Point Cloud Transformer

CS 323 Project 4

Overview

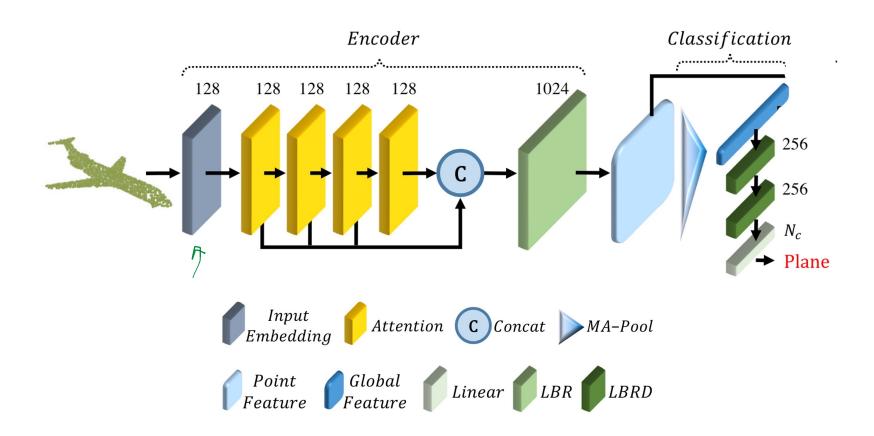
• In this project, you will implement PCT, an attention-based object classifier for 3D point clouds

- The requirements will be as follows:
 - Implement model 1: Naive PCT
 - Implement model 2: PCT with Offset-Attention
 - Implement model 3: PCT with Offset-Attention and Local Neighbor Embedding layer

Dataset: ModelNet40

- 40 categories (such as airplane, car, plant, lamp)
- 9,843 meshes will be used for training
- 2,468 meshes will be used for validation
- The point cloud data points are uniformly sampled from the mesh surfaces
- You will be provided the point cloud data

PCT



Self-Attention Layer

$$(\mathbf{Q}, \mathbf{K}, \mathbf{V}) = \mathbf{F}_{in} \cdot (\mathbf{W}_q, \mathbf{W}_k, \mathbf{W}_v)$$

$$\mathbf{Q}, \mathbf{K} \in \mathbb{R}^{N \times d_a}, \quad \mathbf{V} \in \mathbb{R}^{N \times d_e}$$

$$\mathbf{W}_q, \mathbf{W}_k \in \mathbb{R}^{d_e \times d_a}, \quad \mathbf{W}_v \in \mathbb{R}^{d_e \times d_e}$$
(2)

$$\tilde{\mathbf{A}} = (\tilde{\alpha})_{i,j} = \mathbf{Q} \cdot \mathbf{K}^{\mathrm{T}}.$$
 (3)

These weights are then normalized (denoted SS in Figure 3) to give $\mathbf{A} = (\alpha)_{i,j}$:

$$\bar{\alpha}_{i,j} = \frac{\tilde{\alpha}_{i,j}}{\sqrt{d_a}},$$

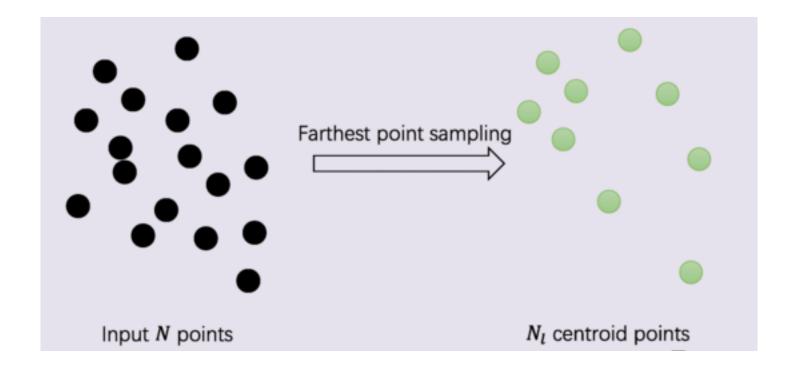
$$\alpha_{i,j} = \operatorname{softmax}(\bar{\alpha}_{i,j}) = \frac{\exp(\bar{\alpha}_{i,j})}{\sum_{k} \exp(\bar{\alpha}_{i,k})},$$
(4)

Local Neighbor Embedding layer

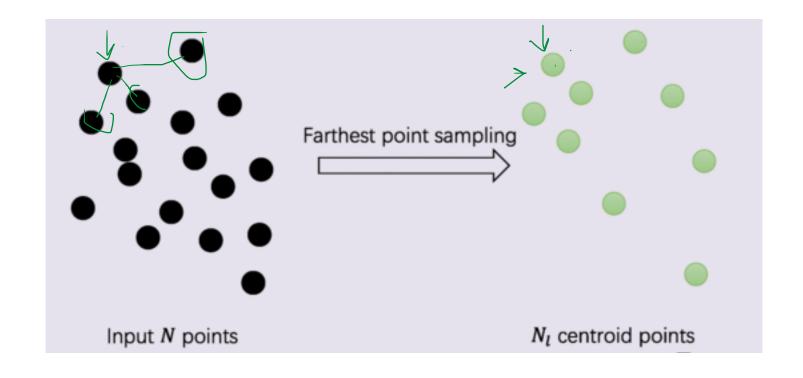
 Grouping and Sampling operations to augment PCT's ability of local feature extraction

 Most of the code for this layer is already implemented, you have to implement small pieces of the code though

Sampling



Grouping



Notes about Grading

- (90 points in total) The maximum points for each sub-task are provided
- (10 points):
 - (5 points) Obtain a validation accuracy of more than or equal to 85% on at least two of the above models
 - (5 points) Obtain a minimum of 80% of validation accuracy on all the three models