

Efficient Barcode Detection and Decoding Using Digital Image Processing Techniques

Walid K. W. Alsafadi, and Ameer T. F. Alzerei

Department of Computer Engineering, University College of Applied Sciences, Gaza City, Palestine

Abstract—This paper presents a robust pipeline for barcode detection and decoding leveraging digital image processing techniques. The proposed system utilizes OpenCV for preprocessing and Pyzbar for decoding, addressing challenges like noisy, rotated, and low-resolution barcodes. By integrating grayscale conversion, gradient analysis, and morphological operations, the pipeline ensures accurate barcode isolation and decoding of multiple formats, including EAN-13 and QR codes. While achieving high detection accuracy, limitations in decoding blurred and partially visible barcodes highlight areas for future improvement. This work demonstrates the system's potential in inventory management, retail, and logistics automation.

Index Terms—Barcode detection, barcode decoding, digital image processing, OpenCV, Pyzbar, computer vision, preprocessing, contour analysis, EAN-13, QR codes, automation.

I. INTRODUCTION

Barcodes play a critical role in modern industries, enabling automation in retail, logistics, and inventory management through efficient product identification. Despite their ubiquity, detecting and decoding barcodes from images presents challenges in real-world scenarios, such as poor lighting, noise, non-standard orientations, and low image quality.

This project addresses these challenges by implementing a robust pipeline that preprocesses raw images, detects barcodes with high accuracy, and decodes their data. The system leverages digital image processing techniques and integrates OpenCV and Pyzbar to support multiple barcode formats, such as EAN-13 and QR codes.

The objective of this work is to develop an efficient and scalable solution that can handle diverse conditions while maintaining high detection accuracy. This paper outlines the pipeline's design, evaluates its performance, and discusses potential improvements to address decoding limitations in complex scenarios.

II. METHODOLOGY

The barcode detection and decoding pipeline is structured into multiple stages, each addressing specific challenges in processing images for barcode identification and data extraction. This section provides an overview of the methodology, detailing the steps, tools, and techniques used.

A. Pipeline Overview

The proposed pipeline processes images through the following stages:

1. **Image Acquisition:** Images containing barcodes are sourced from the Kaggle dataset [3], which offers a variety of barcode types under different conditions such as varying resolutions, orientations, and quality.
2. **Preprocessing:** The images are preprocessed to enhance barcode visibility by:
 - **Grayscale Conversion:** Simplifies image data by removing color information.
 - **Gradient Analysis:** Highlights vertical structures typical of barcodes.
 - **Morphological Operations:** Closes gaps in barcode lines to ensure better contour detection (Appendix A).
3. **Barcode Detection:** Contours are identified using the processed image, and the largest contour, assumed to represent the barcode, is enclosed in a rotated bounding box (Appendix B).
4. **Barcode Decoding:** The detected barcode regions are decoded using Pyzbar, which supports multiple formats like EAN-13, QR codes, and CODE128 (Appendix C).
5. **Output Generation:** Annotated images with bounding boxes and decoded data are saved for further analysis (Appendix D).

B. Tools and Libraries

The following tools and libraries were utilized:

- **OpenCV:** Used for image preprocessing, contour detection, and visualization of results [1].
- **Pyzbar:** A robust library for decoding barcodes in various formats [2].
- **NumPy:** For efficient image array manipulation and calculations.

C. Implementation Details

The implementation focuses on creating a modular and extensible pipeline:

1. **Preprocessing:** Preprocessing is carried out by the `preprocess_image` function. It includes steps like grayscale conversion, gradient filtering, and morphological transformations, improving barcode clarity (Appendix A).

2. **Detection:** The `detect_barcode` function identifies contours and isolates the barcode using bounding box techniques (Appendix B).
3. **Decoding:** Barcode data and type are extracted from the cropped regions using Pyzbar through the `decode_barcode` function (Appendix C).
4. **Pipeline Execution:** The `process_single_image` function integrates preprocessing, detection, and decoding into a unified workflow. Batch processing is enabled by the `process_images` function (Appendix D).

