

AIDS, ASSIGNMENT

DATE:

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Q1) What is AI? AI's Role in COVID-19 Pandemic

-) AI in machine refers to the simulation of human intelligence in machines. AI systems can perform tasks such as learning, reasoning, problem solving, perception and language understanding. AI is categorized in various types also.

AI played a crucial role in various aspects of healthcare and daily life, such as:

Early and diagnosis! AI-based models detected and analyzed patterns

Medical research and drug discovery - It discovers potential treatments.

Remote work and learning: online learning and remote collaboration.

Q2) What are AI Agents terminology, explain with example.

-) An AI agent is an entity that provides perceives its environment through sensors.

Agent Function - The agent function of an agent in response to any percept.

Performance Measure - It evaluates the behaviour of the agent in a environment.

Rational Agent - A rational agent acts so as to maximize the expected value of performance measure.

Task Environment - It includes the performance measure, the external environment, sensor and actuators.

Q3) How AI agents are used to solve 8 puzzle problems

→ The 8 puzzle problem is a sliding puzzle consisting of 3×3 grid with 8 tiles and one empty space. Techniques to solve are:

Breadth - First - Search : explores all possible moves level by level.

Depth First Search - Explores all deeper path first.

A* Algorithm - Uses a heuristic function to find optimal path.

Q4) Categorize a shopping bot for an bookstore according to 6 dimensions

→ Observable - Partially Observable

Deterministic/Stochastic : Deterministic

Episodic / Sequential : Sequential

Static / Dynamic - Dynamic

Discrete / continuous - Discrete

single / Multi agent - Single agent.

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Q4) Describe PEAS Framework

AI System Performance Environment Actuator Sensor

Taxi Driver	Safety, Speed	Roads, traffic	Steering, Braking	Cams, cameras
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Medical Diagnosis	Accuracy, treatment success	Symptoms, Diseases	Prescription	Test, patient history
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Music composer	Harmony	Instruments, Music notes	Speakers	Genre data, user preference
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Aircraft Autolanders	Landing precision	Runway, wind, altitude	I-laps, engine	Cams, gyroscope
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Essay Evaluator	Accuracy, grammar check	Essay	Score System	Text recognition
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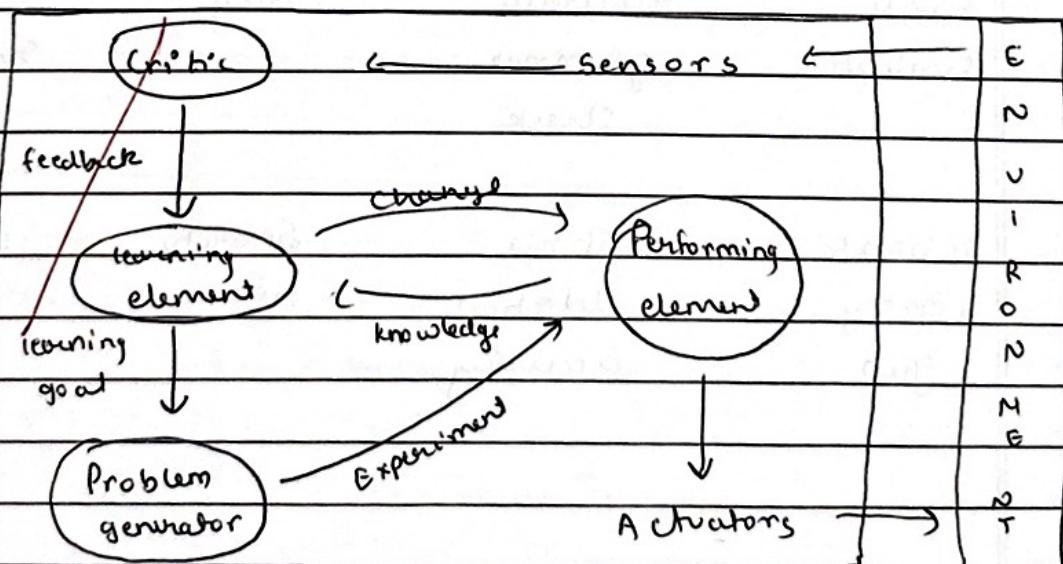
Robotic Sentry Gun	Threat detection, accuracy	Security	Gun movement	Camera Motion sensor.
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Q6) Difference between Model based and Utility based agent.

