

CONTACT INFORMATION	<p>PostDoctoral Scientist CHILI/LSRO Labs - École Polytechnique Fédéral de Lausanne</p> <p>EPFL IC ISIM CHILI RLC D1 740 (Rolex Learning Center) Station 20 CH-1015 Lausanne, SWITZERLAND</p>	<p>Mobile : +33-6 69 69 48 16 E-mail : wafa.johal@epfl.ch WWW : wafa.johal.fr</p>
RESEARCH INTERESTS	<p>I am interested in user adaptation personalization during Human-Robot Interaction in educational contexts. I work with robots having various embodiment and try to base my models on social and cognitive sciences. I also have interest in affective computing, machine learning and symbolic reasoning. I have conducted child-robot interaction (CRI) experiments from protocol design to data analysis.</p>	
ACADEMIA	<p>Postdoctoral Scientist for NCCR Robotics - EPFL Switzerland, October 2015 - ...</p> <p>Computer Human Interaction for Learning and Instruction Lab (Pr. Pierre Dillenbourg), Mobile Robots Group - LSRO (Pr. Francesco Mondada)</p> <ul style="list-style-type: none">• In charge of the robotics part of the CHILI Lab. Working mainly on two research projects : Cellulo and CoWriter• Area of Study : Human-Robot Interaction, Personalization, Robots in education, Tangible Robots, Cognitive Models for HRI <p>Ph.D in Applied Mathematics and Computer Sciences, October 2015</p> <p>University of Grenoble Alps, Laboratory of Informatics of Grenoble - MAGMA Team France</p> <ul style="list-style-type: none">• Thesis Topic : <i>Behavioural Styles for Human-Robot Interaction : Towards Plasticity in HRI</i>• Advisers : Prof. Sylvie Pesty & Prof. Gaëlle Calvary• Jury Members : Mohamed Chetouani (UPMC), Pierre DeLoor (ENIB), Pierre Dillenbourg (EPFL), Dominique Vaufreydaz (UPMF), Dominique Duhaut (ENIB), Nadine Mandran (CNRS).• Area of Study : Affective Computing, Human-Robot Interaction, Personalization, Plasticity <p>M.S., Computer Sciences : Graphics, Vision & Robotics, June 2012</p> <p>University Joseph Fourier, Grenoble, France</p> <ul style="list-style-type: none">• Thesis Topic : <i>Multi-modal detection of intention of interaction by a companion robot</i>• Adviser : Dr. Dominique Vaufreydaz• Area of Study : Activity Recognition, Multi-modal Data Fusion <p>B.S. B.A. Mathematics and Informatics applied to Cognitive Sciences, June 2010</p> <p>Pierre-Mendès France University, Grenoble, France</p> <ul style="list-style-type: none">• <i>Topped, Summa cum Laude</i>• Mathematics : Linear Algebra, Logic, Probabilities, Statistics• Computer Sciences : Algorithms & Programming• Cognitive Sciences : Memory, Learning & Perception <p>Exchange Student for one year in Washington College, MA (U.S.A.), 2009-2010</p>	
JOURNAL PUBLICATIONS	<ul style="list-style-type: none">• Mondada F, Bonnet E., Davrajh S., Johal W. and Stopforth R.. R2T2 : Robotics to Integrate Educational Efforts in South Africa and Europe. <i>International Journal of Advanced Robotic Systems</i>, 2016.• Vaufreydaz D., Johal W., and Combe C., Starting engagement detection towards a companion robot using multimodal features, <i>Robotics and Autonomous Systems</i>, January 2015, ISSN 0921-8890.	
INTERNATIONAL CONFERENCE PUBLICATIONS	<ul style="list-style-type: none">• Özgür A., Johal W., Mondada F and Dillenbourg P. Haptic-Enabled Handheld Mobile Robots : Design and Analysis. <i>ACM CHI Conference on Human Factors in Computing Systems</i> (CHI), 2017.• Johal W., Vogt P, Kennedy J., De Haas M., Paiva A., Castellano G., Okita S., Tanaka F, Belpaeme T, Dillenbourg P. Workshop on Robots for Learning : R4L. <i>ACM/IEEE International Conference on Human-Robot Interaction</i> (HRI), 2017.• Özgür A., Johal W., Mondada F and Dillenbourg P. Windfield : Learning Wind Meteorology with Handheld Haptic Robots. <i>ACM/IEEE International Conference on Human-Robot Interaction</i> (HRI), 2017.• Özgür A., Johal W., Mondada F and Dillenbourg P. Windfield : Demonstrating Wind Meteorology with Handheld Haptic Robots. <i>ACM/IEEE International Conference on Human-Robot Interaction</i> (HRI), 2017.• Özgür A., Lemaignan S., Johal W., Mondada F et al.. Cellulo : Versatile Handheld Robots for Education. <i>ACM/IEEE International Conference on Human-Robot Interaction</i> (HRI), 2017. [Best Paper Award]	

