Report

This report explains the basic logic behind each major step of RNN implementation and shows the training results of sentiment analysis using RNN.

1. RNN Step Forward

Given input data x_t at timestep t, hidden state from previous timestep prev_h (h_{t-1}) , W_x , W_h and b, we calculate next_h (h_t) by

$$a_t = W_x x_t + W_h h_{t-1} + b$$
$$h_t = \tanh(a_t)$$

2. RNN Step Backward

Given dnext_h (dh_t) , gradient of loss with respect to next hidden state t, and with $\frac{\mathrm{dh}_t}{\mathrm{d}a_t} = 1 - h_t^2$, we have

$$dx_{t} = dh_{t} \frac{\partial h_{t}}{\partial a_{t}} \frac{\partial a_{t}}{\partial x_{t}} = W_{x}^{T} dh_{t} (1 - h_{t}^{2})$$

$$dh_{t-1} = dh_{t} \frac{\partial h_{t}}{\partial a_{t}} \frac{\partial a_{t}}{\partial h_{t-1}} = W_{h}^{T} dh_{t} (1 - h_{t}^{2})$$

$$dW_{x} = dh_{t} \frac{\partial h_{t}}{\partial a_{t}} \frac{\partial a_{t}}{\partial W_{x}} = dh_{t} (1 - h_{t}^{2}) x_{t}^{T}$$

$$dW_{h} = dh_{t} \frac{\partial h_{t}}{\partial a_{t}} \frac{\partial a_{t}}{\partial W_{h}} = dh_{t} (1 - h_{t}^{2}) h_{t-1}^{T}$$

$$db = dh_{t} \frac{\partial h_{t}}{\partial a_{t}} \frac{\partial a_{t}}{\partial b} = dh_{t} (1 - h_{t}^{2})$$

3. RNN Forward

To run a vanilla RNN forward on an entire sequence of data, we just loop through T vectors for each input. From timestep t=0 towards timestep t=T-1, in each timestep/iteration, we have h_t , $cache_t=rnn_step_forward(x_t,\ h_{t-1},\ W_x$, W_h , b). h_0 is initialized to a zero matrix as there's no previous h at t=0.

4. RNN Backward

In RNN backward, for each parameter, its gradient is just aggregation of gradients across all positions:

$$dW_x = \sum_{t=0}^{t=T-1} d(W_x)_t$$

$$dW_h = \sum_{t=0}^{t=T-1} d(W_h)_t$$

$$db = \sum_{t=0}^{t=T-1} db_t$$

In each timestep/iteration, we have dx_t , dh_{t-1} , $d(W_x)_t$, $d(W_h)_t$, $db_t = rnn_step_backward(dh_t + dh_{t+}, cache_t)$.

5. Sentiment Analysis

In the forward step, we pass forward data through four layers, namely, vanilla rnn layer, temporal affine layer, average layer and finally affine layer. Loss is calculated by taking softmax and cross-entropy of the final result of forward step. In the backward step, we calculate gradients by going backward in the order of affine layer, average layer, temporal layer and finally vanilla rnn layer.

6. Training & Inference on Small Data

Inference is essentially the same as loss method except that backward operation and loss calculation are not needed. By training the RNN model on a small sample of 100 training examples for a few iterations, we get training loss values as below:

(Iteration 1 / 100) loss: 0.315483 (Iteration 11 / 100) loss: 0.277323 (Iteration 21 / 100) loss: 0.243838 (Iteration 31 / 100) loss: 0.212798 (Iteration 41 / 100) loss: 0.183810 (Iteration 51 / 100) loss: 0.157254 (Iteration 61 / 100) loss: 0.133639 (Iteration 71 / 100) loss: 0.113249 (Iteration 81 / 100) loss: 0.096055 (Iteration 91 / 100) loss: 0.081789

The figure below shows the training loss history.