Feature	Model Based	Utility Based
- Internal Model	Maintaining an internal model of world	Evaluators actions based on utility
- Decision making	uses past state	Selects actions to maximize utility
- Example	Self driving car	AI recommendation
- Goal-oriented	Yes, works towards achieving specific goals.	Yes, but focuses on maximizing satisfaction.

Q7) Architecture of knowledge based and learning Agents.

Learning Agent -



A learning agent improves performance by learning from experience.

Components :-

- Learning Element - Learns from past actions.
- Performance Element - Takes decisions.
- Critic - Evaluates and gives feedback.
- Problem Generator - Suggests new actions.

Example - AI chess bot learns from past games to improve strategy.

Benefit - Adopts over time and makes better decision.

A Knowledge Based Agent (KBA) uses stored knowledge and reasoning to make decisions.

Components :-

1. Knowledge Base (KB) - Stores facts and rules.
2. Inference Engine - Applies logic to derive conclusions.
3. Sensors - collects data from the environment.
4. Actuators - Executes decision.

Example - A medical diagnosis system matches symptoms to diseases using knowledge base.

Benefit - Solves complex problem using logical reasoning.

ENVIRONMENT

INPUT

Sensors

Inference
engine

knowledge
base

Effectors

OUTPUT

Q8) What is AI? Considering the COVID-19 pandemic situation, how AI helped to survive and renovated our way of life with different applications.

(a) Convert the following to predicates:

a) Anita travels by car if available otherwise travels by bus.

$\rightarrow \text{Car Available} : \text{The car is available}$

$\text{Travel By Car}(x) : x \text{ travels by car}$

$\text{Travel By Bus}(x) : x \text{ travels by bus}$

$\text{Car Available} \rightarrow \text{Travel By Car}(\text{Anita}) \wedge \sim \text{Car Available} \rightarrow$
 $\text{Travel By Bus}(\text{Anita})$

b) Bus goes via Andheri and Goregaon.

$\text{Goes Via}(x, y) : x \text{ goes via } y$

$\rightarrow \text{Goes Via}(\text{Bus}, \text{Andheri}) \wedge \text{Goes Via}(\text{Bus}, \text{Goregaon})$

c) Car has puncture so not available -

$\text{Has Puncture}(\text{car}) \rightarrow \sim \text{Car Available}$

Forward Reasoning:

(1) Given: Has Puncture (Car)

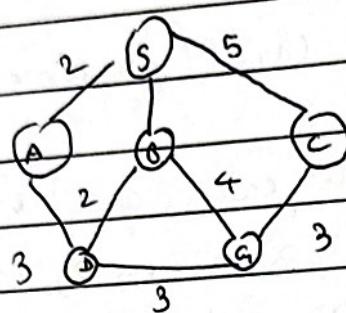
(2) From the 3rd statement, we infer: $\sim \text{Car Available}$

(3) From the 1st line, since car is not available -

Travel By Bus

(4) From the 2nd line, since Anita is travelling by bus,
 the bus goes via Goregaon, we conclude Anita will travel
 by Goregaon.

Q10) Using BFS, travel from S to G



S → A (cost 2)

A → G (cost 3)

S → B (cost 5)

C → G (cost 4)

S → C (cost 5)

A → D (cost 3)

Queue,

Queue [S]

S → Queue [A, B, C]

Dequeue A and explore its neighbours : A, B,

Queue [B, C, D]

Dequeue B and explore its neighbours

Queue [C, D, G]

Dequeue C and queue neighbours

Queue = [D, G]

Dequeue D

Queue = G

Dequeue G

As G is our destination, BFS stops here.

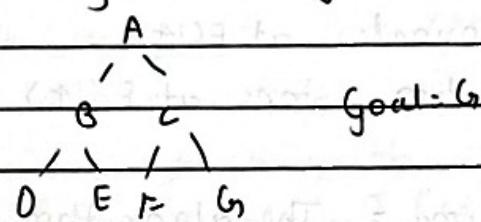
Route from S to G: S → B → G

Q11) What do you mean by depth limited search? Explain Iterative deepening search with example.

