental
 - Military

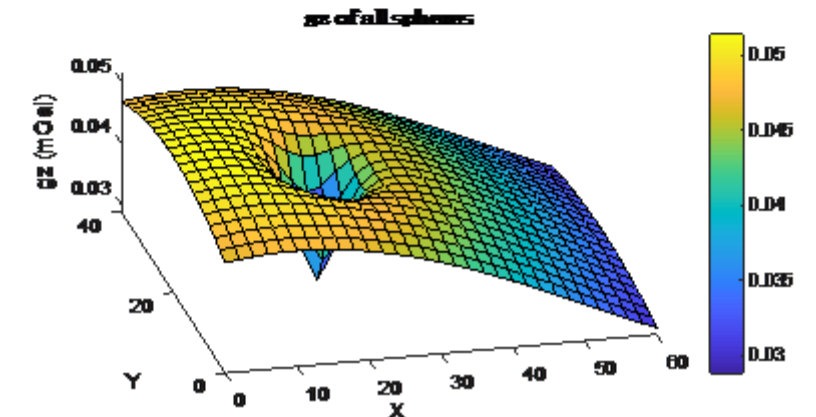
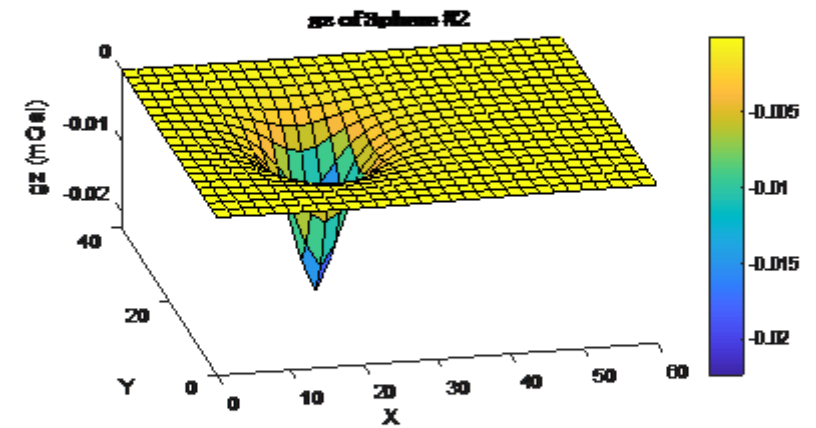
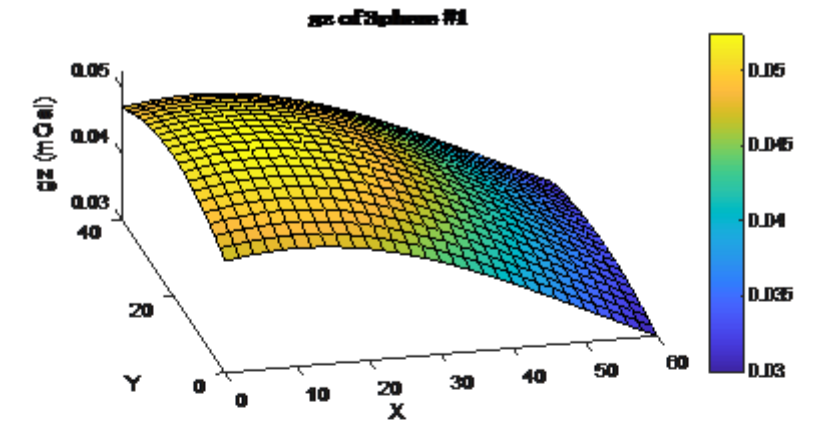
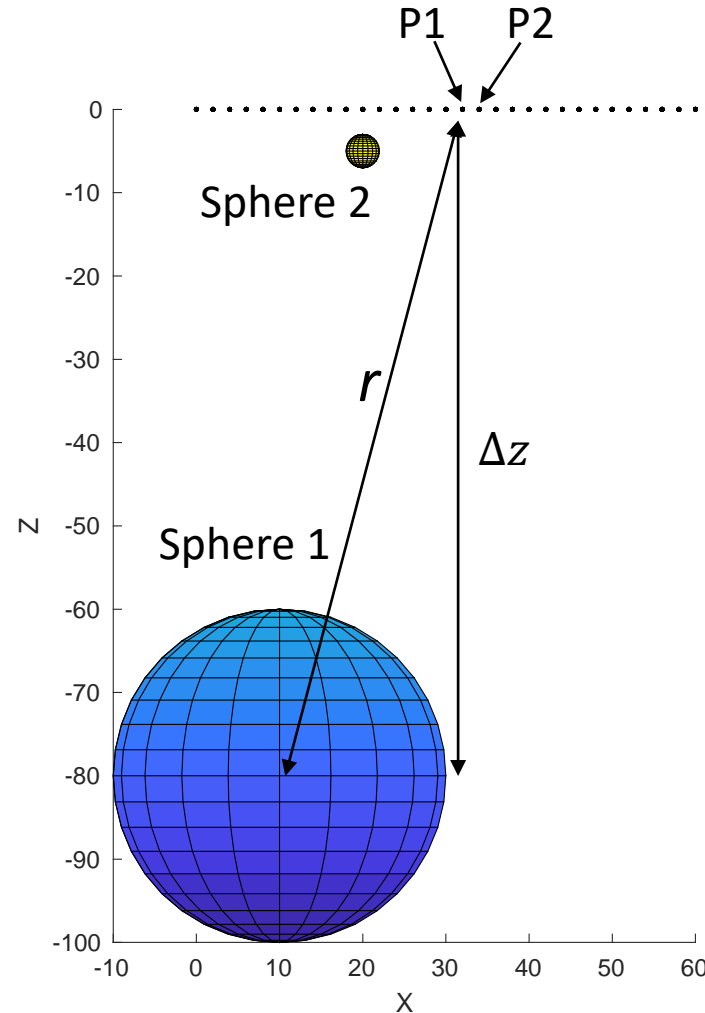
Gravity Signal Decays as $1/r^2$

We measure the vertical component of g on the surface

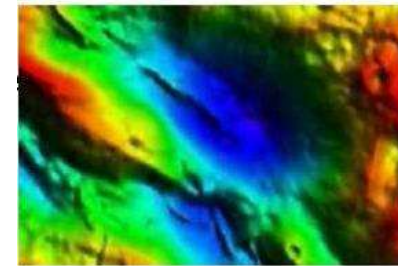
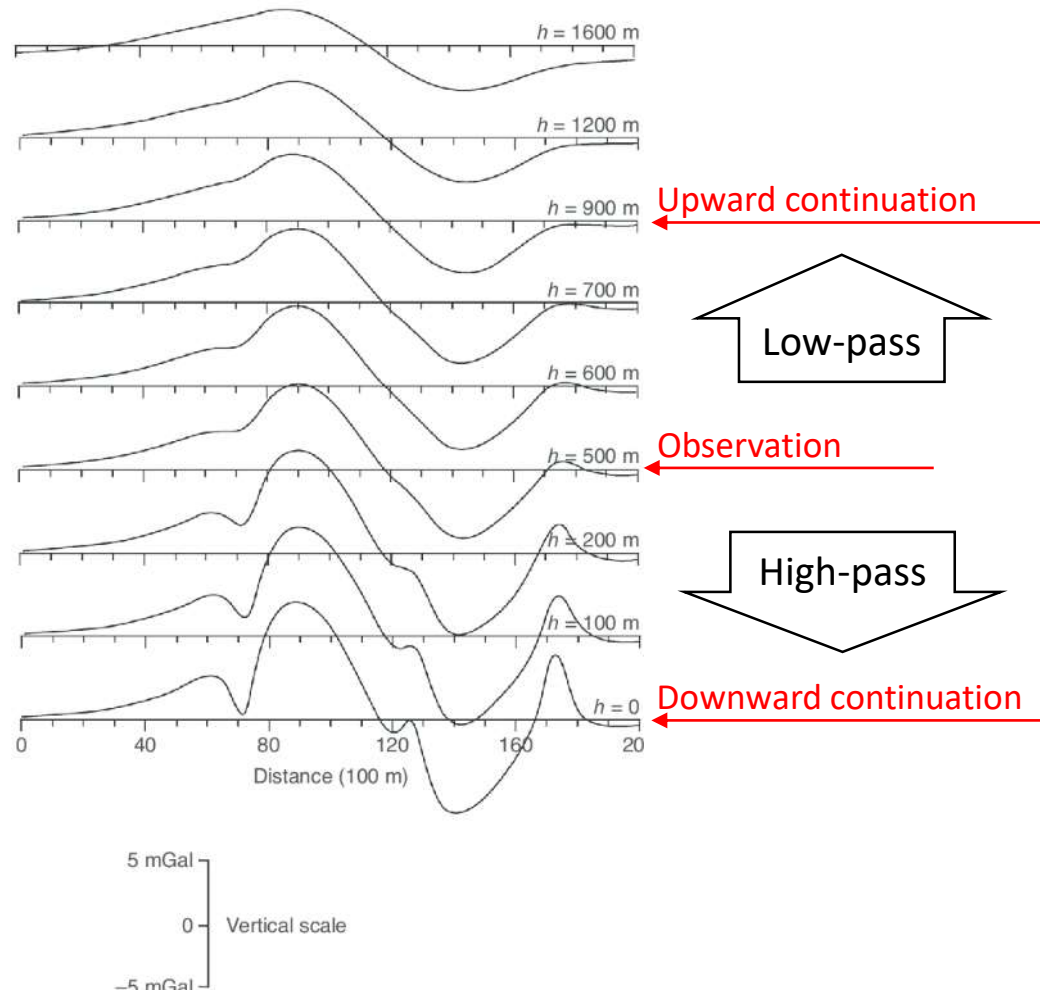
$$g_z = \frac{GM \Delta z}{r^3}$$

Large distance: long-wavelength

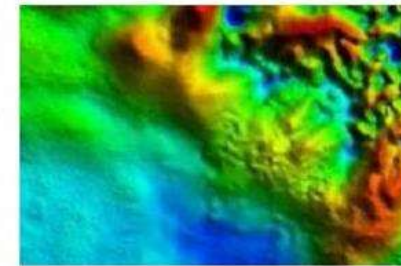
Small distance: short-wavelength



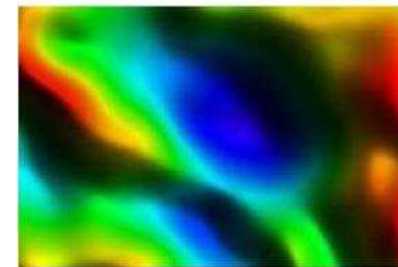
Upward and Downward Continuation



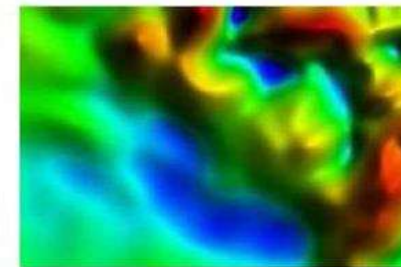
(a)



(b)



(c)



(d)

Original

Upward continued

Residual

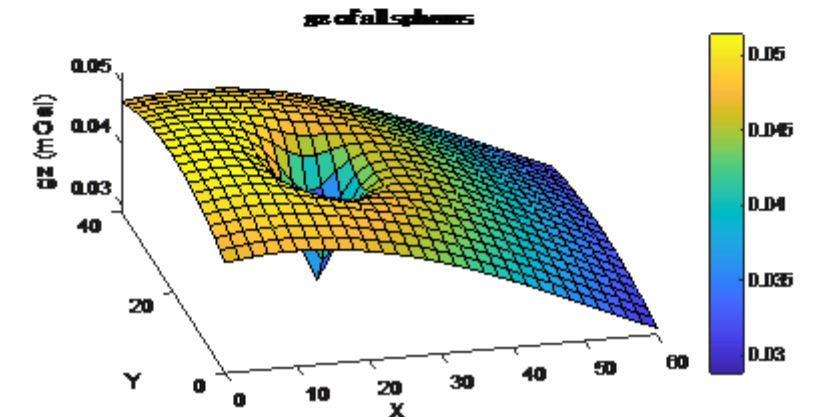
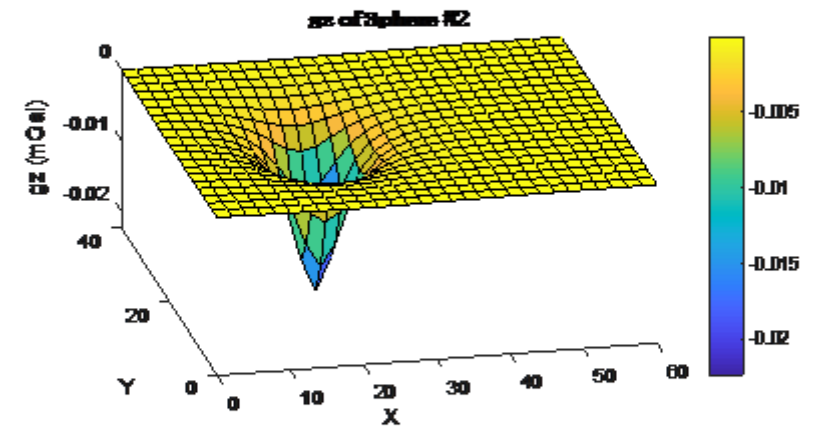
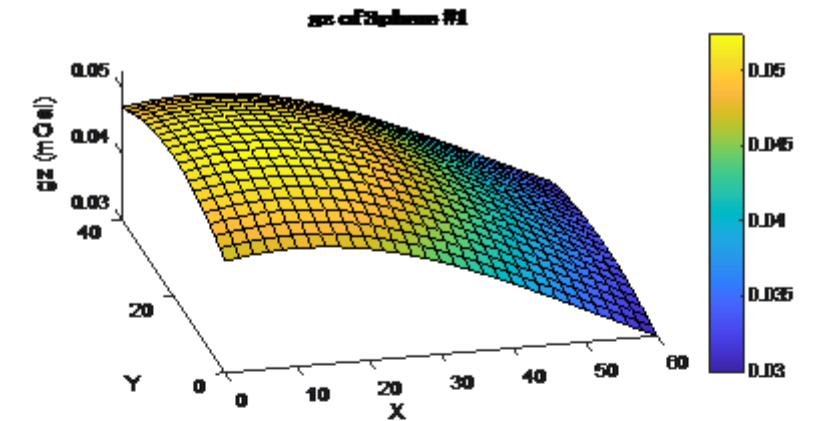
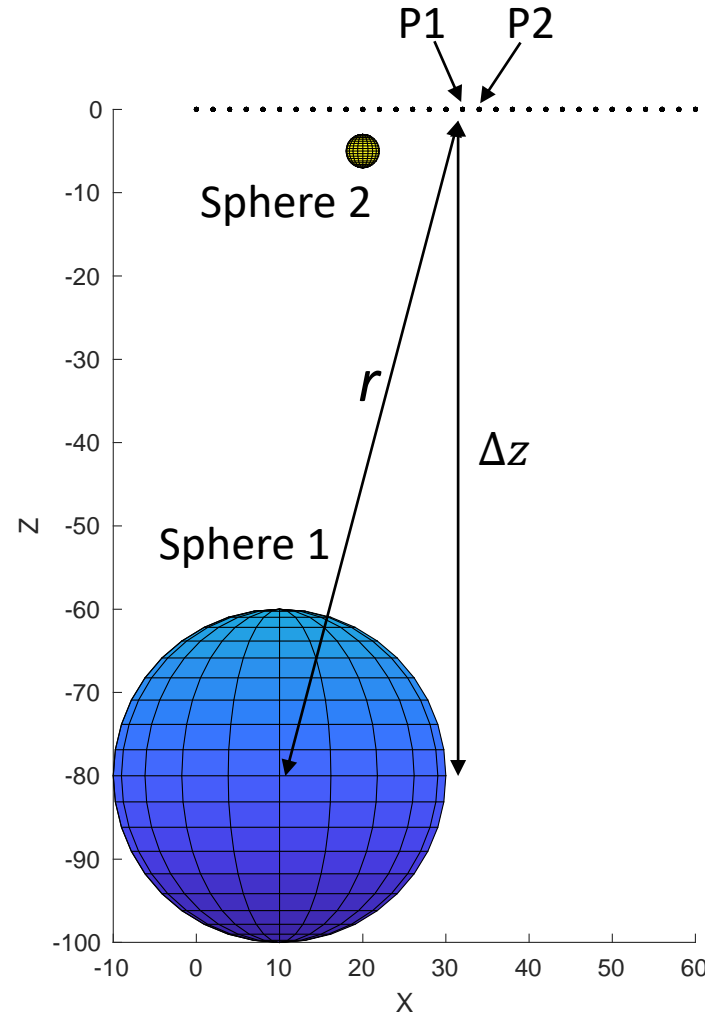
Gravity Signal Decays as $1/r^2$

