# Dr. Wafa JOHAL ARC DECRA Fellow 2021 -2024

### Lecturer (Assistant Professor), University of New South Wales

@ wafa.johal@unsw.edu.au WWW: wafa.johal.org

© orcid.org/0000-0001-9118-0454  $\mathfrak{T}$  Wafa Johal  $R^G$  Wafa Johal

School of Computer Science and Engineering, Faculty of Engineering, UNSW, Sydney





#### EDUCATION

#### September 2012 - Ph.D in Applied Mathematics and Computer Sciences

30 October 2015 University of Grenoble Alps, Laboratory of Informatics of Grenoble - MAGMA Team France

- > Thesis Topic: Behavioral Styles for Human-Robot Interaction: Towards Plasticity in HRI
- > Advisers : Prof. Sylvie Pesty & Prof. Gaëlle Calvary

#### June 2012 M.S., Computer Sciences: Graphics, Vision & Robotics

University Joseph Fourier, Grenoble, France

- > Thesis Topic : Multi-modal detection of intention of interaction by a companion robot
- > Adviser : Dr. Dominique Vaufreydaz

# June 2010 B.S. B.A. Mathematics and Informatics applied to Cognitive Sciences Pierre-Mendès France University,

Grenoble, France Exchange Student for one year in Washington College, MA (U.S.A.), August 2009 - May 2010

#### Other Trainings

October 2017 Applied Machine Learning Days, EPFL, Lausanne, Switzerland.

August 2013 Social Human-Robot Interaction Summer School, Cambridge, UK.



#### ACADEMIC EMPLOYMENT

# August 2019 | Lecturer (Assistant Professor) in Intelligent and Autonomous Systems, University of New South Wales, Sydney, Australia

... | School of Computer Science and Engineering

[Human-Robot Interaction] [Robots in Education] [Tangible Robots] [Cognitive Models for HRI] [Multi-Modal Interaction]

#### August 2019 October 2015

#### Postdoctoral Scientist for NCCR Robotics, EPFL, Switzerland

Computer Human Interaction for Learning and Instruction Lab (Pr. Pierre Dillenbourg), Mobile Robots Group - LSRO (Pr. Francesco Mondada)

- > In charge of the robotics research projects at the CHILI Lab: Cellulo, CoWriter and Animatas
- > Co-supervising 6 PhD students.

Human-Robot Interaction Robots in Education Tangible Robots Cognitive Models for HRI Multi-Modal Interaction



#### **TEACHING ACTIVITIES**

University of New South Wales, Australia

2019 - ...

School of Computer Science and Engineering

- > Lecturer: Robotics Vision COMP3431 (1L)
- > Lecturer: Human-Robot Interaction COMP3431 (1L)
- > Lecturer: Image Formation, Image Processing and Feature Extraction COMP9517 (5L)
- > Lecturer : Memory, visual Design and Evaluation for HCI COMP9511/COMP3511 (3L)
- > Lecturer: Data Acquisition and Data Visualisation in HCI COMP9511/COMP3511 (1L)

Faculty of Art and Design, Guest Lecturer: Robots for Education

#### École Polytechnique Fédérale de Lausanne, Switzerland

October 2015 - Now

- > Visual Computing: Vision & Graphics, AR-game project using processing and various computer vision techniques.
- > Practical on Tangible Swarm Interaction, Master in Robotics

#### Grenoble Institute of Technology, France

October 2012 - July 2014

- > Instructor for ACVL : Software's Analysis, Conception and Validation.
- > Instructor for Introduction to Programming

Pierre Mendès-France University, Grenoble, France

October 2013- January 2014

# RESEARCH PROJECTS

**DECRA FELLOWSHIP** 

2021 - 2024

Proposal author, PI

This project is funded by the ARC. The goal of the project is to investigate novel interaction methods to allow novices to teach robots basic tasks for at home deployment.

350k AUD 3 Years Project

DEC. 2019 - DEC. 2022 **IRECHECK** 

Proposal co-author, International Partner

The IReCheck project, is funded by the Swiss NSF and the French ANR. The goal of the project is to investigate social and task adaptation in a Learning by Teaching task with Typically Developed children and children with Neuro-Developmental Disorders.

