## Vectors & Matrices

## Problem Set 4

Eigenvectors, Eigenvalues and Diagonalization

Xin, Wenkang

May 10, 2023

## Eigenvectors, Eigenvalues and Diagonalization

1

The characteristic equation is given by:

$$\det\begin{pmatrix} 1-\lambda & 2 & 1\\ 2 & 1-\lambda & 1\\ 1 & 1 & 2-\lambda \end{pmatrix} = (1-\lambda)(\lambda-4)(\lambda+1) = 0 \tag{1}$$

For  $\lambda_1 = -1$ , performing row reduction on  $(A - \lambda_1 I)$  yields:

$$\begin{pmatrix} 2 & 2 & 1 \\ 2 & 2 & 1 \\ 1 & 1 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 3 \\ 0 & 0 & -5 \\ 0 & 0 & 0 \end{pmatrix} \tag{2}$$

so  $\hat{\mathbf{e}}_1 = (1, -1, 0)^{\intercal} / \sqrt{2}$ .

Further, for  $\lambda_2 = 1$ , performing row reduction on  $(A - \lambda_2 I)$  yields:

$$\begin{pmatrix} 0 & 2 & 1 \\ 2 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 \\ 0 & -2 & -1 \\ 0 & 0 & 0 \end{pmatrix} \tag{3}$$

so  $\hat{\mathbf{e}}_2 = (1, 1, -2)^{\intercal} / \sqrt{6}$ .

Finally, for  $\lambda_3 = 4$ :

$$\begin{pmatrix} -3 & 2 & 1 \\ 2 & -3 & 1 \\ 1 & 1 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \tag{4}$$

so  $\hat{\mathbf{e}}_3 = (1, 1, 1)^{\intercal} / \sqrt{3}$ .

Therefore we have  $R^{\intercal}AR = \text{diag}(-1, 1, 4)$ , where:

$$R = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & -\frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{pmatrix}$$
 (5)

 $\mathbf{2}$ 

The characteristic equation is given by:

$$\det(H - \lambda I) = (\lambda - 1)(\lambda - 11) = 0 \tag{6}$$

For  $\lambda_1 = 1$ :

$$\begin{pmatrix} 9 & 3i \\ -3i & 1 \end{pmatrix} \to \begin{pmatrix} 3 & i \\ 0 & 0 \end{pmatrix} \tag{7}$$

so  $\hat{\mathbf{e}}_1 = (i, -3)^{\intercal} / \sqrt{10}$ .

For  $\lambda_2 = 11$ :

$$\begin{pmatrix} -1 & 3i \\ -3i & -9 \end{pmatrix} \to \begin{pmatrix} 1 & -3i \\ 0 & 0 \end{pmatrix} \tag{8}$$

so  $\hat{\mathbf{e}}_2 = (3i, 1)^{\intercal} / \sqrt{10}$ .

Therefore, the required unitary matrix is given by:

$$U = \frac{1}{\sqrt{10}} \begin{pmatrix} i & 3i \\ -3 & 1 \end{pmatrix} \tag{9}$$

It is easy to verify that  $U^{\dagger}U=I.$ 

3

(a) Consider the equation  $\mathbf{x}^{\intercal}A\mathbf{x} = x^2 + 3y^2 - 2xy$ , where the matrix A has the form:

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \tag{10}$$

Expanding the matrix product yields the equation  $ax^2 + dy^2 + (b+c)xy = x^2 + 3y^2 - 2xy$ . We choose (a, b, c, d) = (1, 0, -2, 3) for simplicity.

Performing the usual diagonalization procedure on A yields  $\hat{\mathbf{e}}_1 = (1,1)^{\intercal}/\sqrt{2}$  with  $\lambda_1 = 1$  and  $\hat{\mathbf{e}}_2 = (0,1)^{\intercal}$  with  $\lambda_2 = 3$ . Therefore we have the equation:

$$\mathbf{x}^{\mathsf{T}} A \mathbf{x} = \mathbf{x}^{\mathsf{T}} P \hat{A} P^{-1} \mathbf{x} \tag{11}$$

where:

$$P = \begin{pmatrix} \frac{1}{\sqrt{2}} & 0\\ \frac{1}{\sqrt{2}} & 1 \end{pmatrix} \tag{12}$$

and  $\hat{A} = \text{diag}(1,3)$ .

Define the new coordinates with  $\mathbf{x}' = P^{-1}\mathbf{x}$ . In the new coordinate system, we have the equation:

$$x^{2} + 3y^{2} = 1 ag{13}$$

which is an ellipse with semi-major axis 1 and semi-minor axis  $\sqrt{3}$ .

