Multiple Integrals & Vector Calculus

Problem Set 4

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For the loop OABCO, we may break it down to two planes OAB, described by the normal $\mathbf{e}_1 = (0, -1, 1)^{\intercal}/\sqrt{2}$, and OBC, described by the normal $\mathbf{e}_2 = (-1, 0, 1)^{\intercal}/\sqrt{2}$. The vector area of the loop is then given by:

$$\mathbf{S} = \mathbf{S}_1 + \mathbf{S}_2 = A_1 \mathbf{e}_1 + A_2 \mathbf{e}_2 = \left(-1, -\frac{1}{2}, \frac{3}{2}\right)^\mathsf{T}$$
 (1)

where $A_1 = |\overrightarrow{OA} \times \overrightarrow{OB}|/2$ and $A_2 = |\overrightarrow{OB} \times \overrightarrow{OC}|/2$.

We may also consider the projection of the loop onto different planes:

$$A_{xy} = 3/2$$

$$A_{xz} = 1/2$$

$$A_{uz} = 1$$
(2)

Considering the orientation of the loop, we assign negative signs to A_{xz} and A_{yz} , and the results agree with the vector area. From the vector $\mathbf{e} = (0, -1, 1)^{\mathsf{T}}/\sqrt{2}$, the projected area is $\mathbf{S} \cdot \mathbf{e} = \sqrt{2}$.

The maximum projected area is $\mathbf{S} \cdot \hat{S} = 3$.

For the loop OACBO, we still break it down to two planes OAC, described by the normal $\mathbf{e}_3 = \hat{z}$, and CBO, described by the normal $\mathbf{e}_4 = (1, 0, -1)^{\intercal}/\sqrt{2}$. The vector area of the loop is then given by:

$$S = S_3 + S_4 = A_3 \hat{z} + A_4 e_4 = (2, 0, -1)^{\mathsf{T}}$$
(3)

$$\mathbf{S} = \mathbf{S}_3 + \mathbf{S}_4 = A_3 \hat{z} + A_4 \mathbf{e}_4 = (1, 0, 0)^{\mathsf{T}}$$
(4)

The projections are:

$$A_{xy} = 1$$

$$A_{xz} = 0$$

$$A_{yz} = 2$$
(5)

From the vector $\mathbf{e} = (0, -1, 1)^{\intercal} / \sqrt{2}$, the projected area is $\mathbf{S} \cdot \mathbf{e} = 1 / \sqrt{2}$.

$$A_{xy} = 0$$

$$A_{xz} = 0$$

$$A_{yz} = 1$$
(6)

From the vector $\mathbf{e} = (0, -1, 1)^{\intercal} / \sqrt{2}$, the projected area is $\mathbf{S} \cdot \mathbf{e} = 0$. The maximum projected area is $\mathbf{S} \cdot \hat{S} = 1$.

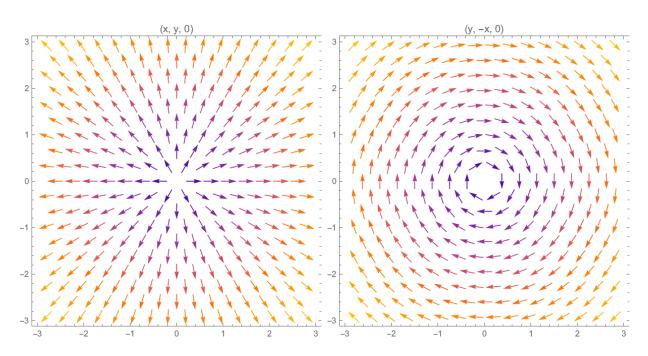
 $\mathbf{2}$

The area of the spherical cap subtended by a cone with half-angle α is given by:

$$A = \int_0^{2\pi} \int_0^{\alpha} r^2 \sin\theta \, d\theta d\phi = (1 - \cos\alpha) 2\pi r^2$$
 (7)

so that the solid angle is $\Omega = 2\pi(1 - \cos \alpha)$.

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It is easy to calculate that

$$\nabla \cdot \mathbf{A} = 2, \quad \nabla \cdot \mathbf{B} = 0 \tag{8}$$

The curls are given by the matrix

$$\nabla \times \mathbf{A} = \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ x & y & 0 \end{pmatrix} = \mathbf{0}, \quad \nabla \times \mathbf{B} = \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ y & -x & 0 \end{pmatrix} = (0, 0, -2)^{\mathsf{T}}$$
(9)

A is a curl-free vector field (like an electric field), and B is a divergence-free vector field (like a magnetic field).

