

Vectors & Matrices

Problem Set 3

Scalar Products and Determinants

Xin, Wenkang

November 15, 2022

Scalar products and determinants

1

(a)

$$\det(A) = i(1) + i(-1) = 0 \quad (1)$$

The matrix is antisymmetric, singular and Hermitian.

(b)

$$\det(A) = \frac{1}{\sqrt{8}} \left[2(\sqrt{2} + \sqrt{18}) + 2(\sqrt{18} + \sqrt{2}) \right] = 8 \quad (2)$$

$$\det(A) = \frac{1}{\sqrt{8}^3} \left[2(\sqrt{2} + \sqrt{18}) + 2(\sqrt{18} + \sqrt{2}) \right] = 1 \quad (3)$$

The matrix is real and orthogonal/unitary/Hermitian.

2

We first have:

$$\mathbf{e}_1 = \frac{\mathbf{v}_1}{|\mathbf{v}_1|} = \frac{1}{\sqrt{2}}(1, 1, 0)^\top \quad (4)$$

Then \mathbf{v}_2 minus its component along \mathbf{e}_1 is:

$$\mathbf{v}'_2 = \mathbf{v}_2 - (\mathbf{v}_2 \cdot \mathbf{e}_1)\mathbf{e}_1 = (1/2, -1/2, 2)^\top \quad (5)$$

Then:

$$\mathbf{e}_2 = \frac{\mathbf{v}_2}{|\mathbf{v}_2|} = \frac{1}{3\sqrt{2}}(1, -1, 4)^\top \quad (6)$$

And:

$$\begin{aligned} \mathbf{v}'_3 &= \mathbf{v}_3 - (\mathbf{v}_3 \cdot \mathbf{e}_1)\mathbf{e}_1 - (\mathbf{v}_3 \cdot \mathbf{e}_2)\mathbf{e}_2 = (-2/3, 2/3, 1/3)^\top \\ \mathbf{e}_3 &= \frac{\mathbf{v}_3}{|\mathbf{v}_3|} = \frac{1}{3}(-2, 2, 1)^\top \end{aligned} \quad (7)$$

Note that:

$$\begin{aligned}
\mathbf{e}_1 \cdot \mathbf{e}_2 &= \frac{1}{\sqrt{2}} \frac{1}{3\sqrt{2}} (1, 1, 0)^\top \cdot (1, -1, 4)^\top = 0 \\
\mathbf{e}_1 \cdot \mathbf{e}_3 &= \frac{1}{\sqrt{2}} \frac{1}{3} (1, 1, 0)^\top \cdot (-2, 2, 1)^\top = 0 \\
\mathbf{e}_2 \cdot \mathbf{e}_3 &= \frac{1}{3\sqrt{2}} \frac{1}{3} (1, -1, 4)^\top \cdot (-2, 2, 1)^\top = 0
\end{aligned} \tag{8}$$

•

3

(a) This is because $A^{-1} = \text{adj}(A)/\det(A)$ and if $\det(A) = 0$, then A^{-1} is not defined.

(b)

$$\det(A) = a(ba - 1) - (a + a) = a(ab - 3) \tag{9}$$

Thus, the matrix is not invertible if $a = 0$ or $ab = 3$.

•

4

(a) Note that:

$$\langle \mathbf{w}, \mathbf{v}_a \rangle = \sum_{i=1}^n w_i v_{ai} = \sum_{i=1}^n \det(\mathbf{v}_1, \dots, \mathbf{v}_{n-1}, \mathbf{e}_i) v_{ai} \tag{10}$$

But the expansion of \mathbf{v}_a is just $\mathbf{v}_a = \sum_{i=1}^n v_{ai} \mathbf{e}_i$. By the multilinear property of the determinant:

$$\langle \mathbf{w}, \mathbf{v}_a \rangle = \det(\mathbf{v}_1, \dots, \mathbf{v}_{n-1}, \mathbf{v}_a) = 0 \tag{11}$$

for any \mathbf{v}_a .

(b)

$$\begin{aligned}
\det(\mathbf{v}_1, \dots, \mathbf{v}_{n-1}, \mathbf{n}) &= \frac{1}{|\mathbf{w}|} \det(\mathbf{v}_1, \dots, \mathbf{v}_{n-1}, \mathbf{w}) \\
&= \frac{1}{|\mathbf{w}|} \sum_{i=1}^n \det(\mathbf{v}_1, \dots, \mathbf{v}_{n-1}, \mathbf{e}_i) w_i \\
&= \frac{1}{|\mathbf{w}|} \sum_{i=1}^n w_i^2 \\
&= |\mathbf{w}|
\end{aligned} \tag{12}$$

(c)

$$w_i = \det(\mathbf{e}_1, \dots, \mathbf{e}_{n-1}, \mathbf{e}_i) \tag{13}$$

which is zero for $i \neq n$ and unity for $i = n$.