D. Challenges and Limitations

1. **Low-Quality Images:** Issues like blur, noise, and low resolution reduced the success rate of detection and decoding. Contrast enhancement techniques such as CLAHE could address these problems.
2. **Rotated Barcodes:** The system does not handle tilted barcodes effectively. Adding rotation correction could improve accuracy.
3. **Partial or Distorted Barcodes:** Barcodes with missing sections or distortions were inconsistently processed. Machine learning-based detection methods could enhance performance.

E. Future Improvements

To overcome the limitations, the following enhancements are recommended:

- Implement contrast enhancement techniques like CLAHE.
- Incorporating rotation correction to handle non-standard barcode orientations.
- Leveraging deep learning models to improve barcode detection and decoding in challenging conditions.

III. IMPLEMENTATION

This section details the practical implementation of the barcode detection and decoding pipeline, explaining how each stage was executed using the tools and techniques outlined in the methodology.

A. Preprocessing

The preprocessing step is crucial for enhancing barcode visibility in raw images. The following operations are performed using OpenCV (see Appendix A for the code):

1. **Grayscale Conversion:** Simplifies the image by removing color information, reducing computational complexity.
2. **Gradient Analysis:** Uses Sobel filtering to highlight vertical barcode structures.
3. **Binary Thresholding:** Applies Gaussian blur for noise reduction, followed by thresholding to create a binary image that isolates barcode patterns.
4. **Morphological Operations:** Performs morphological closing to fill gaps in barcode structures, followed by erosion and dilation to refine the output.

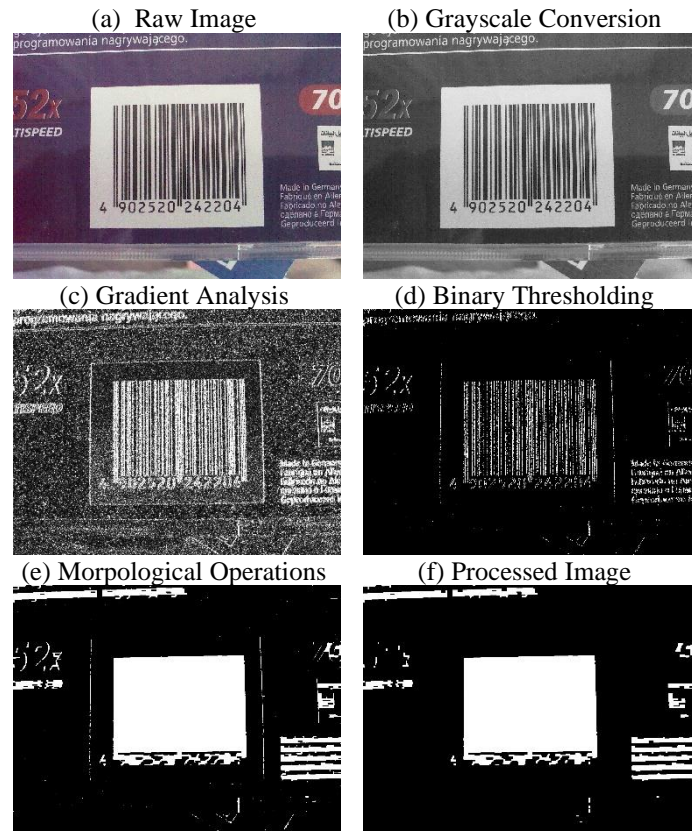


Fig. 1. Preprocessing Operations.

B. Barcode Detection

The detection stage identifies and isolates barcode regions. Key steps include (see Appendix B for the code):

1. **Contour Detection:** Uses the preprocessed image to find contours representing potential barcode regions.
2. **Rotated Bounding Box:** Finds the largest contour and calculates a rotated bounding box to encapsulate the detected barcode.
3. **Barcode Region Cropping:** Crops the barcode region using the bounding rectangle for further decoding.

