

# Lecture 3

## Eigenvalue, Matrix Decomposition

- Motivation
- Eigenvalues and Eigenvectors
- Properties about Eigenvalues
- Eigenvalue Decomposition
- Singular Value Decomposition

# Contents

- Motivation
- Eigenvalues and Eigenvectors
- Properties about Eigenvalues
- Eigenvalue Decomposition
- Singular Value Decomposition

# Example

- In a certain town, 30% married men get divorced each year and 20% single men get married each year.
- There are 8000 married men and 2000 single men at the beginning.  
Assume the total population always remains constant.
- Let  $\mathbf{w}_0 = \begin{pmatrix} 8000 \\ 2000 \end{pmatrix}$  be the initial status, and  $\mathbf{w}_i$  denote the status after  $i$  years.
- What is the marital status when time goes to infinity? How about we change  $\mathbf{w}_0$ ?

# Example

- In a certain town, 30% married men get divorced each year and 20% single men get married each year.

- There are 8000 married men and 2000 single men at the beginning.

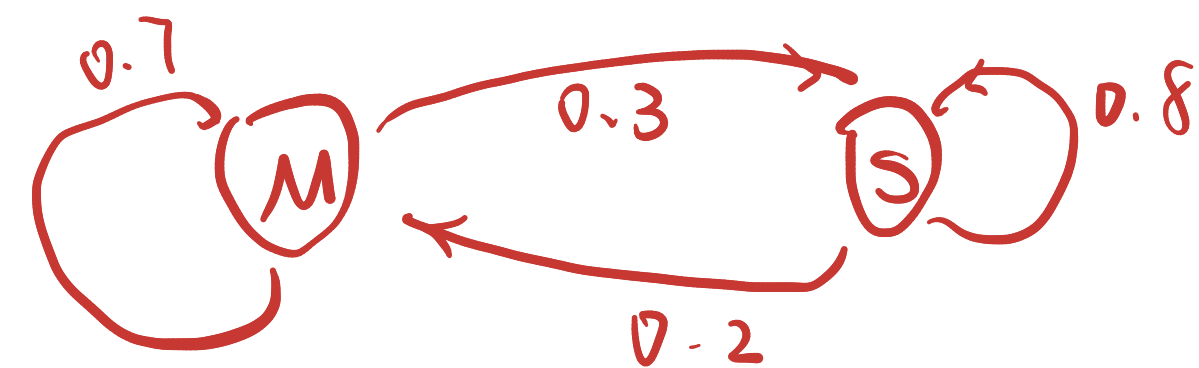
Assume the total population always remains constant.

- Let  $\mathbf{w}_0 = \begin{pmatrix} 8000 \\ 2000 \end{pmatrix}$  be the initial status, and  $\mathbf{w}_i$  denote the status after  $i$  years.

- What is the marital status when time goes to infinity? How about we change  $\mathbf{w}_0$ ?

# Example

- In a certain town, 30% married men get divorced each year and 20% single men get married each year.
- There are 8000 married men and 2000 single men at the beginning. Assume the total population always remains constant.
- Let  $\mathbf{w}_0 = \begin{pmatrix} 8000 \\ 2000 \end{pmatrix}$  be the initial status, and  $\mathbf{w}_i$  denote the status after  $i$  years.
- What is the marital status when time goes to infinity? How about we change  $\mathbf{w}_0$ ?



## Example

$$w^* = \begin{pmatrix} 4000 \\ 6000 \end{pmatrix}$$

$$Aw^* = w^*$$

- In a certain town, 30% married men get divorced each year and 20% single men get married each year.

- There are 8000 married men and 2000 single men at the beginning.

Assume the total population always remains constant.

