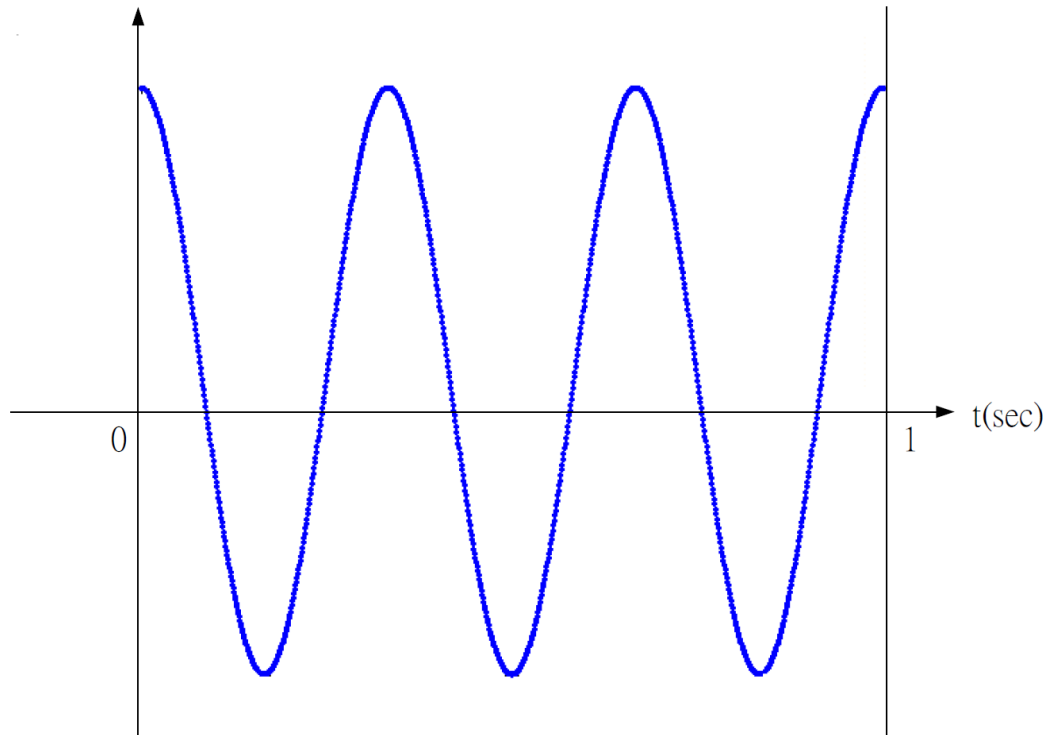


Modulation

Fourier Transform v.s. Communication (1/8)

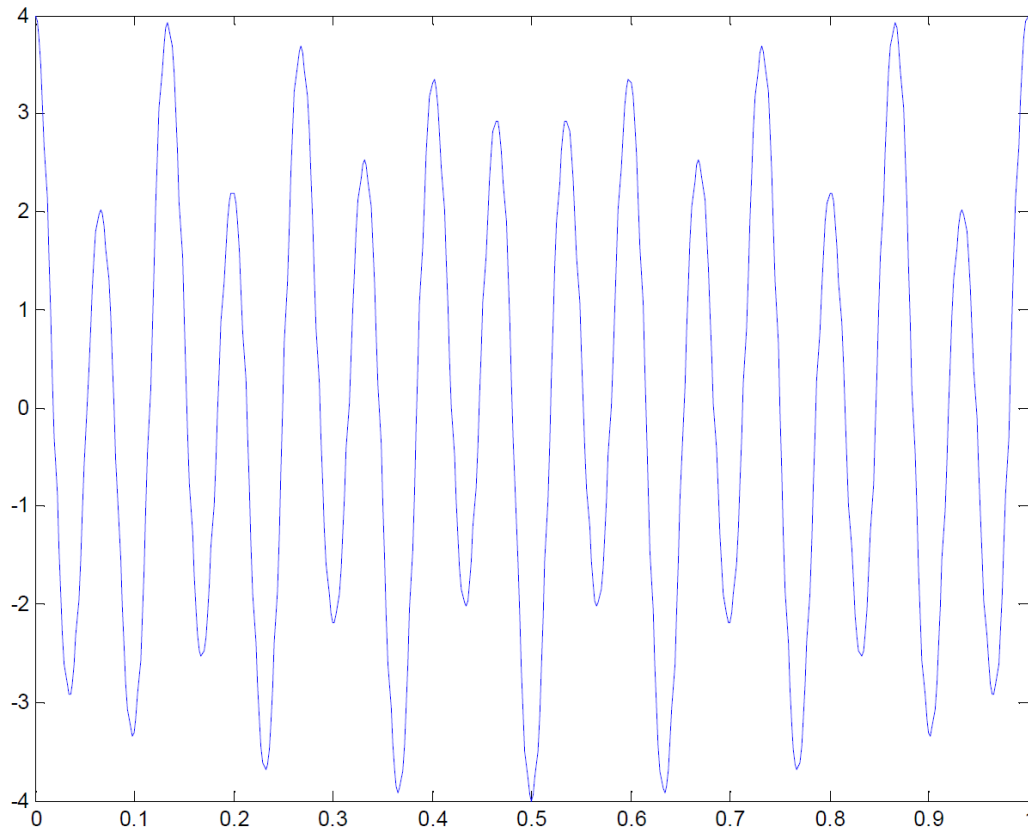
🌾 Look at the following signal, it's cosine with frequency 3



圖一. 頻率為 3 的 cosine 函數

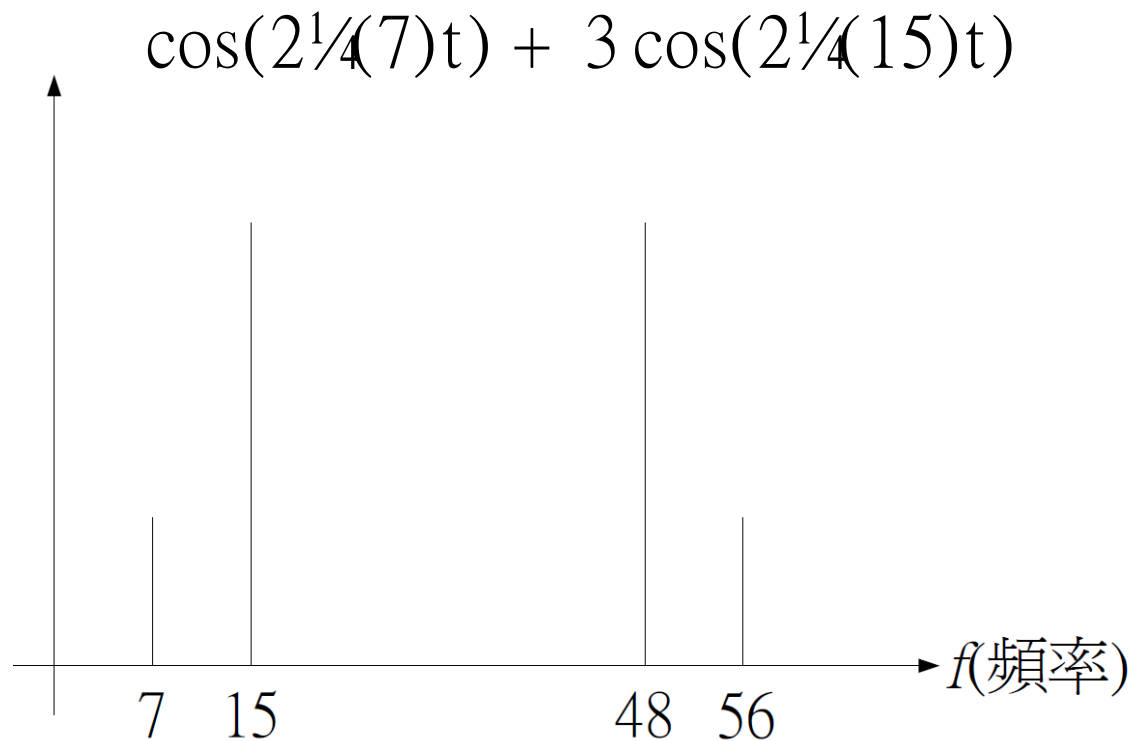
Fourier Transform v.s. Communication (2/8)

