

Transformation of Random Variable

M.Wahaj Tahir
F191014@cfed.nu.edu.pk
wahajt@acm.org

May 2022



**National University of Computer
and Emerging Sciences**

To my mother who keeps on believing in me.

Contents

1	Abstract	4
2	Introduction	5
2.1	What is Transformation?	5
2.2	Methodology	5
2.3	Non-monotonic Functions	7
3	Application of Random Variable	8
4	References	9

1 Abstract

We consider transformations of random variables and derive the c.d.f. and density functions of the transformed random variables. A leading example is the probability integral transform, which transforms a random variable into a uniform random variable. A random variable is a numerical description of the outcome of a statistical experiment. It can be discrete or continuous depending upon the outcome of experiment. Often we are required to generate new distribution or density function with closed forms from a given distribution. Programmatically, it might be easy, but sometimes looking beyond just numbers is required to obtain specific parameters for new distributions such as mean, standard deviation, moment generating functions, etc. Hence, knowing the methodology of generating new distribution by the transformation of a random variable is significant. In this article, we will look at the transformation of a random variable to create a new distribution from a continuous distribution given the transformation function.

2 Introduction

2.1 What is Transformation?

Method of transformations (inverse mappings). Suppose we know the density function of x . Also suppose that the function $y = \phi(x)$ is differentiable and monotonic for values within its range for which the density $f(x) = 0$. This means that we can solve the equation $y = \phi(x)$ for x as a function of y .

2.2 Methodology

Consider a random variable X with a PDF and CDF given by $f_X(x)$ and $F_X(x)$, respectively. Define a new random variable Y such that $Y = g(X)$ for some function $g()$. What is the PDF, $f_Y(y)$ (or CDF), of the new random variable? This problem is often encountered in the study of systems where the PDF for the input random variable X is known and the PDF for the output random variable Y needs to be determined. In such a case, we say that the input random variable has undergone a transformation.

Monotonically Increasing Functions To begin our exploration of transformations of random variables, let's assume that the function is continuous, one-to-one, and monotonically increasing. A typical function of this form is illustrated in Figure 1. This assumption will be lifted later when we consider more general functions, but for now this simpler case applies. Under these assumptions, the inverse function, $X = g^{-1}(Y)$, exists and is well behaved. In order to obtain the PDF of Y , we first calculate the CDF. Recall that $F_Y(y) = Pr(Y \leq y)$. Since there is a one-to-one relationship between values of Y and their cor-

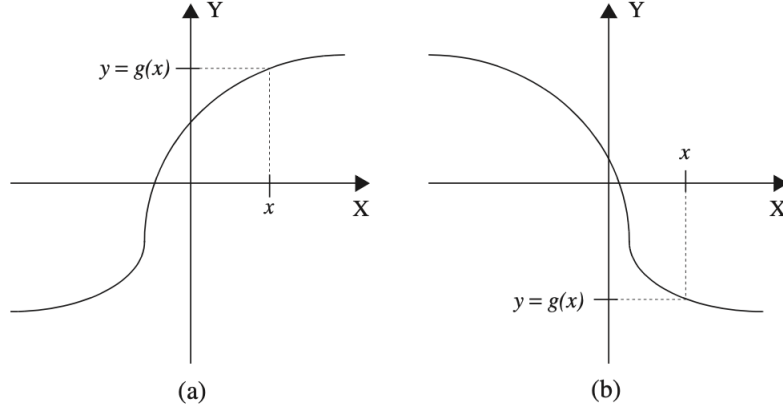


Figure 1: A monotonic increasing function (a) and a monotonic decreasing function (b).

responding values of X , this CDF can be written in terms of X according to

$$F_Y(y) = Pr(g(X) \leq y) = Pr(X \leq g^{-1}(y)) = F_X(g^{-1}(y)). \quad (1)$$

It can also be written as

$$F_X(x) = F_Y(g(x)) \quad (2)$$

Differentiating Equation 1 with respect to y produces

$$f_Y(y) = f_X(g^{-1}(y)) \frac{dg^{-1}(y)}{dy} = f_X(x) \frac{dx}{dy} \Big|_{x=g^{-1}(y)} \quad (3)$$

Differentiating Equation 2 with respect to x produces

$$f_X(x) = f_Y(g(x)) \frac{dy}{dx} \Rightarrow f_Y(y) = \frac{f_X(x)}{dy} \Big|_{x=g^{-1}(y)} \quad (4)$$