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The curl of **A** is:

$$\nabla \times \mathbf{A} = \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ y & -x & z \end{pmatrix} = (0, 0, -2)^{\mathsf{T}}$$
(10)

The area integral of the curl on the hemisphere is given by:

$$\int_{S} (\nabla \times \mathbf{A}) \cdot d\mathbf{a} = -2 \int_{S} da_{z} = -2\pi$$
(11)

The curve C bounding the hemisphere is given by $\{(r, \theta, 0)|r = 1, \theta \in [0, 2\pi]\}$. The line integral of **A** along the curve is given by:

$$\int_C \mathbf{A} \cdot d\mathbf{l} = \int_0^{2\pi} -r^2 \sin^2 \theta - r^2 \cos^2 \theta \, d\theta = -2\pi \tag{12}$$

as expected from Stokes' theorem.

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Still using polar coordinates, the line integral is given by:

$$\int_{C} \mathbf{A} \cdot d\mathbf{l} = \int_{0}^{2\pi} -r \sin^{2}\theta - (3 + r \cos\theta) \cos\theta \, d\theta = -2\pi r = -2\sqrt{2}\pi \tag{13}$$

$$\int_{C} \mathbf{A} \cdot d\mathbf{l} = \int_{0}^{2\pi} -r^{2} \sin^{2} \theta + (3 + r \cos \theta) r \cos \theta d\theta = -4\pi$$
 (14)

Operating in cylindrical coordinates, a point at radius r has the velocity $\mathbf{v} = \omega r \hat{\phi}$. The divergence and curl of \mathbf{v} are:

$$\nabla \cdot \mathbf{v} = 0, \quad \nabla \times \mathbf{v} = 2\omega \hat{z} \tag{15}$$

 \mathbf{v} being divergence-free means that the 'flow' is purely rotational, so a particle cannot change its r as expected from a rigid body. The flow cannot be represented by a potential field, as the curl is non-zero.

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$$\nabla \times (\nabla \phi) = \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ \phi_x & \phi_y & \phi_z \end{pmatrix} = \mathbf{0}$$
 (16)

as the double partial derivatives cancel.

$$\nabla \cdot (\nabla \times \mathbf{A}) = \nabla \cdot \begin{pmatrix} \partial A_z / \partial y - \partial A_y / \partial z \\ \partial A_x / \partial z - \partial A_z / \partial x \\ \partial A_y / \partial x - \partial A_x / \partial y \end{pmatrix} = 0$$
 (17)

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First express $d\mathbf{r}$ in terms of dt:

$$\mathbf{dr} = (2t, 2, 2t^2)^{\mathsf{T}} \mathbf{d}t \tag{18}$$

The line integrals are given by:

$$\int_{C} \phi \, d\mathbf{r} = \int_{0}^{1} 4t^{9} (2t, 2, 2t^{2})^{\mathsf{T}} \, d\mathbf{r} = (8/11, 8/10, 8/12)^{\mathsf{T}}$$
(19)

$$\int_{C} \mathbf{F} \times d\mathbf{r} = \int_{0}^{1} 2(-t^{4} - t^{5}, -t^{5}, 2t^{3} + t^{4})^{\mathsf{T}} d\mathbf{r} = (-11/15, -1/3, 7/5)^{\mathsf{T}}$$
(20)

$$a_{i}b_{j}c_{i} = (\mathbf{a} \cdot \mathbf{c})\mathbf{b}$$

$$a_{i}b_{j}c_{j}d_{i} = (\mathbf{a} \cdot \mathbf{d})(\mathbf{b} \cdot \mathbf{c})$$

$$\delta_{ij}a_{i}a_{j} = \mathbf{a} \cdot \mathbf{a}$$

$$\delta_{ij}\delta_{ij} = 1$$

$$\epsilon_{ijk}a_{i}b_{k} = \mathbf{b} \times \mathbf{a}$$

$$\epsilon_{ijk}\delta_{ij} = 0$$

$$(21)$$

$$\delta_{ij}\delta_{ij} = \delta_{ii} = 3 \tag{22}$$

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$$\nabla r^{n} = \sum_{i} \frac{\partial}{\partial x_{i}} \left(\sum_{j} x_{j} \right)^{n/2} \hat{e}_{i}$$

$$= \sum_{i} \frac{n}{2} \left(\sum_{j} x_{j} \right)^{n/2-1} \frac{\partial \sum_{j} x_{j}^{2}}{\partial x_{i}} \hat{e}_{i}$$

$$= \sum_{i} \frac{n}{2} \left(\sum_{j} x_{j} \right)^{n/2-1} 2x_{i} \hat{e}_{i}$$

$$= nr^{n-2} \mathbf{r}$$

$$= nr^{n-1} \hat{r}$$

$$(23)$$

$$\nabla(\mathbf{a} \cdot \mathbf{r}) = \sum_{i} \frac{\partial}{\partial x_{i}} \left(\sum_{j} a_{j} x_{j} \right) \hat{e}_{i} = \sum_{i} a_{i} \hat{e}_{i} = \mathbf{a}$$
 (24)