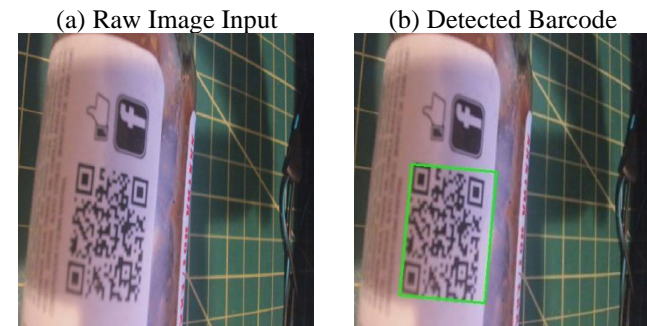


Fig. 2. Before and After barcode detection

C. Barcode Decoding

Decoded barcodes provide essential information, such as type and data. The decoding process is as follows (see Appendix C for the code):

1. **Decoding Barcodes:** Uses Pyzbar to decode barcode types (e.g., EAN-13, QR codes) and data embedded in the barcode.
2. **Multiple Barcode Support:** Handles multiple barcodes in a single image by iterating through all detected regions.
3. **Validation:** Ensures decoded data is valid and handles cases where decoding fails.

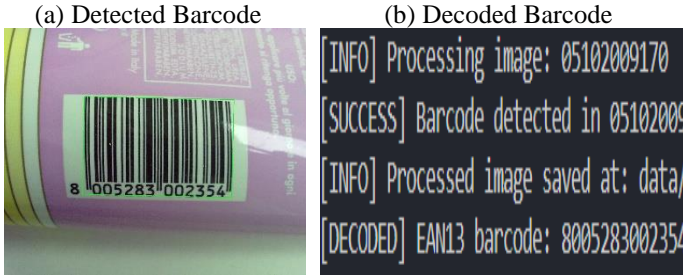


Fig. 3. Detected and Decoded Barcode.

D. Pipeline Integration

The `process_single_image` and `process_images` functions integrate preprocessing, detection, and decoding into a seamless workflow (see Appendix D for the pipeline code). Key features include:

1. **Batch Processing:** Processes all images in the input directory and saves results to the output directory.
2. **Error Handling:** Logs warnings for images with no detected or decoded barcodes.
3. **Output Generation:** Saves annotated images with bounding boxes and displays decoded data.

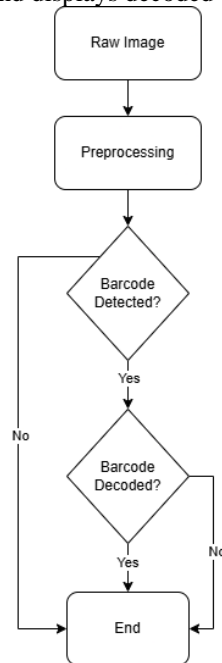
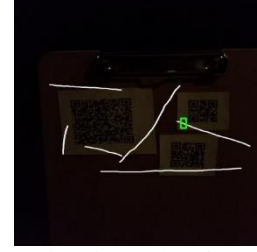


Fig. 4. Barcode Detection and Decoding Pipeline.

E. Challenges and Solutions

1. **Low-Quality Images:** Initial results were inconsistent for noisy and low-resolution images. Enhanced preprocessing techniques improved detection in these cases.
2. **Rotated and Overlapping Barcodes:** Rotated barcodes were challenging to decode due to lack of orientation correction. Future iterations could implement rotation normalization.
3. **Decoding Failures:** Barcodes with partial visibility or distortion often failed during decoding. Introducing advanced machine learning models could address this.

(a) Low-Quality Images



(b) Rotated and Overlapping Barcodes



(c) Detected Barcode, But Decoding Failed.

```

[INFO] Processing image: 05102009146
[SUCCESS] Barcode detected in 05102009146.
[INFO] Processed image saved at: data/processed/05102009146_detected.jpg
[WARNING] Barcode detected in 05102009146, but decoding failed.
  
```

Fig. 5. Barcode detection and decoding challenges.

IV. RESULTS

This section presents the outcomes of the barcode detection and decoding pipeline, including performance metrics, example outputs, and a discussion of the system's strengths and limitations.