🌾 Now look at another signal, we have no idea what it is



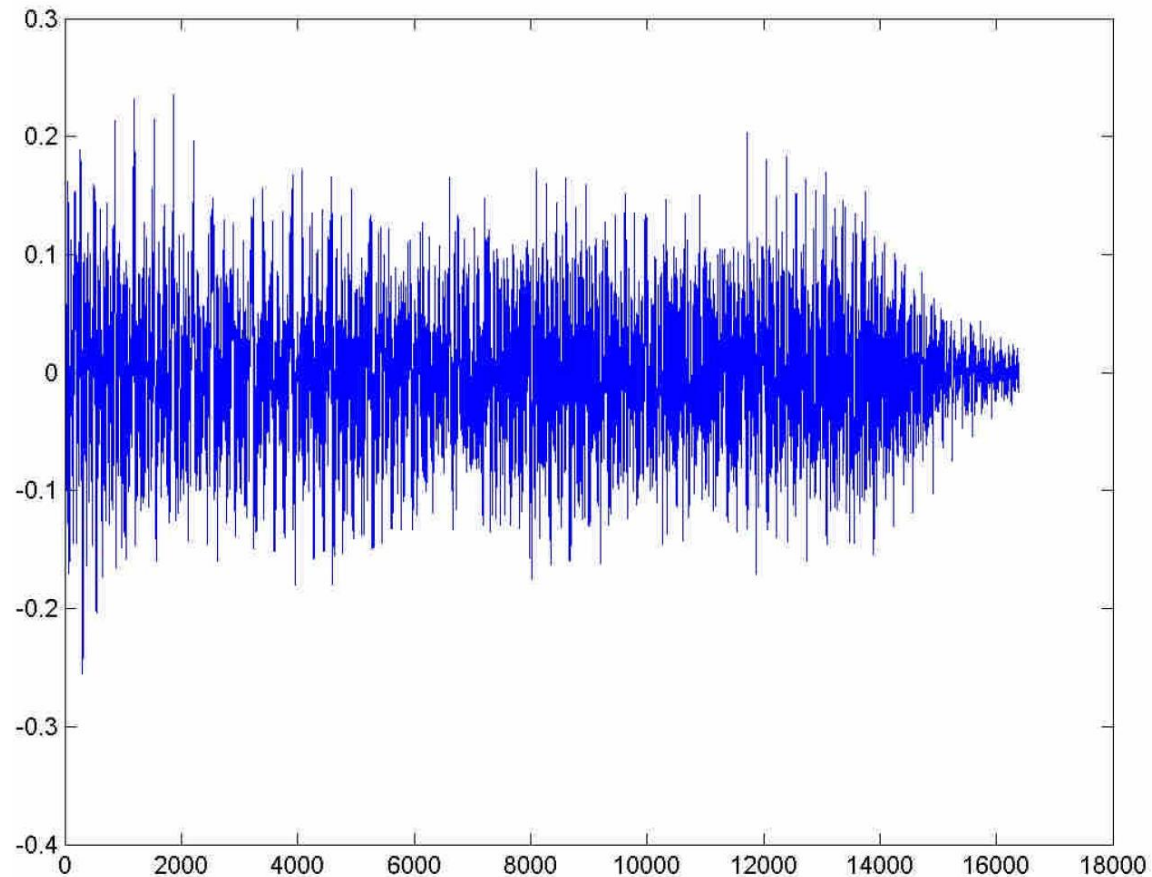
Fourier Transform v.s. Communication (3/8)

- ✿ Using Fourier transform to analyze the signal, we know that the signal is synthesized by two cosine functions



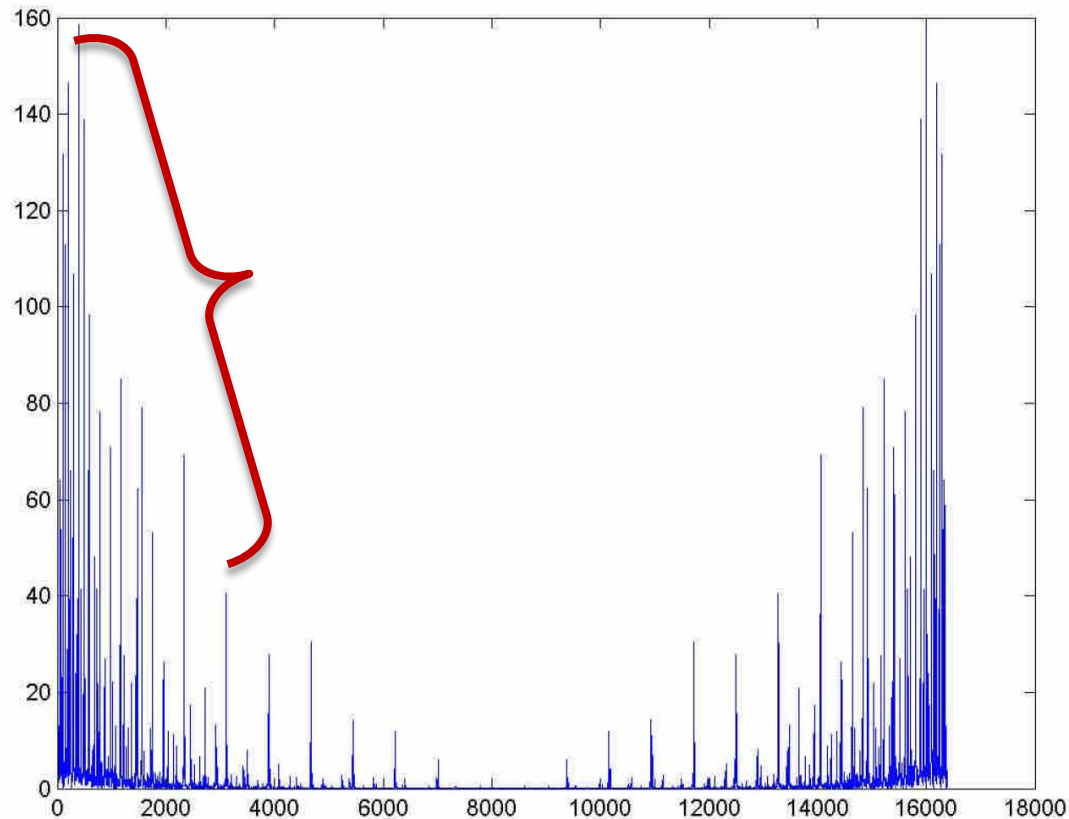
Fourier Transform v.s. Communication (4/8)

