

Mathematics of Discrete Sine Transform (DST)¹

DST_I:

$$y(k) = \sqrt{\frac{2}{N+1}} \sum_{n=0}^{N-1} x(n) \sin\left(\frac{\pi(n+1)(k+1)}{N+1}\right) \quad (1)$$

DST_II:

$$y(k) = \sqrt{\frac{2-\delta_{kN}}{N}} \sum_{n=0}^{N-1} x(n) \sin\left(\frac{\pi(n+\frac{1}{2})(k+1)}{N}\right) \quad (2)$$

DST_III:

$$y(k) = \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} x(n) \frac{1}{\sqrt{1+\delta_{nN}}} \sin\left(\frac{\pi(n+1)(k+\frac{1}{2})}{N}\right) \quad (3)$$

DST_IV:

$$y(k) = \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} x(n) \sin\left(\frac{\pi(n+\frac{1}{2})(k+\frac{1}{2})}{N}\right) \quad (4)$$

References:

<http://onlinelibrary.wiley.com/doi/10.1002/cta.447/pdf>

The general equation for a 2D DST

References:

<https://uk.mathworks.com/matlabcentral/fileexchange/49875-2d-discrete-sine-transform-theory>

¹Implemented Mathematics

The series are indexed from n = 0 and k = 0 to N-1.

All variants of the DCT are unitary (or, equivalently, orthogonal): To find their inverses, switch k and n in each definition. In particular, DST-1 and DST-4 are their own inverses, and DST-2 and DST-3 are inverses of each other.

2D discrete sine transform:

We assume that the length of the domain is equal in X and Y directions. Moreover, we assume that number of nodes are equal in both directions. The discrete sine transform can be written as

$$a_{mn} = \left(\frac{2}{l}\right)^2 \int_0^l \int_0^l u(x, y) \sin\left(\frac{\pi m x}{l}\right) \sin\left(\frac{\pi n y}{l}\right) dx dy$$
$$a_{mn} = \left(\frac{2}{l}\right)^2 \int_0^l \left[\sum_{i=1}^{N-1} u((i-1)\Delta x, y) \sin\left(\frac{\pi m(i-1)\Delta x}{l}\right) + u(i\Delta x, y) \sin\left(\frac{\pi m i \Delta x}{l}\right) \right] \frac{\Delta x}{2} \sin\left(\frac{\pi n y}{l}\right) dy$$
$$a_{mn} = \left(\frac{2}{N-1}\right)^2 \sum_{i=1}^{N-1} \sum_{j=1}^{N-1} \left[U(i, j) \sin\left(\frac{\pi m(i-1)}{N-1}\right) \sin\left(\frac{\pi n(j-1)}{N-1}\right) + U(i, j+1) \sin\left(\frac{\pi m(i-1)}{N-1}\right) \sin\left(\frac{\pi n j}{N-1}\right) \right]$$
$$+ U(i+1, j) \sin\left(\frac{\pi m i}{N-1}\right) \sin\left(\frac{\pi n(j-1)}{N-1}\right) + U(i+1, j+1) \sin\left(\frac{\pi m i}{N-1}\right) \sin\left(\frac{\pi n j}{N-1}\right) \Big]$$

2D inverse sine transform:

$$U(i, j) = \sum_{m=1}^{N-1} \sum_{n=1}^{N-1} a_{mn} \sin\left(\frac{\pi m(i-1)}{N-1}\right) \sin\left(\frac{\pi n(j-1)}{N-1}\right)$$

Mathematics of Discrete Cosine Transform (DCT)²

DCT_I:

$$y(k) = \sqrt{\frac{2}{N}} \sum_{n=1}^N x(n) \frac{1}{\sqrt{1 + \delta_{n1} + \delta_{nN}}} \frac{1}{\sqrt{1 + \delta_{k1} + \delta_{kN}}} \cos\left(\frac{\pi(n-1)(k-1)}{N-1}\right) \quad (5)$$

DCT_II:

$$y(k) = \sqrt{\frac{2}{N}} \sum_{n=1}^N x(n) \frac{1}{\sqrt{1 + \delta_{k1}}} \cos\left(\frac{\pi(2n-1)(k-1)}{2N}\right) \quad (6)$$

DCT_III:

$$y(k) = \sqrt{\frac{2}{N}} \sum_{n=1}^N x(n) \frac{1}{\sqrt{1 + \delta_{n1}}} \cos\left(\frac{\pi(n-1)(2k-1)}{2N}\right) \quad (7)$$

DCT_IV:

$$y(k) = \sqrt{\frac{2}{N}} \sum_{n=1}^N x(n) \cos\left(\frac{\pi(2n-1)(2k-1)}{4N}\right) \quad (8)$$

References:

<https://uk.mathworks.com/help/signal/ref/dct.html>

The general equation for a 2D DCT

$$F(u, v) = \sqrt{\frac{2}{N}} \sqrt{\frac{2}{M}} \sum_{i=0}^{N-1} \sum_{j=0}^{M-1} \Lambda(i) \Lambda(j) \cos\left(\frac{\pi(2i+1)u}{2N}\right) \cos\left(\frac{\pi(2j+1)v}{2M}\right) f(i, j) \quad (9)$$

²Implemented Mathematics

The series are indexed from $n = 1$ and $k = 1$ instead of the usual $n = 0$ and $k = 0$, because MATLAB® vectors run from 1 to N instead of from 0 to N - 1.

All variants of the DCT are unitary (or, equivalently, orthogonal): To find their inverses, switch k and n in each definition. In particular, DCT-1 and DCT-4 are their own inverses, and DCT-2 and DCT-3 are inverses of each other.

and the corresponding inverse 2D DCT transform is $F(u, v)^{-1}$ where

$$\Lambda(\kappa) := \begin{cases} \frac{1}{\sqrt{2}} & \text{for } \kappa = 0 \\ 1 & \text{otherwise} \end{cases}$$

References:

<https://users.cs.cf.ac.uk/Dave.Marshall/Multimedia/node231.html>

The general equation for a 3D DCT

$$F(u, v, w) = \sqrt{\frac{2}{N}} \sqrt{\frac{2}{M}} \sqrt{\frac{2}{P}} \sum_{i=0}^{N-1} \sum_{j=0}^{M-1} \sum_{k=0}^{P-1} \Lambda(i) \Lambda(j) \Lambda(k) \cos\left(\frac{\pi(2i+1)(u)}{2N}\right) \cos\left(\frac{\pi(2j+1)(v)}{2M}\right) \cos\left(\frac{\pi(2k+1)(w)}{2P}\right) f(i, j, k) \quad (10)$$

and the corresponding inverse 3D DCT transform is $F(u, v, w)^{-1}$ where

$$\Lambda(\xi) := \begin{cases} \frac{1}{\sqrt{2}} & \text{for } \xi = 0 \\ 1 & \text{otherwise} \end{cases}$$