$$\begin{aligned} & (C): \left[z \right] - A_{d} + B_{d} \right| = \\ & \left[z \quad 0 \\ 0 \quad z \right] - \left[\frac{J_{0}}{J_{0}} \sin \frac{J_{0}}{J_{0}} \right] + \left[\frac{-1_{0} \cos \frac{J_{0}}{J_{0}} + \frac{1}{I_{0}}}{2J_{0} \sin \frac{J_{0}}{J_{0}}} \right] \\ & = \left[z - \cos \frac{J_{0}}{J_{0}} + k_{1} \left(\frac{1}{I_{0}} - \frac{1}{I_{0}} \cos \frac{J_{0}}{J_{0}} \right) - \frac{1}{2} J_{0} \sin \frac{J_{0}}{J_{0}} + k_{2} \left(\frac{1}{I_{0}} - \frac{1}{I_{0}} \cos \frac{J_{0}}{J_{0}} \right) \right] \\ & = \left[z - \cos \frac{J_{0}}{J_{0}} + k_{1} \left(\frac{1}{I_{0}} - \frac{1}{I_{0}} \cos \frac{J_{0}}{J_{0}} \right) - \frac{1}{2} J_{0} \sin \frac{J_{0}}{J_{0}} + k_{2} \left(\frac{1}{I_{0}} - \frac{1}{I_{0}} \cos \frac{J_{0}}{J_{0}} \right) \right] \\ & = \left[z - \cos \frac{J_{0}}{J_{0}} + \frac{1}{2} J_{0} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{1}{I_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{J_{0}}{J_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \left(\log \cos \frac{J_{0}}{J_{0}} - \frac{J_{0}}{J_{0}} \right) k_{1} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \frac{J_{0}}{J_{0}} \sin \frac{J_{0}}{J_{0}} \right] \\ & = \left[1 - \frac{J_{0}}{2J_{0}} \sin \frac{J_{0}}{J_{0}} + k_{2} - \frac{J_{0}}{J_{0}} \sin \frac{J_{0}}{J_{0}}$$

=> x(k) =0, k=2,3,4,...
So, the response is clearly deadbeat.