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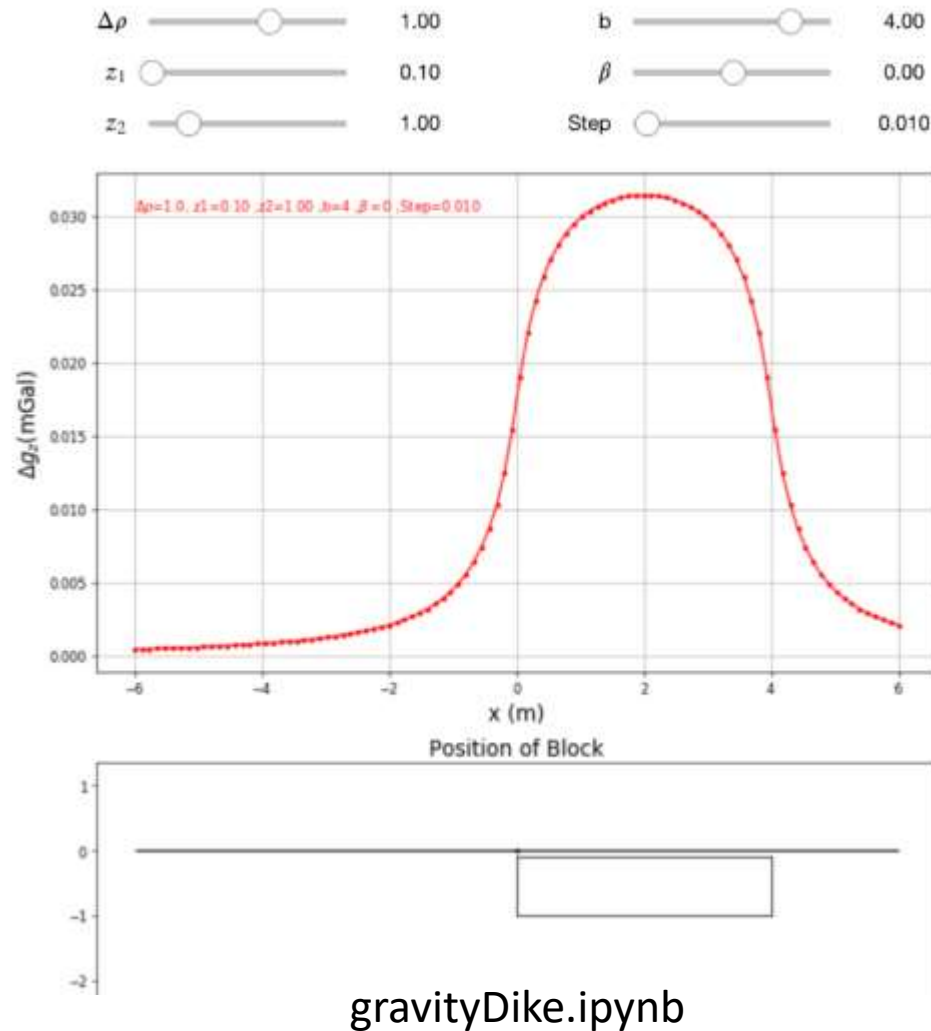
$$g_z = \frac{GM \Delta z}{r^3}$$

Large distance: long-wavelength

Small distance: short-wavelength

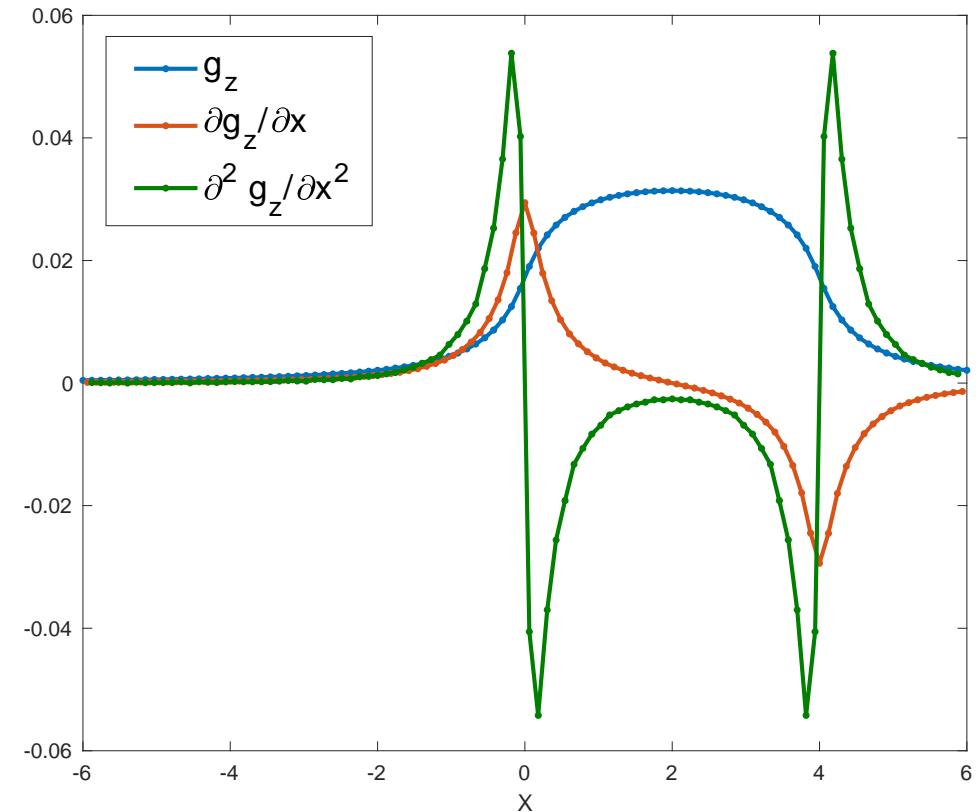


Horizontal Derivative

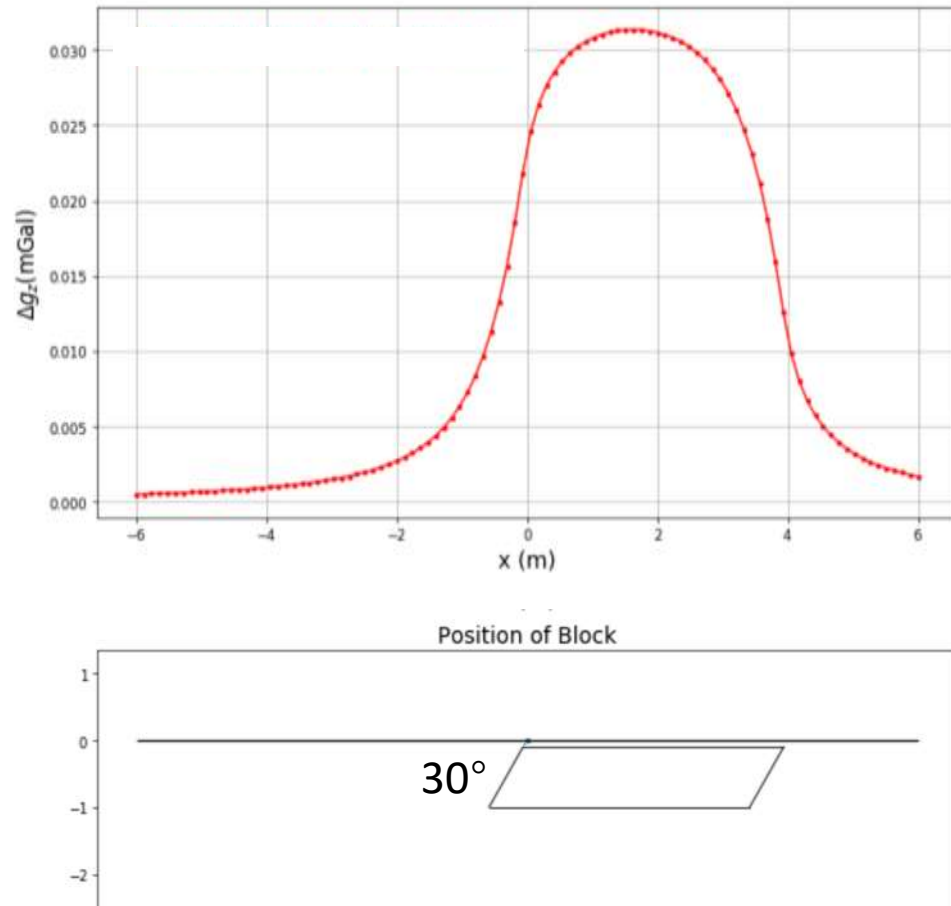


Draw the first and second horizontal derivatives

Which derivative is more useful in defining the edges?

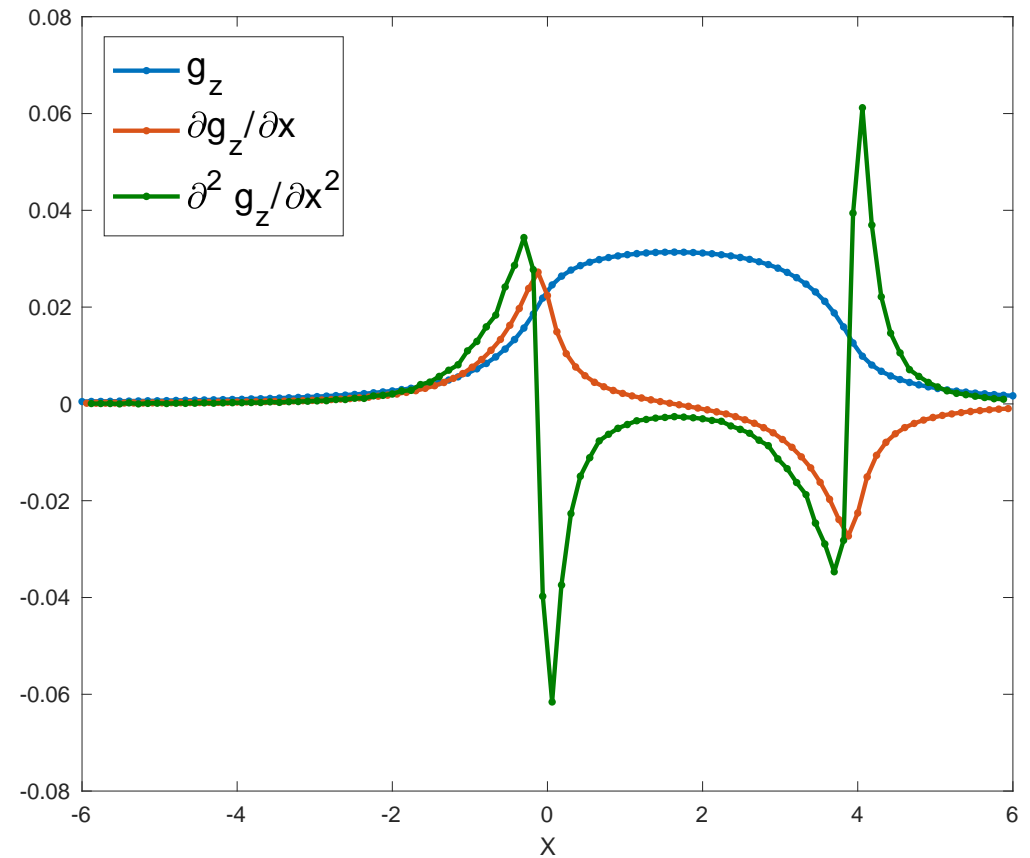


Horizontal Derivative

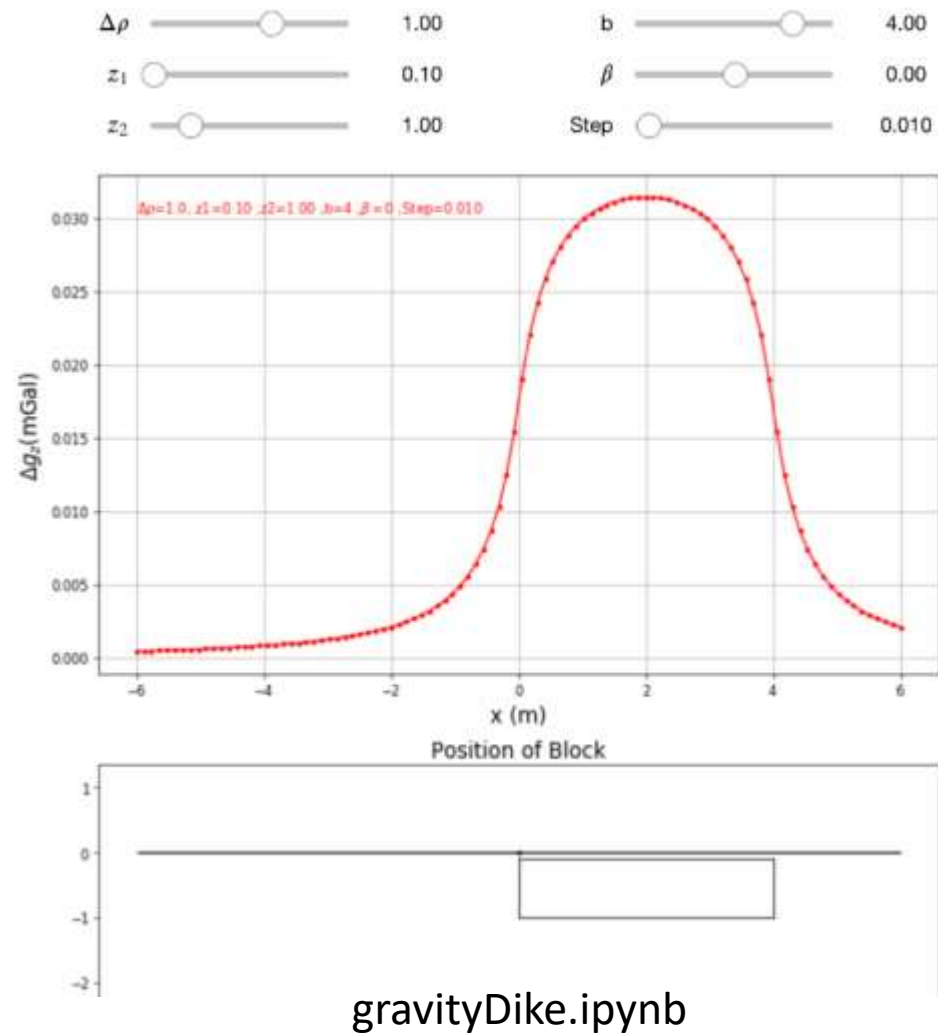


Can you tell the dipping direction from g_z ?

