

Computer Vision I: Low-Middle Level Vision Homework Exercise #2

(total 15 points)

Due: November 28th 11:59 PM.

Problem 1 (Minimax entropy learning, 3 points).

This question aims to refresh the proof process in minimax entropy learning. Let $p(\mathbf{I})$ be a FRAME model with K histograms matched to the underlying model $f(\mathbf{I})$

$$p(\mathbf{I}; \Theta) = \frac{1}{Z(\Theta)} \exp\left\{-\sum_{i=1}^K \langle \lambda_i, H_i(\mathbf{I}) \rangle\right\} \quad (1)$$

The parameter $\Theta = (\lambda_1, \dots, \lambda_K)$ is learned so that the following constraints are satisfied.

$$E_p[H_i(\mathbf{I})] = E_f[H_i(\mathbf{I})] = h_i, \quad i = 1, 2, \dots, K. \quad (2)$$

- **Q1:** Derive the following equation:

$$\frac{\partial \log Z}{\partial \lambda_i} = -E_p[H_i(\mathbf{I})].$$

- **Q2:** Let $\ell(\Theta)$ be the log-likelihood for one observed image \mathbf{I}^{obs} , prove that

$$\frac{\partial^2 \ell(\Theta)}{\partial \lambda_i \partial \lambda_j} = -\frac{\partial^2 \log Z}{\partial \lambda_i \partial \lambda_j} \quad (3)$$

$$= -E_p[(H_i(\mathbf{I}) - h_i)(H_j(\mathbf{I}) - h_j)], i, j \in \{1, 2, \dots, K\} \quad (4)$$

comment: Thus the second derivative of $\ell(\Theta)$ is a negative covariance matrix. So $\ell(\Theta)$ has a single maximum solution.

Now suppose we extract a new feature from the dictionary $F_+ \in \Delta$, and augment the model to

$$p_+(\mathbf{I}; \Theta_+) = \frac{1}{Z(\lambda_+)} \exp\left\{-\sum_{\alpha=1}^K \langle \lambda_\alpha^*, H_\alpha(\mathbf{I}) \rangle - \langle \lambda_+, H_+(\mathbf{I}) \rangle\right\} \quad (5)$$

The new parameter $\Theta_+ = (\lambda_1^*, \dots, \lambda_K^*, \lambda_+)$ is learned to not only satisfy the K constraints specified in equation (2), but also an extra condition:

$$E_{p_+}[H_+(\mathbf{I})] = E_f[H_+(\mathbf{I})] = h_+. \quad (6)$$

Note: To match all the $K + 1$ statistical constraints, the existing parameters $(\lambda_\alpha \rightarrow \lambda_\alpha^*, i = 1, 2, \dots, K)$ must be updated when we introduce new features (marginal) because all features are correlated.

- **Q3:** Derive the steps for proving the following theorem

$$KL(f||p) - KL(f||p_+) = KL(p_+||p).$$

Problem 2 (Learning by information projection, 3 points)

Suppose that we are learning the underlying probability model $f(\mathbf{I})$ of image \mathbf{I} . We start with an initial probability model, denoted as $q(\mathbf{I})$, and observe that $q(\mathbf{I})$ has a different marginal probability over a macroscopic feature $H_i(\mathbf{I})$:

$$E_q[H_i(\mathbf{I})] \neq E_f[H_i(\mathbf{I})] = h_i,$$

where h_i is estimated from a set of examples sampled from $f(\mathbf{I})$. To improve the current model, we learn a new probability model $p(\mathbf{I})$ so that it reproduces this marginal statistics feature ($p(\mathbf{I})$ may not necessarily replicate all the marginal probabilities that model $q(\mathbf{I})$ has matched previously). We denote the set of models that satisfy this constraint equation by,

$$\Omega_i = \{p : E_p[H_i(\mathbf{I})] = E_f[H_i(\mathbf{I})] = h_i\}$$

Now, among all the $p(\mathbf{I})$ in Ω_i , we choose one that is closest to $q(\mathbf{I})$ so that it preserves the learning history.

$$p^* = \arg \min_{p \in \Omega_i} KL(p||q) = \arg \min_{p \in \Omega_i} \int p(\mathbf{I}) \log \frac{p(\mathbf{I})}{q(\mathbf{I})} d\mathbf{I}.$$

1. Derive the formula of $p(\mathbf{I})$ by leveraging the Euler-Lagrange equation (Tips: (I) constrained optimization).
2. Prove that $KL(f||q) - KL(f||p) = KL(p||q)$. (Remark: Since $D(p||q) > 0$, p is closer to f than q).
3. Show that this optimization satisfies the maximum entropy principle when $q(\mathbf{I})$ is a uniform distribution.

