Loop dependence analysis

Troels Henriksen
Based on material by Cosmin Oancea

Motivation

Why do we have to look at sequential loops?

¹A *loop nest* is a collection of multiple loops nested within each other.

Motivation

Why do we have to look at sequential loops?

- A lot of sequential code in C++/Java/Fortran.
- Need to parallelize the implementation of given algorithms.
- Need to optimize parallelism, e.g., cache optimisation requires subscript analysis.

¹A *loop nest* is a collection of multiple loops nested within each other.

Motivation

Why do we have to look at sequential loops?

- A lot of sequential code in C++/Java/Fortran.
- Need to parallelize the implementation of given algorithms.
- Need to optimize parallelism, e.g., cache optimisation requires subscript analysis.

This will require us to:

- 1. Identify the loop nests¹ where most of the runtime is spent.
- 2. Parallelise these loops by analysis about which loops in the nest are parallel.
- 3. Decide on the manner in which loop nests can be re-written in order to optimise locality of reference, load balancing, etc.

¹A *loop nest* is a collection of multiple loops nested within each other.

Loop nests

```
for (int i = 0; i < N; i++)
for (int j = 0; j < M; j++)
... loop-nest body ...
```

Loop nests

```
for (int i = 0; i < N; i++)
for (int j = 0; j < M; j++)
... loop-nest body ...
```

- Identify iterations of *k*-deep nest with *k*-element vector, e.g. $\vec{k} = (i = 2, j = 4)$.
- Ordered lexicographically:

$$(i = 2, j = 4) < (i = 3, j = 3)$$

because third iteration of the outer loop is executed before the fourth iteration of the outer loop.

This is program order.

Dependencies and transformations

Loop transformation: A change to a loop nest that ensures all dependencies are still respected.

Example of valid transformation

```
\begin{array}{lll} \mbox{for (int $j=0$; $i<N$; $i++$)} & \mbox{for (int $i=0$; $i<N$; $i++$)} \\ \mbox{for (int $i=0$; $i<N$; $i++$)} & \Rightarrow & \mbox{for (int $j=0$; $i<N$; $i++$)} \\ \mbox{A[i][j] = i*j;} & \mbox{A[i][j] = i*j;} \end{array}
```

Dependencies and transformations

Loop transformation: A change to a loop nest that ensures all dependencies are still respected.

Example of valid transformation

Example of invalid transformation

Definition of load-store dependencies

True Dep. (RAW)

S1

S2

Anti Dep. (WAR)

$$S1$$
 ... = X $S2$ X = ...

A dependence from S1 to S2 exists in a loop nest iff there are iterations \vec{k} . \vec{l} where

Output Dep. (WAW)

```
X = \dots

X = \dots
```

Loop Dependency:

 $ec{k} < ec{l}$ or $ec{k} = ec{l}$, and there is a path from S1 to S2, and

- 1. S1 accesses memory location M on iteration \vec{k} , and
- 2. S2 accesses memory location M on iteration \vec{l} , and
- 3. one of these accesses is a write.
- We say that S1 is the source and S2 is the sink of the dependence.
- Dependence depicted with an arrow pointing from source to sink.

Three loop nests

```
for (int i = 0; i < N: i++)
  for (int i = 0: i < N: i++)
   S_1: A[i][i] = A[i][i]...
for (int i = 1; i < N; i++)
  for (int i = 1; i < N; i++) {
   S_1: A[i][i] = A[i-1][i-1]...
   S_2: B[i][i] = B[i-1][i]...
for (int i = 1; i < N; i++)
  for (int i = 0; i < N; i++)
   S_1: A[i][i] = A[i-1][i+1]...
```

- Which of these are parallel?
- Can we transform them somehow to be more parallel?
- When is it safe to interchange the loops?