-> Depth limited search (DLS) is an uninformed search algorithm that modifies DFS by introducing a depth limit L , preventing exploration beyond the predefined level. This prevents infinite loops in infinite graphs but risks missing goals beyond L .

Iterative deepening search (IDS) combines DLS with BFS by incrementally increasing the depth limited

Example:



Iteration 1: Depth limit = 0

Nodes visited = A

Result : goal not found.

Iteration 2 : L=1

Nodes visited : A -> B -> C

Goal not found.

Iteration 3 : L=2

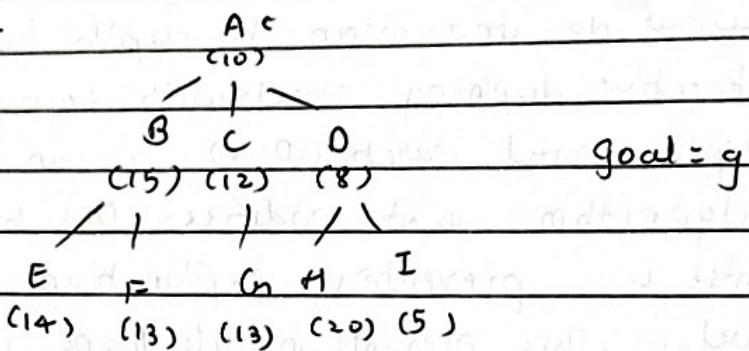
Nodes visited : A -> B -> D -> E -> C -> F -> G

Goal G found at L=2.

Q12) Explain Hill Climbing and its drawbacks in detail with example. Also state limitations of steepest-ascent hill climbing.

-> Hill climbing is a local search optimization algorithm which moves towards better neighboring solutions until it reaches a peak.

Example:-



Steps: Start at root node A(10)

compare its children B, C and D

Move to child with highest value i.e. B(15)

Repeat for B's children E and F

Terminate at E(14)

The algorithm stops at E(14) not reaching the goal.

Drawbacks:

1. Local Maxima - The algorithm greedily selects the best immediate child and can thus get stuck on local maxima.

2. Plateaus - If siblings have equal values, the algorithm can't decide the next step and gets stuck.

3. Ridge - Narrow uphill paths require backtracking which hill climbing algorithm does not support.

Limitations of steepest-Ascent Hill Climbing.

1. Computationally Expensive - Evaluates all neighbours before selecting the best.

2. Can get stuck - It can still get stuck in local maxima, plateaus or ridges.

3. No global optimality - It only focuses on immediate improvements.

(b) Explain simulated Annealing & write its algorithm.

→ Simulated Annealing (SA) is a probabilistic optimization algorithm inspired by metallurgy process of annealing, where materials are heated and cooled to reduce defects. It escapes the local optimal by temporarily accepting worse sol with a probability.

Algorithm:-

1. Initialize

- Set an initial solution and define an initial temp.
- 2. Repeat until stopping condition.
 - Generate a new neighbour sol.
 - Compute change in cost ($\Delta E = E_{\text{new}} - E_{\text{current}}$)
 - If new solution is better i.e. $\Delta E > 0$, accept it.
 - If worse, accept it with probability $P = e^{-\Delta E/T}$
 - Decrease temperature T (cooling schedule)

3) Return best solution.

Example:

~~Travelling Salesman problem~~

~~Swap two cities in a route Accept a longer route (high T) but reject it later (low T)~~

Q1) Explain A* algorithm with an example.

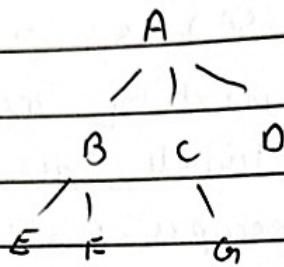
→ A* is a best first search algorithm used in path finding and graph traversal. It uses the following formula $f(n) = g(n) + h(n)$

$g(n) \rightarrow$ cost to reach n from start

$h(n) \rightarrow$ heuristic estimate of cost to reach from goal to n .

$f(n) \rightarrow$ total estimated cost.