🌾 We further analyze 1-sec music signals, as below



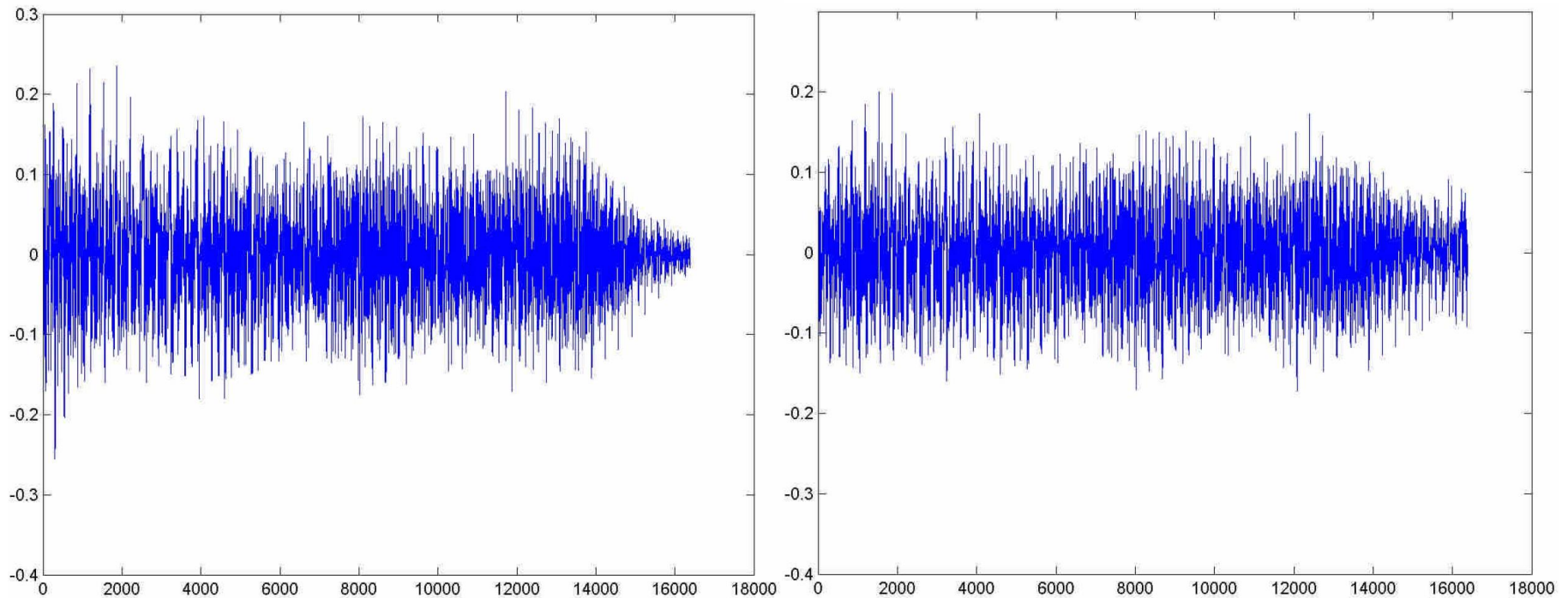
Fourier Transform v.s. Communication (5/8)

🌾 We analyze the signals through discrete Fourier transform, and found that the voice frequency is below 3000Hz



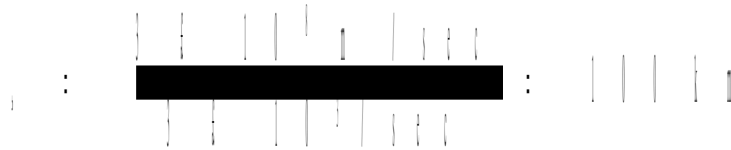
Fourier Transform v.s. Communication (6/8)

🌾 Using inverse Fourier transform to transform signals from frequency domain to time domain with and without filtering (amplitude < 10)



Fourier Transform v.s. Communication (7/8)

✿ We know $\lambda = \frac{v}{f}$, if we want to transmit below-3KHz voice signals, wave length is



✿ The antenna size would be half the wave length, and thus it's 50 km (too ridiculous)

✿ So we need MODULATION

✿ How to do that? Multiply with a cosine function

$$s(t) = m(t) \cos(2\pi f_c t)$$

Fourier Transform v.s. Communication (8/8)

🌾 Why the bandwidth is doubled to transit the modulated signals?

- Assume the original signal is $m(t) = \cos(2\pi f t)$
- The modulated signal is $s(t) = \cos(2\pi f t) \cos(2\pi f_c t)$

$$\cos(2\pi f t) \cos(2\pi f_c t) = \frac{1}{2} [(\cos(2\pi(f_c + f)t) + (\cos(2\pi(f_c - f)t))]$$

- The frequency is modified from f to $f+f_c$ and $f-f_c$

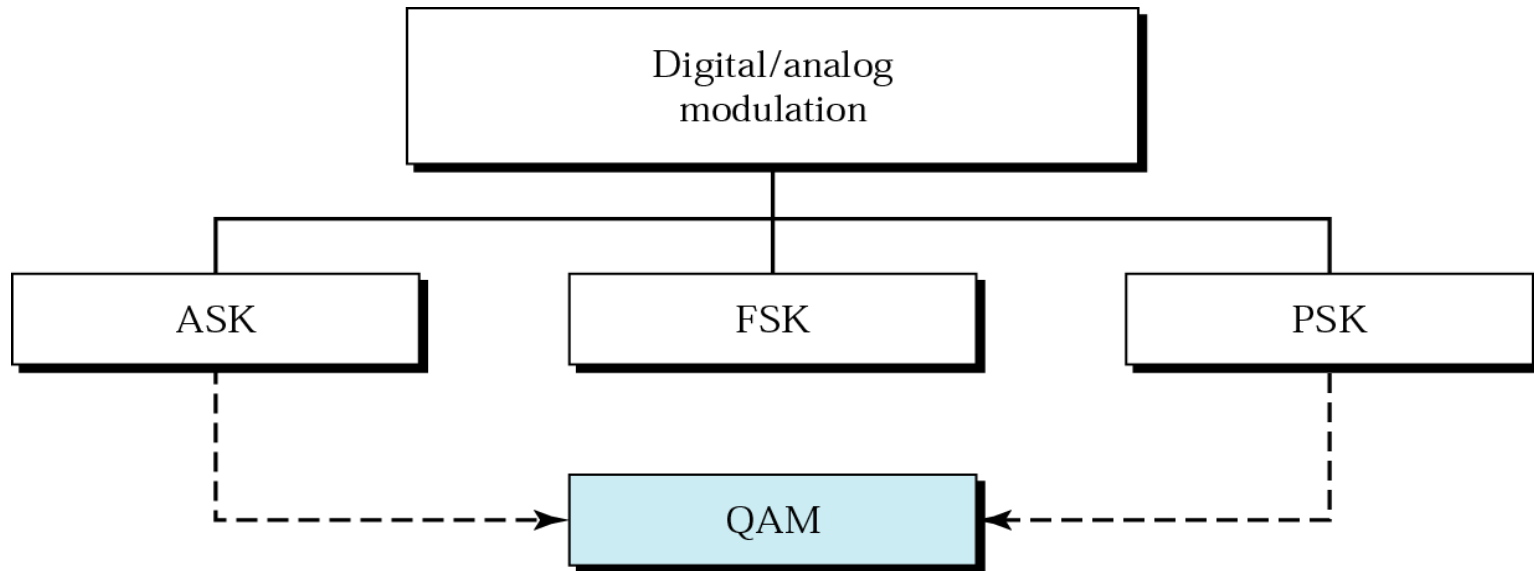
Modulation Techniques

🌾 Analog modulation

- AM, FM, PM

🌾 Digital modulation

- ASK, FSK, PSK, QPSK, QAM



AM (Amplitude Modulation) (1/2)

- ✿ The amplitude of a carrier signal with a constant frequency is as varied as the information signal
- ✿ The power of the transmitted wave varies in amplitude in accordance with the power of the modulating signal

✿ Mathematical representation

- **Carrier signal:** $A \cos(2\pi f_c t)$
- **Modulating signal:** $x(t)$
- **Modulated signal:**

$$s(t) = [A + x(t)] \cos(2\pi f_c t)$$

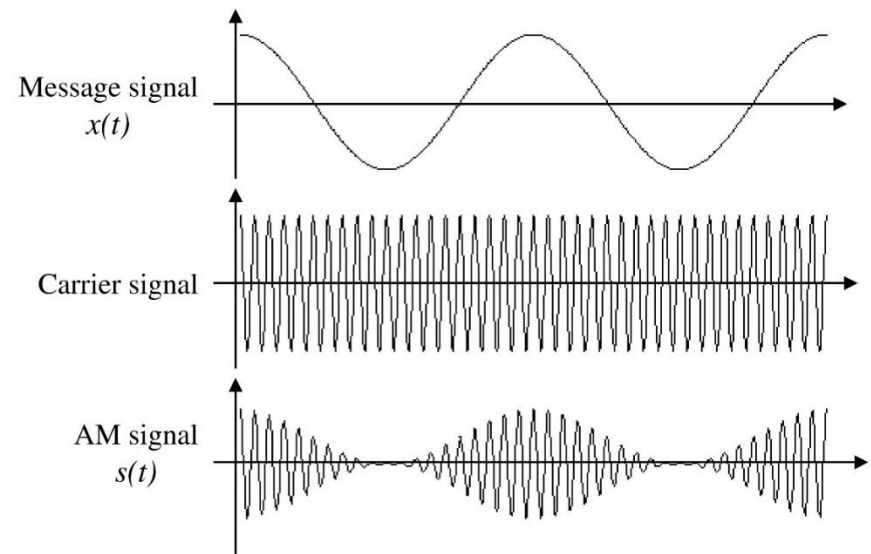


Figure 7.25 Amplitude modulation.