- Let  $w_0 = \begin{pmatrix} 8000 \\ 2000 \end{pmatrix}$  be the initial status, and  $w_i$  denote the status after  $i$  years.

$$w_i = \begin{pmatrix} \text{Married after } i\text{-th year} \\ \text{Single after } i\text{-th year} \end{pmatrix} = \begin{pmatrix} 0.7 & 0.2 \\ 0.3 & 0.8 \end{pmatrix} w_{i-1}$$

- What is the marital status when time goes to infinity? How about we change  $w_0$ ?

$$\begin{aligned} w_t &= Aw_{t-1} = A^2 w_{t-2} \\ &= \dots = A^t w_0 \end{aligned}$$

$$\begin{aligned} &0.7 w_{i-1,1} + 0.2 w_{i-1,2} \\ &0.3 w_{i-1,1} + 0.8 w_{i-1,2} \end{aligned}$$

# Example

- Let

$$A = \begin{bmatrix} 0.7 & 0.2 \\ 0.3 & 0.8 \end{bmatrix}.$$

and  $\mathbf{w}_i = A\mathbf{w}_{i-1} = A^i\mathbf{w}_0$ .

- Using computer, we find  $\mathbf{w}_n \rightarrow \begin{pmatrix} 4000 \\ 6000 \end{pmatrix}$  as  $n \rightarrow \infty$ .
- We represent a general initial marital status as

$$\mathbf{w}_0 = x_1\mathbf{u}_1 + x_2\mathbf{u}_2, \text{ where } \mathbf{u}_1 = \begin{bmatrix} 0.4 \\ 0.6 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

We check that  $A\mathbf{u}_1 = \mathbf{u}_1$  and  $A\mathbf{u}_2 = 0.5\mathbf{u}_2$

- Then the marital status after  $n$  years is

$$A^n\mathbf{w}_0 = x_1A^n\mathbf{u}_1 + x_2A^n\mathbf{u}_2 = x_1\mathbf{u}_1 + x_20.5^n\mathbf{u}_2 \rightarrow x_1\mathbf{u}_1.$$

# Example

- Let

$$A = \begin{bmatrix} 0.7 & 0.2 \\ 0.3 & 0.8 \end{bmatrix}.$$

and  $\mathbf{w}_i = A\mathbf{w}_{i-1} = A^i\mathbf{w}_0$ .

- Using computer, we find  $\mathbf{w}_n \rightarrow \begin{pmatrix} 4000 \\ 6000 \end{pmatrix}$  as  $n \rightarrow \infty$ .

- We represent a general initial marital status as

$$\mathbf{w}_0 = x_1\mathbf{u}_1 + x_2\mathbf{u}_2, \text{ where } \mathbf{u}_1 = \begin{bmatrix} 0.4 \\ 0.6 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

We check that  $A\mathbf{u}_1 = \mathbf{u}_1$  and  $A\mathbf{u}_2 = 0.5\mathbf{u}_2$

- Then the marital status after  $n$  years is

$$A^n\mathbf{w}_0 = x_1A^n\mathbf{u}_1 + x_2A^n\mathbf{u}_2 = x_1\mathbf{u}_1 + x_20.5^n\mathbf{u}_2 \rightarrow x_1\mathbf{u}_1.$$



$$0.4x_1 + x_2 = 8000$$

$$0.6x_1 - x_2 = 2000$$

## Example

- Let

$$\Rightarrow x_1 = 10000$$

$$A = \begin{bmatrix} 0.7 & 0.2 \\ 0.3 & 0.8 \end{bmatrix}$$

$$A u_1 = \begin{pmatrix} 0.7 & 0.2 \\ 0.3 & 0.8 \end{pmatrix} \begin{pmatrix} 0.4 \\ 0.6 \end{pmatrix}$$

$$= \begin{pmatrix} 0.28 + 0.12 \\ 0.12 + 0.48 \end{pmatrix} = \begin{pmatrix} 0.4 \\ 0.6 \end{pmatrix}$$

$$\text{and } w_i = A w_{i-1} = A^i w_0.$$

- Using computer, we find  $w_n \rightarrow \begin{pmatrix} 4000 \\ 6000 \end{pmatrix}$  as  $n \rightarrow \infty$ .

$$A u_2 = \begin{pmatrix} 0.7 & 0.2 \\ 0.3 & 0.8 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$= \begin{pmatrix} 0.7 - 0.2 \\ 0.3 - 0.8 \end{pmatrix} = \begin{pmatrix} 0.5 \\ -0.5 \end{pmatrix}$$

