

```

1  #ifndef ELEMENT_EXTERNAL_FORCE
2  #define ELEMENT_EXTERNAL_FORCE
3
4  #include "/src/Definitions.h"
5
6  namespace Elements {
7  namespace ExternalForce {
8
9  template <class Element, template<class> class NodeType = NodeWithId>
10 class ConstantBodyForce {
11
12 public:
13
14     static const unsigned int NumberOfNodes      = Element::NumberOfNodes;
15     static const unsigned int SpatialDimension    = Element::SpatialDimension;
16     static const unsigned int DegreesOfFreedom    = Element::SpatialDimension;
17
18     typedef Matrix<double, SpatialDimension, 1>      Point;
19     typedef NodeType<Point>                          Node;
20     typedef Matrix<double, DegreesOfFreedom, 1>      Vector;
21     typedef array<Vector, NumberOfNodes>              NodalDisplacements;
22     typedef Matrix<double,
23                     NumberOfNodes*DegreesOfFreedom,
24                     NumberOfNodes*DegreesOfFreedom>  StiffnessMatrix;
25     typedef array<Vector, NumberOfNodes>              Forces;
26
27     ConstantBodyForce(const Element & element
28                       , const Vector & bodyForceVector){
29
30         ignoreUnusedVariables(element);
31         ignoreUnusedVariables(bodyForceVector);
32
33         // TODO: Properly define _nodeIds based on information stored in element
34         //       as an array with NumberOfNodes entries of type size_t
35         // REMINDER: Public members of an object of a class can simply be accessed
36         //       via element._somePublicMember
37
38         _nodeIds = element._nodeIds;
39
40         // TODO: Based on the bar's mass, store the mass of each bar
41         //       in the array nodalWeights. Note, that all information needed
42         //       to obtain a bar's mass can be found in element (such as
43         //       element._properties._density or element._X0, element._X1, the
44         //       latter two of which can be used to evaluate the length of the
45         //       bar, as well as element._properties._area)
46         array<double,NumberOfNodes> nodalWeights;
47         for (unsigned int nodeIndex = 0; nodeIndex < NumberOfNodes; nodeIndex++) {
48             nodalWeights[nodeIndex] = element._properties._density *
49             element._properties._area * element._undeformedBarLength / 2;
50         }
51         //cout<<"nodalWeights is"<<nodalWeights<<endl;
52
53         // TODO: Compute _nodalForces, i.e the equivalent force on each node
54         //       resulting from gravitational loading (identical for all nodes)
55         //       based on bodyForceVector (g) and the mass (m) stored in
56         //       nodalWeights
57         // NOTE: _nodalForces is an array with NumberOfNodes entries of type Vector
58         for (unsigned int nodeIndex = 0; nodeIndex < NumberOfNodes; nodeIndex++) {
59             _nodalForces[nodeIndex] = Vector::Zero();
60             _nodalForces[nodeIndex] = nodalWeights[nodeIndex] * bodyForceVector;
61             //cout<<"_nodalForces is"<<_nodalForces[nodeIndex]<< endl;
62         }
63     }
64
65     double
66     computeEnergy(const NodalDisplacements & displacements) const {
67
68         //ignoreUnusedVariables(displacements);
69
70         double energy = 0.;
71
72

```

```

73     // TODO: Based on _nodalForces and displacements, evaluate the energy
74     for (unsigned int nodeIndex = 0; nodeIndex < NumberOfNodes; nodeIndex++) {
75         energy -= _nodalForces[nodeIndex] .dot(displacements[nodeIndex]);
76     }
77
78     return energy;
79
80 }
81
82 Forces
83 computeForces(const NodalDisplacements & displacements) const {
84
85     ignoreUnusedVariables(displacements);
86
87     Forces nodalForces;
88
89     // TODO: Evaluate/Set the nodalForces
90     // HINT: Easier than you may think...check your private variables...
91     // simply be cautious about the sign...
92     for (unsigned int nodeIndex = 0; nodeIndex < NumberOfNodes; nodeIndex++) {
93         nodalForces[nodeIndex] = Vector::Zero();
94         nodalForces[nodeIndex] -= _nodalForces[nodeIndex];
95     }
96
97     return nodalForces;
98
99 }
100
101 // Ignore this function, as you don't need it for now
102 array<size_t, NumberOfNodes>
103 getNodeIds() const {
104     return _nodeIds;
105 }
106
107 private:
108
109     array<Vector, NumberOfNodes> _nodalForces;
110     array<size_t, NumberOfNodes> _nodeIds;
111 };
112
113 }
114 }
115
116 #endif //ELEMENT_EXTERNAL_FORCE
117

```