CHILI EPFL 490k CHF 3 Years Project

**COWRITING KAZAKH** 

OCT. 2018 - TODAY

Principal Coordinator, Proposal co-author

Hala Khodr

The Cowriter Kazakh project, is a SNSF project that seeds for collaboration between Kazakhs and Swiss researchers. In this project we will deploy the Cowriter robotic system to help

the transition from Cyrillic to Roman alphabet in Kazakhstan. CHILI EPFL 10k CHF 2 Years Project Nazarbayev University

**ANIMATAS** 

FEB. 2018 - TODAY

Proposal co-author, International Partner The Animatas project, is a EU MSCA ITN ETN that aims to explore the use of virtual agents in educational context.

CHILI EPFL 759k CHF 3 Years Project 3 PhD Students

**CELLULO** 2015 - 2019

Project manager, Proposal co-author The Cellulo project, funded by the NCCR Robotics (Swiss NSF), aims to design and propose new use of tangible swarm robots in education.

CHILI/MOBOTS EPFL 1Mo CHF 4 Years 2 PhD + 1 Postdoc

ROBOTS FOR LEARNING

2015 - TODAY

Project manager, Proposal co-author I launched in Fall 2015 the Robots for Learning initiative that aims to create a research community on interactions aspect of using robots for learners. We organized several workshop and training events funded by the NCCR Robotics

CHILI/MOBOTS EPFL 18.5k CHF

FIND YOUR VOICE!

SEPT. 2018 - TODAY

Local Coordinator, Proposal co-author

The project aims to help children who struggle to find their voice in social situations, by training them on joke telling using platform such as Alexa or Google Home. It is a project funded by the SRCD that seeds for cross-country and cross discipline collaboration between researchers.

CHILI EPFL 15k CHF Partners : UCLIC University of Sussex UC Irvine

#### SUPERVISION OF JUNIOR RESEARCHERS

Research Intern, CSE UNSW, Oltan Sevinc Social Navigation in Home Environment Jan. 2021 - ... Yu (Carson) Liu Speech-Driven Gesture Generation for Robots MPhil, CSE UNSW, Sep. 2020 - ... Michael O'Dea Research Intern, CSE UNSW, CoReader - Adaptive Reading Companion Jan. 2020 - Mai 2020 CoPainter - detect and remediate for dysgraphia through drawings Pawel Golinski Master Thesis, IC EPFL,

Jan. 2019 - June 2019

EDRS PhD Student EPFL, Learner Swarm Interaction. Dec. 2018 - now

Master Thesis, STI EPFL, Social and Task Engagement in a Multi-party Collaborative Learning Laila El Hammasy Oct. 2018 - February 2019)

Sina Shahmoradi EDRS PhD Student EPFL, ANIMATAS - Orchestration of Robot Populated Classrooms. Sep. 2018 - July 2019

Utku Norman EDIC PhD Student EPFL, ANIMATAS - Mutual Modelling for Mutual Understanding. Sep. 2018 -July 2019

Jauwairia Nasir EDRS PhD Student EPFL, ANIMATAS - Assessment of Multiparty engagement in Learning task.

Sep. 2018 - July 2019

Florian Zimmerman Master Thesis, IC EPFL, Multi-modal Data Capture and Annotation Feb. 2018 - Jul. 2018 Arzu Guneysu EDRS PhD Student EPFL, Cellulo - Upper-arm Gamified Rehabilitation with Tangible Robots.

Mar. 2017 - July 2019

Sonia Anderson Barbeau Bachelor Thesis in Swiss Pedagogical University (HEP) Vaud, Le robot Cellulo comme

> instrument de régulation des conceptions erronées en lien avec l'apprentissage de la symétrie axiale au primaire. Nov. 2016 - June 2017

Thibault Asselborn EDRS PhD Student EPFL, CoWriter - Adaptive Learning in Child-Robot Interaction. Jun. 2016 -

Nov. 2016 - 2020 Elmira Yadollahi EDRS PhD Student EPFL, CoReader - CRI for Reading. Dr. Ayberk Ozgur EDIC PhD Student EPFL, Cellulo - Haptic Swarm Robots for Education. October 2015 -

December 2017

EDRS PhD Student EPFL, CoWRiter Mutual-Modeling for Child-Robot Interaction. Alexis Jacq October

2015 - July 2018

# Institutional Responsibilities

- > Early Career Academic Representative at the Faculty of Engineering Board Meeting
- > School of CSE's Early Career Academic Representative at Eng. ECAN
- > AI-Seminar Series, @UNSW, fortnightly talks around AI research in a broad sense. AI-Seminar Website. 2020-...