4

(a) The characteristic equation is given by:

$$\det(R - \lambda I) = 1 - 2\lambda \cos \phi + \lambda^2 = \lambda^2 - (e^{i\phi} + e^{-i\phi})\lambda + 1 = 0$$

$$\tag{14}$$

Solving the quadratic equation for  $\lambda$  yields  $\lambda_{1,2} = e^{\pm i\phi}$ .

(b) Performing the usual diagonalization procedure on A yields  $\hat{\mathbf{e}}_1 = (-1, 1, 0)^{\intercal}/\sqrt{2}$  with the two-fold degenerate  $\lambda_1 = 0$  and  $\hat{\mathbf{e}}_2 = (1, 0, 0)^{\intercal}$  with  $\lambda_2 = 1$ .

As the number of eigenvectors is less than three, the eigenvectors cannot form a basis for  $\mathbb{R}^3$ . Therefore, A is not diagonalisable.

Performing Gram-Schmidt procedure on  $\hat{\mathbf{e}}_1$  and  $\hat{\mathbf{e}}_2$ . We have  $\hat{\mathbf{e}}_1' = \hat{\mathbf{e}}_1$  and:

$$\hat{\mathbf{e}}_{2}' = \frac{\hat{\mathbf{e}}_{2} - (\hat{\mathbf{e}}_{2} \cdot \hat{\mathbf{e}}_{1}')\hat{\mathbf{e}}_{1}'}{|\hat{\mathbf{e}}_{2} - (\hat{\mathbf{e}}_{2} \cdot \hat{\mathbf{e}}_{1}')\hat{\mathbf{e}}_{1}' = |} = (1, 1, 0)^{\mathsf{T}} / \sqrt{2}$$
(15)

But this is just  $\hat{\mathbf{e}}_1 + 2\hat{\mathbf{e}}_2$ . So there are only two linearly independent eigenvectors. Therefore, A is not diagonalisable.

5

(a) Let us assume that M is diagonalisable so that we have:

$$\mathbf{v}^{\mathsf{T}} M \mathbf{v} = \mathbf{v}^{\mathsf{T}} P \hat{M} P^{-1} \mathbf{v} = \mathbf{v}'^{\mathsf{T}} \hat{M} \mathbf{v}' = \sum_{i=1}^{n} \lambda_i v_i'^2$$
(16)

where  $\mathbf{v}' = P^{-1}\mathbf{v}$  is the new coordinates.

Since  $v_i'^2 \ge 0$ ,  $\mathbf{v}^{\intercal} M \mathbf{v} > 0$  for all  $\mathbf{v}$  if  $\lambda_i > 0$ , provided that  $\mathbf{v} \ne \mathbf{0}$ . Vice versa for the case where  $\mathbf{v}^{\intercal} M \mathbf{v} < 0$ .

(b) The characteristic polynomial is given by:

$$\chi(\lambda) = \lambda^2 - \operatorname{tr}(M)\lambda + \det(M) \tag{17}$$

Therefore, the two solutions of  $\chi(\lambda) = 0$  satisfy  $\lambda_1 + \lambda_2 = \operatorname{tr}(M)$  and  $\lambda_1 \lambda_2 = \det(M)$ .

Another way to see this is to note that  $\operatorname{tr}(M) = \operatorname{tr}(P\hat{M}P^{-1}) = \operatorname{tr}(\hat{M}) = \lambda_1 + \lambda_2$  and  $\det(M) = \det(P\hat{M}P^{-1}) = \det(\hat{M}) = \lambda_1\lambda_2$ .

(c) 
$$M \text{ is } \begin{cases} \text{positive definite} & \text{if } \det(M) > 0 \text{ and } \operatorname{tr}(M) > 0 \\ \text{negative definite} & \text{if } \det(M) > 0 \text{ and } \operatorname{tr}(M) < 0 \\ \text{negative indefinite} & \text{if } \det(M) <= 0 \end{cases}$$
 (18)

(d)  $M_1$  is positive indefinite;  $M_2$  is indefinite;  $M_3$  is negative definite.