Loop A

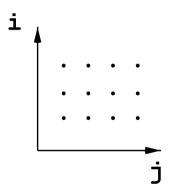
```
for (int i = 0; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[j][i] = A[j][i]...
```

- Reads from *A*[3][3].
- Writes to A[3][3].
- So no dependency on other iterations—write that as a dot.

Loop A

```
for (int i = 0; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[j][i] = A[j][i]...
```

- Reads from *A*[3][3].
- Writes to *A*[3][3].
- So no dependency on other iterations—write that as a dot.



Loop B

```
for (int i = 1; i < N; i++)

for (int j = 1; j < N; j++) {

S_1 : A[j][i] = A[j-1][i-1]...

S_2 : B[j][i] = B[j-1][i]...

}
```

- Reads from *A*[2][1], *B*[2][2].
- Writes to *A*[3][2], *B*[3][2].
- So iteration (i,j) writes values read by iterations (i,j+1),(i+1,j+1).

Loop B

```
for (int i = 1; i < N; i++)

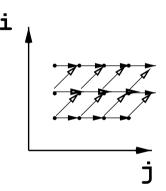
for (int j = 1; j < N; j++) {

S_1 : A[j][i] = A[j-1][i-1]...

S_2 : B[j][i] = B[j-1][i]...

}
```

- Reads from *A*[2][1], *B*[2][2].
- Writes to A[3][2], B[3][2].
- So iteration (i,j) writes values read by iterations (i,j+1), (i+1,j+1).



Loop C

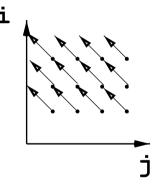
```
for (int i = 1; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[i][j] = A[i-1][j+1]...
```

- Reads from *A*[1][4].
- Writes to *A*[2][3].
- So iteration (i,j) writes values read by iterations (i+1,j-1).

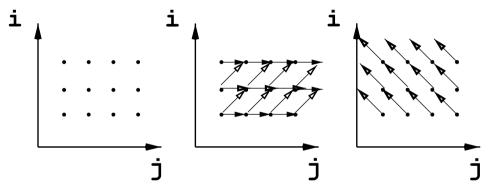
Loop C

```
for (int i = 1; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[i][j] = A[i-1][j+1]...
```

- Reads from *A*[1][4].
- Writes to *A*[2][3].
- So iteration (i,j) writes values read by iterations (i+1,j-1).



Loop-Nest Dependencies



- Wouldn't want to visualise for for more than two dimensions.
- How can we summarize this information?

Aggregate Dependencies via Direction Vectors

Dependency Direction

For a dependency from S1 in iteration \vec{k} (source) to S2 in \vec{l} (sink) where $\vec{k} \leq \vec{l}$, the elements of the direction vector $\vec{D}(\vec{k}, \vec{l})$ are defined by:

- 1. $D_i(\vec{k}, \vec{l}) = "<" \text{ if } k_i < l_i,$
- 2. $D_i(\vec{k}, \vec{l}) = "=" \text{ if } k_i = l_i,$
- 3. $D_i(\vec{k}, \vec{l}) = ">" \text{ if } k_i > l_i,$
- 4. $D_i(\vec{k}, \vec{l}) = "*"$ if cannot be determined.
- If the source is a write and the sink a read, then a RAW dependency.
- If the source is a read, then WAR.
- If both are writes, then WAW.

A direction vector cannot have > as the first non-= symbol, as that would mean that the sink depends on a future iteration.

How to compute the direction vectors

- For any two statements S1 and S2 that may access the same array A (and at least one of the accesses is a write),
- lacksquare in two symbolic iterations $I^1 \equiv (i_1^1, \dots i_m^1)$ and $I^2 = (i_1^2, \dots i_m^2)$ (such that $I^1 < I^2$)
- on indices $A[e_1^1] \dots [e_n^1]$ and $A[e_1^2] \dots [e_n^2]$, respectively,
- then the direction vectors may be derived from the equations

$$\left\{egin{aligned} e_1^1 &= e_1^2 \ & \cdots \ e_n^1 &= e_n^2 \end{aligned}
ight.$$

