

ROS Guide for Walking Machine

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Chapter 1

Introduction

Welcome to the Walking Machine ROS guide. This guide was build to help new recruits learn ROS. The bases of our robot is ROS which stands for "Robot Operating System" which is develop by the open-source robotics foundation. At the time of writing the current Long Term Release is Kinetic Kame.

Our Robot S.A.R.A. was build at École de Technologie Supérieur at Montréal Québec Canada by Walking Machine. The acronym S.A.R.A. means Système d'Assistance Robotique Autonome.

Chapter 2

Installing ROS

