

basesim_smart:

[1, 1, 1, 0, 1, 0, 1, 1, 1, 1, 0, 1, 1, 1, 4]

[[0. 0. 0. 0.]

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[1. 1. 1. 1.]

Iteration: 1

Fail

Moves: 1

Iteration: 2

Fail

Moves: 8

Iteration: 3

Fail

Moves: 3

Iteration: 4

Fail

Moves: 9

Iteration: 5

Fail

Moves: 1

Iteration: 6

Fail

Moves: 3

Iteration: 7

Fail

Moves: 9

Iteration: 8

Fail

Moves: 6

Iteration: 9
Fail
Moves: 5
Iteration: 10
Fail
Moves: 7
Successses: 0
Iteration: 11
Fail
Moves: 14
Iteration: 12
Fail
Moves: 1
Iteration: 13
Fail
Moves: 5
Iteration: 14
Moves: 14
Iteration: 15
Fail
Moves: 1
Iteration: 16
Moves: 10
Iteration: 17
Fail
Moves: 3
Iteration: 18
Fail
Moves: 3
Iteration: 19
Fail
Moves: 14
Iteration: 20
Fail
Moves: 7
Successses: 2
Iteration: 21
Fail
Moves: 1
Iteration: 22
Moves: 10
Iteration: 23
Moves: 6

Iteration: 24
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Iteration: 25
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Iteration: 26
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Iteration: 27
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Iteration: 28
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Iteration: 29
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Iteration: 30
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Successsses: 9
Iteration: 31
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Iteration: 40
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Successsses: 10
Iteration: 41
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Successsses: 10
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Successsses: 10
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Successsses: 10
Iteration: 81
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Successses: 10
Iteration: 91
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Iteration: 99
Moves: 6