```
#include "mpi.h"
1
    #include "Definitions.h"
2
3
    #include "MeshUtilities.h"
    #include "Quadrature.h"
4
    #include "PostProcessorVtk.h"
5
    #include "ElementTests.h"
6
7
8
    #include "MaterialModelNeoHookean.h"
    #include "ElementTypes.h"
9
10
    #include "Wall.h"
11
12
    #include "IsoparametricElement.h"
    #include "Assembler.h"
13
    #include "SolverImplicit.h"
14
15
    const unsigned int
16
                              Spatial Dimension = 3;
17
    const unsigned int
                              DegreesOfFreedom = 3;
18
    const unsigned int numberOfQuadraturePoints = 1;
19
20
    typedef MaterialModels::NeoHookean<SpatialDimension>
                                                                     MaterialModel;
21
22
    typedef ElementTypes::Simplex<SpatialDimension>
                                                                      ElementType;
23
    typedef Elements::IsoparametricElement<MaterialModel,</pre>
24
                                          numberOfQuadraturePoints,
                                          ElementType,
25
                                          DegreesOfFreedom>
                                                                      Element;
2.6
27
                                                                      ElementProperties;
    typedef Element::Properties
28
    typedef Element::Node
                                                                     Node;
29
    typedef Element::Vector
                                                                      Vector;
30
    typedef Element::Point
                                                                     Point;
31
    typedef Element::Stress
                                                                      Stress;
32
    typedef Element::Strain
                                                                      Strain;
33
34
    typedef SingleElementMesh<Element>
                                                                     Mesh:
35
36
    typedef Element
                                                                      PhysicalElement;
37
    typedef Elements::ExternalForce::Wall<SpatialDimension,DegreesOfFreedom>
38
                                                                      ExternalElement;
39
    typedef Assembler<PhysicalElement>
                                                                      PhysicalAssembler;
40
    typedef Assembler<ExternalElement>
                                                                      ExternalAssembler:
41
    typedef SolverImplicitDynamics<PhysicalAssembler,ExternalAssembler</pre>
42
                                                   ,PhysicalAssembler> Solver;
43
44
45
    const unsigned int NumberOfNodesPerElement = Element::NumberOfNodes;
46
47
48
    int main(int arc, char *argv[]) {
49
50
      ignoreUnusedVariables(arc,argv);
51
        // The following lines simply create an output directory
52
53
      char sprintfBuffer[500];
54
      sprintf(sprintfBuffer, "Output_Main4");
      const string outputPath = string(sprintfBuffer);
55
56
57
      printf("Writing files to %s\n", outputPath.c_str());
58
      const bool createNewDirectories = true;
59
      Utilities::directoryCreator(outputPath, createNewDirectories, Quiet);
60
61
      %%%%%%%%%%%%%%%%%%%%
62
      63
      64
65
      // TODO: Create your materialModel
66
67
      // ...
