Regression Hung-yi Lee 李宏毅

Regression: Output a scalar

Stock Market Forecast



) = Dow Jones Industrial Average at tomorrow

Self-driving Car

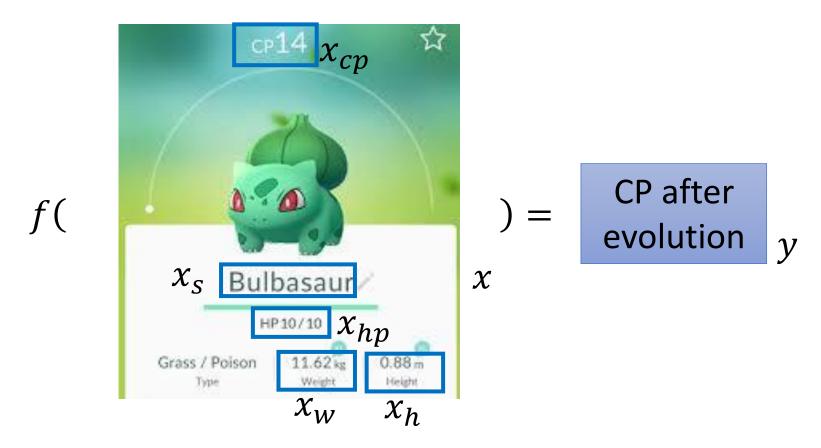
) = 方向盤角度

Recommendation

$$f($$
 使用者A 商品B $)=$ 購買可能性

Example Application

Estimating the Combat Power (CP) of a pokemon after evolution



Step 1: Model

$$y = b + w \cdot x_{cp}$$

A set of function Model

$$f_1, f_2 \cdots$$

w and b are parameters (can be any value)

$$f_1$$
: y = 10.0 + 9.0 · x_{cp}

$$f_2$$
: y = 9.8 + 9.2 · x_{cp}

$$f_3$$
: y = -0.8 - 1.2 · x_{cp}

infinite



x) =

CP after evolution

Linear model:
$$y = b + \left| w_i x_i \right|$$

 x_i : x_{cp} , x_{hp} , x_w , x_h ...