AM (Amplitude Modulation) (2/2)

- ✿ Bandwidth of an AM scheme is twice that of the modulating signal (double sideband nature)
- ✿ The receiver filters the carrier signal, and rebuild the information
- ✿ Since up to $1/3$ of the overall signal power is contained in the sidebands, and $2/3$ of the signal power is contained in the carrier, AM is an inefficient scheme

FM (Frequency Modulation) (1/2)

🌾 Modulated signal: $s(t) = A_c \cos(2\pi f_c t + 2\pi k_f \int_{-\infty}^t x(\tau) d\tau)$

- k_f : peak frequency deviation,
- Modulation index is defined as $\beta = \frac{k_f A_x}{f_m}$
- f_m : max used modulating frequency

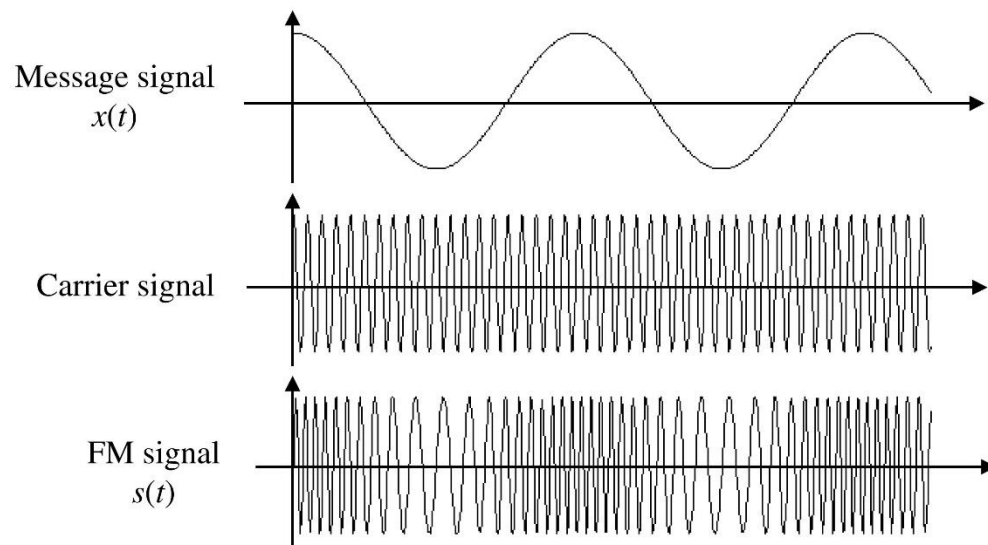


Figure 7.26 Frequency modulation.

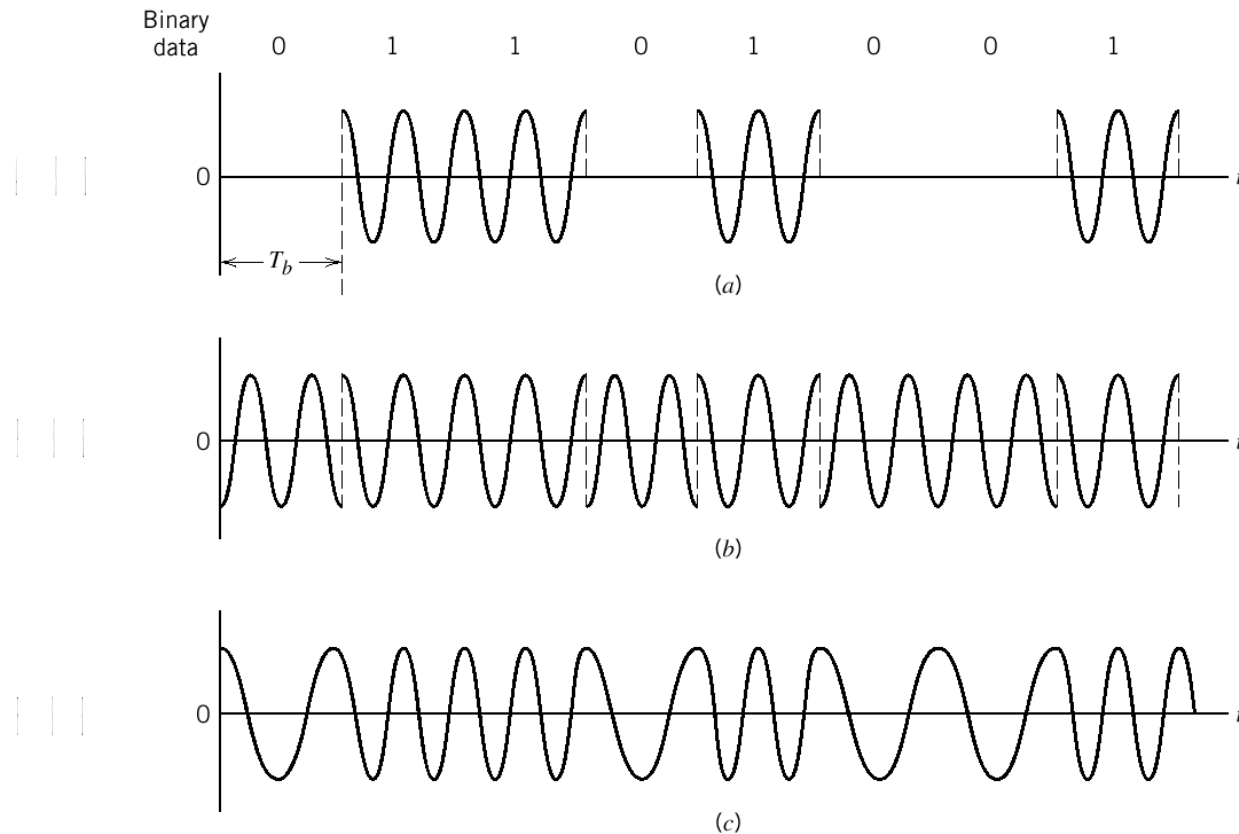
FM (Frequency Modulation) (2/2)

- The carrier frequency varies between the extremes of $f_c + \Delta f$ & $f_c - \Delta f$
- In FM, the total wave power does not change when the frequency alters
- To recover the signal, the receiver rebuilds the information wave by checking how the known carrier signal has modified the information
- An FM system provides a better SNR than an AM system
- Another advantage of FM is that it needs less radiated power
- However, it does require a larger bandwidth than AM
- The bandwidth of a FM signal may be determined using

$$BW = 2(\beta + 1)f_m$$

Digital Signal Modulation

🌿 Amplitude shift keying (ASK), frequency shift keying (FSK), phase shift keying (PSK)



Carrier signal: $\cos(2\pi f_c t)$

QPSK (Quadrature Phase Shift Keying)

- 🌾 BPSK: carrying 1 bit, and thus 0 or 1
- 🌾 QPSK: carrying 2 bits, and thus 00, 01, 10, or 11