Thus, $\mathbf{w} = \mathbf{e}_n$.

(d) Explicitly writing the components of \mathbf{w} :

$$w_1 = \det(\mathbf{v}_1, \mathbf{v}_2, \mathbf{e}_1) = \det \begin{pmatrix} x_1 & x_2 & 1 \\ y_1 & y_2 & 0 \\ z_1 & z_2 & 0 \end{pmatrix} = y_1 z_2 - y_2 z_1 \tag{14}$$

$$w_2 = \det(\mathbf{v}_1, \mathbf{v}_2, \mathbf{e}_2) = \det \begin{pmatrix} x_1 & x_2 & 0 \\ y_1 & y_2 & 1 \\ z_1 & z_2 & 0 \end{pmatrix} = z_1 x_2 - z_2 x_1 \tag{15}$$

$$w_3 = \det(\mathbf{v}_1, \mathbf{v}_2, \mathbf{e}_3) = \det \begin{pmatrix} x_1 & x_2 & 0 \\ y_1 & y_2 & 0 \\ z_1 & z_2 & 1 \end{pmatrix} = x_1 y_2 - x_2 y_1 \tag{16}$$

Hence, $\mathbf{w} = \mathbf{v}_1 \times \mathbf{v}_2$.

•

5

(a)

$$A^{-1} = \frac{1}{\det(A)} \operatorname{adj}(A) = \frac{1}{2} \begin{pmatrix} 1 & 1 & -2 \\ -7 & 1 & 4 \\ 5 & -1 & -2 \end{pmatrix} = \begin{pmatrix} 1/2 & 1/2 & -1 \\ -7/2 & 1/2 & 2 \\ 5/2 & -1/2 & -1 \end{pmatrix} \tag{17}$$

$$X = A^{-1}B = \begin{pmatrix} 1/2 & 1/2 & -1 \\ -7/2 & 1/2 & 2 \\ 5/2 & -1/2 & -1 \end{pmatrix} \begin{pmatrix} 2 & 4 & 6 \end{pmatrix} = (-3, 7, -3)^\top \quad (18)$$

(b)

$$x_1 = \det \begin{pmatrix} 2 & 2 & 3 \\ 4 & 4 & 5 \\ 6 & 3 & 4 \end{pmatrix} / \det(A) = -3 \quad (19)$$

$$x_2 = \det \begin{pmatrix} 1 & 2 & 3 \\ 3 & 4 & 5 \\ 1 & 6 & 4 \end{pmatrix} / \det(A) = 7 \quad (20)$$

$$x_3 = \det \begin{pmatrix} 1 & 3 & 2 \\ 3 & 5 & 4 \\ 1 & 4 & 6 \end{pmatrix} / \det(A) = -3 \quad (21)$$

(c)

$$\left(\begin{array}{ccc|c} 1 & 2 & 3 & 2 \\ 3 & 4 & 5 & 4 \\ 1 & 3 & 4 & 6 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 4/3 & 5/3 & 4/3 \\ 0 & 1 & 7/5 & 14/5 \\ 0 & 0 & 1 & -3 \end{array} \right) \quad (22)$$

Therefore:

$$X = (-3, 7, -3)^\top \quad (23)$$

The row reduction method is least computationally demanding as only addition and subtraction operations are required.

•

6

(a) Note that:

$$\langle f, g \rangle = \int_{-\infty}^{\infty} e^{-x^2} f(x) g(x) \, dx = \int_{-\infty}^{\infty} e^{-x^2} g(x) f(x) \, dx = \langle g, f \rangle \quad (24)$$

$$\langle f, \alpha g + \beta h \rangle = \int_{-\infty}^{\infty} e^{-x^2} f(x) [\alpha g(x) + \beta h(x)] \, dx = \alpha \langle f, g \rangle + \beta \langle f, h \rangle \quad (25)$$

$$\langle f, f \rangle = \int_{-\infty}^{\infty} e^{-x^2} f(x) f(x) \, dx = \int_{-\infty}^{\infty} e^{-x^2} f(x)^2 \, dx \geq 0 \quad (26)$$

$$\langle f, f \rangle = 0 \implies f(x) = 0 \quad \forall x \quad (27)$$

Therefore, $\langle f, g \rangle$ is a scalar product.

(b)

$$\langle p_0, p_1 \rangle = \int_{-\infty}^{\infty} e^{-x^2} \frac{2}{n_0 n_1} dx = 0 \quad (28)$$

as this is an odd function.