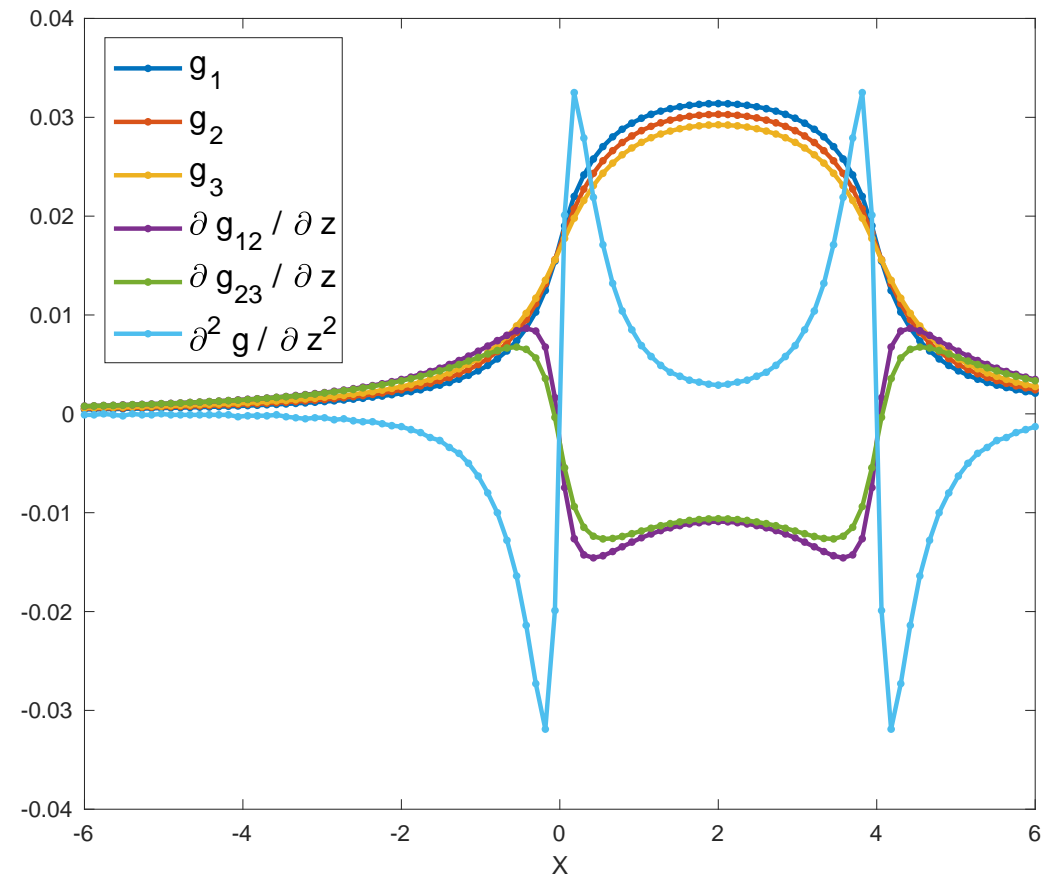
Which derivative is more useful in finding the dip?



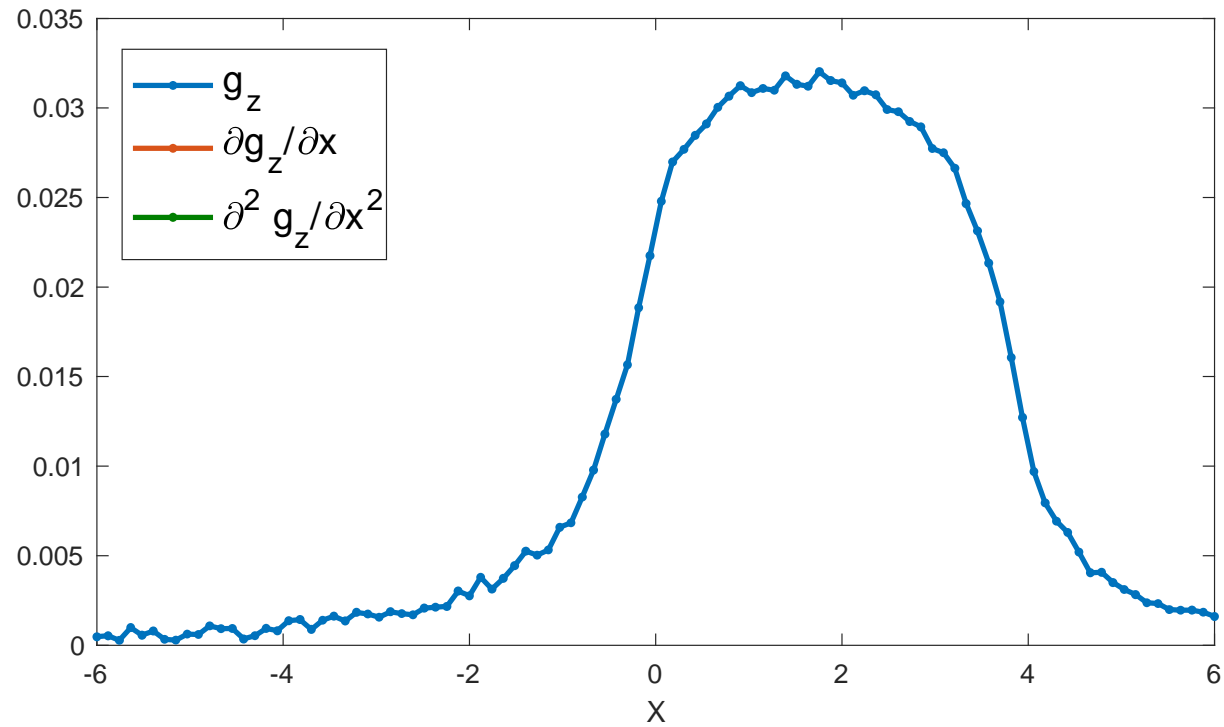
Vertical Derivatives



g_1 : 0 m above surface
 g_2 : 0.1 m above surface
 g_3 : 0.2 m above surface

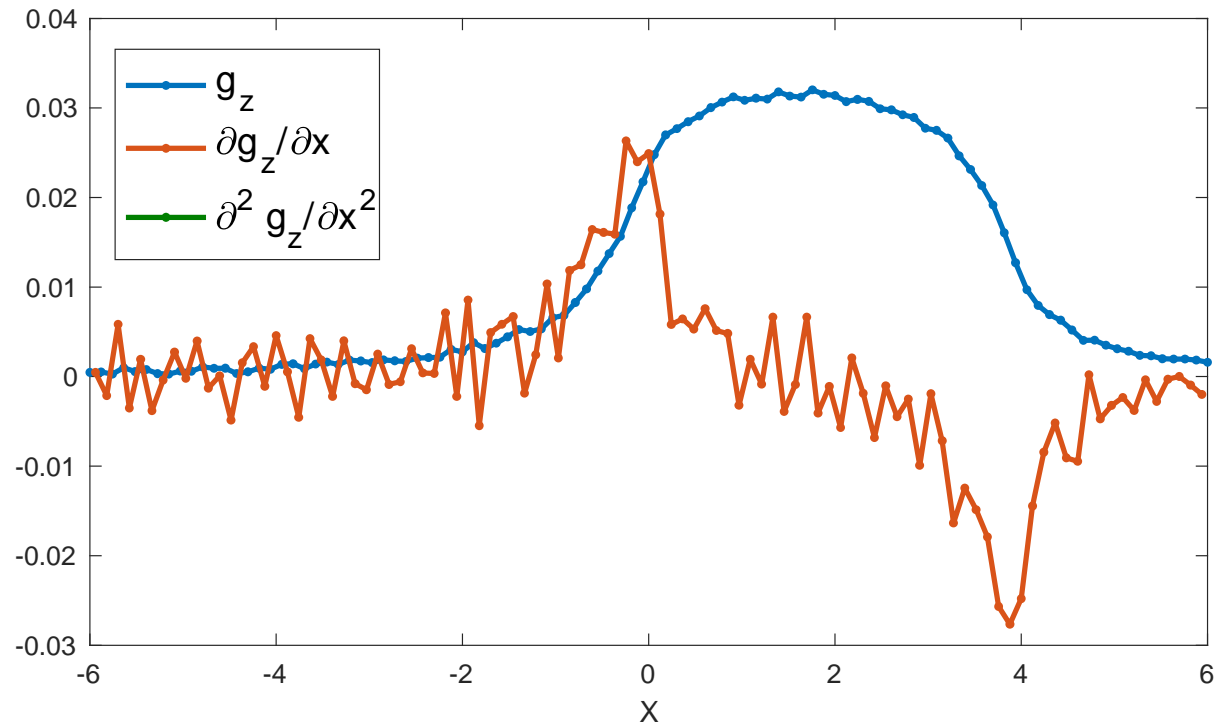


High Order Derivative?



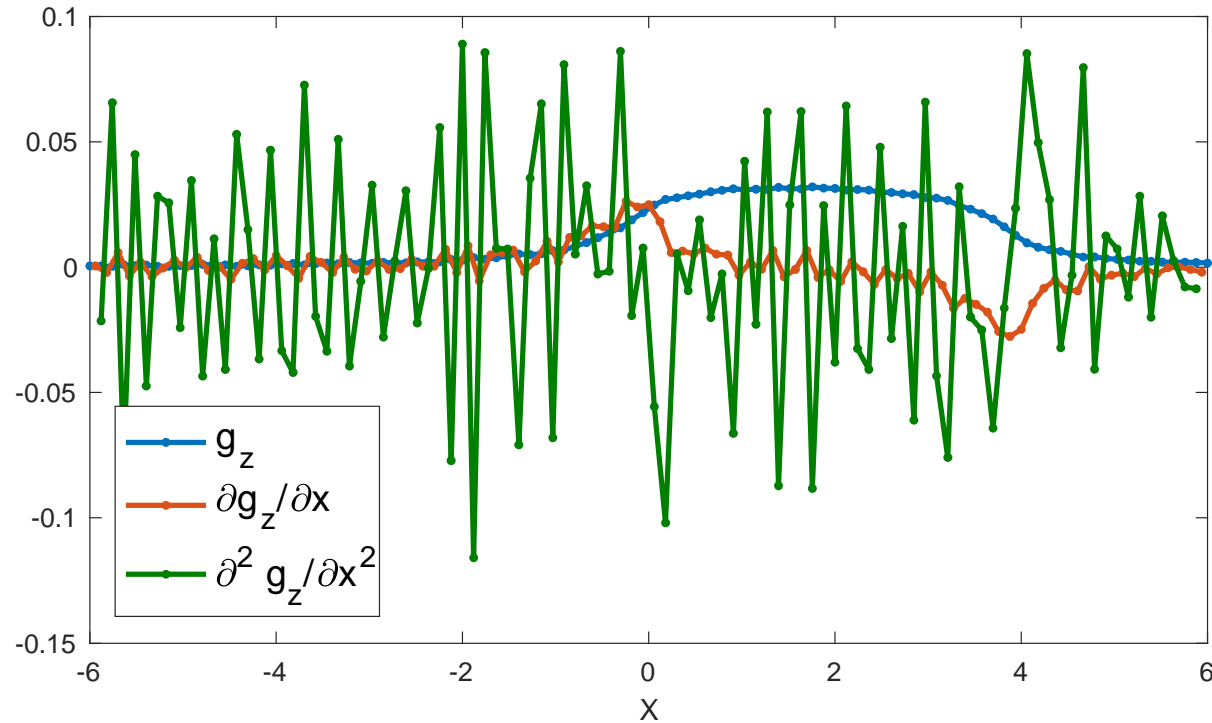
1% Gaussian noise in data

High Order Derivative?