feature

 w_i : weight, b: bias

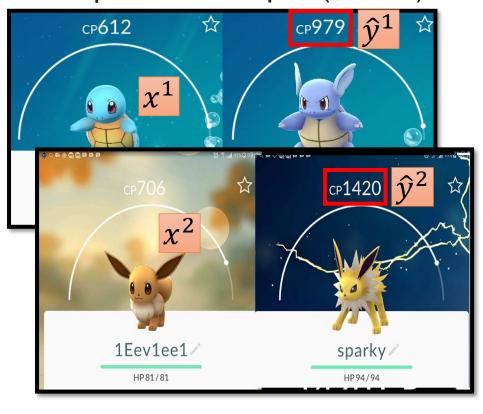
 $y = b + w \cdot x_{cp}$

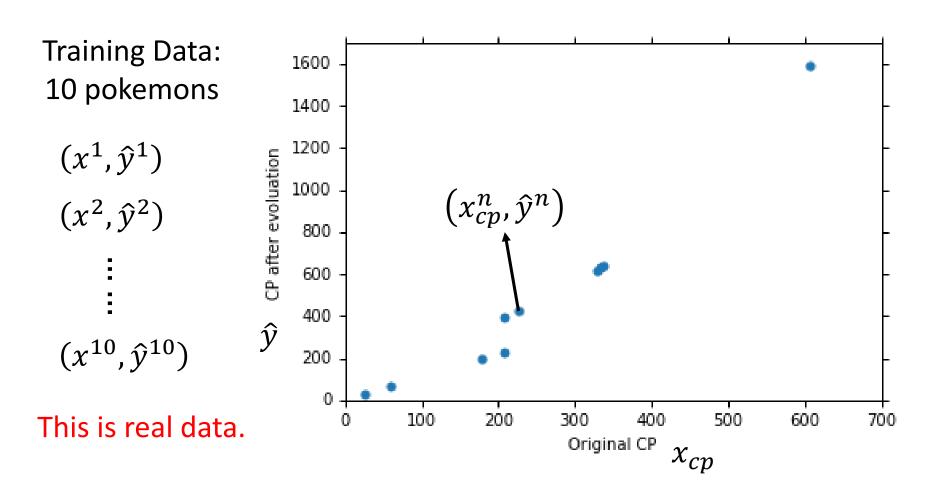
A set of function

Model

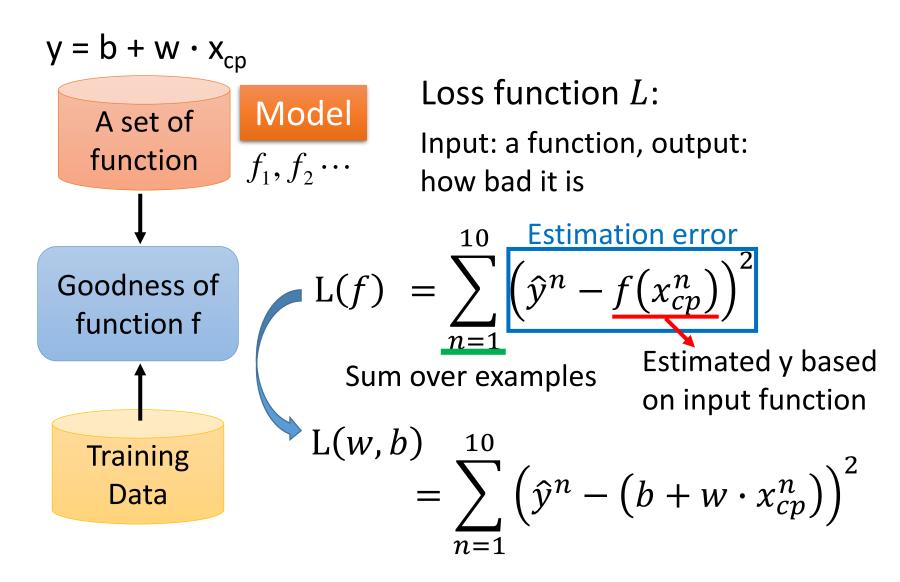
 $f_1, f_2 \cdots$

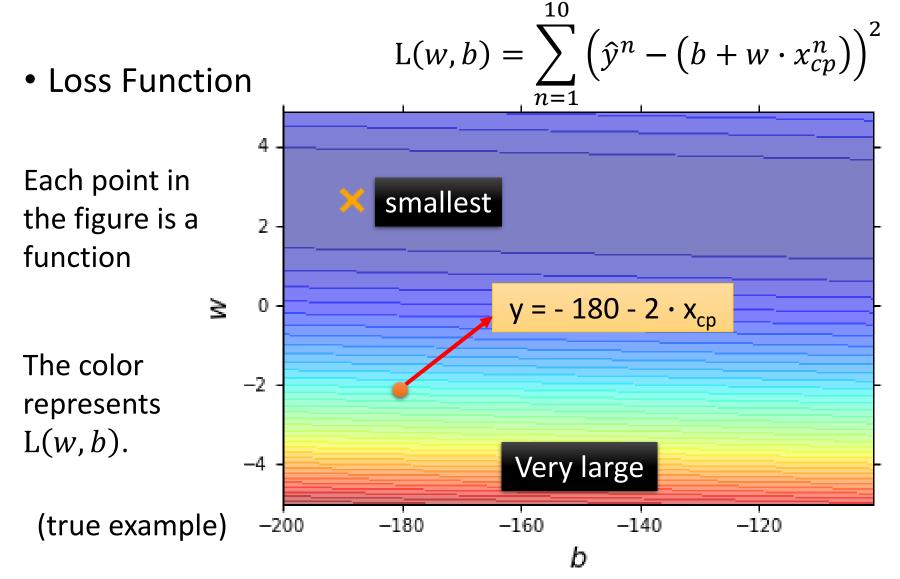
Training Data function function input: Output (scalar):