- We represent a general initial marital status as

$$w_0 = x_1 u_1 + x_2 u_2, \text{ where } u_1 = \begin{bmatrix} 0.4 \\ 0.6 \end{bmatrix}, u_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$A^n u_1 = A^{n-1} (A u_1) = A^{n-1} u_1$$

We check that  $A u_1 = u_1$  and  $A u_2 = 0.5 u_2$

- Then the marital status after  $n$  years is  $A^n u_2 = A^{n-1} (A u_2) = 0.5 A^{n-1} u_2$

$$A^n w_0 = x_1 A^n u_1 + x_2 A^n u_2 = x_1 u_1 + x_2 0.5^n u_2 \rightarrow x_1 u_1.$$

# Contents

- Motivation
- Eigenvalues and Eigenvectors
- Properties about Eigenvalues
- Eigenvalue Decomposition
- Singular Value Decomposition

# Definition

- Let  $A$  be an  $n \times n$  matrix.
- A scalar  $\lambda$  is said to be an **eigenvalue** of  $A$  if there exists a nonzero vector  $x$  such that

$$Ax = \lambda x.$$

eigenvalue

eigenvector associated with  $\lambda$

- The vector  $x$  is said to be an **eigenvector** belonging to  $\lambda$ .

$(\lambda, x)$  is an eigen-pair of  $A$

# Implications

$$Ax = \lambda x$$

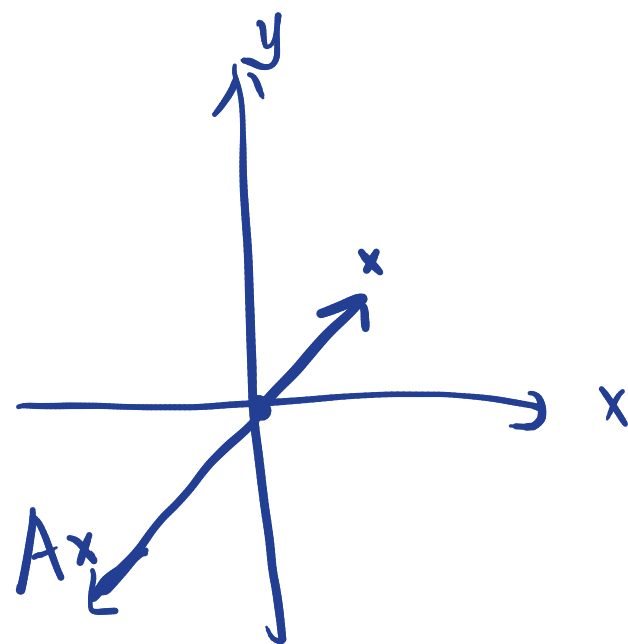
$$cAx = \lambda x \quad c \neq 0 \Leftrightarrow A(cx) = \lambda(cx)$$

- An eigenvector  $x$  and  $Ax$  have the same direction.
- If  $x$  is an eigenvector belonging to  $\lambda$ , so is  $cx$  for any  $c \neq 0$ .
- If  $x$  is an eigenvector of  $A$  belonging to  $\lambda$ , then  $x$  is an eigenvector of  $A^s$  belonging to  $\lambda^s$ .

$$Ax = \lambda x \Rightarrow A^s x = A^{s-1}(Ax) = \lambda A^{s-1}x = \dots = \lambda^s x$$

$s \in \mathbb{N}_+$

$$x = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$



$$A = \begin{pmatrix} 0 & -3 \\ 1 & -4 \end{pmatrix}$$

$$Ax = \begin{pmatrix} -3 \\ -3 \end{pmatrix}$$

# Example

- Let

$$A = \begin{bmatrix} 0 & -3 \\ 1 & -4 \end{bmatrix}, \mathbf{u} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- Then

$$A\mathbf{u} = \begin{bmatrix} 0 & -3 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -3 \\ -3 \end{bmatrix} = (-3)\mathbf{u}.$$

- Thus,  $-3$  is the eigenvalue of  $A$  and the corresponding eigenvector is  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

# Equivalent Characterizations

- Note that  $A\mathbf{x} = \lambda\mathbf{x}$  is equivalent to

$$\boxed{A} \begin{bmatrix} x \\ \vdots \end{bmatrix} = \lambda \begin{bmatrix} x \\ \vdots \end{bmatrix}$$

$$(A - \lambda I)\mathbf{x} = \mathbf{0}.$$

$$I = \begin{pmatrix} 1 & & \\ & \ddots & \\ & & 1 \end{pmatrix}$$

Note that it is not  $(A - \lambda)\mathbf{x} = \mathbf{0}$ .