6

(a) 
$$\chi_A(\lambda) = \det(A - \lambda I) = (A_{11} - \lambda)(A_{22} - \lambda) - A_{12}A_{21} = \lambda^2 - \operatorname{tr}(A)\lambda + \det(A)$$
 (19)

(b)

$$\chi_{A}(\lambda) = (A_{11} - \lambda) \det \begin{pmatrix} A_{22} - \lambda & A_{23} \\ A_{32} & A_{33} - \lambda \end{pmatrix} - A_{12} \det \begin{pmatrix} A_{21} & A_{23} \\ A_{31} & A_{33} - \lambda \end{pmatrix} + A_{13} \det \begin{pmatrix} A_{21} & A_{22} - \lambda \\ A_{31} & A_{32} \end{pmatrix} \\
= -\lambda^{3} + \operatorname{tr}(A)\lambda^{2} - \frac{1}{2} [\operatorname{tr}(A)^{2} - \operatorname{tr}(A^{2})]\lambda + \det(A) \tag{20}$$

(c) For a general A, the characteristic polynomial has the form:

$$\chi_A(\lambda) = (-1)^n \lambda^n + (-1)^{n-1} \operatorname{tr}(A) \lambda^{n-1} + \dots + \det(A)$$
 (21)

7

(a) For a given eigenvector of P, we have the equation  $P\mathbf{v} = \lambda \mathbf{v}$ . Apply P on both sides:

$$P^2 \mathbf{v} = \lambda P \mathbf{v} = \lambda^2 \mathbf{v} \tag{22}$$

But  $P^2 = P$  so  $\lambda^2 \mathbf{v} = \lambda \mathbf{v}$ . This shows that  $\lambda$  is either zero or unity. The diagonalisation of P is therefore:

$$\hat{P} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \tag{23}$$

(b) P projects an arbitrary vector onto a line depending on the diagonalisation of P. The number of ones in  $\hat{P}$  is the dimension of the space projected, and it is equal to  $\operatorname{tr}(P)$ 

(c) 
$$(Q^2)_{ij} = Q_{ik}Q_{kj} = n_i n_k n_k n_j = n_i n_j = Q_{ij}$$
 (24)

as  $\sum n_k^2 = 1$  for a unit vector.

Therefore,  $Q^2 = Q$  and Q is a projector.  $tr(Q) = Q_{ii} = n_i n_i = 1$  so it projects to a one-dimensional space.

(d) 
$$P^{2} = (I - Q)^{2} = I - 2Q + Q^{2} = I - Q = P$$
 (25)

We know that  $P_{ij} = \delta_{ij} - n_i n_j$ . Thus:

$$\operatorname{tr}(P) = \delta_{ij}(\delta_{ij} - n_i n_j) = 1 - n_i n_i = 0$$
(26)

Therefore, P projects onto a zero-dimensional space.

$$\operatorname{tr}(P) = \delta_{ij}(\delta_{ij} - n_i n_j) = n - n_i n_i = n - 1 \tag{27}$$

Therefore, P projects onto a n-1-dimensional space.

•

8

(a) For a given eigenvector of U, we have the equation  $U\mathbf{v} = \lambda \mathbf{v}$ . Taking the Hermitian of both sides:

$$\mathbf{v}^{\dagger}U^{\dagger} = \lambda^{*}\mathbf{v}^{\dagger}$$

$$\mathbf{v}^{\dagger}U^{\dagger}U\mathbf{v} = \lambda^{*}\lambda\mathbf{v}^{\dagger}\mathbf{v}$$

$$\mathbf{v}^{\dagger}\mathbf{v} = |\lambda|^{2}\mathbf{v}^{\dagger}\mathbf{v}$$
(28)

Therefore,  $|\lambda| = 1$ .

(b) We have the equation  $R\mathbf{v} = \lambda \mathbf{v}$ . Taking the transpose of both sides:

$$\mathbf{v}^{\mathsf{T}} R^{\mathsf{T}} = \lambda \mathbf{v}^{\mathsf{T}}$$

$$\mathbf{v}^{\mathsf{T}} R^{\mathsf{T}} R \mathbf{v} = \lambda \lambda \mathbf{v}^{\mathsf{T}} \mathbf{v}$$

$$\mathbf{v}^{\mathsf{T}} \mathbf{v} = \lambda^{2} \mathbf{v}^{\mathsf{T}} \mathbf{v}$$
(29)

This implies  $\lambda = \pm 1$  so 1 is always an eigenvalue of R.