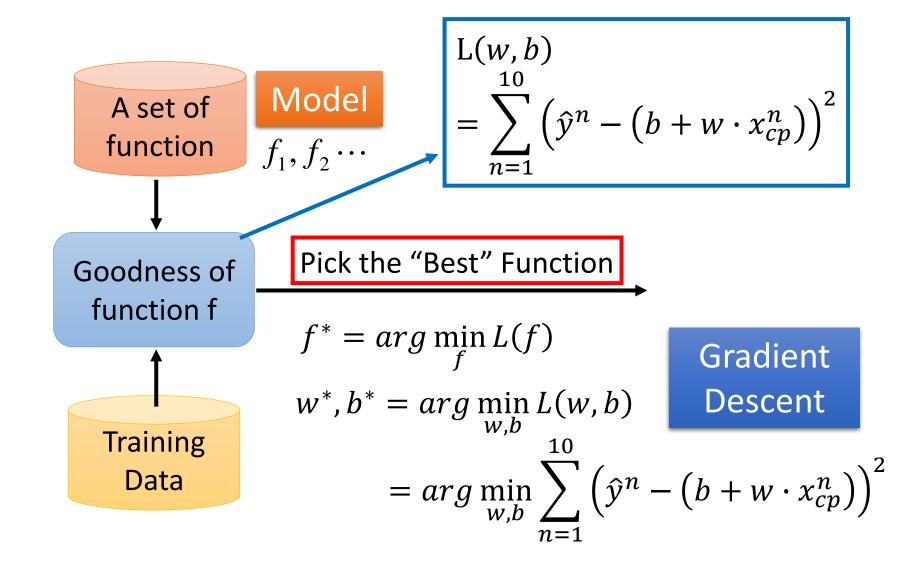


Source: https://www.openintro.org/stat/data/?data=pokemon



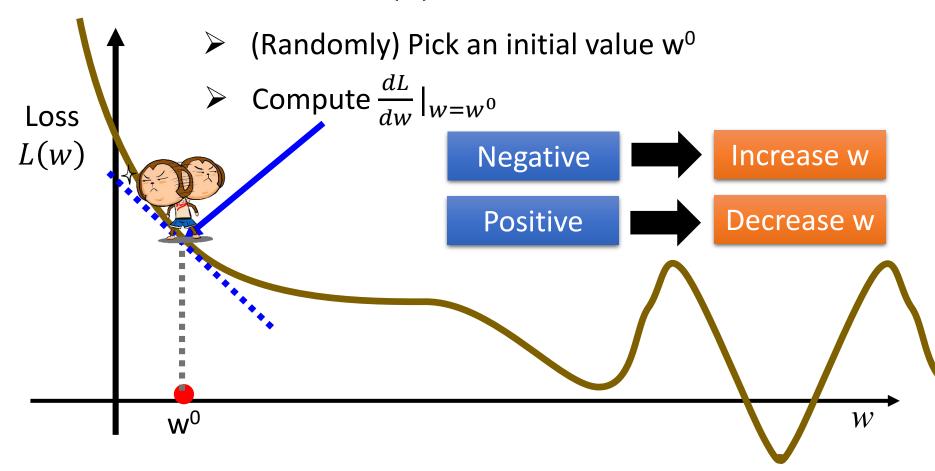


Step 3: Best Function



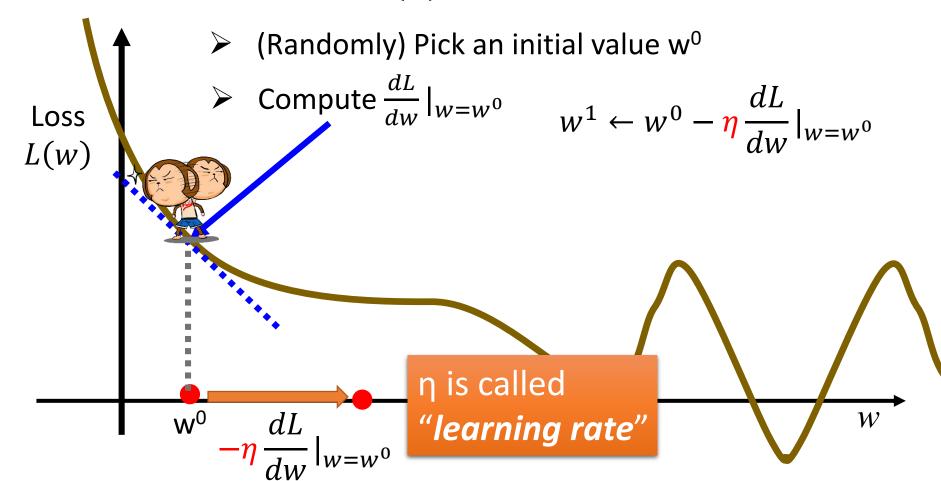
$$w^* = arg \min_{w} L(w)$$

• Consider loss function L(w) with one parameter w:



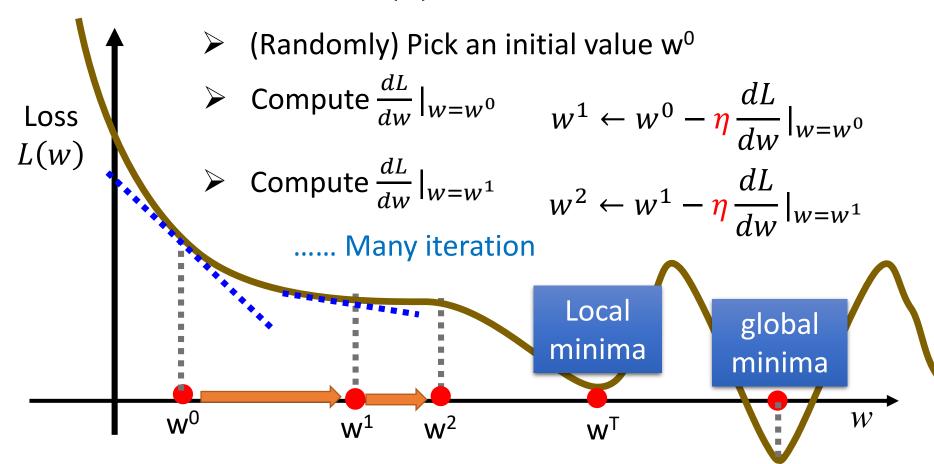
$$w^* = arg \min_{w} L(w)$$

• Consider loss function L(w) with one parameter w:



$$w^* = arg \min_{w} L(w)$$

• Consider loss function L(w) with one parameter w:



Step 3: Gradient Descent $\left| \frac{\partial L}{\partial w} \right|$

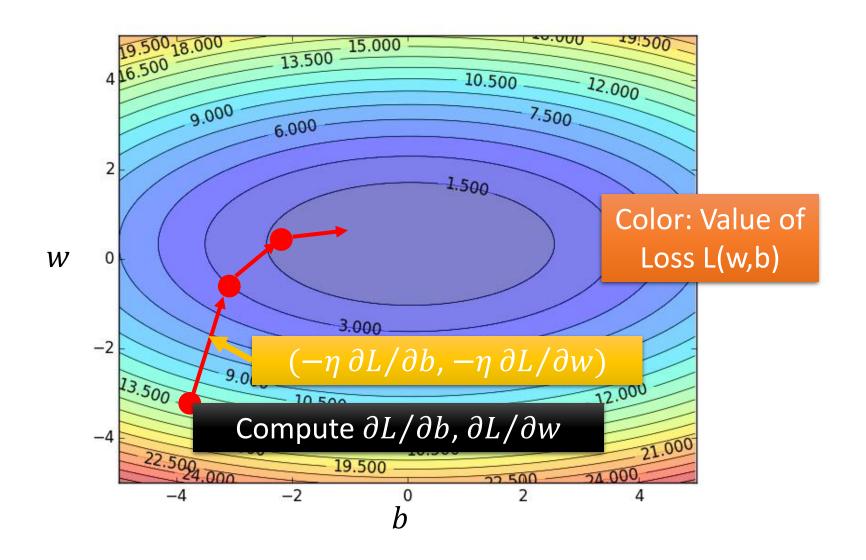
$$\begin{bmatrix} \frac{\partial L}{\partial w} \\ \frac{\partial L}{\partial b} \end{bmatrix}$$
 gradient

- How about two parameters? $w^*, b^* = arg \min_{w,b} L(w,b)$
 - (Randomly) Pick an initial value w⁰, b⁰
 - \triangleright Compute $\frac{\partial L}{\partial w}|_{w=w^0,b=b^0}$, $\frac{\partial L}{\partial b}|_{w=w^0,b=b^0}$

$$w^{1} \leftarrow w^{0} - \frac{\partial L}{\partial w}|_{w=w^{0},b=b^{0}} \qquad b^{1} \leftarrow b^{0} - \frac{\partial L}{\partial b}|_{w=w^{0},b=b^{0}}$$