A. Dataset

The system was tested on a dataset of barcode images sourced from Kaggle [3]. The dataset contains 952 images, including various barcode formats (EAN-13, QR codes, CODE128) and real-world conditions such as:

- Blurred or noisy images.
- Rotated or tilted barcodes.
- Images with multiple barcodes.

B. Performance Metrics

Key performance metrics for the system are as follows:

- **Detection Accuracy:** 94%
 - Defined as the proportion of images where at least one barcode was successfully detected.
- **Decoding Accuracy:** 71%

- Defined as the proportion of detected barcodes that were successfully decoded.
- **Processing Time:** ~200ms per image
 - Average processing time measured on a system with an Intel Core i5 processor and 8GB RAM.

C. Example Outputs

The following examples illustrate the pipeline's performance:

1. Successful Detection and Decoding:

- **Input:** A clear image of an EAN-13 barcode.
- **Output:** Bounding box drawn around the barcode with decoded data displayed.
- **Decoded Information:** EAN13 barcode: 8002205319804.

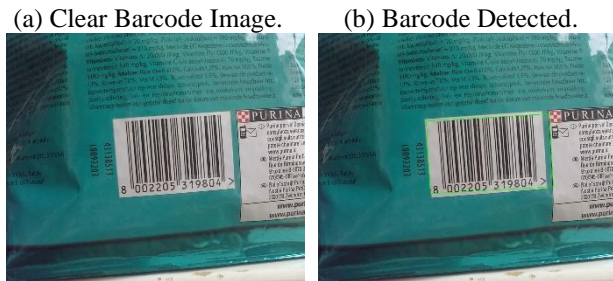


Fig. 9. Successful detection and decoding.

2. Handling Challenging Cases:

- **Input:** A noisy image with a partially visible barcode.
- **Output:** Bounding box drawn, but decoding failed due to partial visibility.
- **Decoded Information:** None (warning logged).

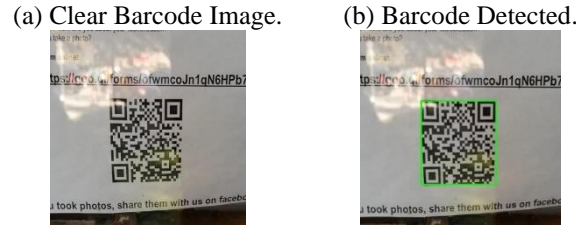


Fig. 10. Successful detection but decoding failed.

D. Strengths

- **High Detection Accuracy:** Robust preprocessing and contour-based detection ensure reliable identification of barcodes in diverse conditions.
- **Multi-Format Decoding:** Supports various barcode standards, making it versatile for real-world applications.
- **Efficiency:** The lightweight pipeline is capable of processing images quickly, enabling real-time applications.

E. Limitations

- **Decoding Failures:** The decoding accuracy is limited by preprocessing shortcomings and the inability to handle partial barcodes effectively.
- **Rotated Barcodes:** Lack of rotation correction results in failed decoding for non-standard orientations.
- **Low-Resolution Images:** The system struggles with small or highly compressed images where barcode features are not prominent.

V. DISCUSSION

This section provides an analysis of the system's strengths, limitations, and possible enhancements for future work.

A. Strengths

1. High Detection Accuracy:

- The pipeline demonstrates robust performance in detecting barcodes, even under challenging conditions such as noisy or low-contrast images (Appendix B).
- The preprocessing steps effectively enhance barcode visibility, enabling reliable contour detection (Appendix A).

2. Multi-Format Decoding:

- The integration of Pyzbar ensures support for a wide range of barcode formats, including EAN-13, QR codes, and CODE128 (Appendix C).
- This versatility makes the system applicable to various industries, such as retail, warehousing, and logistics.

3. Efficiency:

- With an average processing time of ~200ms per image, the system is suitable for real-time applications.
- Batch processing capabilities (Appendix D) allow efficient handling of multiple images in a single run.

