view frames Result Recorded at time: 16.515 world Broadcaster: /robot_state_publisher | Broadcaster: /robot_state_publisher Broadcaster: /gazebo Average rate: 10000.0 Buffer length: 0.0 Average rate: $1000\overline{0}.0$ Average rate: 10.212 Buffer length: 4.896 Buffer length: 0.0 Most recent transform: 16.411 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 11.515 logical_camera1_link world interface robot frame Broadcaster: /robot_state_publisher Average rate: 10000.0 Buffer length: 0.0 Broadcaster: /robot_state_publisher | Broadcaster: /robot_state_publisher Broadcaster: /gazebo Broadcaster: /gazebo Broadcaster: /gazebo Average rate: 10000.0 Buffer length: 0.0 Average rate: 10000.0 Average rate: 10.212 Buffer length: 4.896 Average rate: 10.212 Average rate: 10.212 Buffer length: 4.896 Buffer length: 0.0 Buffer length: 4.896 Most recent transform: 16.411 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 16.411 Most recent transform: 16.411 Oldest transform: 0.0 Oldest transform: 11.515 Oldest transform: 11.515 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 11.515 robot ground plane frame camera_link fib14 panda_link0 robot_box_01_frame robot_Banana_frame $Broadcaster: /robot_state_publisher$ Broadcaster: /robot_state_publisher Average rate: 50.2 Average rate: 10000.0 Buffer length: 5.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 16.5 Oldest transform: 11.5 Oldest transform: 0.0 camera_link_optical panda_link1 Broadcaster: /robot_state_publisher Average rate: 50.2 Buffer length: 5.0 Most recent transform: 16.5 Oldest transform: 11.5 panda_link2 Broadcaster: /robot_state_publisher Average rate: $50.\overline{2}$ Buffer length: 5.0 Most recent transform: 16.5 Oldest transform: 11.5 panda_link3 Broadcaster: /robot state publisher Average rate: $50.\overline{2}$ Buffer length: 5.0 Most recent transform: 16.5 Oldest transform: 11.5 panda_link4 Broadcaster: /robot state publisher Average rate: 50.2 Buffer length: 5.0 Most recent transform: 16.5 Oldest transform: 11.5 panda_link5 Broadcaster: /robot_state_publisher Average rate: 50.2 Buffer length: 5.0 Most recent transform: 16.5 Oldest transform: 11.5 panda_link6 Broadcaster: /robot_state publisher Average rate: $50.\overline{2}$ Buffer length: 5.0 Most recent transform: 16.5 Oldest transform: 11.5 panda link7 Broadcaster: /robot_state_publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 panda link8 Broadcaster: /robot_state_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 panda hand Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $50.\overline{2}$ Average rate: $50.\overline{2}$ Buffer length: 5.0 Buffer length: 5.0 Most recent transform: 16.5 Most recent transform: 16.5 Oldest transform: 11.5 Oldest transform: 11.5 panda_rightfinger panda_leftfinger