- The following statements are equivalent:
  - $\lambda$  is an eigenvalue of  $A$ .
  - $(A - \lambda I)\mathbf{x} = \mathbf{0}$  has a nontrivial solution.
  - $\mathcal{N}(A - \lambda I) \neq \{\mathbf{0}\}$ .
  - $A - \lambda I$  is singular.
  - $\det(A - \lambda I) = 0$ .
- $\mathcal{N}(A - \lambda I)$  is called the **eigenspace** of eigenvalue  $\lambda$ .
- All nonzero vectors in  $\mathcal{N}(A - \lambda I)$  are eigenvectors corresponding to  $\lambda$ .

# Equivalent Characterizations

- Note that  $A\mathbf{x} = \lambda\mathbf{x}$  is equivalent to

$$(A - \lambda I)\mathbf{x} = \mathbf{0}.$$

Note that it is not  $(A - \lambda)\mathbf{x} = \mathbf{0}$ .

- The following statements are equivalent:
  - $\lambda$  is an eigenvalue of  $A$ .
  - $(A - \lambda I)\mathbf{x} = \mathbf{0}$  has a nontrivial solution.
  - $\mathcal{N}(A - \lambda I) \neq \{\mathbf{0}\}$ .
  - $A - \lambda I$  is singular.
  - $\det(A - \lambda I) = 0$ .
- $\mathcal{N}(A - \lambda I)$  is called the **eigenspace** of eigenvalue  $\lambda$ .
- All nonzero vectors in  $\mathcal{N}(A - \lambda I)$  are eigenvectors corresponding to  $\lambda$ .

# Equivalent Characterizations

- Note that  $A\mathbf{x} = \lambda\mathbf{x}$  is equivalent to

$$(A - \lambda I)\mathbf{x} = \mathbf{0}.$$

Note that it is not  $(A - \lambda)\mathbf{x} = \mathbf{0}$ .

- The following statements are equivalent:
  - $\lambda$  is an eigenvalue of  $A$ .
  - $(A - \lambda I)\mathbf{x} = \mathbf{0}$  has a nontrivial solution.
  - $\mathcal{N}(A - \lambda I) \neq \{\mathbf{0}\}$ .
  - $A - \lambda I$  is singular.
  - $\det(A - \lambda I) = 0$ .
- $\mathcal{N}(A - \lambda I)$  is called the **eigenspace** of eigenvalue  $\lambda$ .
- All nonzero vectors in  $\mathcal{N}(A - \lambda I)$  are eigenvectors corresponding to  $\lambda$ .



# Equivalent Characterizations

- Note that  $A\mathbf{x} = \lambda\mathbf{x}$  is equivalent to

$$(A - \lambda I)\mathbf{x} = \mathbf{0}.$$

Note that it is not  $(A - \lambda)\mathbf{x} = \mathbf{0}$ .

- The following statements are equivalent:
  - $\lambda$  is an eigenvalue of  $A$ .
  - $(A - \lambda I)\mathbf{x} = \mathbf{0}$  has a nontrivial solution.
  - $\mathcal{N}(A - \lambda I) \neq \{\mathbf{0}\}$ .
  - $A - \lambda I$  is singular.
  - $\det(A - \lambda I) = 0$ .
- $\mathcal{N}(A - \lambda I)$  is called the **eigenspace** of eigenvalue  $\lambda$ .
- All nonzero vectors in  $\mathcal{N}(A - \lambda I)$  are eigenvectors corresponding to  $\lambda$ .

# Characteristic polynomial

- Step 2: Solve chara. equation.