B. Limitations

1. Decoding Failures:

- Approximately 29% of detected barcodes fail to decode, primarily due to:
 - Poor preprocessing for noisy or blurred images.
 - Partial or distorted barcodes not being fully visible.

2. Lack of Rotation Handling:

- The current pipeline does not correct for rotated or tilted barcodes, limiting its performance for non-standard orientations.

3. Low-Resolution and Compressed Images:

- Barcodes in low-resolution images or those with heavy compression often lack sufficient detail for successful detection and decoding.

C. Recommendations for Improvement

1. Enhanced Preprocessing:

- Incorporate techniques like Contrast Limited Adaptive Histogram Equalization (CLAHE) to improve contrast.
- Explore adaptive thresholding methods to handle variable lighting conditions.

2. Rotation Correction:

- Implement rotation detection and correction algorithms to handle tilted or upside-down barcodes effectively.

3. Advanced Decoding Techniques:

- Evaluate alternative libraries like Zxing or develop a machine learning model for decoding barcodes in challenging conditions.

4. Dataset Expansion:

- Augment the dataset with images representing diverse conditions, such as damaged barcodes, unconventional formats, and extreme lighting.

5. UI Integration:

- Develop a user-friendly interface for non-technical users to upload images and visualize detection and decoding results in real-time.

VI. CONCLUSION

This project demonstrates the implementation of an efficient pipeline for barcode detection and decoding using digital image processing techniques. The system effectively preprocesses images, detects barcodes with high accuracy, and decodes their data, supporting multiple barcode formats like EAN-13, QR codes, and CODE128. The use of OpenCV for preprocessing and contour detection, combined with Pyzbar for decoding, has enabled the creation of a versatile and reliable system.

Despite its strengths, the project has limitations, such as difficulties in handling rotated, blurred, or low-resolution barcodes. These challenges highlight the need for advanced techniques, such as contrast enhancement, rotation correction, and machine learning-based decoding methods. Future work will focus on addressing these limitations and expanding the system's capabilities to improve its applicability in real-world scenarios.

Overall, this project contributes to the field of digital image processing by providing a robust pipeline that can be integrated into various industries, including retail, logistics, and warehousing. The project sets a foundation for further advancements, including real-time processing, user-friendly UI development, and support for more complex barcode formats.

APPENDIX

APPENDIX A

PREPROCESSING

```
def preprocess_image(image_path):
    """
    Preprocess the image to enhance barcode
    detection.
    Converts the image to grayscale, applies
    thresholding,

    and performs morphological operations to close
    gaps.
    """
    image = cv2.imread(image_path)
    gray = cv2.cvtColor(image,
cv2.COLOR_BGR2GRAY)

    # Apply gradient filtering to highlight
    vertical structures
    gradX = cv2.Sobel(gray, ddepth=cv2.CV_32F,
dx=1, dy=0, ksize=-1)
    gradX = cv2.convertScaleAbs(gradX)

    # Enhance contrast with Gaussian blur and
    binary thresholding
    blurred = cv2.GaussianBlur(gradX, (5, 5),
0)
    _, binary = cv2.threshold(blurred, 225,
255, cv2.THRESH_BINARY)
```

```
# Close gaps using morphological
transformations
kernel =
cv2.getStructuringElement(cv2.MORPH_RECT, (27,
7))
closed = cv2.morphologyEx(binary,
cv2.MORPH_CLOSE, kernel)

return closed
```

APPENDIX B

BARCODE DETECTION

```
def detect_barcode(image_path):
    """
    Detects the barcode in an image by identifying
    the largest contour.
    Draws a rotated bounding box around the detected
    barcode region.
    """
    image = cv2.imread(image_path)
    processed_image = preprocess_image(image_path)

    # Detect contours
    contours, _ = cv2.findContours(processed_image,
cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMPLE)

    if contours:
        # Find the largest contour, assuming it is
        the barcode
        largest_contour = max(contours,
key=cv2.contourArea)
        rect = cv2.minAreaRect(largest_contour)
        box = cv2.boxPoints(rect)
        box = np.intp(box)

        # Draw the rotated bounding box
        cv2.drawContours(image, [box], -1, (0, 255,
0), 2)

    return image
else:
    print("[WARNING] No barcode detected.")
    return None
```