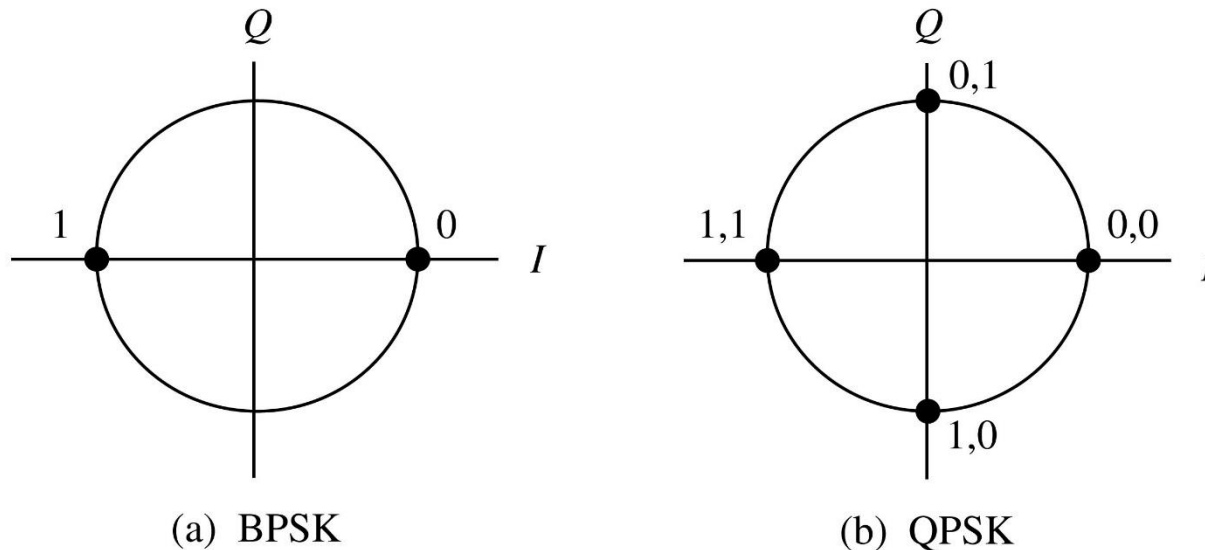


Figure 7.29 Signal constellations of BPSK and QPSK.

QAM (Quadrature Amplitude Modulation)

🌾 ASK+PSK

🌾 For example, a 16QAM uses 12 phases and 3 amplitudes to represent 4-bit symbol

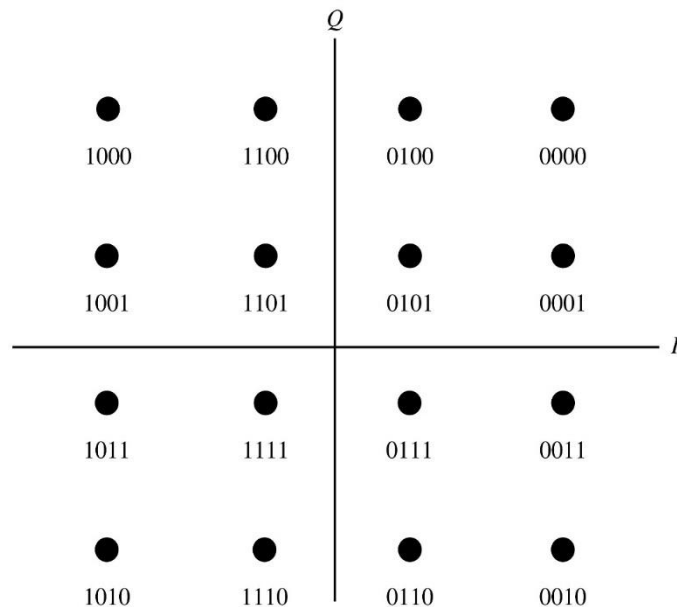


Figure 7.31 Rectangular constellation of 16QAM.

Table 7.2: ▶
A Representative
QAM Table

| Bit sequence represented | Amplitude | Phase shift |
|--------------------------|-----------|-------------|
| 000 | 1 | 0 |
| 001 | 2 | 0 |
| 010 | 1 | $\pi/2$ |
| 011 | 2 | $\pi/2$ |
| 100 | 1 | π |
| 101 | 2 | π |
| 110 | 1 | $3\pi/2$ |
| 111 | 2 | $3\pi/2$ |

MCS Mode Table of IEEE 802.11n & 11ac

MCS Index - 802.11n and 802.11ac

| | | | | | | | | | | | 802.11n | 802.11ac |
|--------------|---------------|-----------------|------------|--------|-----------------|-------|-----------------|-----|-----------------|-------|------------------|----------|
| HT MCS Index | VHT MCS Index | Spatial Streams | Modulation | Coding | 20MHz Data Rate | | 40MHz Data Rate | | 80MHz Data Rate | | 160MHz Data Rate | |
| | | | | | No SGI | SGI | No SGI | SGI | No SGI | SGI | No SGI | SGI |
| 0 | 0 | 1 | BPSK | 1/2 | 6.5 | 7.2 | 13.5 | 15 | 29.3 | 32.5 | 58.5 | 65 |
| 1 | 1 | 1 | QPSK | 1/2 | 13 | 14.4 | 27 | 30 | 58.5 | 65 | 117 | 130 |
| 2 | 2 | 1 | QPSK | 3/4 | 19.5 | 21.7 | 40.5 | 45 | 87.8 | 97.5 | 175.5 | 195 |
| 3 | 3 | 1 | 16-QAM | 1/2 | 26 | 28.9 | 54 | 60 | 117 | 130 | 234 | 260 |
| 4 | 4 | 1 | 16-QAM | 3/4 | 39 | 43.3 | 81 | 90 | 175.5 | 195 | 351 | 390 |
| 5 | 5 | 1 | 64-QAM | 2/3 | 52 | 57.8 | 108 | 120 | 234 | 260 | 468 | 520 |
| 6 | 6 | 1 | 64-QAM | 3/4 | 58.5 | 65 | 121.5 | 135 | 263.3 | 292.5 | 526.5 | 585 |
| 7 | 7 | 1 | 64-QAM | 5/6 | 65 | 72.2 | 135 | 150 | 292.5 | 325 | 585 | 650 |
| | 8 | 1 | 256-QAM | 3/4 | 78 | 86.7 | 162 | 180 | 351 | 390 | 702 | 780 |
| | 9 | 1 | 256-QAM | 5/6 | n/a | n/a | 180 | 200 | 390 | 433.3 | 780 | 866.7 |
| 8 | 0 | 2 | BPSK | 1/2 | 13 | 14.4 | 27 | 30 | 58.5 | 65 | 117 | 130 |
| 9 | 1 | 2 | QPSK | 1/2 | 26 | 28.9 | 54 | 60 | 117 | 130 | 234 | 260 |
| 10 | 2 | 2 | QPSK | 3/4 | 39 | 43.3 | 81 | 90 | 175.5 | 195 | 351 | 390 |
| 11 | 3 | 2 | 16-QAM | 1/2 | 52 | 57.8 | 108 | 120 | 234 | 260 | 468 | 520 |
| 12 | 4 | 2 | 16-QAM | 3/4 | 78 | 86.7 | 162 | 180 | 351 | 390 | 702 | 780 |
| 13 | 5 | 2 | 64-QAM | 2/3 | 104 | 115.6 | 216 | 240 | 468 | 520 | 936 | 1040 |
| 14 | 6 | 2 | 64-QAM | 3/4 | 117 | 130.3 | 243 | 270 | 526.5 | 585 | 1053 | 1170 |
| 15 | 7 | 2 | 64-QAM | 5/6 | 130 | 144.4 | 270 | 300 | 585 | 650 | 1170 | 1300 |
| | 8 | 2 | 256-QAM | 3/4 | 156 | 173.3 | 324 | 360 | 702 | 780 | 1404 | 1560 |
| | 9 | 2 | 256-QAM | 5/6 | n/a | n/a | 360 | 400 | 780 | 866.7 | 1560 | 1733.3 |
| 16 | 0 | 3 | BPSK | 1/2 | 19.5 | 21.7 | 40.5 | 45 | 87.8 | 97.5 | 175.5 | 195 |
| 17 | 1 | 3 | QPSK | 1/2 | 39 | 43.3 | 81 | 90 | 175.5 | 195 | 351 | 390 |
| 18 | 2 | 3 | QPSK | 3/4 | 58.5 | 65 | 121.5 | 135 | 263.3 | 292.5 | 526.5 | 585 |
| 19 | 3 | 3 | 16-QAM | 1/2 | 78 | 86.7 | 162 | 180 | 351 | 390 | 702 | 780 |
| 20 | 4 | 3 | 16-QAM | 3/4 | 117 | 130 | 243 | 270 | 526.5 | 585 | 1053 | 1170 |
| 21 | 5 | 3 | 64-QAM | 2/3 | 156 | 173.3 | 324 | 360 | 702 | 780 | 1404 | 1560 |
| 22 | 6 | 3 | 64-QAM | 3/4 | 175.5 | 195 | 364.5 | 405 | n/a | n/a | 1579.5 | 1755 |
| 23 | 7 | 3 | 64-QAM | 5/6 | 195 | 216.7 | 405 | 450 | 877.5 | 975 | 1755 | 1950 |
| | 8 | 3 | 256-QAM | 3/4 | 234 | 260 | 486 | 540 | 1053 | 1170 | 2106 | 2340 |
| | 9 | 3 | 256-QAM | 5/6 | 260 | 288.9 | 540 | 600 | 1170 | 1300 | n/a | n/a |