Horizontal 1st derivative: Not too bad

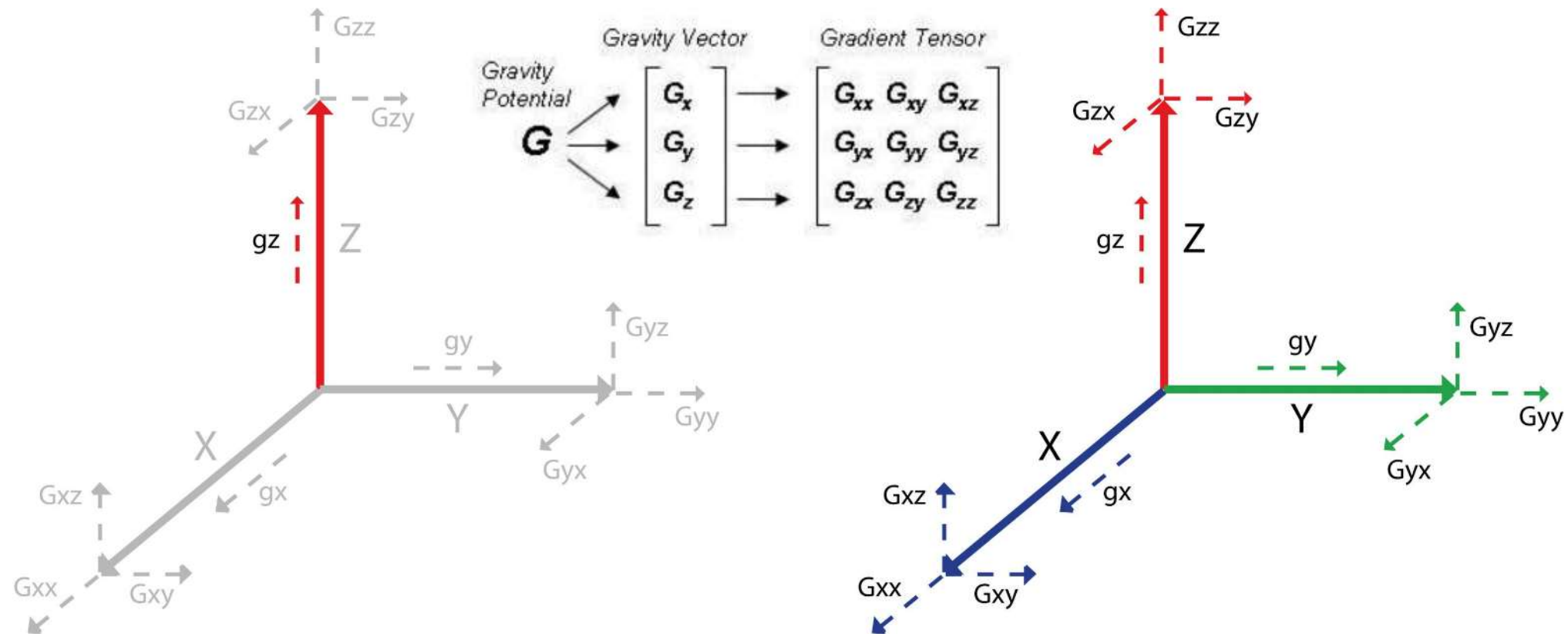
High Order Derivative?



Horizontal 2nd derivative: Caution!

Derivative magnifies noise in data

Full Tensor Gradient: More from g_x and g_y



3D-FTG

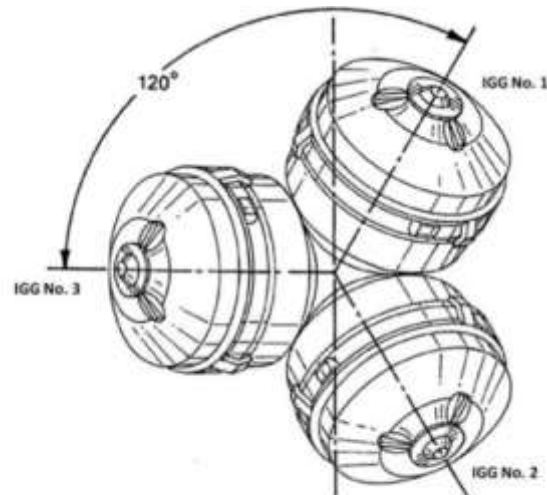


Figure 3 – Umbrella-like arrangement of Gravity Gradient Instruments (GGI) according to Brett & Brewster (2010).

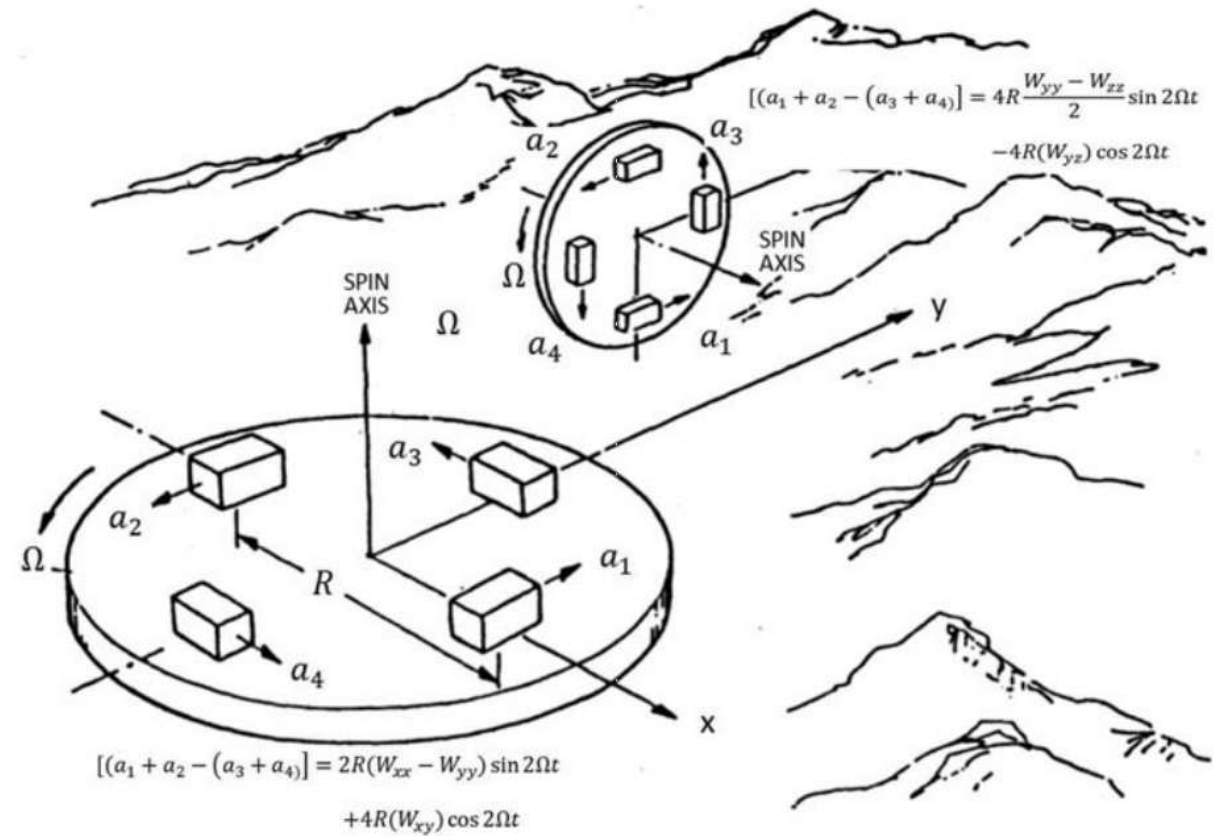
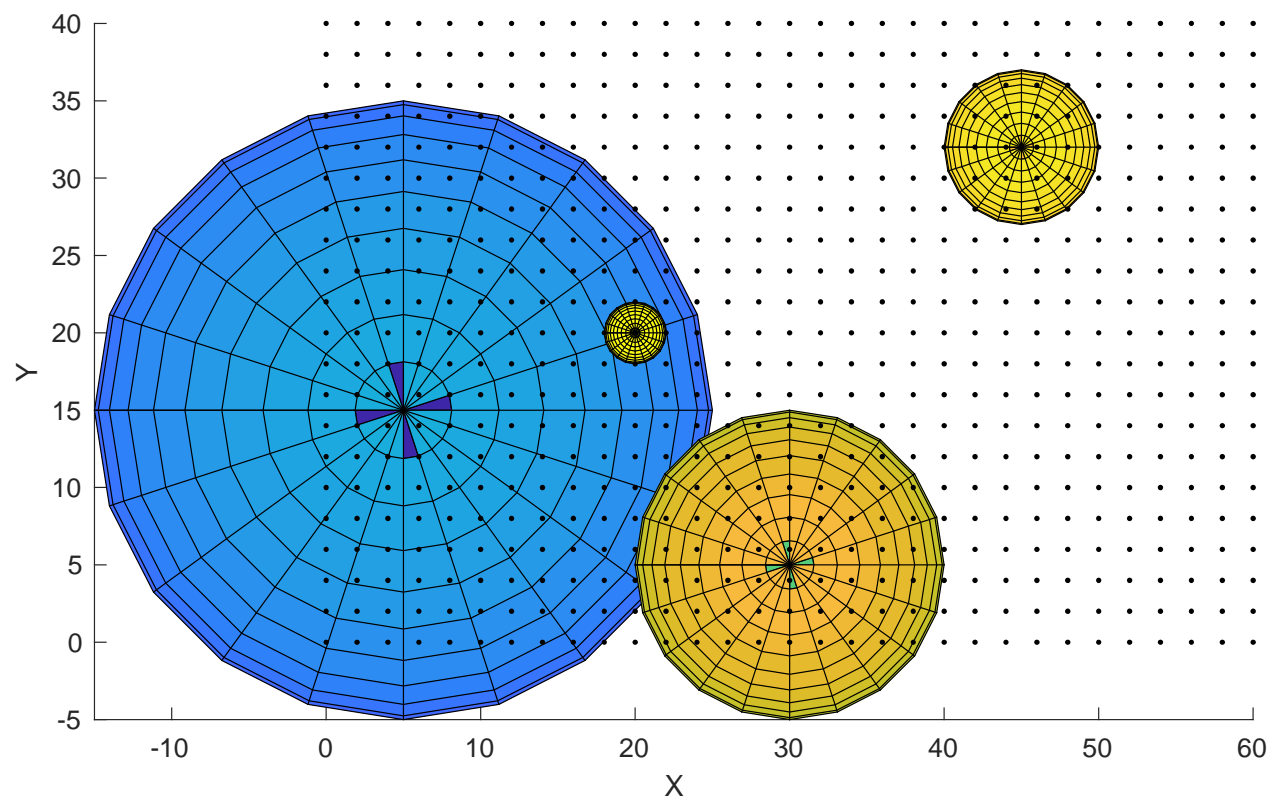
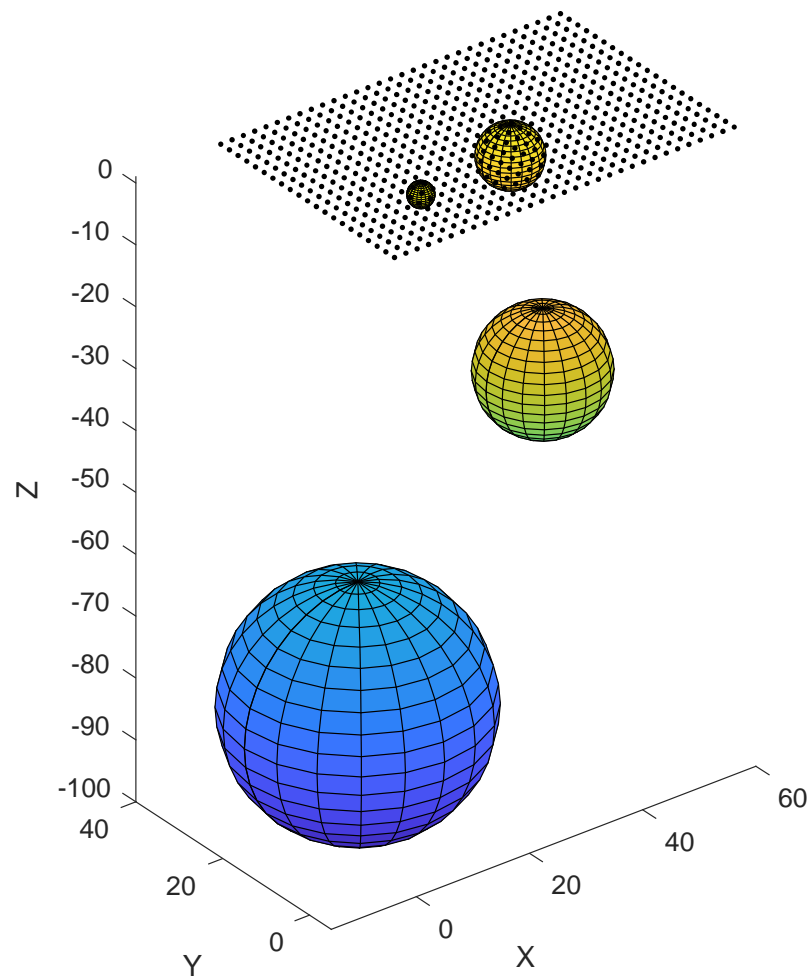
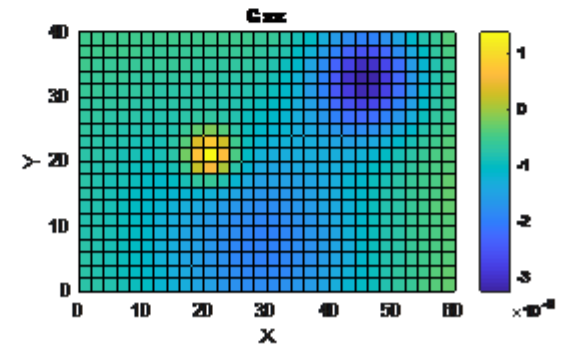
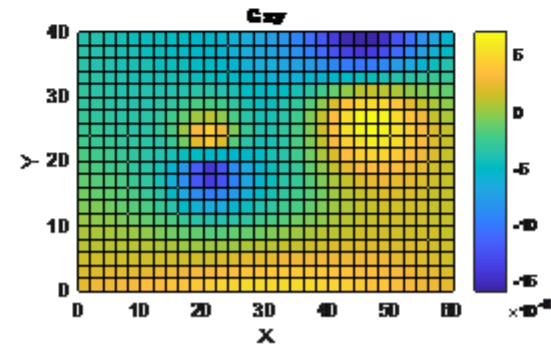
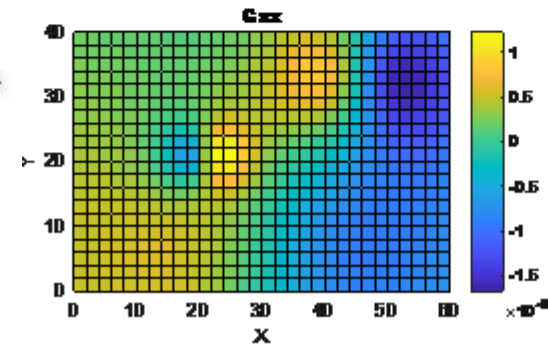
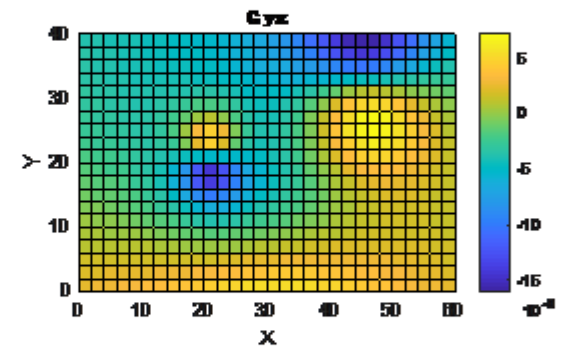
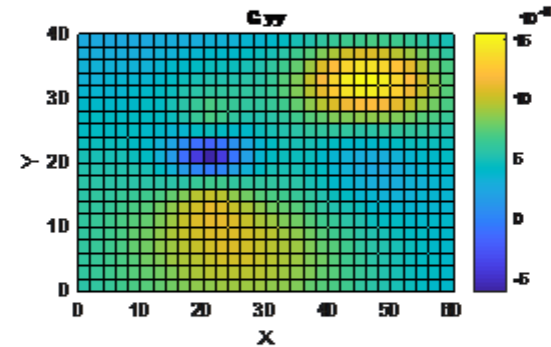
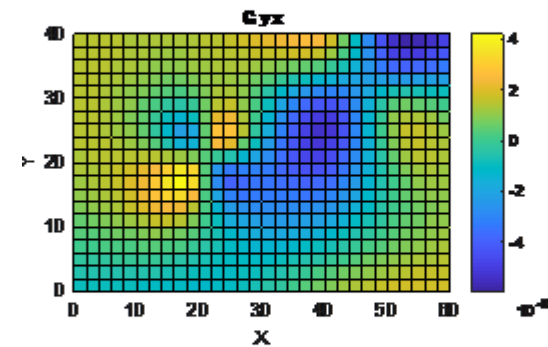
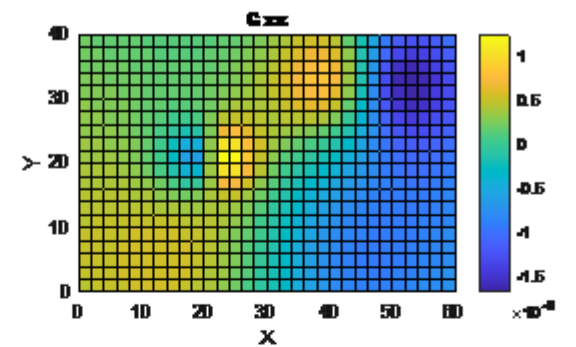
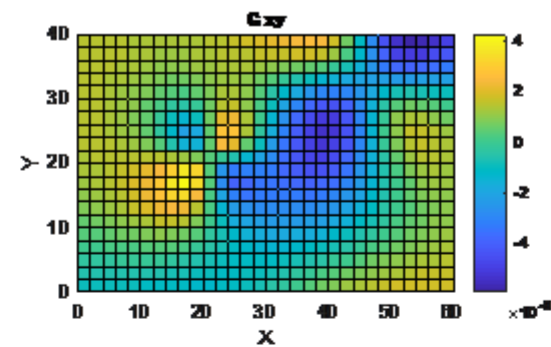
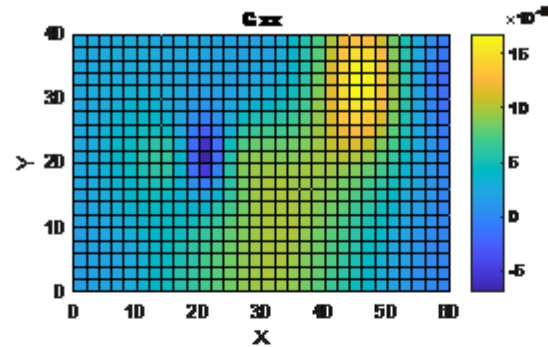
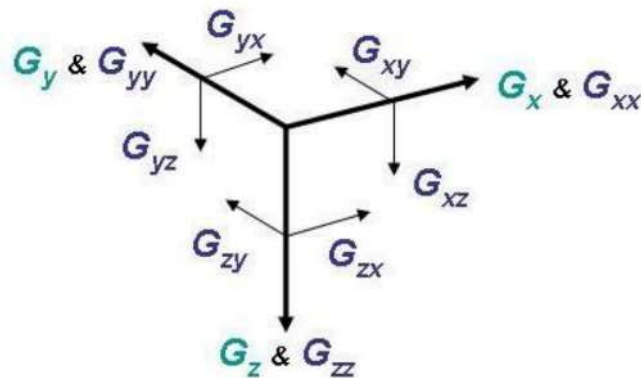
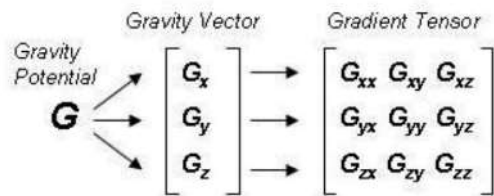
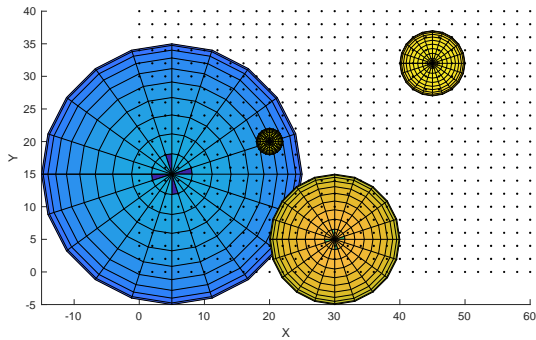