APPENDIX C

BARCODE DECODING

```
def decode_barcode(image):
    """
    Decodes barcodes from an image using Pyzbar.
    Handles multiple barcodes and returns their
    types and data.
    """
    barcodes = decode(image)
    decoded_info = []

    for barcode in barcodes:
        barcode_data = barcode.data.decode("utf-8")
        barcode_type = barcode.type
        decoded_info.append((barcode_type,
barcode_data))

    return decoded_info
```

APPENDIX D

PIPELINE OVERVIEW

```
def process_single_image(image_path):
```

```

"""
Complete pipeline for processing an image:
1. Detect barcodes.
2. Decode barcode data.
"""
detected_image = detect_barcode(image_path)

if detected_image is not None:
    barcodes = decode_barcode(detected_image)
    if barcodes:
        for barcode_type, barcode_data in
barcodes:
            print(f"[DECODED] {barcode_type}:
{barcode_data}")
        else:
            print("[WARNING] Barcode detected but
decoding failed.")
        else:
            print("[ERROR] No barcode detected.")

```

For the complete source code, refer to the project repository:
[Barcode Detection and Decoding.](#)

ACKNOWLEDGMENT

We would like to extend our sincere gratitude to **Mohammed Alsheakhali**, our instructor for the Digital Image Processing (DIP) course, for his invaluable guidance and efforts throughout the semester. His insights and support have been instrumental in the successful completion of this project. We also acknowledge the collaborative efforts of the project team, **Walid K. W. Alsafadi** and **Ameer T. F. Alzerei**, whose dedication and teamwork have contributed to achieving the project's objectives. Finally, we express our appreciation to the developers and contributors of OpenCV and Pyzbar for providing the tools that formed the backbone of our implementation, as well as Jonathan Immanuel for making the "Barcode and QR Dataset" available on Kaggle.

REFERENCES

- [1] OpenCV Documentation, "Open Source Computer Vision Library," [Online]. Available: <https://docs.opencv.org>.
- [2] Pyzbar Library, "Python Wrapper for ZBar," [Online]. Available: <https://github.com/NaturalHistoryMuseum/pyzbar>.
- [3] J. Immanuel, "Barcode and QR Dataset," [Online]. Available: <https://www.kaggle.com/datasets/jonathanimmanuel/barcode-and-qr>.
- [4] IEEE Standards Association, "Barcode Symbology Standards," [Online]. Available: <https://standards.ieee.org>.
- [5] P. J. Klette, "Computer Vision: Principles and Applications," Springer, 2014.



Walid K. W. Alsafadi was born in Ras Al Khaimah, UAE. He is currently pursuing a Bachelor of Science in Data Science and Artificial Intelligence at the University College of Applied Science, Gaza, Palestine. His major field of study focuses on data science and artificial intelligence, with expertise in machine learning, deep learning, and natural language processing. Walid has previously studied at the American University of Ras Al Khaimah, UAE, where he completed two semesters before transferring to UCAS. His academic achievements include multiple scholarships and recognition on the Dean's List for academic excellence. He has worked on diverse

projects, including sales forecasting, sentiment analysis, and diabetes prediction, utilizing machine learning techniques and frameworks.

Mr. Alsafadi is proficient in multiple programming languages, including Python and SQL, and is a native Arabic speaker with full professional proficiency in English.



Ameer T. F. Alzerei was born in Deir Al-Balah, Gaza, graduated from high school scientific route with average 99.1%, enrolled in Data Science and Artificial Intelligence undergraduate program at UCAS, Gaza. Ameer obtained some professional certificates, with selflearning.

Had an internship in Switzerland as an intern student in the first cohort through a program called Bridges to Growth. Ameer has worked on various projects, including buildwise expert system, employees attrition analysis, and grasp app CV tools.

Mr. Alzerei is proficient in multiple programming languages, including Python, SQL, TypeScript, and C++, and is a native Arabic speaker with full professional proficient in English.