The system of equations models the definition of a dependency: both accesses need to refer to the same memory location!

```
for (int i = 0; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[j][i] = A[j][i]...
```

```
for (int i = 0; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[j][i] = A[j][i]...
```

Produces this set of equations for S_1 :

$$\begin{cases} i_1 = i_2 \\ j_1 = j_2 \end{cases}$$

```
for (int i = 0; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[j][i] = A[j][i]...
```

Produces this set of equations for S_1 :

$$\begin{cases} i_1 = i_2 \\ j_1 = j_2 \end{cases}$$

This implies $i_1 = i_2, j_1 = j_2$, so the direction vector is

```
for (int i = 1; i < N; i++)

for (int j = 1; j < N; j++) {

S_1: A[j][i] = A[j-1][i-1]...

S_2: B[j][i] = B[j-1][i]...

}
```

```
for (int i = 1; i < N; i++)

for (int j = 1; j < N; j++) {

S_1 : A[j][i] = A[j-1][i-1]...

S_2 : B[j][i] = B[j-1][i]...

}
```

Assuming (i_1, j_1) is the read from a given element of an array:

$$S_1: egin{cases} i_1-1=i_2 \ j_1-1=j_2 \end{cases} \qquad \qquad S_2: egin{cases} i_1=i_2 \ j_1-1=j_2 \end{cases}$$

```
for (int i = 1; i < N; i++)

for (int j = 1; j < N; j++) {

S_1 : A[j][i] = A[j-1][i-1]...

S_2 : B[j][i] = B[j-1][i]...

}
```

Assuming (i_1, j_1) is the read from a given element of an array:

$$S_1: \begin{cases} i_1-1=i_2 \\ j_1-1=j_2 \end{cases}$$
 $S_2: \begin{cases} i_1=i_2 \\ j_1-1=j_2 \end{cases}$

- \bullet $i_1 > i_2, j_1 > j_2.$
- If (i_1, j_1) is source, then direction vector is [>,>], which is **illegal**.
- So direction vector: [<,<]</p>

```
for (int i = 1; i < N; i++)

for (int j = 1; j < N; j++) {

S_1 : A[j][i] = A[j-1][i-1]...

S_2 : B[j][i] = B[j-1][i]...

}
```

Assuming (i_1, j_1) is the read from a given element of an array:

$$S_1: egin{cases} i_1-1=i_2\ j_1-1=j_2 \end{cases}$$

- \bullet $i_1 > i_2, j_1 > j_2.$
- If (i_1, j_1) is source, then direction vector is [>,>], which is **illegal**.
- So direction vector: [<,<]

$$\mathcal{S}_2: egin{cases} i_1=i_2\ j_1-1=j_2 \end{cases}$$

- Similar reasoning.
- Direction vector: [=,<]

```
for (int i = 1; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[i][j] = A[i-1][j+1]...
```

```
for (int i = 1; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[i][j] = A[i-1][j+1]...
```

Produces this set of equations for S_1 :

$$\begin{cases} i_1 - 1 = i_2 \\ j_1 + 1 = j_2 \end{cases}$$

```
for (int i = 1; i < N; i++)
for (int j = 0; j < N; j++)
S_1: A[i][j] = A[i-1][j+1]...
```

Produces this set of equations for S_1 :

$$\begin{cases} i_1 - 1 = i_2 \\ j_1 + 1 = j_2 \end{cases}$$

Implies $i_1 > i_2, j_1 < j_2$, but which of $(i_1, j_1), (i_2, j_2)$ is the sink and which is the source?

- Picking (i_1, j_1) as source gives us [>, <], which is illegal.
- So it must be [<,>].

Summary

- Dependencies constrain how we can reorder the statements of a program.
- A dependency connects source and sink statements, and the source must run before the sink.
- Direction vectors are a tool we can use to qualify the dependencies in a loop nest.
- This is fiddly material. Read the course notes!