 \triangleright Compute $\frac{\partial L}{\partial w}|_{w=w^1,b=b^1}$, $\frac{\partial L}{\partial b}|_{w=w^1,b=b^1}$

$$w^2 \leftarrow w^1 - \frac{\partial L}{\partial w}|_{w=w^1,b=b^1}$$
 $b^2 \leftarrow b^1 - \frac{\partial L}{\partial b}|_{w=w^1,b=b^1}$



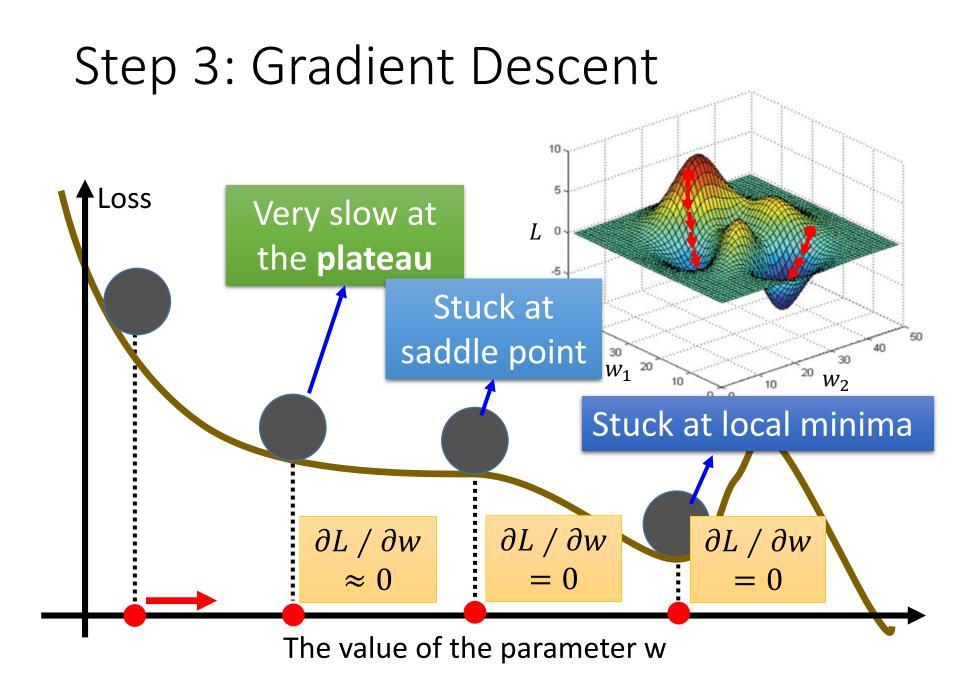
• When solving:

$$\theta^* = \arg \max_{\theta} L(\theta)$$
 by gradient descent

• Each time we update the parameters, we obtain θ that makes $L(\theta)$ smaller.

$$L(\theta^0) > L(\theta^1) > L(\theta^2) > \cdots$$

Is this statement correct?



• Formulation of $\partial L/\partial w$ and $\partial L/\partial b$

$$L(w,b) = \sum_{n=1}^{10} (\hat{y}^n - (b + w \cdot x_{cp}^n))^2$$

$$\frac{\partial L}{\partial w} = ? \sum_{n=1}^{10} 2 \left(\hat{y}^n - \left(b + w \cdot x_{cp}^n \right) \right)$$

$$\frac{\partial L}{\partial h} = ?$$

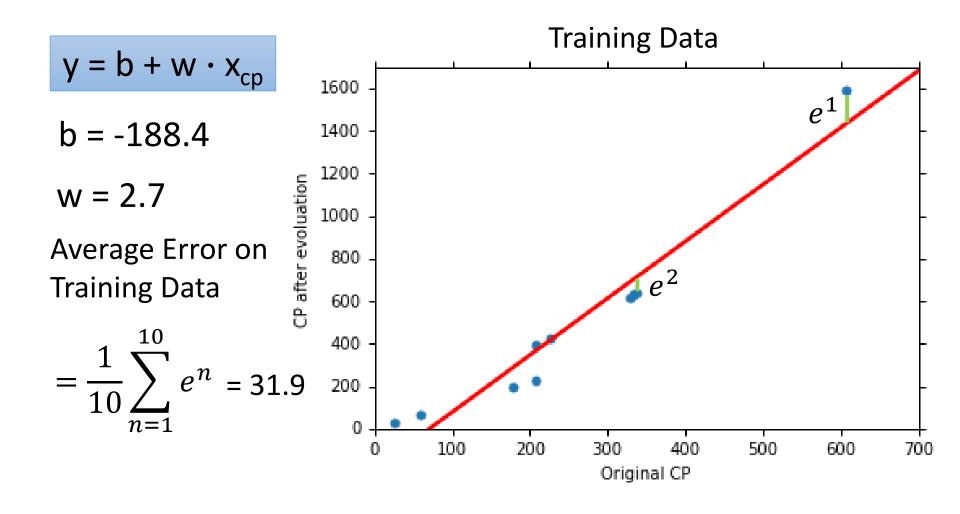
• Formulation of $\partial L/\partial w$ and $\partial L/\partial b$

$$L(w,b) = \sum_{n=1}^{10} \left(\hat{y}^n - \left(b + w \cdot x_{cp}^n \right) \right)^2$$

$$\frac{\partial L}{\partial w} = ? \sum_{n=1}^{10} 2\left(\hat{y}^n - \left(b + w \cdot x_{cp}^n\right)\right) \left(-x_{cp}^n\right)$$