$\pi/4$ QPSK

- ✿ $\pi/4$ QPSK consists of two QPSK
- ✿ When performing modulation, switch between these two QPSK on symbol basis
- ✿ Possible phase differences: $\pm (\pi/4), \pm(3\pi/4)$
- ✿ An example: symbols are 01 10 00 11
 - Initial state is 11 as marked
 - The phase differences of modulated signal are $[-\pi/4, +3\pi/4, +3\pi/4, +3\pi/4]$

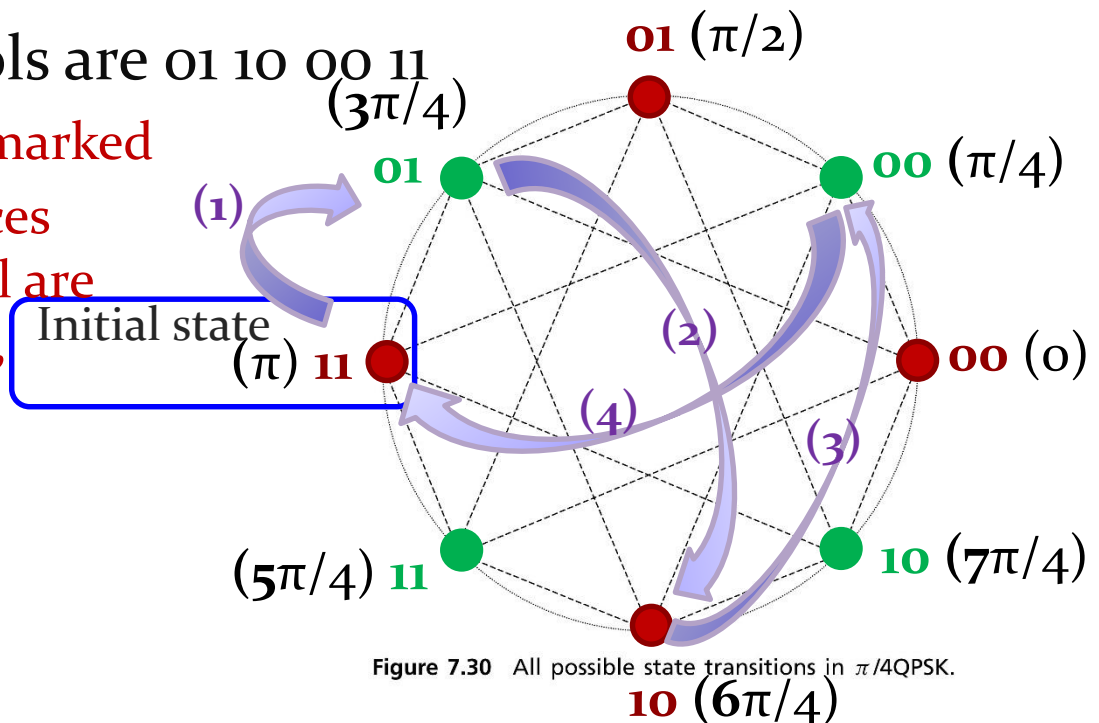


Figure 7.30 All possible state transitions in $\pi/4$ QPSK.

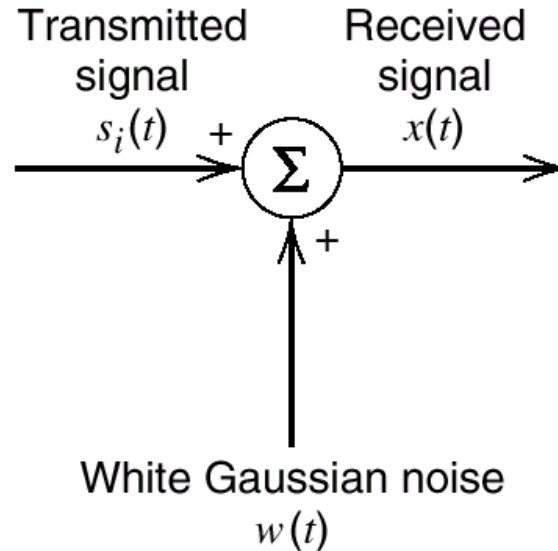
Signal representations and transmissions

– How do we transmit messages to others?

- Start by defining a set of characters(symbols), m_1, m_2, \dots, m_M
- Represent the symbols with certain signal formats, s_1, \dots, s_M
- Signal $s_i(t)$ is transmitted over a channel at a speed of $1/T$ sec
- Suppose the channel has the following two characteristics:
 - The channel is linear, with a bandwidth that is wide enough to accommodate the transmission of signal with negligible distortion
 - The channel is corrupted by an additive noise $w(t)$, which is the sample function of a *zero-mean white Gaussian noise process*
- We refer to this channel as an additive white Gaussian noise (AWGN) channel, and express the received signal $x(t)$ as

$$x(t) = s_i(t) + w(t), \quad \left\{ \begin{array}{l} 0 \leq t \leq T \\ i = 1, 2, \dots, M \end{array} \right\}$$