Eg - $g_{\text{goal}} = c_n$



Node	$g(n, n)$	$b(n, n)$
A	0	6
B	1	4
C	2	2
D	4	7
E	3	5
F	5	3
G	6	0

Steps:

1. Start at root node A.

$$f(A) = g(A) + h(A) = 0 + 6 = 6$$

2. Expand neighbours : B, C, D

$$f(B) = 1 + 4 = 5$$

~~$f(C) = 2 + 2 = 4$~~

~~$f(D) = 4 + 7 = 11$~~

3. Choose lowest val that is ~~$f(C) = 4$~~

4. Expand neighbours of C: G

$$f(G) = 2 + 4 + 0 = 6$$

5. Goal reached at G with total cost 6.

Advantages -

- efficient for finding shortest paths in weighted graphs
- balances exploration by considering both $g(n)$ & $h(n)$

Q15

Explain Min-Max algorithm and draw game tree for Tic Tac Toe game.

-) The Min max algorithm is a decision making algorithm used in two-player games. It assumes
- one player (MAX) tries to maximize the score.
 - other player (MIN) tries to minimize the score.
 - Game tree represents all possible moves.

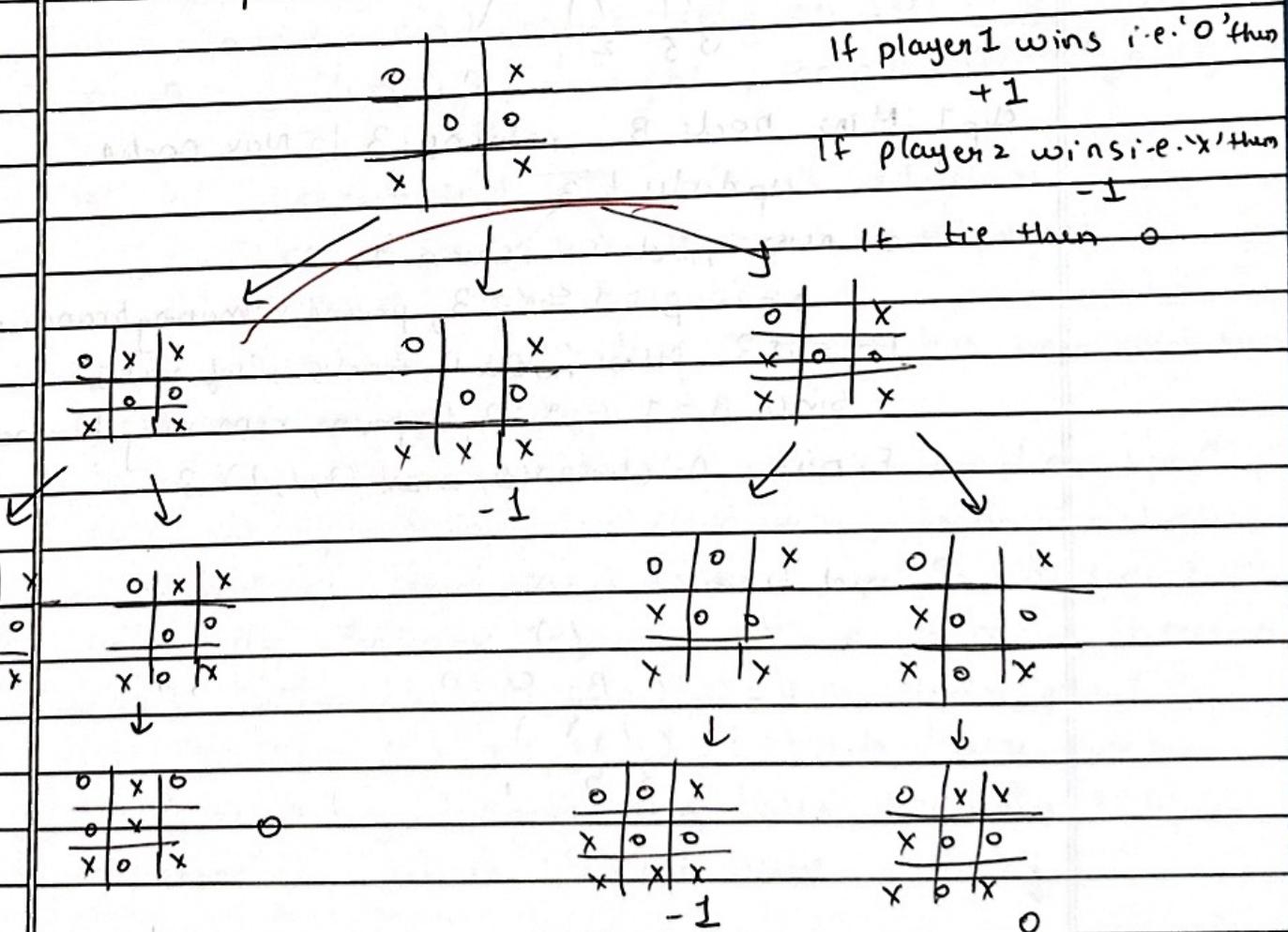
Algorithm -

(1) Generate game tree.

(2) Assign scores

(3) MAX picks highest value from children
MIN picks lowest value

(4) Repeat until Root Node is evaluated



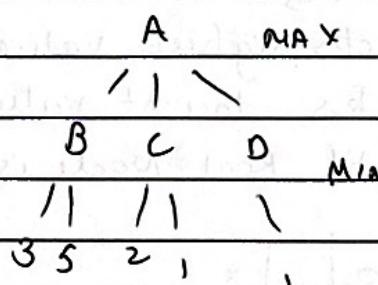
Q16) Explain Alpha - beta pruning algorithm for adversarial search with example.

-> Alpha - beta pruning is an optimization technique for the minimax algorithm used in adversarial search purpose like game playing AI. It reduces computational complexity by pruning branches of game tree that do not influence the final decision.

α - best value maximizing player can guarantee

β - best value minimizing player can guarantee.

Example -



Step 1: MIN node B returns 3 to Max node A

update to 3

2. MIN node C return 1

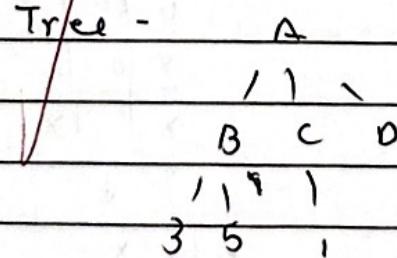
since $\beta = 1 \leq \alpha = 3$, prune remaining branches under C

Final 3. MIN node D finds leaf val 1

since $\beta = 1 \leq \alpha = 3$, prune remaining branches under D