- Adam C., **Johal W.**, Pellier D., Fiorino H. and Pesty S., Social Human-Robot Interaction : A New Cognitive and Affective Interaction-Oriented Architecture, *International Conference on Social Robotics (ICSR)*, 2016
- Özgür A., **Johal W.** and Dillenbourg P. Permanent Magnet-Assisted Omnidirectional Ball Drive. *International Conference on Intelligent Robots and Systems (IROS)*, 2016.
- **Johal W.**, Jacq A., Paiva A. and Dillenbourg P. Child-Robot Spatial Arrangement in a Learning by Teaching Activity. *25th IEEE International Symposium on Robot and Human Interactive Communication*. August 2016. New York City, USA.
- Ta V.C., **Johal W.**, Portaz M., Castelli E., Vaufreydaz D., The Grenoble system for the Social Touch Challenge at ICMI 2015. *International Conference on Multimodal Interaction*. (ICMI2015).
- **Johal W.**, Calvary G., Pesty S., Non-verbal Signals in HRI : Interference in Human Perception. *International Conference on Social Robotics*. (ICSR2015).
- **Johal W.**, Pellier D., Adam C., Fiorino H., Pesty S., A Cognitive and Affective Architecture for Social Human-Robot Interaction. HRI'15 Extended Abstracts. DOI=10.1145/2701973.2702006 [**Best Paper Award Finalist**]
- **Johal W.**, Robots Interacting with Style. HRI'15 Extended Abstracts. DOI=10.1145/2701973.2702706
- **Johal W.**, Calvary G., Pesty S., Toward Companion Robots Behaving with Style. In *Proceedings of the 2014 IEEE International Symposium on Robot and Human Interactive Communication (ROMAN)*. Edinburgh. 2014. doi: 10.1109/ROMAN.2014.6926393
- **Johal W.**, Adam C., Fiorino H., Pesty S., Duhaut D.. Acceptability of a companion robot for children in daily life situations *5th IEEE Conference on Cognitive InfoCommunications*. (CogInfoCom) Nov 2014. Vietri, Italy. doi: 10.1109/CogInfoCom.2014.7020474
- **Johal W.**, Calvary G. and Pesty S.. A Robot with Style because you are Worth it!. In *CHI '14 Extended Abstracts on Human Factors in Computing Systems (CHI EA '14)*. Toronto, Canada. DOI=10.1145/2559206.2581229
- **Johal W.**, Dugdale J., Pesty S.. Modelling interactions in a mixed agent world. In *Proceeding of 25th European Modeling and Simulation Symposium (EMSS)*. Athens, Greece, 23-25 Sept 2013
- **Benkaouar (Johal) W.**, Vaufreydaz D.. Multi-sensors engagement detection with a robot companion in a home environment. *Workshop on Assistance and Service Robotics in a Human Environment at IEEE International Conference on Intelligent Robots and Systems (IROS2012)*, Vilamoura, Algarve - Portugal, oct 2012.

FRENCH CONFERENCE PUBLICATIONS

- Jacq A., **Johal W.** and Dillenbourg P. Non-recursive Approach for Mutual Understanding.. *Journée de travail sur la robotique interactive et cognitive*. Avril. 2016. Toulouse, France
- **Johal W.**, Pesty S., Calvary G., Des Styles pour une Personnalisation de l'Interaction Homme-Robot. *Journées Nationales de la Robotique Interactive (JNRI)*. Nov. 2014. Toulouse, France
- **Johal W.**, Pesty S. Calvary G., Les Styles pour la Plasticité des Robots Compagnons. *Workshop Affect, Compagnon Artificiel, Interaction (WACAI)* 2014. Rouen, France
- Adam C., **Johal W.**, Ben-Farhat I., Jost C., Fiorono H., Pesty S. , Duhaut D.. Acceptabilité d'un robot compagnon dans des situations de la vie quotidienne. *Deuxième conférence III - Intercompréhension de l'intraspécifique à l'interspécifique*. Lorient, 30 Sept - 1Oct 2013

OTHER PUBLICATIONS

- Jacq A., **Johal W.**, Dillenbourg P. and Paiva A.. Cognitive Architecture for Mutual Modelling. *Workshop on Cognitive Architectures for Social HRI (HRI'16)*. Christchurch, New Zealand. 2016
- **Johal W.**, Pesty S., Calvary G.. Expressing Parenting Styles with Companion Robots. *Workshop on Applications for Emotional Robots at Human-Robot Interaction conference (HRI'14)* . Bielefeld. 2014

INTERN AND PHD TUTORING

Thibault Asselborn, EDRS PhD Student EPFL, Adaptive Learning in CRI. Summer 2016 - ..

Elmira Yadollahi, EDRS PhD Student EPFL/IST Lisbon, CoReader - CRI for Reading. Fall 2016 - ..

Ayberk Ozgur, IC PhD Student EPFL, Cellulo - Haptic Swarm Robots for Education. Fall 2015 - ...

Alexis Jacq, EDRS PhD Student EPFL/IST Lisbon, Mutual-Modeling for CRI. Fall 2015 - ..