Figure 2 – Representation of rotational accelerometers gravity gradient according to Metzger (1986).

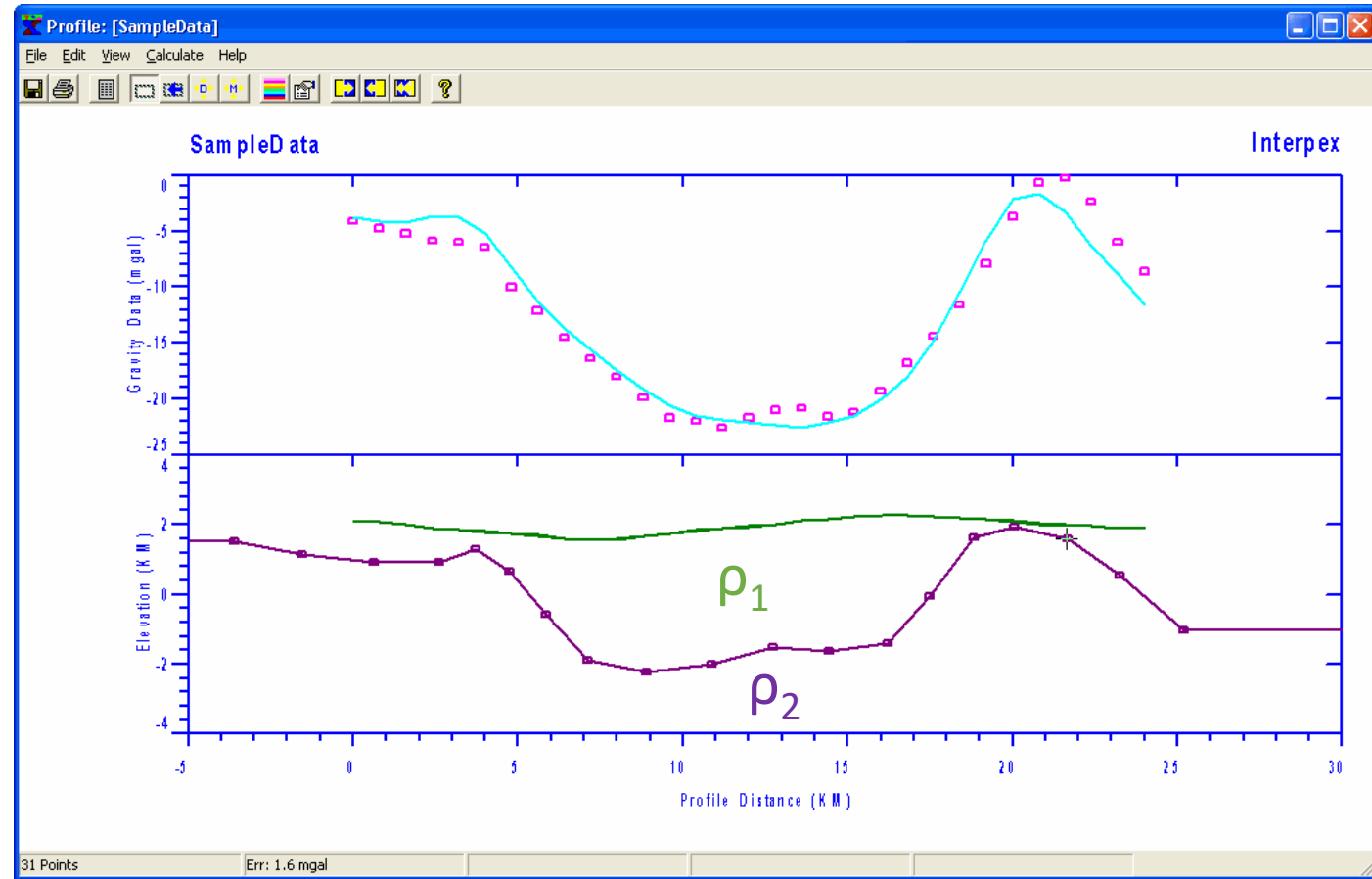
The Four-Sphere Model



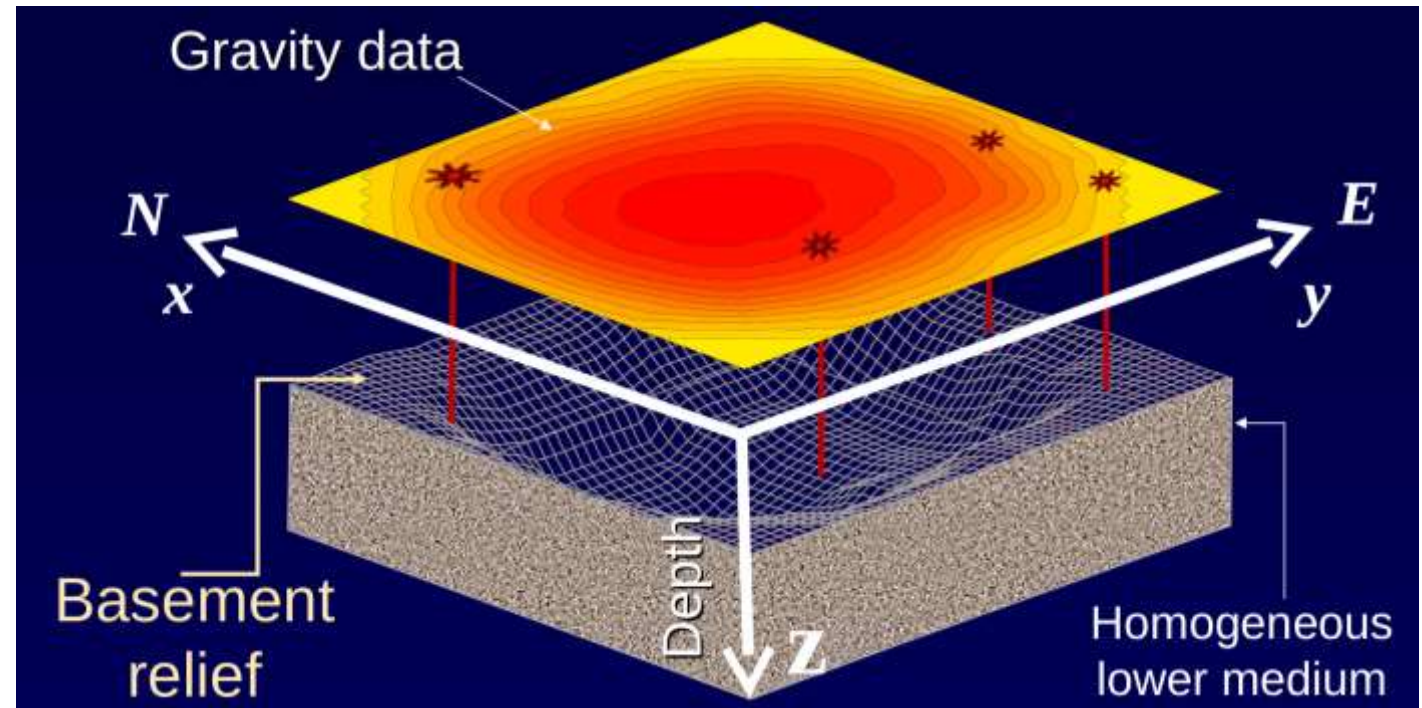
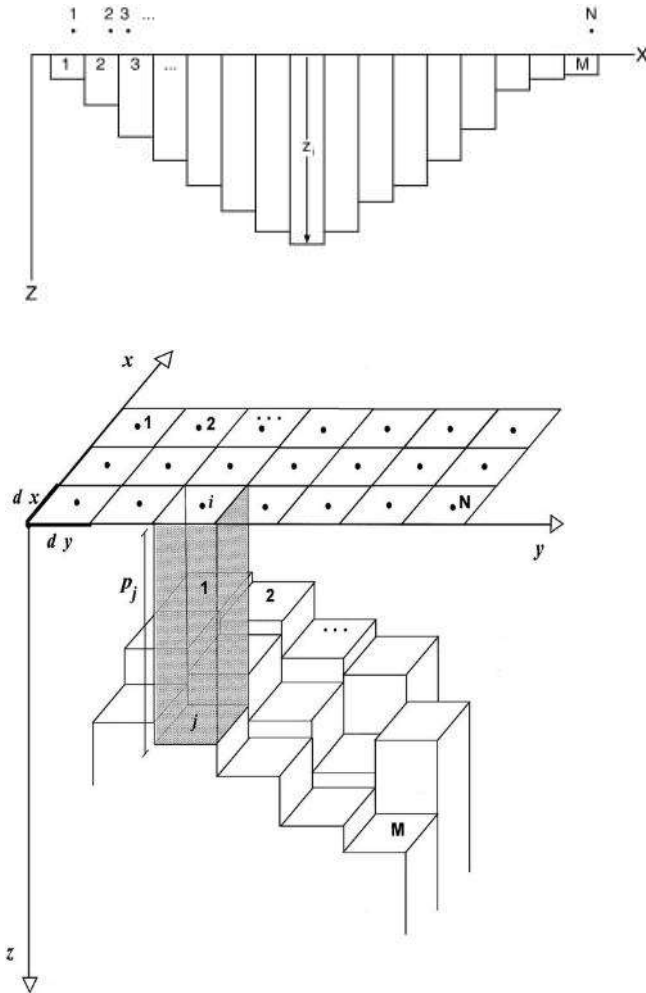
Full Tensor Gravity Gradient