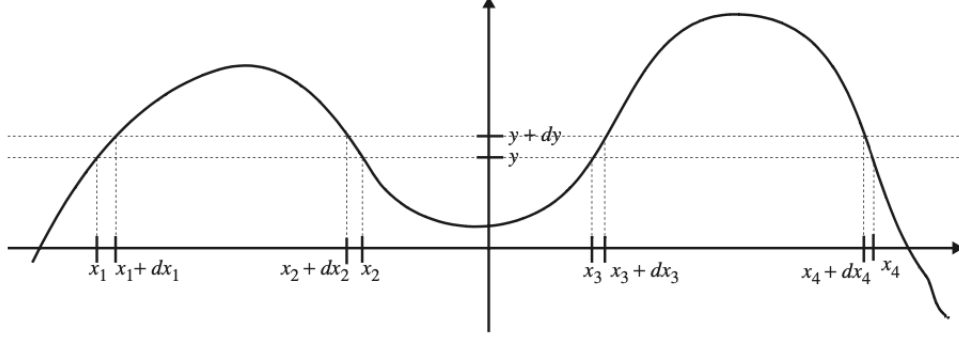


Figure 2: Non-monotonic Function

2.3 Non-monotonic Functions

Non-monotonic Functions Finally, we consider a general function that is not necessarily monotonic. Figure 2 illustrates one such example. In this case, we cannot associate the event $Y \leq y$ with events of the form $X \leq g^1(y)$ or $X \geq g^1(y)$ because the transformation is not monotonic. To avoid this problem, we calculate the PDF of Y directly, rather than first finding the CDF. Consider an event of the form $y \leq Y < y + dy$ for an infinitesimal dy . The probability of this event is $Pr(y \leq Y < y + dy) = f_Y(y)dy$. In order to relate the PDF of Y to the PDF of X , we relate the event $y \leq Y < y + dy$ to events involving the random variable X . Because the transformation is not monotonic, there may be several values of x that map to the same value of y . These are the roots of the equation $x = g^{-1}(y)$. Let us refer to these roots as x_1, x_2, \dots, x_N . Furthermore, let X^+ be the subset of these roots at which the function $g(x)$ has a positive slope, and similarly let X^- be the remaining roots for which the slope of the function is negative. This graphic represents the same property of Non-monotonic Functions.

3 Application of Random Variable

Probability plays a vital role in our life that we couldn't even predict, Simply I would say we can predict the future or moreover we can predict qiyammat (just a joke), By the probability, we can predict car accidents ratio in one month, Cancer detection, Earthquakes, Weather Conditions, Time of the body start decomposing and many more, Today's world is living in technology there are different domains of Computer Sciences where the probability plays its role are

1. Machine learning
2. Data Science
3. Artificial Intelligence
4. Simulation of system

4 References

My References [2] [3] [6] [4] [5] [1]

References

- [1] John M Chambers, Colin L Mallows, and BW4159820341 Stuck. A method for simulating stable random variables. *Journal of the american statistical association*, 71(354):340–344, 1976.
- [2] Zhao-Hui Lu, Chao-Huang Cai, and Yan-Gang Zhao. Structural reliability analysis including correlated random variables based on third-moment transformation. *Journal of Structural Engineering*, 143(8):04017067, 2017.
- [3] Ming-Na Tong, Yan-Gang Zhao, and Zhao-Hui Lu. Normal transformation for correlated random variables based on l-moments and its application in reliability engineering. *Reliability Engineering & System Safety*, 207:107334, 2021.
- [4] Yan-Gang Zhao, Ming-Na Tong, Zhao-Hui Lu, and Jun Xu. Monotonic expression of polynomial normal transformation based on the first four l-moments. *Journal of Engineering Mechanics*, 146(7):06020003, 2020.
- [5] Yan-Gang Zhao, Ye-Yao Weng, and Zhao-Hui Lu. An orthogonal normal transformation of correlated non-normal random variables for structural reliability. *Probabilistic Engineering Mechanics*, 64:103130, 2021.
- [6] Yan-Gang Zhao, Xuan-Yi Zhang, and Zhao-Hui Lu. Complete monotonic expression of the fourth-moment normal

transformation for structural reliability. *Computers & Structures*, 196:186–199, 2018.