-
- The received signal can thus be modeled as

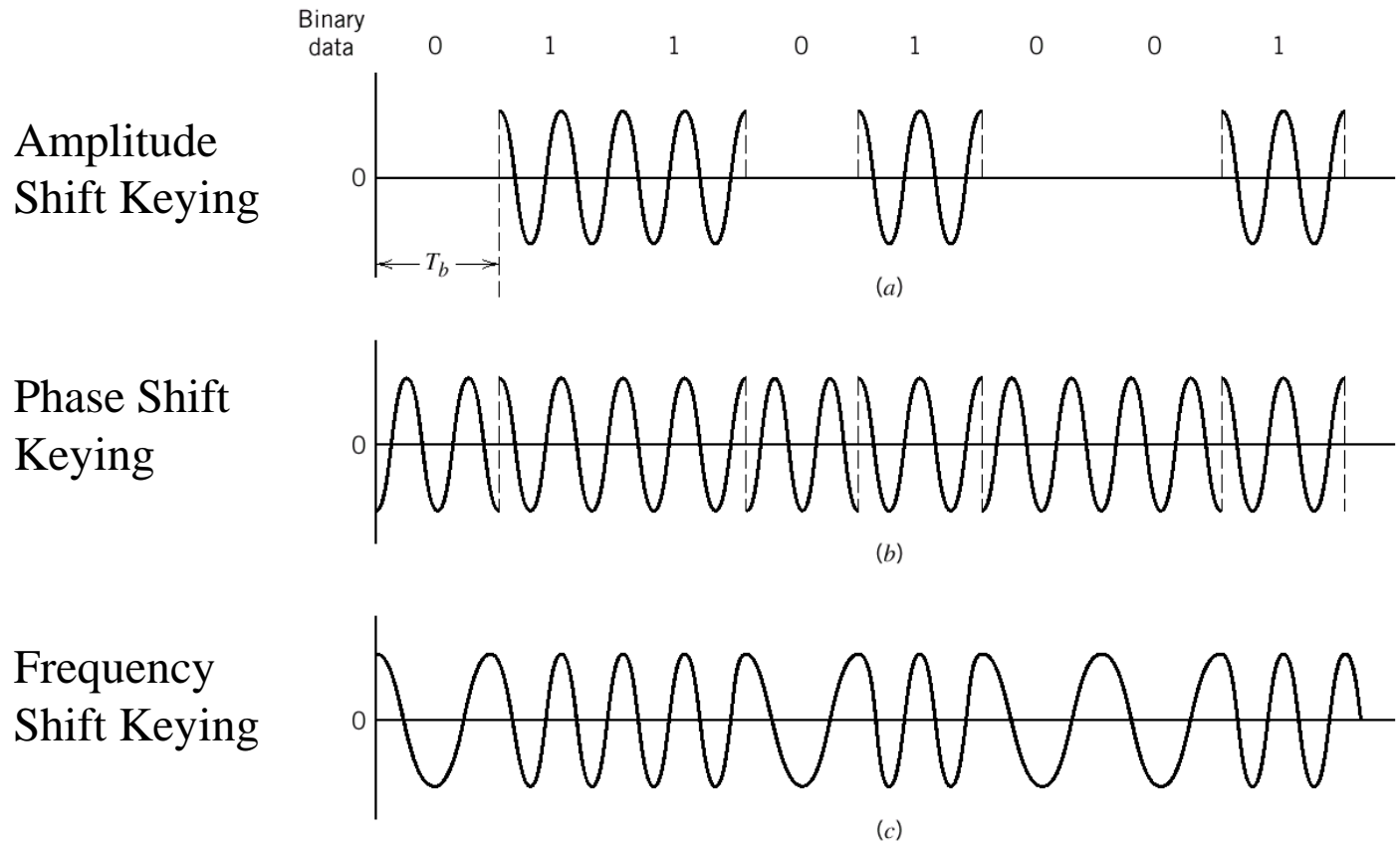


– What does the receiver do?

- Observes the received signal $x(t)$ for a duration of T
- Makes a best estimate of the transmitted signal $s_i(t)$, or m_i , such that $P_e = \sum_{i=1}^M p_i P(\hat{m} \neq m_i | m_i)$ is minimized

– What are the basic types of signals for data transmissions?

- Consider a simple sinusoidal wave $s(t) = \cos(2\pi f_c t)$
- What can we do to transmit a binary data stream with $s(t)$



-
- Take PSK as an example, we may have

- $s_1(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t)$ to represent a binary symbol 1

- $s_2(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t + \pi)$ to represent a binary symbol 0

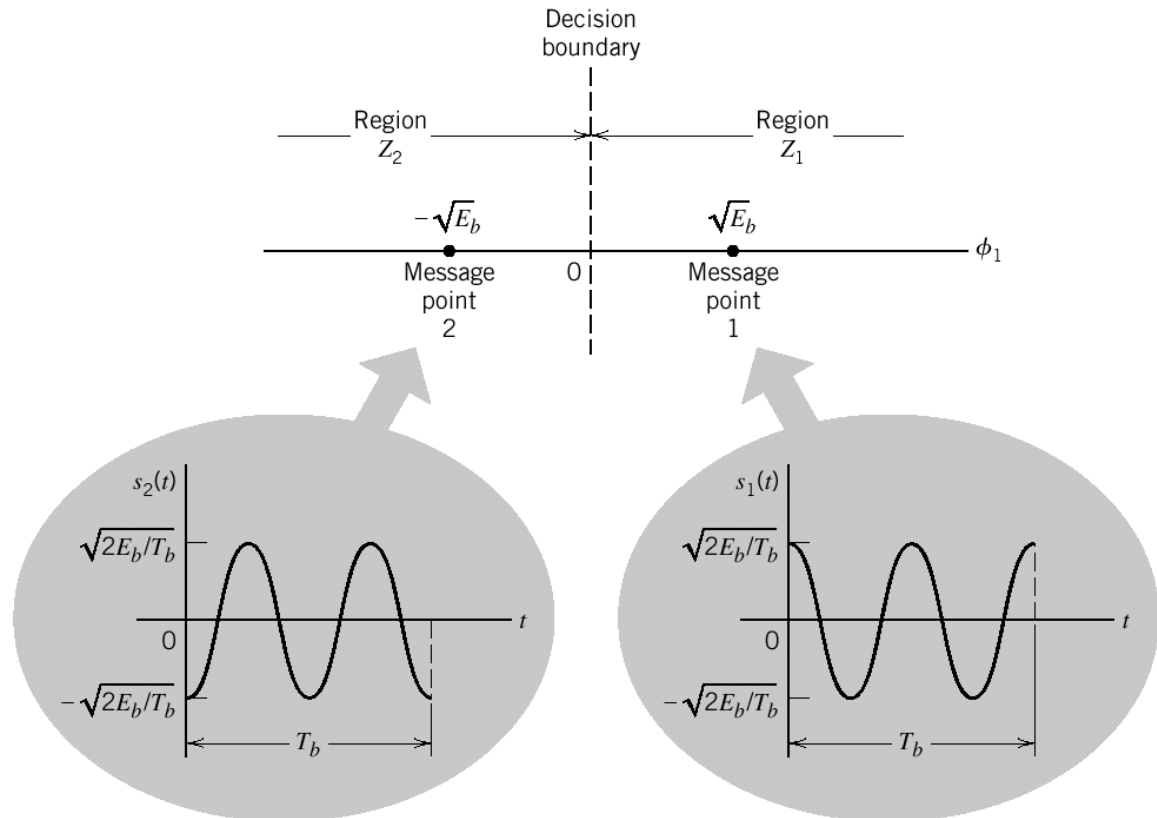
where $0 \leq t \leq T_b$, and E_b is the energy per bit

- To ensure that each transmitted bit contains an integral number of cycles of the carrier wave, we have $f_c = n_c / T_b$, with $n_c \in \mathbb{N}$
 - Two sinusoidal waves that differ only in a relative phase of 180° are referred to as *antipodal signals*
 - This type of modulation is referred to as binary PSK (BPSK)
 - Define a basis function $\phi_1(t) = \sqrt{\frac{2}{T_b}} \cos(2\pi f_c t)$, $0 \leq t < T_b$
 - Then $s_1(t) = \sqrt{E_b} \phi_1(t)$ and $s_2(t) = -\sqrt{E_b} \phi_1(t)$, $0 \leq t < T_b$

- A coherent BPSK signal is therefore characterized *by having a one-dimensional signal space $\phi_1(t)$* , with a signal constellation consisting of two message points, i.e. $M=2$
- The coordinate of the two message points of BPSK on $\phi_1(t)$ are

$$s_{11} = \int_0^{T_b} s_1(t)\phi_1(t)dt = +\sqrt{E_b}$$

$$s_{21} = \int_0^{T_b} s_2(t)\phi_1(t)dt = -\sqrt{E_b}$$



Recall the BPSK modulation

- $s_1(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t)$ for the message bit $m_1 = 1$
- $s_2(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t + \pi)$ for the message bit $m_2 = 0$
where $0 \leq t \leq T_b$, and E_b is the energy per bit

How do we do detection? Remember that we have noise!!