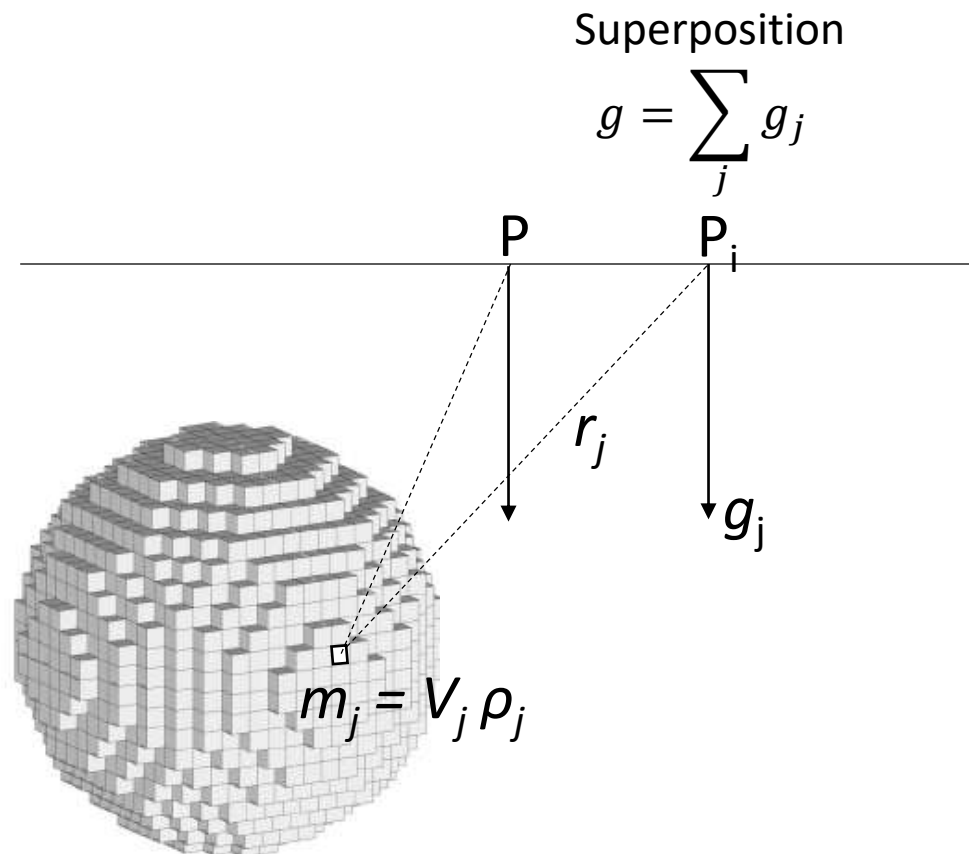
Geometric Inversion - Interactive



Geometric Inversion - Basement Relief



Pixel/Voxel Inversion



Data = Integration over a volume:

Not enough information to fully recover the true model

$$\begin{bmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{bmatrix} \begin{bmatrix} \rho \\ \rho \\ \rho \\ \rho \\ \rho \end{bmatrix} = \begin{bmatrix} d \\ d \\ d \\ d \\ d \end{bmatrix}$$

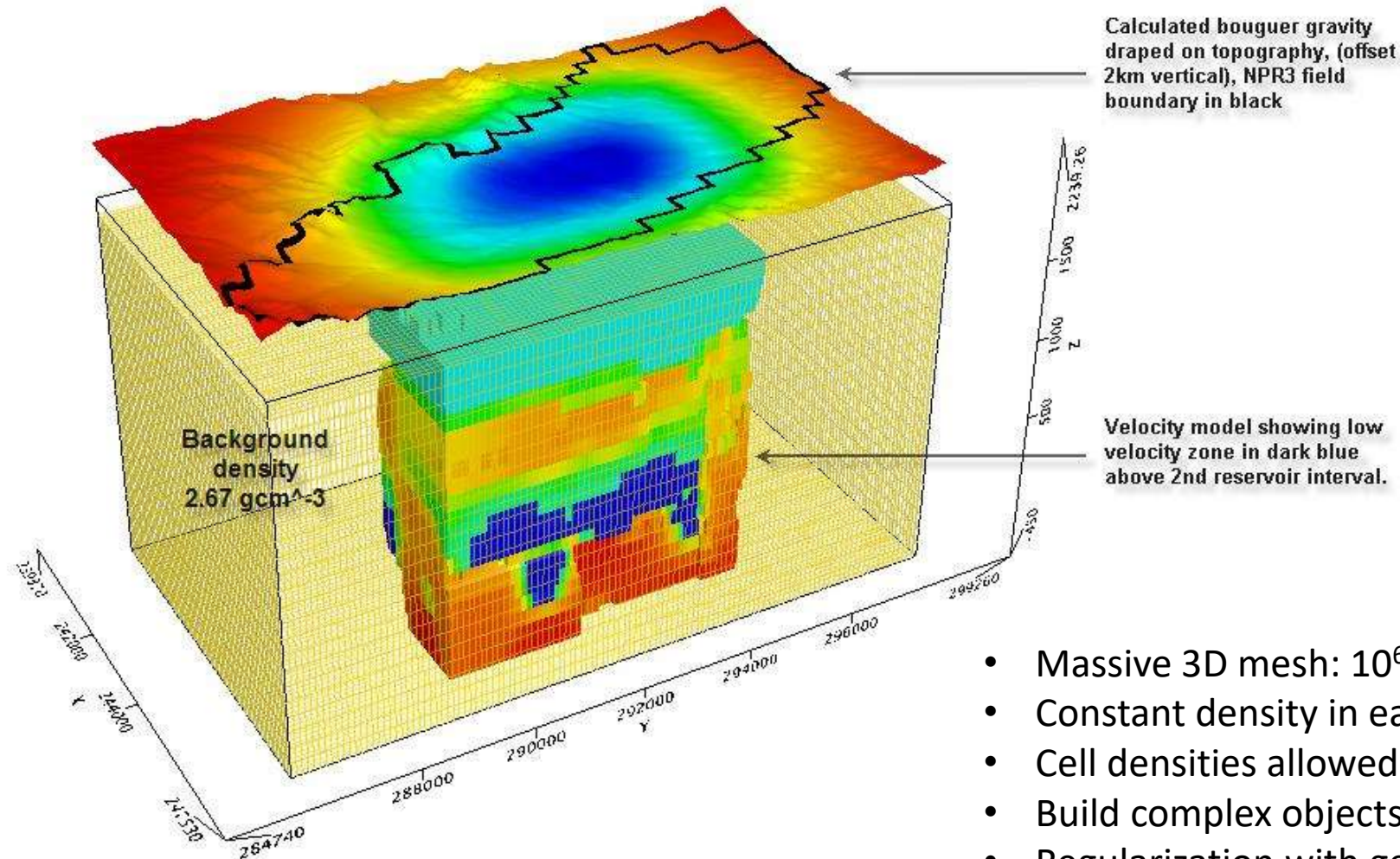
A_{ij} : Contribution of the j^{th} element to the i^{th} datum

Linear problem but the **inverse problem is ill-posed!**

So the piece-wise constant density model ρ is

$$\begin{bmatrix} \rho \\ \rho \\ \rho \\ \rho \\ \rho \end{bmatrix} = \begin{bmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{bmatrix}^{-1} \begin{bmatrix} d \\ d \\ d \\ d \\ d \end{bmatrix} \quad ???$$

3D Voxel Inversion



- Massive 3D mesh: 10^6 cells
- Constant density in each cell
- Cell densities allowed to vary
- Build complex objects: like Lego
- Regularization with geological a prior information

Planetary Science – Crater on Moon



Gravity field of the Orientale basin from the Gravity Recovery and Interior Laboratory Mission

Maria T. Zuber^{1,*}, David E. Smith¹, Gregory A. Neumann², Sander Goossens³, Jeffrey C. Andrews-Hanna^{4,5}, James W. Head⁶, Walter S. Kiefer⁷, Sami W. Asmar⁸, Alexander S. Konopliv⁹, Frank G. Lemoine², Isamu Matsuyama⁹, H. Jay Melosh¹⁰, Patrick J. McGovern⁷, Francis Nimmo¹¹, Roger J. Phillips⁵, Sean C. Solomon^{12,13}, G. Jeffrey Taylor¹⁴, Michael M. Watkins^{8,15}, Mark A. Wieczorek¹⁶, James G. Williams⁸, Johanna C. Jansen⁴, Brandon C. Johnson^{1,6}, James T. Keane⁹, Erwan Mazarico², Katarina Miljković^{1,17}, Ryan S. Park⁸, Jason M. Soderblom¹, Dah-Ning Yuan⁸

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¹³Lamont-Doherty Earth Observatory, Columbia University, Palisades, NY 10964, USA.

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¹⁵Center for Space Research, University of Texas, Austin, TX 78712 USA.

¹⁶Institut de Physique du Globe de Paris, Sorbonne Paris Cité, Université Paris Diderot, 75205 Paris Cedex 13, France.

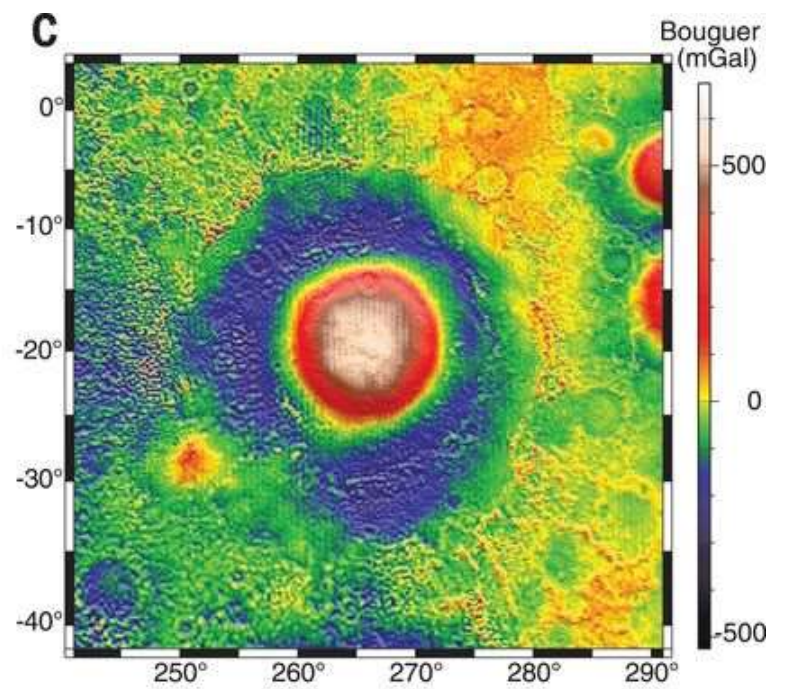
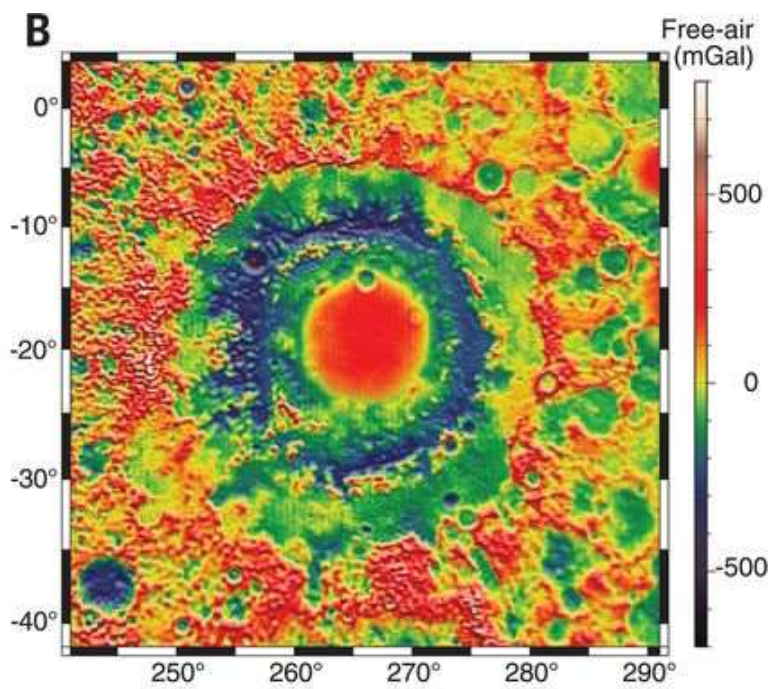
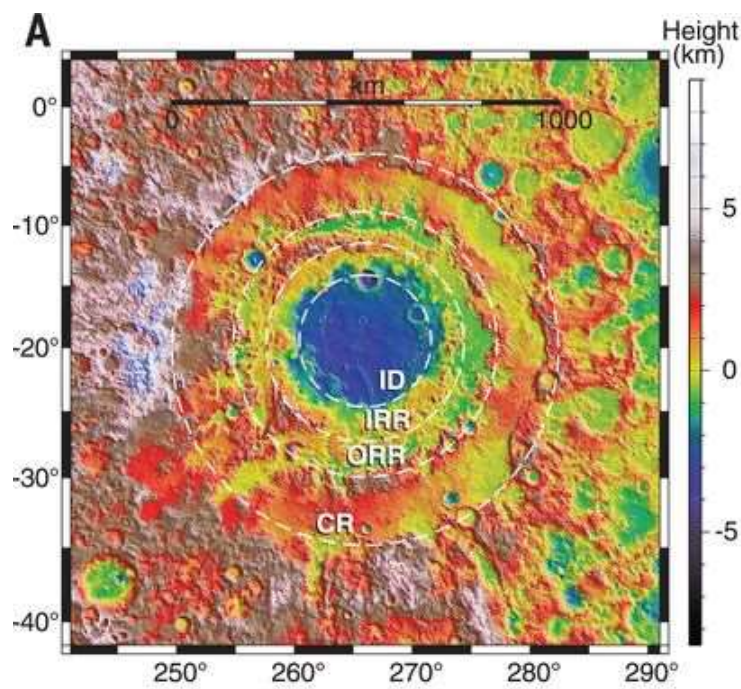
¹⁷Department of Applied Geology, Curtin University, Perth, Western Australia 6845, Australia.