Final : A chooses max (3, 1, 1) = 3

Pruned Tree -



17. Explain WUMPUS world environment giving its PEAS description.

→ Explain how percept sequence is generated for WUMPUS world problem.

1. P - Maximize Rewards

- +1000 for collecting gold & exiting grid

- Minimize penalties

- 1000 for falling into a pit or being eaten by WUMPUS.

- 1 pt for each action taken

- 10 pts for using arrow

2. E - Grid Layout (4x)

containing pits, WUMPUS, gold, walls, breeze,

- Partially observable - agent cannot see entire grid and must rely on sensory inputs

3. A - Move left, right, forward, Grab (gold), shoot

4. S - Breeze - indicates pit is adjacent

Stench - indicates Wumpus is adjacent

Glisten - gold indication

Bump - indicates a wall has been encountered

Generating percept sequence -

- Initial position - Agent starts at a defined pos usually (1,1)

- Movement & perception - while moving, sensors detect surroundings e.g. - breeze means a pit is in adjacent cell

- Creating Percept Sequence - After each move, it records percepts. Example - At (1,2) → [None, Breeze, None]

At (2,1) → [Stench, Breeze, None]

- Decision Making: Agent uses these sequences for logical reasoning to decide its next move.

Q18) Solve the following crypto-arithmetic prb.
 $SEND + MORE = MONEY$

1. Set up the Eqn

$$\begin{array}{r} SEND \\ + MORE \\ \hline \end{array}$$

~~MONEY~~

2. Since N is leading digit, it must be 1, because sum of 2 four-digits cannot exceed 19998.
 $\therefore N = 1$

$$\begin{array}{r} SEND \\ + 1 \cancel{M} O R E \\ \hline 1 O N E Y \end{array}$$

3. $O+E=y$ (if carry=0)

$O+E+D+F=10$ (if carry=1)

Tens place

$$N+T+R+carry-E$$

Hundreds place: $E+O+carry=10$

Thousands place: $S+I=1+carry$

$$S+carry=0$$

$\therefore S=9$ since there is no carry.