(c)

$$\hat{R} = (\mathbf{u}_{1} \quad \mathbf{u}_{2} \quad \mathbf{n})^{\mathsf{T}} R (\mathbf{u}_{1} \quad \mathbf{u}_{2} \quad \mathbf{n}) 
= (\mathbf{u}_{1} \quad \mathbf{u}_{2} \quad \mathbf{n})^{\mathsf{T}} (R\mathbf{u}_{1} \quad R\mathbf{u}_{2} \quad \mathbf{n}) 
= \begin{pmatrix} (R\mathbf{u}_{1}) \cdot \mathbf{u}_{1} & (R\mathbf{u}_{2}) \cdot \mathbf{u}_{1} & \mathbf{n} \cdot \mathbf{u}_{1} \\ (R\mathbf{u}_{1}) \cdot \mathbf{u}_{2} & (R\mathbf{u}_{2}) \cdot \mathbf{u}_{2} & \mathbf{n} \cdot \mathbf{u}_{2} \\ (R\mathbf{u}_{1}) \cdot \mathbf{n} & (R\mathbf{u}_{2}) \cdot \mathbf{n} & \mathbf{n} \cdot \mathbf{n} \end{pmatrix}$$

$$= \begin{pmatrix} (R\mathbf{u}_{1}) \cdot \mathbf{u}_{1} & (R\mathbf{u}_{2}) \cdot \mathbf{u}_{1} & 0 \\ (R\mathbf{u}_{1}) \cdot \mathbf{u}_{2} & (R\mathbf{u}_{2}) \cdot \mathbf{u}_{2} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \cos \phi & -\sin \phi & 0 \\ \sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
(30)

(d) From the form of R, we have  $\operatorname{tr}(\hat{R}) = \operatorname{tr}(R) = 2\cos\phi + 1$  or:

$$\cos \phi = \frac{\operatorname{tr}(R) - 1}{2} \tag{31}$$

(e) Consider the determinant and the transpose of the matrix R:

$$R = \frac{1}{3\sqrt{2}} \begin{pmatrix} 3 & 0 & 3\\ -1 & -4 & 1\\ 2\sqrt{2} & -\sqrt{2} & -2\sqrt{2} \end{pmatrix}$$
 (32)

We have det(R) = 1 and  $R^{\dagger}R = I$ . Hence R is a rotation matrix. The characteristic polynomial of R is:

$$(1/\sqrt{2} - \lambda)[(4/\sqrt{2} + \lambda)(2/3 + \lambda) + 1/3] + 1/\sqrt{2}[\sqrt{2} + 2(4/(3\sqrt{2}) + \lambda)/3] = 0$$
(33)

Substituting  $\lambda = 1$  verifies that 1 is an eigenvalue of R. Further:

$$R - I = \frac{1}{3\sqrt{2}} \begin{pmatrix} 3 - 3\sqrt{2} & 0 & 3\\ -1 & -4 - 3\sqrt{2} & 1\\ 2\sqrt{2} & -\sqrt{2} & -5\sqrt{2} \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -1 - \sqrt{2}\\ 0 & 1 & 3 - 2\sqrt{2}\\ 0 & 0 & 0 \end{pmatrix}$$
(34)

This gives us:

$$\mathbf{n} = \frac{1}{\sqrt{13 - 2\sqrt{2}}} \begin{pmatrix} 1 + \sqrt{2} \\ -3 + 2\sqrt{2} \\ 1 \end{pmatrix} \tag{35}$$

and

$$\cos \phi = \frac{\operatorname{tr}(R) - 1}{2} = -\frac{5\sqrt{2} + 1}{6\sqrt{2}} \tag{36}$$

9

(a) Suppose that  $M = P\hat{M}P^{-1}$  such that  $\ddot{\mathbf{x}} = P\hat{M}P^{-1}\mathbf{x}$ . Then:

$$P^{-1}\ddot{\mathbf{x}} = \hat{M}P^{-1}\mathbf{x}$$

$$(P^{-1}\mathbf{x})_i = \hat{M}_{ii}(P^{-1}\mathbf{x})_i$$
(37)

This is an linear second order ODE with constant coefficients for  $(P^{-1}\mathbf{x})_i$  that can be easily solved.

- (b) The eigenvalues of M are  $\hat{M}_{ii} = \lambda_i$ , which are the (square of) oscillating frequencies of the transformed coordinates (normal coordinates).
- (c) The coefficient matrix has the form:

$$M = \begin{pmatrix} -k & -l \\ -l & -k \end{pmatrix} \tag{38}$$

Consider the characteristic equation:

$$\det(M - \Omega^2 I) = (k + \Omega^2)^2 - l^2 = 0 \tag{39}$$

Thus, the eigenfrequencies are  $\Omega_{1,2} = \sqrt{\pm l - k}$ . The eigenfrequencies can be real or imaginary depending on the sign of  $(\pm l - k)$ . For imaginary eigenfrequencies only, the solution is oscillatory. For real eigenfrequencies, the solution is exponentially decaying. For a combination of real and imaginary eigenfrequencies, the solution is a combination of oscillatory and exponential.

•