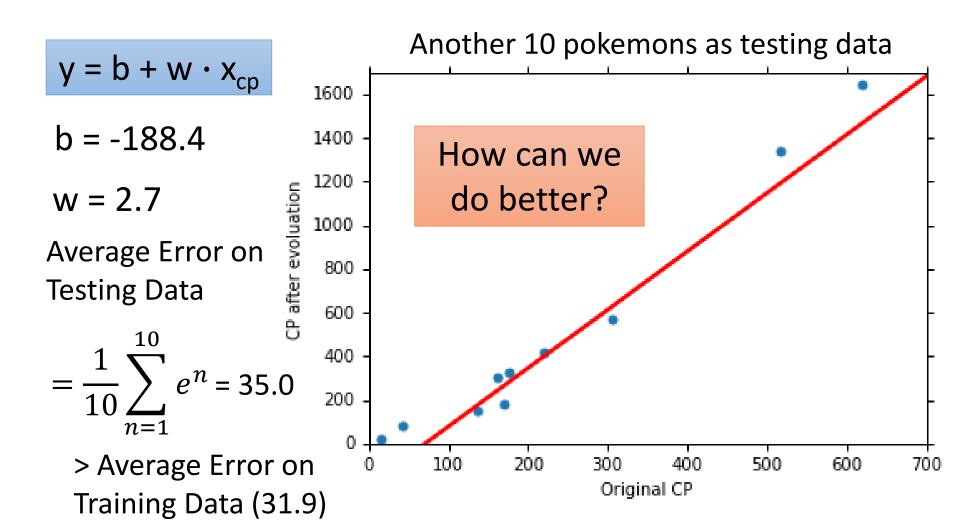
$$\frac{\partial L}{\partial b} = ? \sum_{n=1}^{10} 2 \left(\hat{y}^n - \left(b + w \cdot x_{cp}^n \right) \right)$$

How's the results?



How's the results? - Generalization

What we really care about is the error on new data (testing data)



$$y = b + w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2$$

Best Function

$$b = -10.3$$

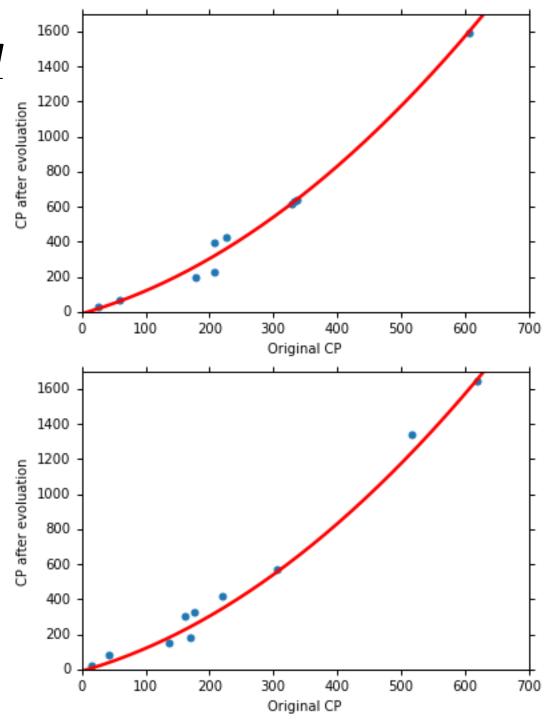
$$W_1 = 1.0, W_2 = 2.7 \times 10^{-3}$$

Average Error = 15.4

Testing:

Average Error = 18.4

Better! Could it be even better?



$$y = b + w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2 + w_3 \cdot (x_{cp})^3$$

Best Function

$$b = 6.4, w_1 = 0.66$$

$$w_2 = 4.3 \times 10^{-3}$$

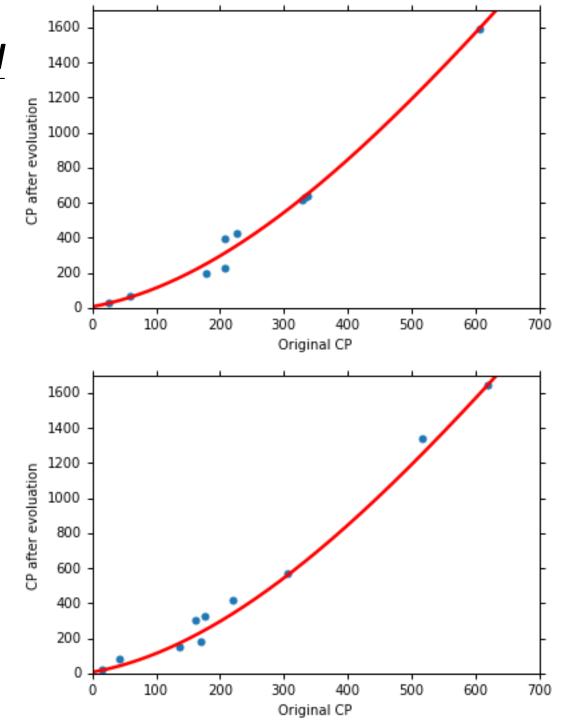
$$w_3 = -1.8 \times 10^{-6}$$

Average Error = 15.3

Testing:

Average Error = 18.1

Slightly better. How about more complex model?



$$y = b + w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2 + w_3 \cdot (x_{cp})^3 + w_4 \cdot (x_{cp})^4$$