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(a)
$$\nabla \cdot \mathbf{r} = \partial_{x_i} x_i = 3 \tag{25}$$

$$\nabla \times \mathbf{r} = \epsilon_{ijk} \partial_{x_i} x_k \hat{e}_i = \mathbf{0} \tag{26}$$

(b)

$$\nabla \cdot (r^n \mathbf{r}) = \sum_i \partial_{x_i} \left[\left(\sum_j x_j^2 \right)^{n/2} x_i \right]$$

$$= \sum_i \left(\sum_j x_j^2 \right)^{n/2} + x_i \frac{n}{2} \left(\sum_j x_j^2 \right)^{n/2 - 1} 2x_i$$

$$= r^n + nr^{n - 1}$$
(27)

$$\nabla \cdot (r^n \mathbf{r}) = \sum_i \partial_{x_i} \left[\left(\sum x_j^2 \right)^{n/2} x_i \right]$$

$$= \sum_i \left(\sum x_j^2 \right)^{n/2} + x_i \frac{n}{2} \left(\sum x_j^2 \right)^{n/2-1} 2x_i$$

$$= 3r^n + nr^n$$

$$= (3+n)r^n$$
(28)

$$\nabla \times (r^n \mathbf{r}) = \epsilon_{ijk} \partial_{x_i} (r^n x_k) \hat{e}_i = \epsilon_{ijk} r^{n-1} n x_j x_k \hat{e}_i = n r^{n-2} (\mathbf{r} \times \mathbf{r}) = \mathbf{0}$$
(29)

(c)
$$\nabla \cdot [(\mathbf{a} \cdot \mathbf{r})\mathbf{b}] = \sum_{i} \partial_{x_{i}} \left(\sum_{j} a_{j} x_{j} \right) b_{i} = \sum_{i} a_{i} b_{i} = \mathbf{a} \cdot \mathbf{b}$$
 (30)

$$\nabla \times [(\mathbf{a} \cdot \mathbf{r})\mathbf{b}] = \epsilon_{ijk} \partial_{x_j} \left(\sum_{l} a_l x_l \right) b_k \hat{e}_i = \epsilon_{ijk} \delta_{lj} a l b_k \hat{e}_i = \mathbf{a} \times \mathbf{b}$$
 (31)

(d)
$$\nabla \cdot (\mathbf{a} \times \mathbf{r}) = \partial_{x_i} \epsilon_{ijk} a_j x_k = 0$$
 (32)

$$\nabla \times (\mathbf{a} \times \mathbf{r}) = \epsilon_{ijk} \partial_{x_j} (\epsilon_{klm} a_l x_m) \hat{e}_i = \epsilon_{kji} \epsilon_{klm} a_l \delta_{mj} \hat{e}_i = \delta_{il} \delta_{jm} a_l \delta_{mj} \hat{e}_i - \delta_{im} \delta_{jl} a_l \delta_{mj} \hat{e}_i = \mathbf{a}$$
 (33)

$$\nabla \times (\mathbf{a} \times \mathbf{r}) = \delta_{il} \delta_{im} a_l \delta_{mj} \hat{e}_i - \delta_{im} \delta_{jl} a_l \delta_{mj} \hat{e}_i = 3a_i \hat{e}_i - a_i \hat{e}_i = 2\mathbf{a}$$
(34)

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$$\nabla \times (\nabla \phi) = \nabla \times (\partial_{x_i} \phi_i \mathbf{e}_i) = \epsilon_{ijk} \partial_{x_j} \partial_{x_k} \phi_k \mathbf{e}_i$$
(35)

Note that $\epsilon_{ijk}\partial_{x_j}\partial_{x_k} = \epsilon_{ikj}\partial_{x_k}\partial_{x_j} = -\epsilon_{ikj}\partial_{x_k}\partial_{x_j} = 0$. Therefore, $\nabla \times (\nabla \phi) = \mathbf{0}$.

$$\nabla \cdot (\nabla \times \mathbf{A}) = \nabla \cdot (\epsilon_{ijk} \partial_{x_j} A_k \mathbf{e}_i) = \epsilon_{ijk} \partial_{x_i} \partial_{x_j} A_k = 0$$
(36)