- The received signal is given by $x(t) = s_i(t) + w(t)$, and
$$x_1 = \int_0^{T_b} x(t) \phi_1(t) dt = \pm \sqrt{E_b} + \int_0^{T_b} w(t) \phi_1(t) dt$$
- The sampled noise
$$w_1 = \int_0^{T_b} w(t) \phi_1(t) dt$$
is Gaussian given that $w(t)$ is a Gaussian random process

-
- Define a random variable W_1 and a random process $W(t)$ for w_1 and $w(t)$, respectively. The variance of W_1 is

- $$\begin{aligned}\sigma_{x_1}^2 &= E \left[\int_0^{T_b} W(t) \phi_1(t) dt \int_0^{T_b} W(u) \phi_1(u) du \right] \\ &= E \left[\int_0^{T_b} \int_0^{T_b} \phi_1(t) \phi_1(u) W(t) W(u) dt du \right] \\ &= \int_0^{T_b} \int_0^{T_b} \phi_1(t) \phi_1(u) E[W(t) W(u)] dt du \\ &= \int_0^{T_b} \int_0^{T_b} \phi_1(t) \phi_1(u) \frac{N_0}{2} \delta(t - u) dt du \\ &= \frac{N_0}{2} \int_0^{T_b} \phi_1^2(t) dt = \frac{N_0}{2}\end{aligned}$$

- Similarly, it is easy to show that

$$\text{cov}[X_i X_j] = \frac{N_0}{2} \int_0^{T_b} \phi_i(t) \phi_j(t) dt = 0, \quad i \neq j$$

- Therefore, the received samples of signals are modeled as

$$x_1 = \pm\sqrt{E_b} + w_1 \quad \text{with} \quad w_1 \sim \mathcal{N}(0, N_0/2)$$

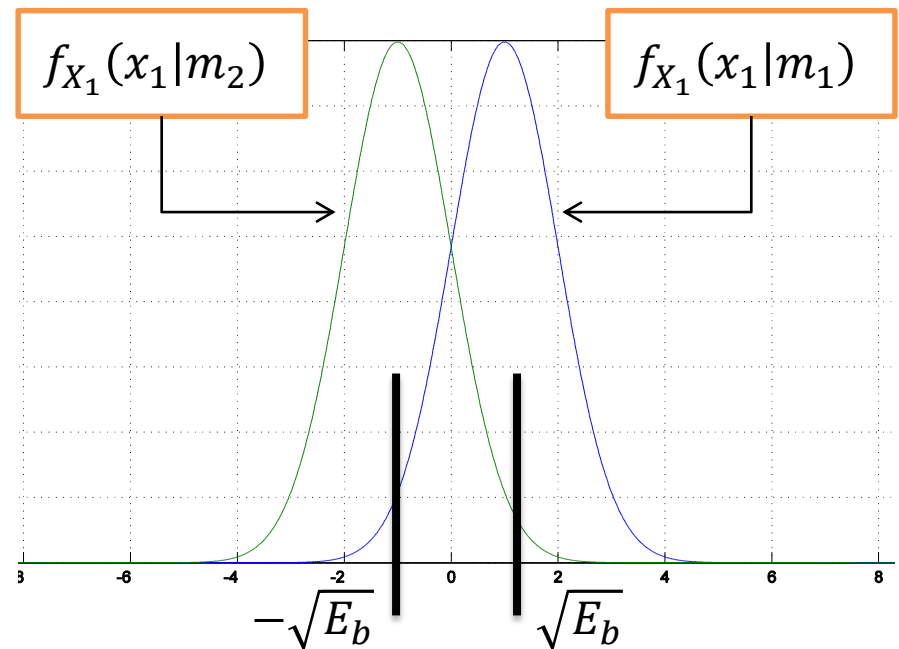
- The conditional probability density function (PDF) of x_1 is

$$f_{X_1}(x_1|m_i) = \frac{1}{\sqrt{\pi N_0}} \exp \left[-\frac{1}{N_0} (x_1 - s_{i1})^2 \right], \quad s_{i1} = \pm\sqrt{E_b}$$

- Suppose the probability mass function (PMF), $p(m_1)=p(m_2)=0.5$

- The decision rule follows as

$$f_{X_1}(x_1|m_2) \underset{m_2}{\overset{m_1}{\gtrless}} f_{X_1}(x_1|m_1)$$



-
- The probability of mistaking 1 a 0 is, therefore, given by

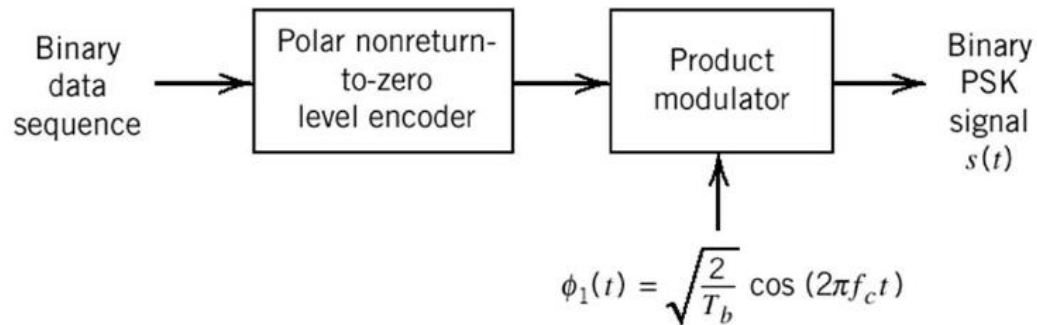
$$\begin{aligned} p_{10} &= \int_0^\infty f_{x_1}(x_1|m_2 = 0)dx_1 \\ &= \frac{1}{\sqrt{\pi N_0}} \int_0^\infty \exp \left[-\frac{1}{N_0} (x_1 + \sqrt{E_b})^2 \right] dx_1 = \frac{1}{\sqrt{\pi}} \int_{\sqrt{E_b/N_0}}^\infty \exp [-z^2] dz \\ &= \frac{1}{2} \operatorname{erfc} \left(\sqrt{\frac{E_b}{N_0}} \right) \end{aligned}$$

- Since $p_e = p_{10}p(0) + p_{01}p(1)$ and $p_{01} = p_{10}$ with $p(0) = p(1) = 0.5$
- Finally, we have the bit error rate (BER) of BPSK as follows

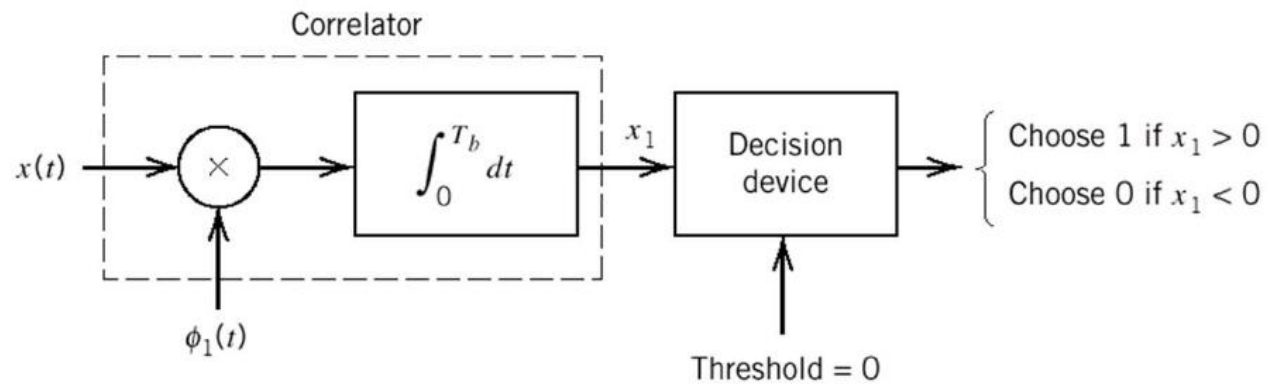
$$p_e = \frac{1}{2} \operatorname{erfc} \left(\sqrt{\frac{E_b}{N_0}} \right)$$

– Generation and detection of BPSK

- Polar nonreturn-to-zero (NRZ) level encoder:



(a)



(b)

HW₂

- Generate a series of binary random numbers
- Modulate the binary numbers with BPSK, given that the carrier frequency f_c is 1 MHz, and the symbol energy E_b is 10 dB and frequency is 1 KHz
- Demodulate the transmitted signal using the block diagram on pp. 27
- Add the demodulated samples by AWGN noise $\mathcal{N}(0, N_0/2)$, with $N_0=1$
- Do symbol detection on the resultant samples
- Calculate the BER
- Redo the same experiments with $0 \text{ dB} \leq E_b \leq 30 \text{ dB}$
- Draw and compare the BER with the theoretical values