*Corresponding author. Email: zuber@mit.edu

– Hide authors and affiliations

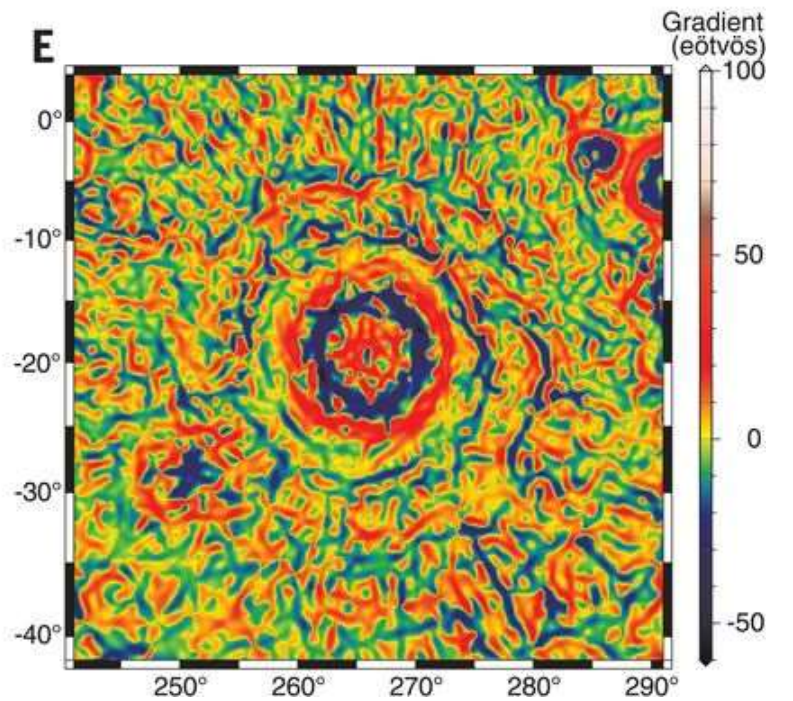
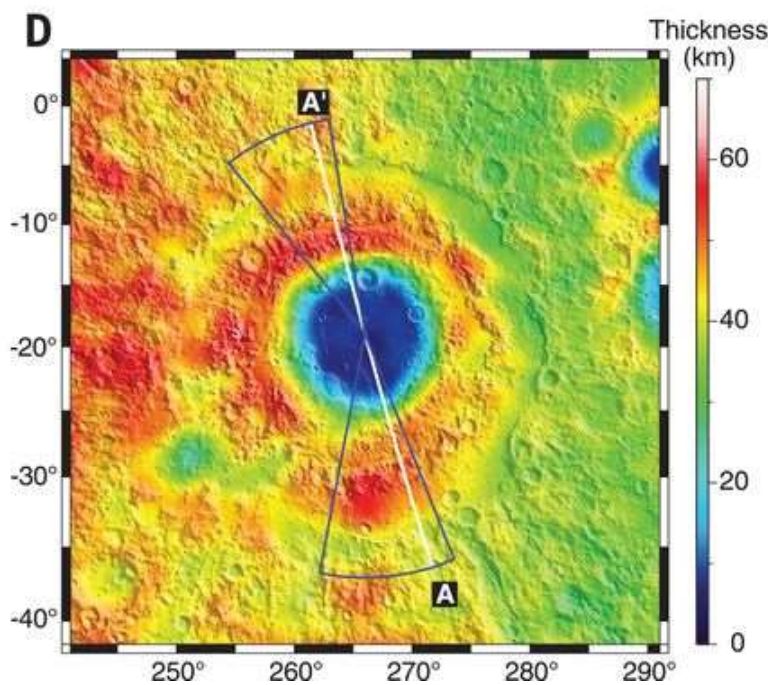
Science 28 Oct 2016:
Vol. 354, Issue 6311, pp. 438-441
DOI: 10.1126/science.aag0519

<http://science.sciencemag.org/content/354/6311/438>

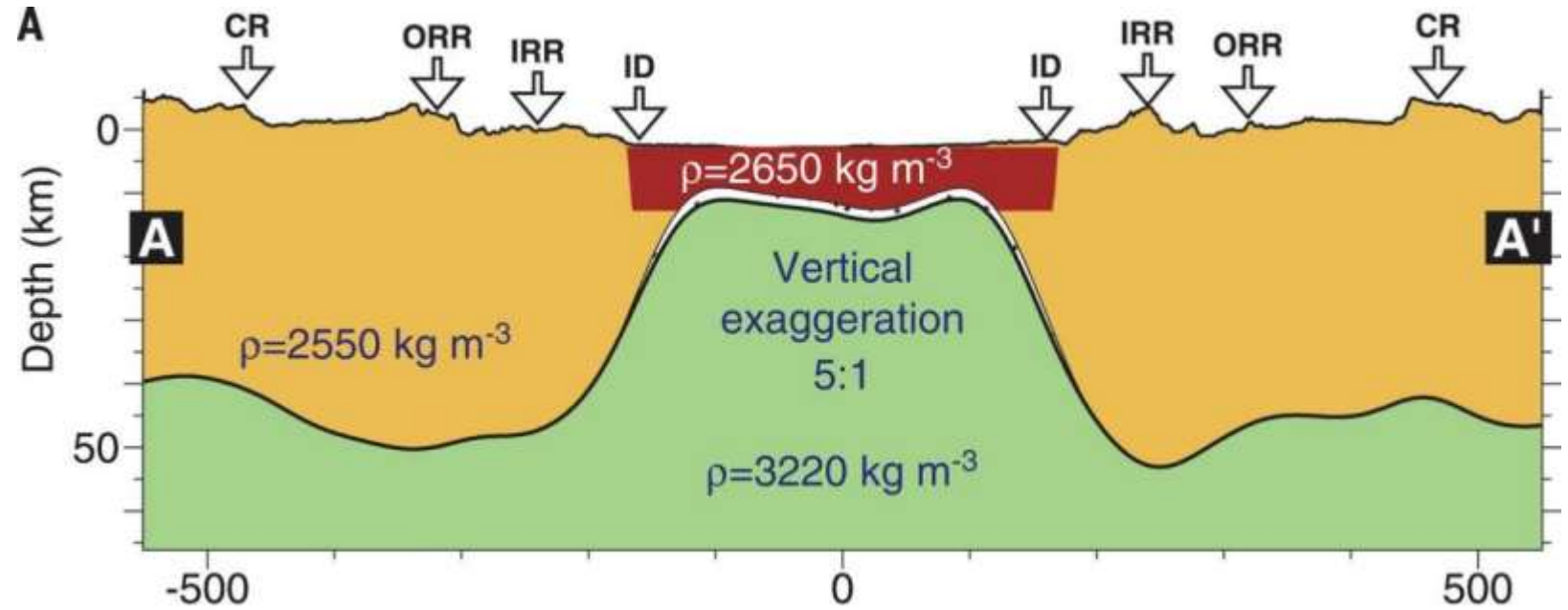
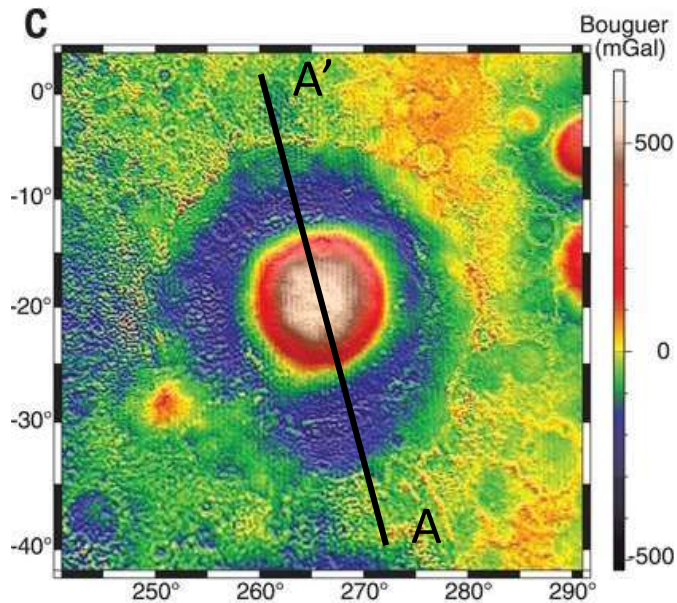


GRAIL

https://youtu.be/_hknIsPNsl8

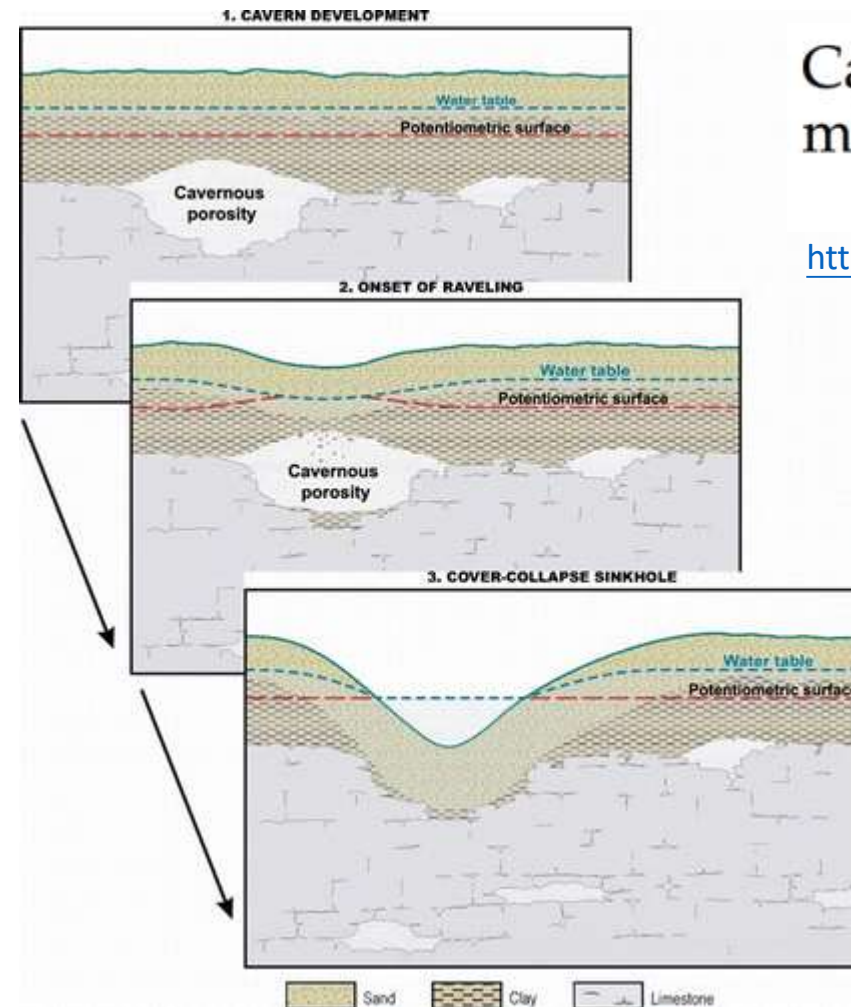


Density of the Moon's Interior



Can you sketch a density structure along the cross section A-A'?

Environmental – Sinkholes



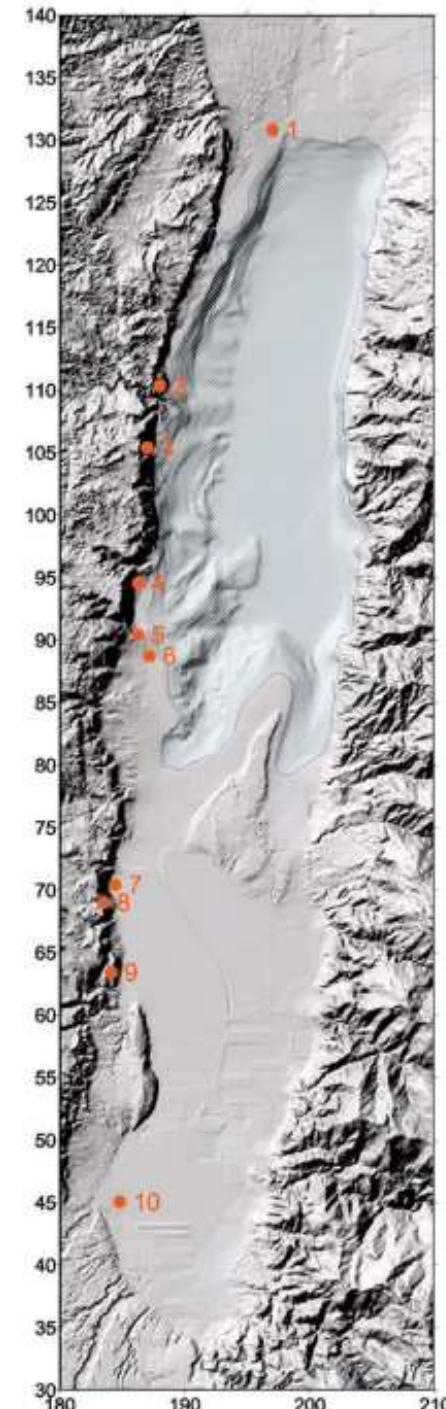
Cave detection and 4-D monitoring: A microgravity case history near the Dead Sea

M. RYBAKOV, V. GOLDSCHMIDT, L. FLEISCHER, and Y. ROTSTEIN, The Geophysical Institute of Israel

<https://library.seg.org/doi/pdf/10.1190/1.1487303n>



Figure 2. One of largest sinkholes in the Dead Sea area (after Gilat, 1999).