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#### ACADEMIC DUTIES AND ACTIVE MEMBERSHIPS IN SCIENTIFIC SOCIETIES

#### Edition

- ♦ Associate Editor
  - > IEEE Robotics and Automation Letters (RA-L) Human-Robot Interaction
- ⋄ Editor Special Issue
  - > Frontiers Robotics and Al, on "Robots for Learning" 2020-2021.
  - > International Journal of Social Robotics Springer, on "Robots for Learning", June 2018.
- ♦ Publication co-Chair for the 8<sup>th</sup> ACM International Conference on Human-Agent Interaction (HAI 2020)
- ⋄ Program Committee
  - > IEEE International Conference on Robot and Human Interactive Communication, RO-MAN 2018, 2019, 2020.
  - > ACM Interaction Design and Children (IDC) Conference, IDC 2018.
  - > International Conference on Human Robot Interaction, HRI 2018, HRI 2019, HRI 2020.
  - > International Conference on Social Robotics, ICSR 2016, ICSR 2020.
  - > Workshop on Behavior, Emotion and Representation: Building Blocks of Interaction at International Conference on Human-Agent Interaction, October 2017.

#### Reviewer for:

#### Funding Agencies or Other Institutions

- o Dutch Research Council (NWO), Reviewer for Research Proposal, March 2020
- o TA-Swiss, Social and Empathetic Robots Expert Panelist at Bern, September 2018
- o ERA.Net RUS PLUS FP7, Robotics Expert Panelist at the S&T Council, October 2017

#### Journals

- ♦ Frontiers in Robotics and Al, 2019, 2020
- ♦ International Journal of Human-Robot Interaction, 2016, 2017, 2018, 2019
- International Journal of Social Robotics, 2016, 2017, 2018
- ♦ IEEE Robotics and Automation Magazine (IEEE-RAM), 2016
- ♦ Journal of Cognitive Systems Research, 2016
- ♦ Journal on Interaction Studies, 2016
- ⋄ Transaction on Learning Technologies, 2017
- ♦ International Journal of Child-Computer Interaction, 2017

#### Conferences

- > ACM International Conference on Tangible, Embedded, and Embodied Interaction (TEI), 2020
- > RAS IEEE International Conference on Robotics and Automation (ICRA), 2020
- > ACM SIG Interaction Design and Children Conference (IDC), 2018
- > ACM CHI Conference on Human Factors in Computing Systems (CHI), 2017
- > ACM Conference on Computer-Supported Cooperative Work and Social Computing (CSCW), 2017, 2018
- > Springer International Conference on Social Robotics (ICSR), 2015, 2016, 2018, 2020
- > ACM-SIG/IEEE International Conference on Human Robot Interaction (HRI), 2015, 2016, 2017, 2018, 2019
- > IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN), 2014, 2015, 2016, 2018, 2019,

# ORGANIZATIONAL DUTIES

- > "Workshop on Robots for Learning Building Robots for Classroom Context" @RoMan 2019, R4L@HRI2019. New Delhi, India October 14, 2019.
- > "Workshop on Robots for Learning Adaptive Learning" @HRI 2019, R4L@HRI2019. Daegu, South Korea March 11, 2019.
- > Winter School on "Developing Technologies in Educational Settings", 2. EPFL, Switzerland Feb 4-8, 2019.
- > "Workshop on the Near Future of Child Robot Interaction" @IDC 2018, CRI@IDC. Trondheim, Norway June 20, 2018.
- > "Workshop on Robots for Learning Inclusive Learning" @HRI 2018, R4L@HRI2018. Chicago, IL USA March 5, 2018.
- > "Workshop on Robots for Learning" @HRI 2017, R4L@HRI. Vienna, Austria March 6, 2017.
- > "Workshop on Robots for Learning" @RoMan 2016, R4L. New York, USA August 27, 2016.
- > "Workshop on Social Robots in Education", @NewFriends 2016. Barcelona, Spain November 2, 2016.
- > "Workshop Affect, Compagnon Artificiel, Interaction", WACAI 2012. Grenoble, France 15 & 16 November 2012.
- > PersyCup Robotic Challenge. Grenoble, France 21 Mai 2015.