Further:

$$\langle p_0, p_2 \rangle = \int_{-\infty}^{\infty} e^{-x^2} \frac{2}{n_0 n_2} (4x^2 - 2) dx = \frac{2}{n_0 n_2} \left[-e^{x^2} x \right]_{-\infty}^{\infty} = 0 \quad (29)$$

and:

$$\langle p_1, p_2 \rangle = \int_{-\infty}^{\infty} e^{-x^2} \frac{2}{n_1 n_2} 2x(4x^2 - 2) dx = 0 \quad (30)$$

as this is an odd function.

Hence, p_i are orthogonal under the defined scalar product.

(c)

$$\langle p_0, p_0 \rangle = \int_{-\infty}^{\infty} e^{-x^2} \frac{1}{n_0^2} dx = \frac{1}{n_0^2} \sqrt{\pi} = 1 \quad (31)$$

so $n_0 = \pi^{1/4}$.

$$\langle p_1, p_1 \rangle = \int_{-\infty}^{\infty} e^{-x^2} \frac{4}{n_1^2} x^2 dx = \frac{2}{n_1^2} \sqrt{\pi} = 1 \quad (32)$$

so $n_1 = \sqrt{2}\pi^{1/4}$.

$$\langle p_2, p_2 \rangle = \int_{-\infty}^{\infty} e^{-x^2} \frac{1}{n_2^2} (4x^2 - 2)^2 dx = \frac{8}{n_2^2} \sqrt{\pi} = 1 \quad (33)$$

so $n_2 = 2\sqrt{2}\pi^{1/4}$.

•

7

(a) Consider the equation $\mathbf{0} = \sum_i^k a_i \mathbf{w}_i$. Taking a scalar product of both sides with an arbitrary vector \mathbf{v} gives:

$$\begin{aligned}\langle \mathbf{v}, \mathbf{0} \rangle &= \left\langle \mathbf{v}, \sum_i^k a_i \mathbf{w}_i \right\rangle \\ \sum_i^k a_i \langle \mathbf{v}, \mathbf{w}_i \rangle &= 0\end{aligned}\tag{34}$$

As \mathbf{v} is arbitrary, we can choose $\mathbf{v} = \mathbf{w}_j$ for some j . As \mathbf{w}_i are orthogonal and non-zero:

$$\sum_i^k a_i \langle \mathbf{w}_j, \mathbf{w}_i \rangle = a_j \langle \mathbf{w}_j, \mathbf{w}_j \rangle = 0\tag{35}$$

where $\langle \mathbf{w}_j, \mathbf{w}_j \rangle > 0$.

This implies $a_j = 0$ for all j . There is therefore only the trivial solution to the equation, and vectors \mathbf{w}_i are linearly independent.

(b)

$$\langle \mathbf{e}_i, \mathbf{v} \rangle = \langle \mathbf{e}_i, v_j \mathbf{e}_j \rangle = v_j \langle \mathbf{e}_i, \mathbf{e}_j \rangle = \delta_{ij} v_j = v_i\tag{36}$$

(c)

$$\langle \mathbf{u}, \mathbf{v} \rangle = \langle \mathbf{u}, v_i \mathbf{e}_i \rangle = v_i \langle \mathbf{u}, \mathbf{e}_i \rangle = \langle \mathbf{u}, \mathbf{e}_i \rangle \langle \mathbf{e}_i, \mathbf{v} \rangle\tag{37}$$

(d)

$$\langle \mathbf{e}_i, \mathbf{e}'_j \rangle = \langle \mathbf{e}_i, U_{kj} \mathbf{e}_k \rangle = U_{kj} \delta_{ik} = U_{ij}\tag{38}$$

Consider the product $U^\dagger U$:

$$(U^\dagger U)_{ij} = U_{ik}^\dagger U_{kj} = U_{ki}^* U_{kj} = \langle \mathbf{e}_k, \mathbf{e}_i \rangle^* \langle \mathbf{e}_k, \mathbf{e}_j \rangle = \langle \mathbf{e}'_i, \mathbf{e}_k \rangle \langle \mathbf{e}_k, \mathbf{e}'_j \rangle = \langle \mathbf{e}'_i, \mathbf{e}'_j \rangle = \delta_{ij}\tag{39}$$

This shows that U is unitary.