4. Try $E=5$

~~If $O=7$ then~~

$$y = 7 + 5 = 12 \text{ (invalid)}$$

~~$D=2$ then~~

$$y = 7$$

5. $y = 7$

Assume $N=8$

$$N+R=F$$

$$B+R=5 \text{ (impossible)} \therefore \boxed{N=6}$$

Final : $S=9, E=5, N=6, D=7, O=0, R=8, Y=2$

$$\begin{array}{r}
 \text{SEND} \\
 + \text{MORE} \\
 \hline
 \text{MONEY}
 \end{array}
 \quad
 \begin{array}{r}
 9 \ 5 \ 6 \ 7 \\
 1 \ 0 \ 8 \ 5 \\
 1 \ 0 \ 6 \ 5 \ 2
 \end{array}$$

Q1a) Consider the axioms.

- > 1. $\forall x (\text{graduating}(x) \rightarrow \text{Happy}(x))$
- 2. $\forall x (\text{Happy}(x) \rightarrow \text{smiling}(x))$
- 3. $\exists x (\text{graduating}(x))$

2. Convert each to clause form

$$1. \forall x (\neg \text{Happy}(x) \vee \text{smiling}(x))$$

$$\{\neg \text{Happy}(x), \text{smiling}(x)\}$$

~~$$2. \forall x (\neg \text{Happy}(x) \vee \text{graduating}(x))$$~~

~~$$\{\neg \text{Happy}(x), \text{Happy}(x)\}$$~~

~~$$3. \text{Graduating}(c)$$~~

3. Prove "Is someone smiling?" using resolution

$$\exists x (\text{smiling}(x))$$

clause Form: ($\# = \text{smiling}(y)$)

$$C_1 = \{\neg \text{Graduating}(x), \text{Happy}(x)\}$$

$$C_2 = \{\neg \text{Happy}(y), \text{smiling}(y)\}$$

$$C_3 = \text{Graduating}(c)$$

Resolution btwn $C_3 \& C_1$

Substitute c for x in C_1 :

From $\text{Graduating}(c)$
 $\text{Happy}(c)$

Resolving with C_2 ~~$\text{smiling}(c)$~~

Graduating (A)

$\sim \text{graduating}(x) \vee \text{happy}(x)$

Happy (x)

$\sim \text{happy}(x) \vee \text{smiling}(x)$

Smiling (x)

$\sim \text{smiling}(x)$

{ }
3

\rightarrow someone is smiling.

Q20) Explain Modus Ponens with example.

\rightarrow Modus Ponens is a fundamental rule of inference in logic. It states that if $P \rightarrow Q$ is true P is true, then Q must also be true. Formula: $P \rightarrow Q, P \quad Q$

Ex, if it is raining, then it is soggy ($P \rightarrow Q$)

it is raining (P)

\therefore it is soggy (Q)

Q21) Explain forward & backward chaining algo with examples.

\rightarrow Forward chaining - It is data driven, inference algorithm that starts with known facts & applies inference rules to derive new facts until the goal is reached.

fact: A, B

Rule : $A \rightarrow C, B \rightarrow D, C \wedge D \rightarrow E$

Goal : I

start with A & B

apply $A \rightarrow C$ to derive C

$B \rightarrow D$ to derive D

$(A \wedge B) \rightarrow I$ to derive I

The goal I reached.

Backward Chaining:

BC is a goal driven, starts with goals work backward to find the facts that support it starts with goal.

fact: A, B

rule: $A \rightarrow C$, $B \rightarrow D$, $C \wedge D \rightarrow I$

goal: I

find the rule $C \wedge D \rightarrow I$

if C & D are true

✓ use $A \rightarrow C$ since A is true, C is true

w, $B \rightarrow D$ since B is true, D is true

C & D are true, I is true.

conclusion: I is reached.

~~S~~