Problem 3 (Information projection, 3 points)

Considering the feature pursuit in a family of models,

$$p_0(x) \rightarrow p_1(x) \rightarrow \cdots \rightarrow p_K(x) \quad \sim \quad f(x).$$

where

$$p_K(x; \Theta_K) = \frac{1}{Z_K} \exp\left\{-\sum_{i=1}^K \lambda_i h_i(x)\right\}.$$

For simplicity, we treat λ_i as a scalar rather than a vector.

In the minimax entropy process, when we add a new feature statistics $h_K(x)$, we need to update all the parameters $\lambda_i = 1, \dots, K$ in the new model $p_K(x; \Theta_K)$ by MLE, so that all the K constraint equations are satisfied,

$$E_{p_K}[h_i(x)] = h_i^{\text{obs}}, \quad i = 1, 2, \dots, K.$$

In a different method, we can pursue a series of models in the following way,

$$q_0(x) \rightarrow q_1(x) \rightarrow \dots \rightarrow q_K(x) \sim f(x).$$

with

$$q_K(x) = \frac{1}{z_K} q_{K-1}(x) \exp\{-\beta_K h_K(x)\}.$$

In this model, β_K is decided by the new constraint

$$E_{q_K}[h_K(x)] = E_f[h_K(x)] \approx h_K^{\text{obs}}.$$

In comparison to the previous p-series, the q-series observes the constraints one-by-one, and fixes the previous parameters $\beta_i, i = 1, 2, \dots, K-1$ when we learn β_K , i.e.

$$q_K(x;) = \frac{1}{z_1 z_2 \dots z_K} q_0(x) \exp\left\{-\sum_{i=1}^K \beta_i h_i(x)\right\}.$$

1. For the q-series, derive the formula for $\frac{\partial \log z_K}{\partial \beta_k}$.
2. Suppose we denote by $Z_K = z_1 z_2 \dots z_{K-1}$ as the normalizing function for $q_K(x)$, derive $\frac{\partial^2 \log Z_K}{\partial \beta_i \partial \beta_j}$, $\forall i, j \leq K$.
3. Prove that $KL(f||q_K) - KL(f||q_{K+1}) = KL(q_{K+1}||q_K) \geq 0$, and prove the q-series will converge to f

Problem 4 (Typical set, 3 points)

Suppose we toss a coin N times and observe a 0/1 sequence (for head and tail respectively),

$$S_N = (x_1, x_2, \dots, x_N), \quad x_i \in \{0, 1\}.$$

S_N is said to be of *type* q (i.e. the frequency of 1 is q in the sequence) with $q = \frac{1}{N} \sum_{i=1}^N x_i$.

Let $\Omega(q)$ be the set of all sequences S_N of type q . For simplicity, we discretize q to finite precision.

1. What is the cardinality of $\Omega(q)$ for $q = 0.2$ and $q = 0.5$ respectively? (Suppose we only care about the exponential order or rate).

2. Suppose we know that the underlying probability is $x_i = 1$ (or $x_i = 0$) with probability p (or $1 - p$ respectively), by sampling from this probability N times, what is the probability $p(S_N)$ that we observe a sequence $S_N \in \Omega(q)$? What is the total probability mass $p(\Omega(q))$ for all the sequences in set $\Omega(q)$?
3. In the above question, show that as $N \rightarrow \infty$, only sequences from the type p , i.e. set $\Omega(p)$, can be observed.

Problem 5 (Poisson Distribution and Random Sampling, 3 points)

Consider a lattice Λ of dimensions $n \times n$, on which N points are randomly distributed independently and uniformly. The point density is defined as $\lambda = \frac{N}{n^2}$. Now, take a frame of size $l \times l$ and count the number of points, k , within this frame. By sliding the frame across the lattice, generate a histogram of k values ($k = 0, 1, \dots$). Compare this histogram with the corresponding Poisson distribution given by

$$P_{Poisson}(k) = \frac{(\lambda l^2)^k}{k!} e^{-\lambda l^2}.$$

Finally, plot the histogram alongside the Poisson distribution in a single figure to evaluate the agreement between the two.

1. Plot the lines with the following settings (in total 8 settings):
 - $n = 1024$
 - $\lambda = 0.1, 0.05$
 - $L = 10, 50, 100, 1000$
2. Please prove that if $0 < \frac{l}{n} \ll 1$, $0 < \frac{k}{N} \ll 1$ and by neglecting higher-order infinitesimal terms, the probability of k points inside the frame P_s is Poisson distribution, i.e. $P_s(k) = P_{poisson}(k)$.