## Foundations Statistics

## Wafaa Mohammed

## Exercise 4.2. [MAP estimation for 1D Gaussians]

(Source: Jaakkola.) Consider samples  $x_1, ..., x_n$  from a Gaussian random variable with known variance  $\sigma^2$  and unknown mean  $\mu$ . We further assume a prior distribution (also Gaussian) over the mean,  $\mu \sim \mathcal{N}(m, s_2)$ , with fixed mean m and fixed variance  $s^2$ . Thus the only unknown is  $\mu$ .

- a. Calculate the MAP estimate  $\hat{\mu}_{MAP}$ . You can state the result without proof. Alternatively, with a lot more work, you can compute derivatives of the log posterior, set to zero and solve.
- b. Show that as the number of samples n increase, the MAP estimate converges to the maximum likelihood estimate.
- c. Suppose n is small and fixed. What does the MAP estimator converge to if we increase the prior variance  $s^2$ ?
- d. Suppose n is small and fixed. What does the MAP estimator converge to if we decrease the prior variance  $s^2$ ?

Solution. a.

$$\hat{\mu}_{MAP} = \frac{n\bar{x}}{n + \frac{\sigma^2}{s^2}} + \frac{\frac{\sigma^2}{s^2}m}{n + \frac{\sigma^2}{s^2}}$$

where  $\bar{x} = \sum_{i=1}^{n} x_i$ .

b.

The maximum likelihood estimate of the mean is the empirical mean  $\hat{\mu}_{MLE} = \bar{x}$ . As  $n \to \infty$ , the fixed ratio  $\frac{\sigma^2}{s^2}$  becomes negligible compared to it. Thus,

$$\hat{\mu}_{MAP} = \frac{n\bar{x}}{n} + 0 = \bar{x}$$

C.

As  $s^2 \to \infty$ , the ratio  $\frac{\sigma^2}{s^2}$  converges to zero. Thus,

$$\hat{\mu}_{MAP} = \frac{n\bar{x}}{n+0} + \frac{0}{n} = \bar{x}$$

The intuition behind this is that when the prior variance increases, the prior becomes flat (uninformative), and the posterior is dominated by the likelihood.

d.

As  $s^2 \to 0$ , the small value of n will be negligible compared to it. Thus,

$$\hat{\mu}_{MAP} = 0 + \frac{\frac{\sigma^2}{s^2}m}{\frac{\sigma^2}{s^2}} = m$$

The intuition behind this is that when the prior variance decreases, the prior places almost all its weight at  $\mu = m$ , so the posterior will be dominated by the prior.