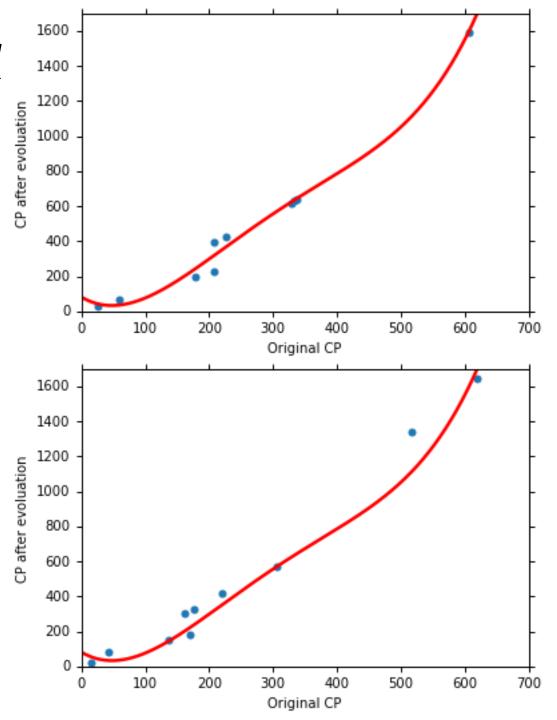
Best Function

Average Error = 14.9

Testing:

Average Error = 28.8

The results become worse ...



y = b +
$$w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2$$

+ $w_3 \cdot (x_{cp})^3 + w_4 \cdot (x_{cp})^4$
+ $w_5 \cdot (x_{cp})^5$

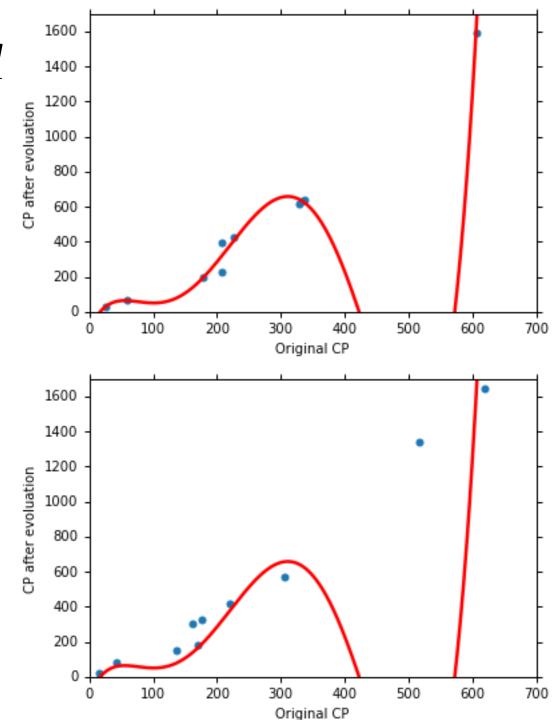
Best Function

Average Error = 12.8

Testing:

Average Error = 232.1

The results are so bad.



Model Selection

1.
$$y = b + w \cdot x_{cp}$$

2.
$$y = b + w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2$$

3.
$$y = b + w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2 + w_3 \cdot (x_{cp})^3$$

4.
$$y = b + w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2$$
$$+ w_3 \cdot (x_{cp})^3 + w_4 \cdot (x_{cp})^4$$

$$y = b + w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2$$
5.
$$+ w_3 \cdot (x_{cp})^3 + w_4 \cdot (x_{cp})^4 + w_5 \cdot (x_{cp})^5$$

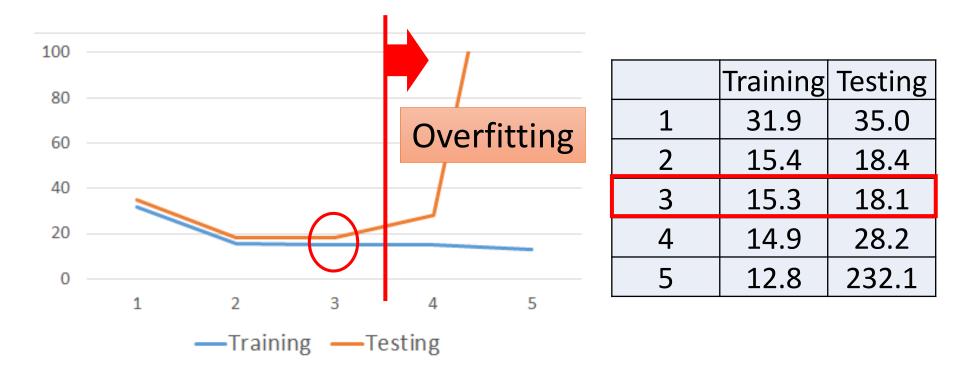
Training Data



A more complex model yields lower error on training data.

If we can truly find the best function

Model Selection



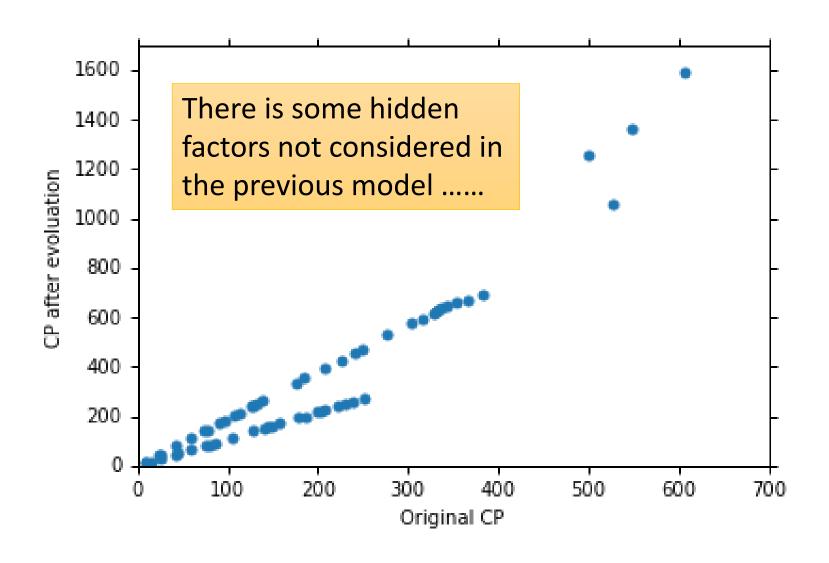
A more complex model does not always lead to better performance on *testing data*.