•

8

(a) We have:

$$\langle R\mathbf{v}, R\mathbf{w} \rangle = (R\mathbf{v})^\top R\mathbf{w} = \mathbf{v}^\top R^\top R\mathbf{w} = \mathbf{v}^\top \mathbf{w}\tag{40}$$

For this equation to be valid, $R^\top R = I$. Further note that:

$$\det(R^\top R) = \det(R)^2 = \det(I) = 1\tag{41}$$

so $\det(R) = \pm 1$.

(b) Let the matrix have the form:

$$R = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad (42)$$

We have:

$$\begin{aligned} R^T R &= \begin{pmatrix} a^2 + c^2 & ab + cd \\ ab + cd & b^2 + d^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ a^2 + c^2 &= b^2 + d^2 = 1 \\ ab + cd &= 0 \end{aligned} \quad (43)$$

We immediately have $c = \pm\sqrt{1-a^2}$ and $d = \pm\sqrt{1-b^2}$ from the first equation. Then from the second equation:

$$\begin{aligned} ab + cd &= ab \pm \sqrt{1-a^2}\sqrt{1-b^2} = 0 \\ a^2 b^2 &= (1-a^2)(1-b^2) \\ a^2 + b^2 &= 1 \end{aligned} \quad (44)$$

Then we can rewrite R :

$$R = \begin{pmatrix} a & \pm\sqrt{1-a^2} \\ \sqrt{1-a^2} & \mp a \end{pmatrix} \quad (45)$$

Now we make the substitution $a = \cos \phi$, and we have:

$$R = \begin{pmatrix} \cos \phi & \sin \phi \\ -\sin \phi & \cos \phi \end{pmatrix} \quad (46)$$

The lower sign ($-\sin \phi$ and $+\cos \phi$) corresponds to two-dimensional rotations; the other sign represents the case where $\det(R) = -1$, which corresponds to a rotation followed by a reflection.

(c)

$$\begin{aligned}
R(\phi_1)R(\phi_2) &= \begin{pmatrix} \cos \phi_1 & -\sin \phi_1 \\ \sin \phi_1 & \cos \phi_1 \end{pmatrix} \begin{pmatrix} \cos \phi_2 & -\sin \phi_2 \\ \sin \phi_2 & \cos \phi_2 \end{pmatrix} \\
&= \begin{pmatrix} \cos \phi_1 \cos \phi_2 - \sin \phi_1 \sin \phi_2 & -\sin \phi_1 \cos \phi_2 - \cos \phi_1 \sin \phi_2 \\ \sin \phi_1 \cos \phi_2 + \cos \phi_1 \sin \phi_2 & \cos \phi_1 \cos \phi_2 + \sin \phi_1 \sin \phi_2 \end{pmatrix} \\
&= R(\phi_1 + \phi_2)
\end{aligned} \tag{47}$$

(d) Let $z = Ae^{i\alpha}$, then $z' = Ae^{i(\alpha+\phi)}$.

•

9

(a) By analogy and symmetry, we have:

$$R_1(\phi) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \phi & -\sin \phi \\ 0 & \sin \phi & \cos \phi \end{pmatrix} \tag{48}$$

and:

$$R_2(\phi) = \begin{pmatrix} \cos \phi & 0 & \sin \phi \\ 0 & 1 & 0 \\ -\sin \phi & 0 & \cos \phi \end{pmatrix} \tag{49}$$

Then:

$$\begin{aligned}
R &= R_1(\alpha_3)R_2(-\alpha_2)R_3(\alpha_1) \\
&= \begin{pmatrix} \cos \alpha_2 \cos \alpha_3 & \sin \alpha_1 \sin \alpha_2 \cos \alpha_3 - \cos \alpha_1 \sin \alpha_3 & \cos \alpha_1 \sin \alpha_2 \cos \alpha_3 + \sin \alpha_1 \sin \alpha_3 \\ \cos \alpha_2 \sin \alpha_3 & \sin \alpha_1 \sin \alpha_2 \sin \alpha_3 + \cos \alpha_1 \cos \alpha_3 & \cos \alpha_1 \sin \alpha_2 \sin \alpha_3 - \sin \alpha_1 \cos \alpha_3 \\ -\sin \alpha_2 & \sin \alpha_1 \cos \alpha_2 & \cos \alpha_1 \cos \alpha_2 \end{pmatrix}
\end{aligned} \tag{50}$$

(b) For small α_i :

$$R = \begin{pmatrix} 1 & -\alpha_3 & \alpha_2 \\ 1 & 1 & -\alpha_1 \\ -\alpha_2 & \alpha_1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \alpha_1 \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} + \alpha_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix} + \alpha_3 \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \tag{51}$$

(c)

$$\delta \mathbf{x} = R\mathbf{x} - \mathbf{x} \approx \begin{pmatrix} 0 & -\alpha_3 & \alpha_2 \\ \alpha_3 & 0 & -\alpha_1 \\ -\alpha_2 & \alpha_1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \alpha_2 x_3 - \alpha_3 x_2 \\ \alpha_3 x_1 - \alpha_1 x_3 \\ \alpha_1 x_2 - \alpha_2 x_1 \end{pmatrix} = \alpha \times \mathbf{x} \quad (52)$$

•

10

(a) This is because if $\mathbf{w} = I$, then $\langle \mathbf{v}, \mathbf{w} \rangle = \mathbf{0}$ for all \mathbf{v} .