68
      const double materialModelParameter0 = 5.0 * power(10,5);
69
      const double materialModelParameter1 = 5.0 * power(10,7);
70
71
      MaterialModel materialModel(materialModelParameter0,materialModelParameter1);
73
```

```
74
       // %%%%%%%%%%%%%%%% Problem 4) (ii) Creation of mesh
                                                                     8888888888888888888
 75
       88888888888888888888
 76
 77
       Mesh mesh;
 78
       MeshUtilities::readMeshFromFile("SphereTetMesh_002000.dat",&mesh);
 79
 80
       const size_t numberOfNodes
                                   = mesh._nodes.size();
 81
       const size_t numberOfElements = mesh._connectivity.size();
 82
 83
       //88888888888888888888888
 84
       //%%%%%%%%%%%%%%%%%%% Problem 4) (iii) Preliminary stuff for elements
 85
       86
       27
       // Create the element type and the element properties
 88
 29
       const double elementMultiplier = 1522;
 90
       ElementType elementType;
 91
       ElementProperties elementProperties(elementMultiplier);
 92
 93
       // Choose a quadrature rule
 94
       const QuadratureRule<Element::SpatialDimension, numberOfQuadraturePoints>
 95
       quadratureRule = Quadrature::buildSimplicialQuadrature<Element::SpatialDimension,
       numberOfQuadraturePoints>();
 96
 97
       ignoreUnusedVariables(elementType);
 98
       ignoreUnusedVariables(quadratureRule);
 99
100
       88888888888888888888888
       101
       102
                                                                    88888888888888888888888
103
104
       // Wall parameter
105
       const double wallStrength = 1.0*1.0e8;
106
       Vector wallOriginPosition = Vector::Zero(); wallOriginPosition (2) = +0.0;
107
       Vector wallNormalDirection= Vector::Zero(); wallNormalDirection(2) = -1.0;
108
109
       ignoreUnusedVariables(wallStrength);
110
111
       // TODO: Collect all external elements
112
       vector<ExternalElement> externalElements; externalElements.clear();
113
       for (unsigned int indexNode = 0; indexNode < numberOfElements /* TODO: set */;</pre>
       indexNode++){
114
115
          // Read out the nodes corresponding no the indexElement'th element
116
             array<Node,SpatialDimension+1> nodesSimplex;
117
             for (unsigned int indexNode = 0; indexNode < SpatialDimension+1; indexNode++)</pre>
118
119
                 nodesSimplex[indexNode] =
                 mesh._nodes[mesh._connectivity[indexElement][indexNode]];
120
             }
121
         Element simplexElement(nodesSimplex,
122
                               elementProperties,
                               elementType,
123
124
                             & quadratureRule,
125
                             & materialModel);
126
         // REMINDER: You can push new elements into a vector via the .push_back option
127
         externalElements.push_back(simplexElement);
128
       }
129
130
131
       // TODO:Collect all physical elements
132
       vector<PhysicalElement> physicalElements; physicalElements.clear();
133
       for (unsigned int indexElement = 0; indexElement < numberOfElements /* TODO: set</pre>
       */; indexElement++){
134
135
              // Read out the nodes corresponding no the indexElement'th element
136
             array<Node,SpatialDimension+1> nodesSimplex;
137
             for (unsigned int indexNode = 0; indexNode < SpatialDimension+1; indexNode++)</pre>
138
         {
139
                 nodesSimplex[indexNode] =
```

```
mesh._nodes[mesh._connectivity[indexElement][indexNode]];
140
           }
141
        Element simplexElement(nodesSimplex,
142
                          elementProperties,
143
                          elementType,
                         & quadratureRule,
144
145
                         & materialModel);
146
        // REMINDER: You can push new elements into a vector via the .push_back option
147
        physicalElements.push_back(simplexElement);
148
149
150
151
152
      //8888888888888888888888
                                                         153
      154
      155
156
      // TODO: Create assemblers corresponding to your physical and external elements
157
158
      // ...
159
        PhysicalAssembler physicalAssembler(physicalElements, numberOfNodes);
160
        ExternalAssembler externalAssembler(externalElements, numberOfNodes);
161
162
      //888888888888888888888888
                                                     88888888888888888888888
      163
164
      //88888888888888888888888
                                                     88888888888888888888888
165
166
      // TODO: Create an object of your SolverImplicitDynamics class
167
168
      // ...