This is *Overfitting*.

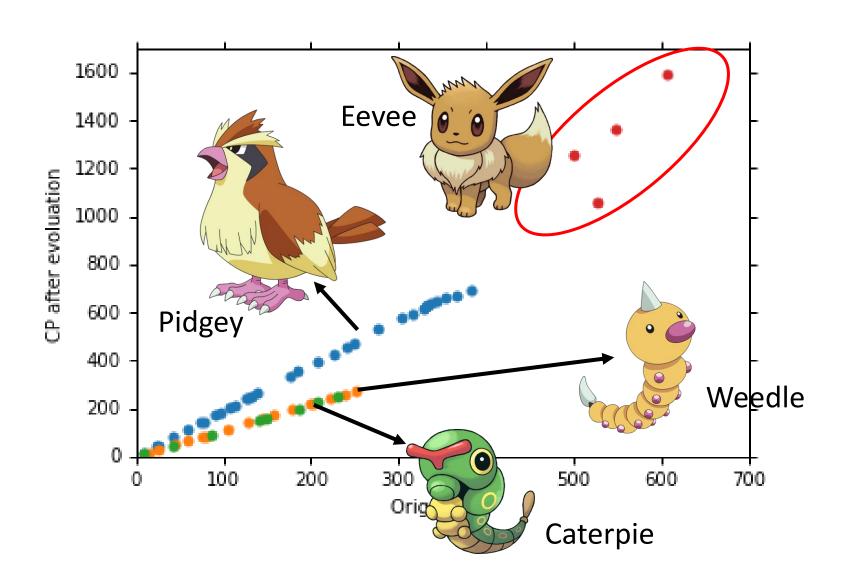


Select suitable model

Let's collect more data



What are the hidden factors?



Back to step 1: Redesign the Model

$$y = b + \sum w_i x_i$$

Linear model?

$$x_s = \text{species of } x$$



If
$$x_s = \text{Pidgey}$$
: $y = b_1 + w_1 \cdot x_{cp}$

If
$$x_s$$
 = Weedle: $y = b_2 + w_2 \cdot x_{cp}$

If
$$x_s$$
 = Caterpie: $y = b_3 + w_3 \cdot x_{cp}$

If
$$x_s$$
 = Eevee: $y = b_4 + w_4 \cdot x_{cp}$



Back to step 1: Redesign the Model

$$y = b + \sum w_i x_i$$

Linear model?

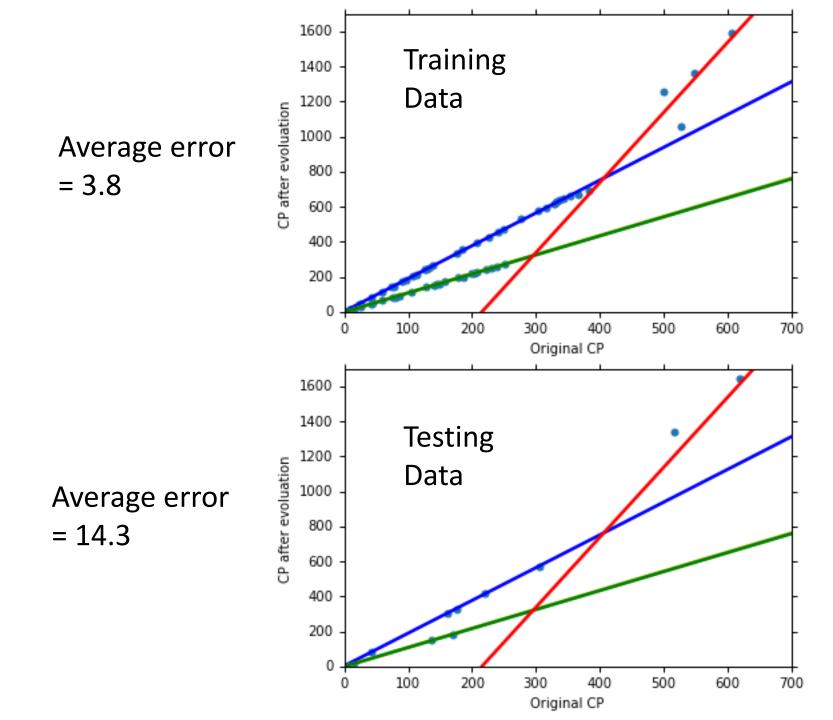
$$y = b_{1} \cdot \begin{vmatrix} 1 \\ +w_{1} \end{vmatrix} \cdot \begin{vmatrix} 1 \\ 1 \end{vmatrix} x_{cp}$$
 $+b_{2} \cdot \begin{vmatrix} 0 \\ +w_{2} \end{vmatrix} \cdot \begin{vmatrix} 0 \\ +w_{3} \end{vmatrix} \cdot \begin{vmatrix} 0 \\ +w_{4} \end{vmatrix}$