Forward Modeling: Feasibility Study

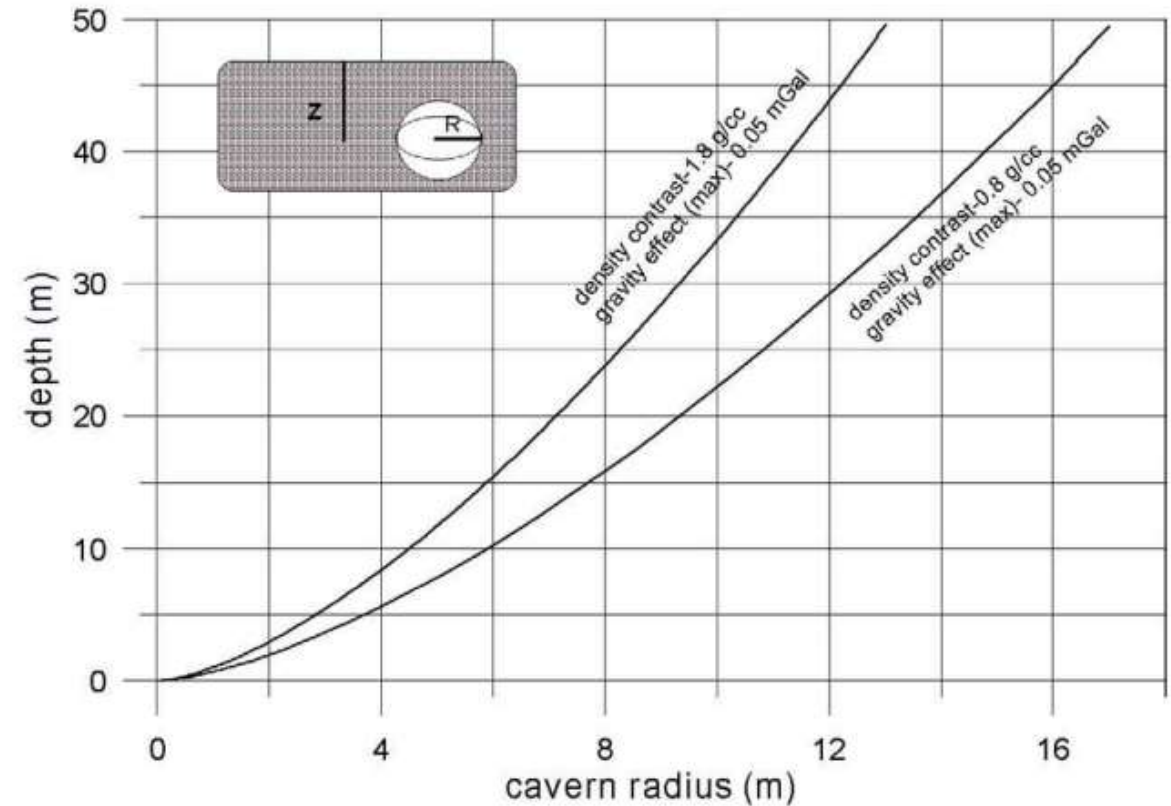
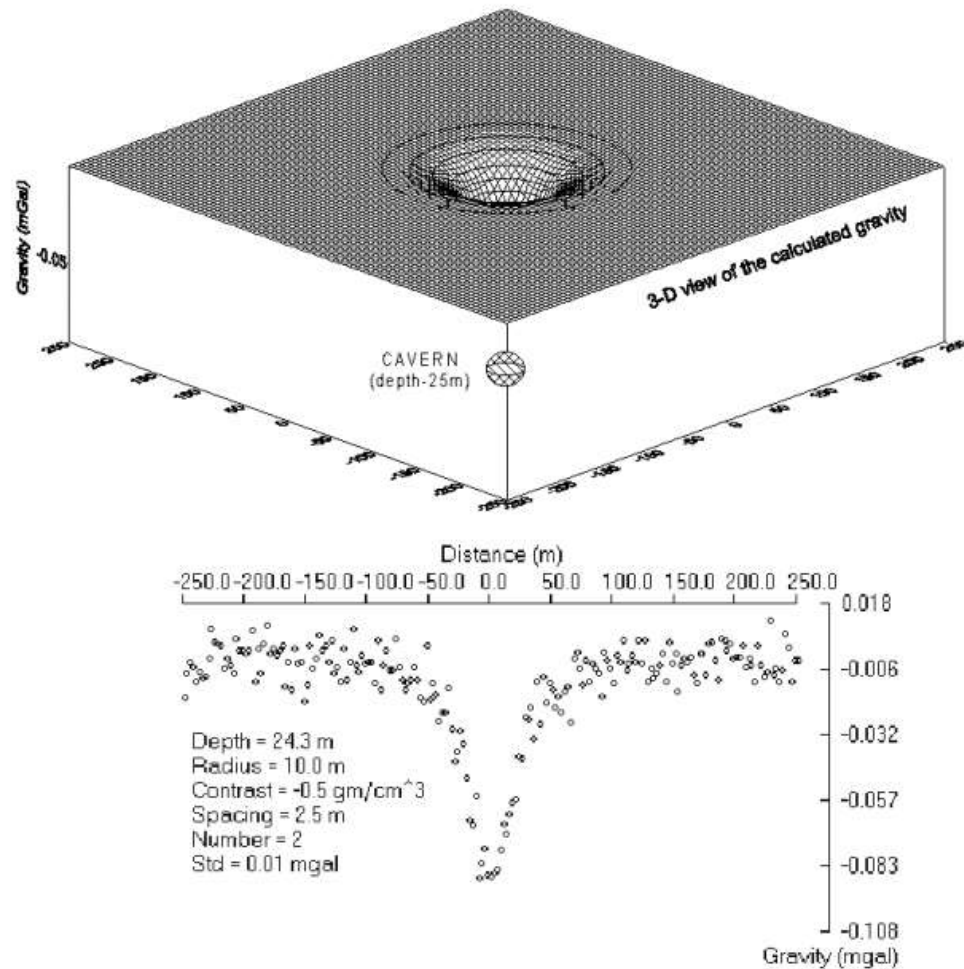
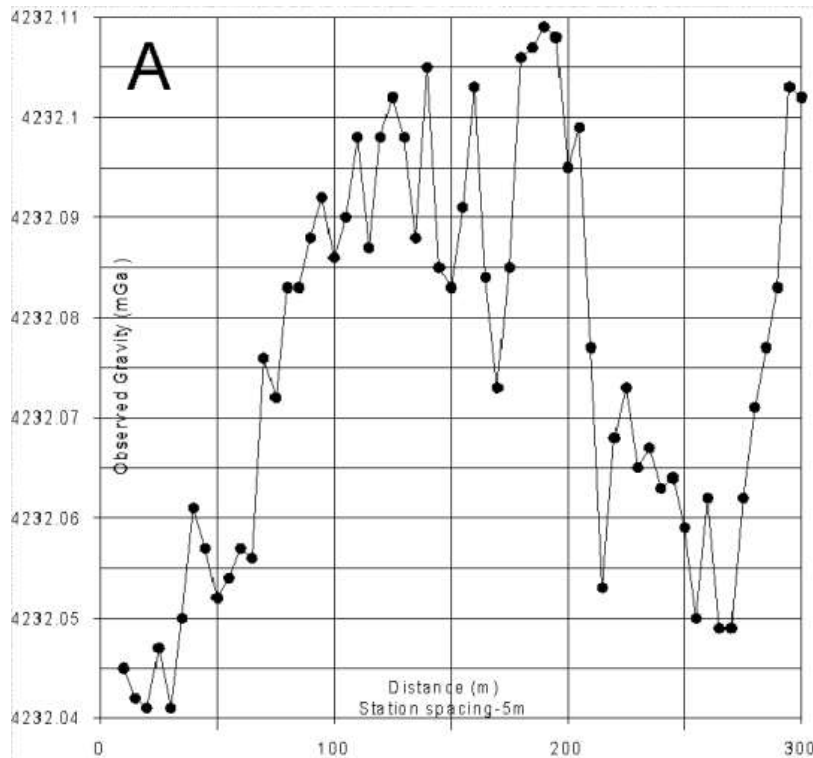


Figure 6. Effect of detectability threshold level and density contrast—maximum depth for detection of spherical concealed cavern. Large density contrast corresponds to air-filled cavern and small density contrast to saltwater-filled cavern.

Cavern Mapping Result



Raw gravity data along a line

- Gravimeter accuracy 0.005 mGal
- Scintrex CG-3M: 0.001 mGal
- Geodetic control: Laser Total Station (a few mm)
- Real-time elevation of the instrument
- Base station repeated hourly
- Repeat measurement: 10% of all stations
- Fully terrain corrected: 25-m grid DTM + precise local survey near the station

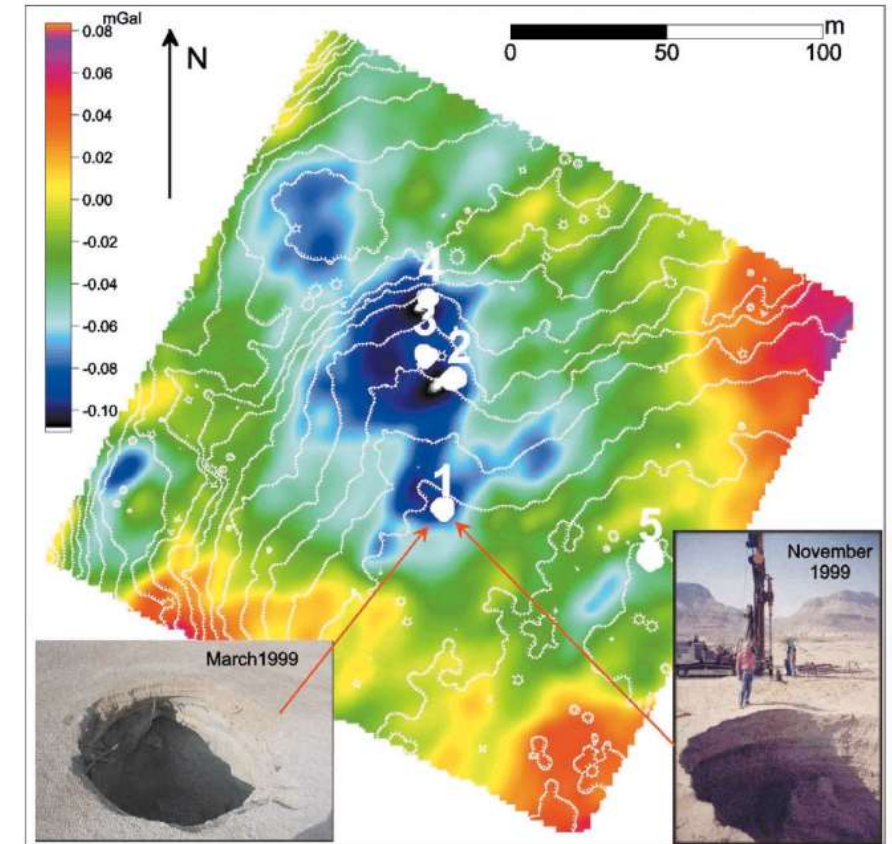


Figure 9. Residual gravity map of the Hever site superimposed by detailed topography (white contours - 0.25-m interval). White circles denote open sinkholes. Photos show growth of sinkhole 1 between March and November 1999.

Military – Submarine Navigation

How do submarines use gravity gradients to avoid collisions with underwater mountains?

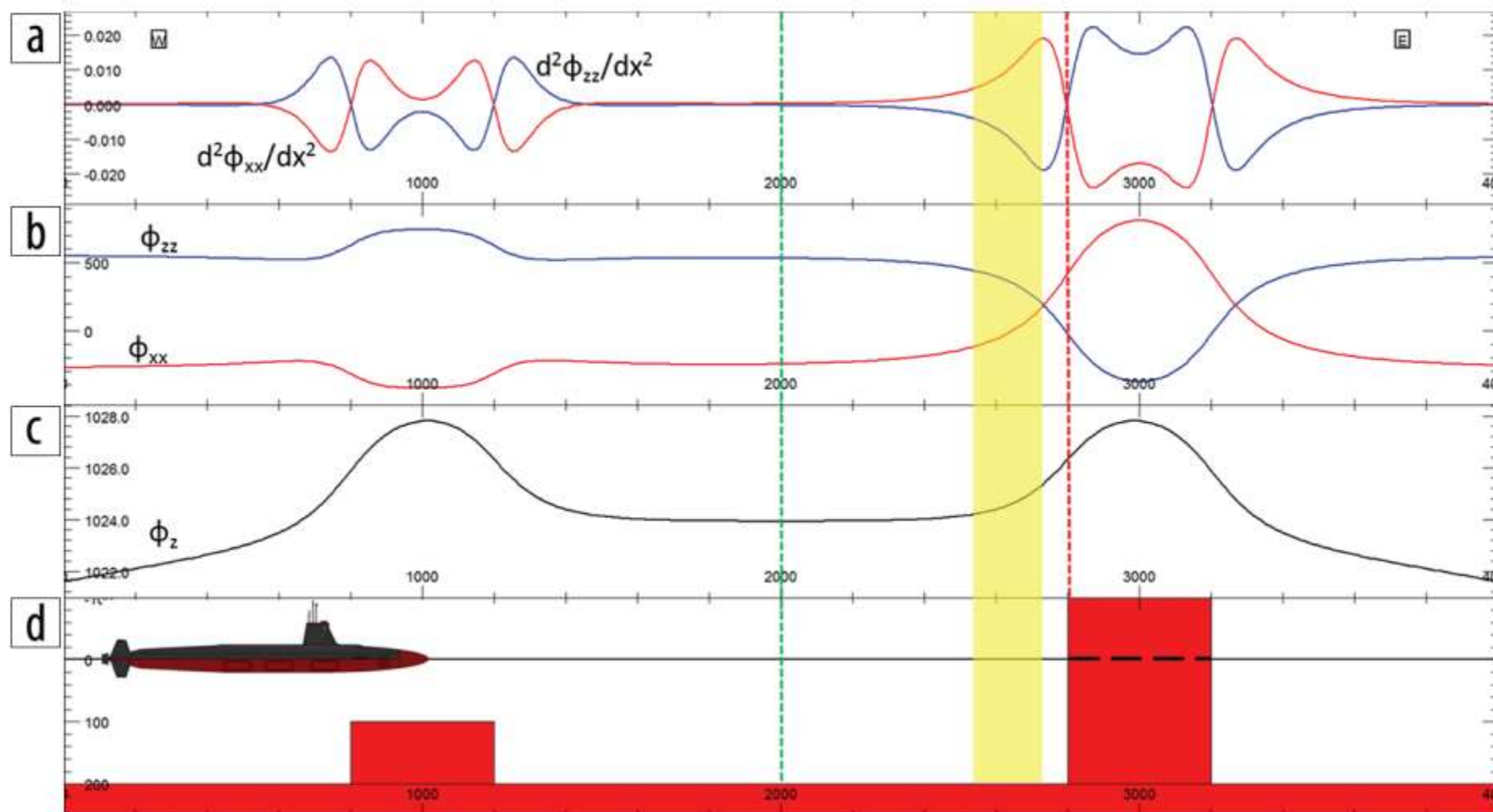
Carlos Cevallos¹

<https://library.seg.org/doi/pdf/10.1190/tle34121498.1>

Gradient Tensor

$$\begin{bmatrix} G_{xx} & G_{xy} & G_{xz} \\ G_{yx} & G_{yy} & G_{yz} \\ G_{zx} & G_{zy} & G_{zz} \end{bmatrix}$$

Military – Submarine Navigation



Collision warning:

- Φ_{xx} is increasing
- Φ_{zz} is diminishing
- The second horizontal derivatives of Φ_{xx} and Φ_{zz} attain a maximum and a minimum, respectively

Can gravity gradient be used to detect another submarine?

Summary

- Nature of gravity data: Ambiguity
- Approaches to identify sources of signals:
 - Regional removal
 - Upward/downward continuation
 - Derivatives
 - Full tensor gradients
- Gravity inversion
- Applications: Planetary science, environmental, military, basin, etc.
- What's your impression about the gravity method?