169
170
      Solver solver(physicalAssembler,externalAssembler,physicalAssembler);
171
                                     = 1000 ;
172
      const unsigned int maxIterations
                                     = 1e-4 ;
173
      const double
                      tolerance
174
175
176
177
      178
      179
      180
181
      // TODO: Initiate all states that you need for your solver
182
      vector<Vector> currentNodalDisplacement(numberOfNodes, Vector::Zero());
183
      vector<Vector> currentNodalAcceleration(numberOfNodes, Vector::Zero());
184
185
      vector<Vector> currentNodalVelocity(numberOfNodes, Vector:: Vector:: Zero());
      // TODO: Impose the initial velocity
186
187
      for (unsigned int nodeIndex = 0; nodeIndex < numberOfNodes; nodeIndex++) {</pre>
188
         for (unsigned int dofIndex = 0; dofIndex < DegreesOfFreedom; dofIndex++) {</pre>
189
190
           if (dofIndex == 0){
191
              currentNodalVelocity[nodeIndex](dofIndex) = 0;
192
           }
193
           else if (dofIndex == 1){
194
              currentNodalVelocity[nodeIndex](dofIndex) = 0;
195
           }
196
           else if (dofIndex == 2){
197
              currentNodalVelocity[nodeIndex](dofIndex) = -10;
198
           }
199
         }
200
        }
201
2.02
      // Empty boundary conditions
2.03
      vector<EssentialBoundaryCondition> emptyEssentialBoundaryConditions;
204
      emptyEssentialBoundaryConditions.clear();
205
206
      207
      208
      209
```

```
// TODO: Chose the number of loadsteps
210
211
        const unsigned int numberOfLoadsteps = 100; // ...
212
213
        for (unsigned int loadstepIndex = 0; loadstepIndex < numberOfLoadsteps;</pre>
        loadstepIndex++){
2.14
215
          if (loadstepIndex % unsigned(1) == 0) {
216
            printf("\ntimestep %6u (%%%5.1f) at %s\n",
217
                     loadstepIndex,
                     100. * loadstepIndex / float(numberOfLoadsteps),
218
219
                     Utilities::getLocalTimeString().c_str());
220
          }
221
222
          // TODO: Call solver
223
224
225
          vector<Vector> displacements
226
             = solver.computeNewmarkUpdate(essentialBCs,
             currentNodalDisplacement,currentNodalVelocity,currentNodalAcceleration,
             maxIterations, tolerance, true);
227
228
          if (!(loadstepIndex%1)){
229
230
            printf("Giving output at loadstep (%d/%d).\n",loadstepIndex,numberOfLoadsteps);
231
232
            // TODO: define the following four vectors
233
                                                  (numberOfNodes
                                                                    ,Stress::Zero()); // ...
            const vector<Stress> nodeStresses
234
            const vector<Stress> elementStresses (numberOfElements,Stress::Zero()); // ...
235
            const vector<Strain> nodeStrains
                                                  (numberOfNodes
                                                                   ,Strain::Zero()); // ...
236
            const vector<Strain> elementStrains (numberOfElements,Stress::Zero()); // ...
237
              nodeStresses = assembler.computeElementStresses(displacements);
238
              elementStresses = assembler.computeNodalStresses (displacements);
239
              nodeStrains = assembler.computeElementStrains(displacements);
240
              elementStrains= assembler.computeNodalStrains(displacements);
2.41
242
243
            // !!! NOTHING TO BE DONE FROM HERE ONWARDS
            1.11
244
            sprintf(sprintfBuffer, "%s/WallImpact_%03u",outputPath.c_str(),loadstepIndex);
245
246
            PostProcessors::Vtk::NamedArrays<int,double> vtkNamedArrays;
247
            PostProcessors::Vtk::makeDeformedMeshFile<Element>( mesh,
248
                                                                  currentNodalDisplacement,
249
                                                                  nodeStresses,
250
                                                                  elementStresses,
251
                                                                  MaterialModel::getStressComp
                                                                  onentNames(),
252
                                                                  nodeStrains,
253
                                                                  elementStrains,
254
                                                                  MaterialModel::getStrainComp
                                                                  onentNames(),
255
                                                                  emptyEssentialBoundaryCondit
                                                                  ions,
256
                                                                  string(sprintfBuffer),
257
                                                                  vtkNamedArrays);
258
          }
259
260
        }
261
262
        return 0;
263
      }
264
```