$$\delta(x_S = \text{Pidgey})$$

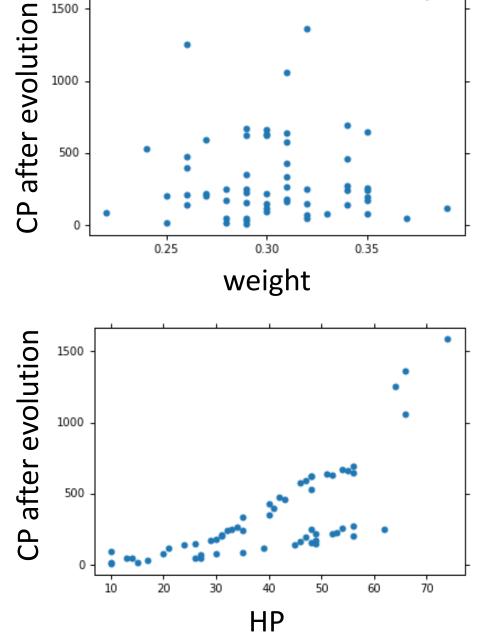
$$\begin{cases} = 1 & \text{If } x_S = \text{Pidgey} \\ = 0 & \text{otherwise} \end{cases}$$

$$\text{If } x_S = \text{Pidgey}$$

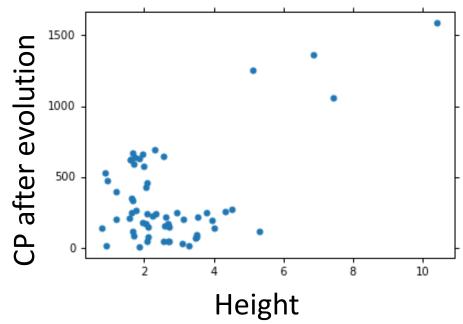
$$y = b_1 + w_1 \cdot x_{cp}$$



Are there any other hidden factors?



1500



Back to step 1: Redesign the Model Again



If
$$x_{S} = \text{Pidgey}$$
: $y' = b_{1} + w_{1} \cdot x_{cp} + w_{5} \cdot (x_{cp})^{2}$

If $x_{S} = \text{Weedle}$: $y' = b_{2} + w_{2} \cdot x_{cp} + w_{6} \cdot (x_{cp})^{2}$

If $x_{S} = \text{Caterpie}$: $y' = b_{3} + w_{3} \cdot x_{cp} + w_{7} \cdot (x_{cp})^{2}$

If $x_{S} = \text{Eevee}$: $y' = b_{4} + w_{4} \cdot x_{cp} + w_{8} \cdot (x_{cp})^{2}$
 $y = y' + w_{9} \cdot x_{hp} + w_{10} \cdot (x_{hp})^{2}$
 $y = y' + w_{11} \cdot x_{h} + w_{12} \cdot (x_{h})^{2} + w_{13} \cdot x_{w} + w_{14} \cdot (x_{w})^{2}$

Training Error = 1.9

Testing Error = 102.3

Overfitting!



Back to step 2: Regularization

$$y = b + \sum w_i x_i$$

$$L = \sum_{n} \left(\hat{y}^{n} - \left(b + \sum_{i} w_{i} x_{i} \right) \right)^{2} + \lambda \sum_{i} (w_{i})^{2}$$

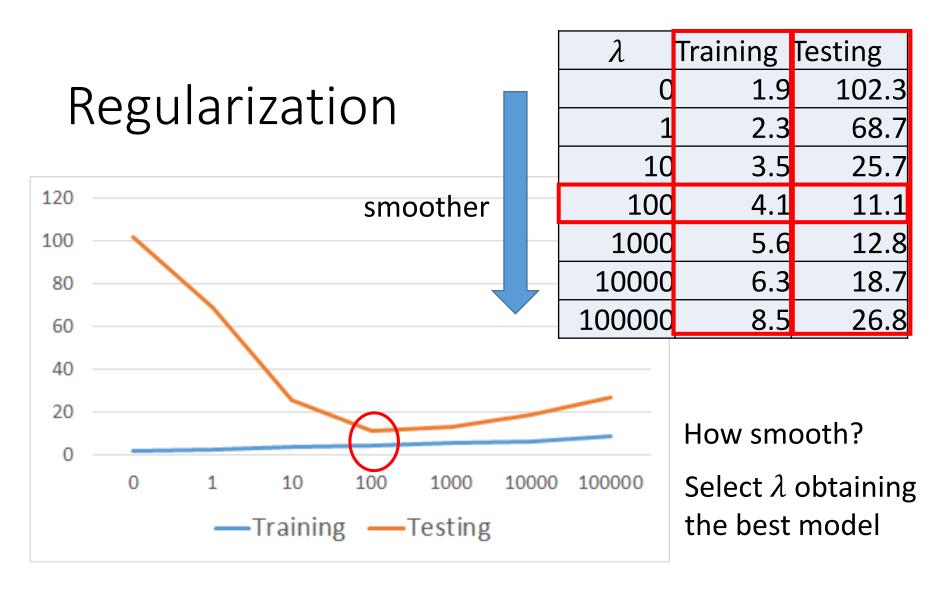
The functions with smaller w_i are better

$$+\lambda\sum(w_i)^2$$

 \triangleright Smaller w_i means ... smoother

moother
$$y = b + \sum w_i x_i$$
$$y + \sum w_i \Delta x_i = b + \sum w_i (x_i + \Delta x_i)$$

> We believe smoother function is more likely to be correct Do you have to apply regularization on bias?



- \triangleright Training error: larger λ , considering the training error less
- > We prefer smooth function, but don't be too smooth.

Conclusion

- Pokémon: Original CP and species almost decide the CP after evolution
 - There are probably other hidden factors
- Gradient descent
 - More theory and tips in the following lectures
- We finally get average error = 11.1 on the testing data
 - How about new data? Larger error? Lower error?
- Next lecture: Where does the error come from?
 - More theory about overfitting and regularization
 - The concept of validation

Reference

• Bishop: Chapter 1.1

Acknowledgment

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