Jérémy Lascaux, CS Under-Grad. Student, IUT2- UPMF. Developing an Affective Math Game with Nao Robot. Spring 2014.

Anshul Singh Parihar, Electrical Engineering, IIT Jodhpur, India Agent-Based Simulation of Human-Robot Interaction for Experiment Design. Spring 2014.

TEACHING

École Polytechnique Fédérale de Lausanne, Switzerland

October 2015 - ...

- Visual Computing :
- Vision & Graphics, AR-game project using processing and various computer vision techniques.

Grenoble Institute of Technology, France

Teaching Assistant

October 2012 - July 2014

- Instructor for ACVL : Software's Analysis, Conception and Validation.
 - Methods for Requirement Analysis
 - Software Design Patterns
 - UML Diagrams and Object Constraint Language
- Instructor for Introduction to Programming
 - OCaml and Python
 - Beginning of complexity analysis

Pierre Mendès-France University, Grenoble, France

October 2013- January 2014

- Instructor for INF f-1 : Undergraduate Beginner Programming, Lectures & Practical Sessions

Joseph Fourier University, Grenoble, France

October 2011- January 2012

- Instructor for Biology Undergraduates : C2i, Burautic, Basic HTML, Lectures & Practical Sessions

ACADEMIC
SERVICES

Conferences & Events

- Guest Editor Special Issue for the International Journal of Social Robotics - Springer, on "[Robots for Learning](#)".
- Organization Committee, "Workshop on Robots for Learning" @HRI 2017, [R4L@HRI](#). Vienna, Austria - March 6, 2017.
- Organization Committee, "Workshop on Robots for Learning" @RoMan 2016, [R4L](#). New York, USA - August 27, 2016.
- Session Chair on Implicit Human-Robot Communication, [RO-MAN 2016](#). New York, USA - August 29, 2016.
- International Program Committee, International Conference on Social Robotics, [ICSR 2016](#). Kansas City, USA - November 1-3, 2016.
- Member of Organization Committee, "Workshop on Social Robots in Education" , [@NewFriends 2016](#). Barcelona, Spain - November 2, 2016.
- Member of Organization Committee, "Workshop Affect, Compagnon Artificiel, Interaction" , [WACAI 2012](#). Grenoble, France - 15 & 16 November 2012.
- Member of Organization Committee, [PersyCup Robotic Challenge](#). Grenoble, France - 21 Mai 2015.

Reviewer for :

- ◇ *International Journal of Human-Robot Interaction*, 2016
- ◇ *International Journal of Social Robotics*, 2016
- ◇ *IEEE Robotics and Automation Magazine (IEEE-RAM)*, 2016
- ◇ *Journal of Cognitive Systems Research*, 2016
- ◇ *Journal on Interaction Studies*, 2016
- ◇ *Transaction on Learning Technologies*, 2017
- *ACM CHI Conference on Human Factors in Computing Systems (CHI)*, 2017
- *ACM Conference on Computer-Supported Cooperative Work and Social Computing (CSCW)*, 2017
- *International Conference on Social Robotics (ICSR)*, 2015, 2016
- *International Conference on Human Robot Interaction (HRI)*, 2015, 2016, 2017
- *IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN)*, 2014, 2015, 2016

LANGUAGE

- French : Mother tongue
- English : Fluent - TOEFL, 1 year in USA, Masters taught in English

REFERENCES
AVAILABLE TO
CONTACT

Prof. Pierre Dillenbourg (e-mail : pierre.dillenbourg@epfl.ch) - EPFL

- ◇ Head of [Computer Human Interaction for Learning and Instruction Lab](#). *I work with Pr. Dillenbourg on the CoWriter and Cellulo projects.*

Prof. Francesco Mondada (e-mail : francesco.mondada@epfl.ch) - EPFL

- ◇ Head of [MOBOTS Group](#), [LSRO-Lab](#). *I work with Pr. Mondada on the Cellulo project.*

Prof. Sylvie Pesty (e-mail : Sylvie.Pesty@imag.fr) - [University Institute of Technology \(IUT2-UPMF\)](#),

- ◇ Member of [MAGMA Team](#), [LIG-Lab](#). *Prof. Pesty is my supervisor for my PhD.*

Prof. Gaëlle Calvary (e-mail : Gaelle.Calvary@imag.fr) - [ENSIMAG Grenoble Institute of Technology](#),

- ◇ Member of [Engineering of Computer Human Interaction Team](#), [LIG-Lab](#). *Prof. Calvary is my co-supervisor for my PhD.*

Dr. Dominique Vaufreydaz (e-mail : Dominique.Vaufreydaz@inria.fr) - [University Pierre Mendès-France](#)

- ◇ Member of [PRIMA Team](#), [INRIA](#) & [LIG-Lab](#). *Prof. Vaufreydaz was my supervisor during my Masters.*

MORE
INFORMATION

More information and auxiliary documents can be found at
<http://wafa.johal.fr/>.