# Invited Talks

- > Social (Flying) Robots for Education. EduDrone Conference. September 2020.
- > Orchestration of robot-populated classrooms. UC Sand Diego, California, USA. November 2019.
- > Robots in Education. Swiss Technology Assessment Foundation. Focus group on Robotics. Bern Switzerland, May 2019.
- > From diagnosis to adaptive learning: CoWriter and Disgraphia. Applied Machine Learning Days, Lausanne Switzerland, January 2019.
- > Robots for Learning. University of Nazerbachev, Astana, Kazakhstan, January 2019.
- > Assistive Human-Robot Interaction: From Education to Re-Education. ETH Zurich, Switzerland Dec. 2018.
- > Teacher symposium on Computational Thinking, Entre-Deux-Lacs, HEPL, Yverdon-les-bains. Switzerland, Nov. 2018.
- > HRI 2019 Mini symposium, Stanford University, Palo Alto, CA, USA. Nov. 2018.
- > Tangible Human-Robot Interaction: From Learning to Re-Learning, BioX Lab Stanford, Palo Alto, CA, USA. Nov. 2018.
- > Enabling smooth and personalized user-robot interaction to enhance learning, University of New South Wales, Sydney, Australia. Nov. 2018.
- > Swarm Robotics Pushing the state of the art, Rome, Italy, Oct. 2018.
- > HRI 2018 Mini symposium, Cornell University, Ithaca, NY, USA. Nov. 2017.
- > The Classroom of Tomorrow Swarm Robots in Education, Swissnex Boston, USA, April 2016.
- > Non-verbal Communication in Human Robot Interaction, MIT Media Lab, Personal Robotics Group, April 2016.
- > Engagement & adaptation: How human-robot interaction can help in everyday life, Naver Labs Europe, December 2016.

# **P** AWARDS

- 2020 Best Demo Award for our paper CoWriting Kazakh Learning a New Script with a Robot Demonstration.
- 2019 Best Reviewer Award for the 27th International Conference on Computers in Education.
- 2018 Best Paper Award: Honorable Mention. *When Deictic Gestures in a Robot Can Harm Child-Robot Collaboration.* ACM Interaction Design and Children Conference (IDC 2018), Trondheim, Norway.
- 2017 Best Paper Award: ACM Human-robot Interaction Conference (HRI), Vienna, Austria.
- 2015 Winner of the Social Touch Challenge at International Conference on Multimodal Interaction (ICMI). Nov. 2015.
- 2015 Best Paper Award: Honorable Mention, ACM Human-robot Interaction Conference 2015 (HRI), Portland, USA.
- 2015 HRI Pioneers: International Conference on Human Robot Interaction 2015 (HRI), Portland, USA.

# **66** References

#### Pierre Dillenbourg

Professor IC, EPFL

@ pierre.dillenbourg@epfl.ch

+41 21 693 20 71

#### Dominique Vaufreydaz

A-Professor in CS, INRIA GRENOBLE

@ dominique.vaufreydaz@inria.fr

+33 4 76 61 55 19

#### Sylvie Pesty

Professor in CS, LIG LAB GRENOBLE

@ sylvie.pesty@imag.fr

+33 4 57 42 15 43





### OTHERS

1996-2010 Scout at Eclaireurs Eclaireuses de France (EEDF)
2004 Youth Worker Diploma (BAFA - Brevet d'Aptitude aux
Fonctions d'Animateur)

# **\*** Career Breaks

Feb. 2017 - May 2017. Maternity leave after the birth of my son, Lausanne, Switzerland.