(b) We have:

$$\langle \Lambda \mathbf{v}, \Lambda \mathbf{w} \rangle = (\Lambda \mathbf{v})^\top \eta \Lambda \mathbf{w} = \mathbf{v}^\top (\Lambda^\top \eta \Lambda) \mathbf{w} = \mathbf{v}^\top \eta \mathbf{w} \quad (53)$$

Then:

$$\Lambda^\top \eta \Lambda = \eta \quad (54)$$

Since $\det(\eta) = 1$:

$$\det(\Lambda^\top \eta \Lambda) = \det(\Lambda)^2 = 1 \quad (55)$$

Thus, $\det\{\Lambda\} = \pm 1$.(c) Suppose that Λ has the form:

$$\Lambda = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad (56)$$

From $\Lambda^\top \eta \Lambda = \eta$ and $\det\{\Lambda\} = 1$, we have:

$$\begin{aligned} a^2 - c^2 &= d^2 - b^2 = 1 \\ ab - cd &= 0 \\ ac - bd &= 1 \end{aligned} \quad (57)$$

We immediately have $c = \pm\sqrt{a^2 - 1}$ and $d = \pm\sqrt{b^2 + 1}$ from the first equation. Then from the second equation:

$$\begin{aligned}
ab - cd &= ab \pm \sqrt{a^2 - 1}\sqrt{b^2 + 1} = 0 \\
a^2b^2 &= (a^2 - 1)(b^2 + 1) \\
a^2 - b^2 &= 1
\end{aligned} \tag{58}$$

Then we can rewrite Λ :

$$\Lambda = \begin{pmatrix} a & \sqrt{a^2 - 1} \\ \sqrt{a^2 - 1} & a \end{pmatrix} \tag{59}$$

Now we make the substitution $a = \cosh \phi$, and we have:

$$\Lambda = \begin{pmatrix} \cosh \phi & \sinh \phi \\ \sinh \phi & \cosh \phi \end{pmatrix} = \sqrt{\frac{1}{1 - \beta^2}} \begin{pmatrix} 1 & \beta \\ \beta & 1 \end{pmatrix} \tag{60}$$

where $\beta \equiv \tanh \phi$.

(d) We have:

$$\begin{aligned}
\Lambda(\phi_1)\Lambda(\phi_2) &= \begin{pmatrix} \cosh \phi_1 & \sinh \phi_1 \\ \sinh \phi_1 & \cosh \phi_1 \end{pmatrix} \begin{pmatrix} \cosh \phi_2 & \sinh \phi_2 \\ \sinh \phi_2 & \cosh \phi_2 \end{pmatrix} \\
&= \begin{pmatrix} \cosh \phi_1 \cosh \phi_2 - \sinh \phi_1 \sinh \phi_2 & \cosh \phi_1 \sinh \phi_2 + \sinh \phi_1 \cosh \phi_2 \\ \cosh \phi_1 \sinh \phi_2 + \sinh \phi_1 \cosh \phi_2 & \cosh \phi_1 \cosh \phi_2 + \sinh \phi_1 \sinh \phi_2 \end{pmatrix} \\
&= \Lambda(\phi_1 + \phi_2)
\end{aligned} \tag{61}$$

This means:

$$\begin{aligned}
\Lambda(\beta_1)\Lambda(\beta_2) &= \Lambda(\beta) \\
\frac{1}{\sqrt{1 - \beta_1^2}\sqrt{1 - \beta_2^2}} \begin{pmatrix} 1 + \beta_1\beta_2 & \beta_1 + \beta_2 \\ \beta_1 + \beta_2 & 1 + \beta_1\beta_2 \end{pmatrix} &= \frac{1}{\sqrt{1 - \beta^2}} \begin{pmatrix} 1 & \beta \\ \beta & 1 \end{pmatrix}
\end{aligned} \tag{62}$$

Solving this leads to the relationship:

$$\beta = \frac{\beta_1 + \beta_2}{1 + \beta_1\beta_2} \tag{63}$$

which is the angle sum formula for hyperbolic tangent.

•