Eliminating loop dependencies

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Based on material by Cosmin Oancea

A seemingly sequential loop

```
float tmp;
for (int i = 2; i < N; i++) {
   S<sub>1</sub>: tmp = 2 * B[i-2];
   S<sub>2</sub>: A[i] = tmp;
   S<sub>3</sub>: B[i] = tmp + B[i-1];
}
```

Dependencies:

- $S_3 \rightarrow S_1$ with direction < due to B.
- lacksquare $S_1 o S_3$ with direction = due to tmp.
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- $S_3 \rightarrow S_1$ with direction < due to B.
- $S_1 \rightarrow S_3$ with direction = due to tmp.
- $S_1 \rightarrow S_2$ with direction = due to tmp.

Loop distribution

A transformation that factors out some statements of a loop, typically to improve locality or parallelism.

```
float tmp;
for (int i = 2; i < N; i++) {
 S_1: tmp = 2 * B[i-2];
 S_2: A[i] = tmp;
```





 $S_3: B[i] = tmp + B[i-1];$

• We distribute S_2 because it is not in a dependency cycle.

```
float tmp:
for (int i = 2; i < N; i++) {
 S_3: B[i] = tmp + B[i-1];
```

- S_1 : tmp = 2 * B[i-2]:

 S_2 : A[i] = tmp;

• We distribute S_2 because it is not in a dependency cycle.

- for (int i = 2; i < N; i++) {

must use array expansion to save all the values of tmp we will need.

But we have a problem, because we will not be reading the right tmp value. We

```
float tmp[N];
for (int i = 2; i < N; i++) {
    S1: tmp[i] = 2 * B[i-2];
    S3: B[i] = tmp[i] + B[i-1];
}
for (int i = 2; i < N; i++) {
    S2: A[i] = tmp[i];
}</pre>
```

- We distribute S_2 because it is not in a dependency cycle.
- But we have a problem, because we will not be reading the right tmp value. We must use array expansion to save all the values of tmp we will need.
- Instead of a single sequential loop, we now have a sequential loop and a parallel loop, and a bunch of extra memory usage. Worth it? Depends.

Eliminating false dependencies

False dependencies

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Anti dependency (WAR)

$$.. = X$$

 $X = \dots$

- Often a read from original array element followed by later update.
- Eliminate by copying original array.

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Anti and output dependencies are often referred to as *false dependencies* because they can be eliminated in most cases by copying or privatisation.

Anti dependency (WAR)

$$\dots = X$$

 $X = \dots$

- Often a read from original array element followed by later update.
- Eliminate by copying original array.

Output dependency (WAW)

$$X = \dots$$

X = ...

- Often the case that every read is covered by a write in same iteration.
- Can often be fixed by privatisation.

Eliminating WAR dependencies by copying

```
float tmp = A[0];

for (int i=0; i< N-1; i++)

A[i] = A[i+1];

A[N-1] = tmp;
```

Eliminating WAR dependencies by copying

```
float Acopy[N];
                                      #pragma omp parallel for
                                      for (int i=0; i<N; i++)
float tmp = A[0];
                                          Acopy[i] = A[i];
for (int i=0; i< N-1; i++)
    A[i] = A[i+1];
                                      tmp = A[0];
A[N-1] = tmp:
                                      #pragma omp parallel for
                                      for (int i=0; i<N-1; i++)
                                          A[i] = Acopv[i+1]:
                                      A[N-1] = tmp:
```

Eliminating WAW dependencies by privatisation

```
int A[M];
for (int i=0; i<N; i++) {
  for (int j=0, j<M; j++) // Overwrites all of A
    A[j] = (4*i+4*j) % M;
  for (int k=0; k<N; k++)
    X[i][k] = X[i][k-1] * A[ A[(2*i+k)%M] % M];
}</pre>
```

- Dependencies on A in all directions (*).
- Reads from A un-analysable because of the indirect access A[A[...]].
- But there is hope for parallelising this!

Eliminating WAW dependencies by privatisation

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}</pre>
```

- Dependencies on A in all directions (*).
- Reads from A un-analysable because of the indirect access A[A[...]].
- But there is hope for parallelising this!
 - All reads from A must necessarily access values written in the same (outer) iteration.
 - ► So we can give each (outer) iteration its own copy of A!

Privatising A

```
int A[M];
for (int i=0; i<N; i++) {
  for (int j=0, j<M; j++)
    A[j] = (4*i+4*j) % M;
  for (int k=0; k<N; k++)
    X[i][k] = X[i][k-1] * A[ A[(2*i+k)%M] % M];
}</pre>
```

■ Make room for N copies of A and give each iteration its own.

Privatising A

```
int A_expanded[N*M];
#pragma omp parallel for
for (int i=0; i<N; i++) {
  int *A = &A_expanded[i*M];
  for (int j=0, j<M; j++)
    A[j] = (4*i+4*j) % M;
  for (int k=0; k<N; k++)
    X[i][k] = X[i][k-1] * A[ A[(2*i+k)%M] % M];
}</pre>
```

- Make room for N copies of A and give each iteration its own.
- This may use a *lot* of memory—we really need only a copy *per thread*...

Privatising A

```
int A[M];
#pragma omp parallel for lastprivate(A)
for (int i=0; i<N; i++) {
  for (int j=0, j<M; j++)
    A[j] = (4*i+4*j) % M;
  for (int k=0; k<N; k++)
    X[i][k] = X[i][k-1] * A[ A[(2*i+k)%M] % M];
}</pre>
```

- Make room for N copies of A and give each iteration its own.
- This may use a *lot* of memory—we really need only a copy *per thread*...
- The OpenMP lastprivate clause automatically creates the per-thread private copies we need.

Summary

- Don't give up hope if a loop seems sequential.
- Loop distribution can let us extract parallel parts from partially sequential loops.
- Array expansion is sometimes needed to make this work.
- Copying can sometimes be used to eliminate WAR dependencies.
- Privatisation can sometimes be used to eliminate WAW dependencies.
- Making code more parallel often adds overhead and usually requires more memory—always measure the effect of your changes.