Find  $\lambda$  st.  $p(\lambda) = 0$

$$\lambda_1 = 4 \quad \lambda_2 = -3$$

- $p(\lambda) = \det(A - \lambda I)$  is an  $n$ th degree polynomial in  $\lambda$ .
- $p(\lambda)$  is called the **characteristic polynomial** of  $A$ .
- $p(\lambda) = 0$  is called the **characteristic equation** of  $A$ .
- A scalar  $\lambda$  is an eigenvalue of  $A$  if and only if  $p(\lambda) = 0$ .

$$A = \begin{pmatrix} 3 & 2 \\ 3 & -2 \end{pmatrix}$$

- Step 1: write down characteristic polynomial

$$\begin{aligned} p(\lambda) &= \det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 2 \\ 3 & -2-\lambda \end{vmatrix} = (3-\lambda)(-2-\lambda) - 6 \\ &= \lambda^2 - \lambda - 12 = (\lambda - 4)(\lambda + 3) \end{aligned}$$

## Example

- The characteristic polynomial of  $A = \begin{bmatrix} 3 & 2 \\ 3 & -2 \end{bmatrix}$  is

$$p(\lambda) = \begin{vmatrix} 3 - \lambda & 2 \\ 3 & -2 - \lambda \end{vmatrix} = \lambda^2 - \lambda - 12 = (\lambda - 4)(\lambda + 3) = 0.$$

- Hence, the the eigenvalues of  $A$  are  $\lambda_1 = 4$  and  $\lambda_2 = -3$ .
- The eigenvectors belonging to  $\lambda_1$  are nonzero solutions of

$$\begin{pmatrix} -1 & 2 \\ 3 & -6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\Rightarrow x_1 = 2x_2$$

$$(A - 4I)\mathbf{x} = \mathbf{0}.$$

$$\begin{pmatrix} -1 & 2 \\ 3 & -6 \end{pmatrix}$$

$$c \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \text{ where } c \neq 0.$$

The eigenvectors belonging to  $\lambda_2$  are nonzero solutions of

$$\begin{pmatrix} 6 & 2 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$(A + 3I)\mathbf{x} = \mathbf{0}.$$

$$\begin{pmatrix} 6 & 2 \\ 3 & 1 \end{pmatrix}$$

$$c \begin{pmatrix} 1 \\ -3 \end{pmatrix}, \text{ where } c \neq 0.$$

$$\lambda_1 = 0$$

$$\lambda_2 = 1$$

## Example

$$(A - \lambda_1 I)x = 0 = \begin{pmatrix} 2 & -3 & 1 \\ 1 & -2 & 1 \\ 1 & -3 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$\begin{cases} 2x_1 - 3x_2 + x_3 = 0 \\ x_1 - 2x_2 + x_3 = 0 \\ x_1 - 3x_2 + 2x_3 = 0 \end{cases} \Rightarrow x_1 = x_2 = x_3$$

Find the eigenvalues and the corresponding eigenvectors of

$$\Rightarrow c \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, c \neq 0$$

$$\textcircled{1} A - \lambda I = \begin{pmatrix} 2-\lambda & -3 & 1 \\ 1 & -2-\lambda & 1 \\ 1 & -3 & 2-\lambda \end{pmatrix} \quad A = \begin{bmatrix} 2 & -3 & 1 \\ 1 & -2 & 1 \\ 1 & -3 & 2 \end{bmatrix}$$

$$\det(A - \lambda I) = \begin{vmatrix} 2-\lambda & -3 & 1 \\ 1 & -2-\lambda & 1 \\ 1 & -3 & 2-\lambda \end{vmatrix}$$

$$\begin{vmatrix} -(-3) & 1 & 1 \\ 1 & 2-\lambda & 1 \\ 1 & 1 & -2-\lambda \end{vmatrix} + \begin{vmatrix} 1 & -2-\lambda \\ 1 & -3 \end{vmatrix}$$

$$\lambda = -\lambda(\lambda - 1)^2$$

$$(A - \lambda_2 I)x = 0$$

$$\Rightarrow \begin{pmatrix} 1 & -3 & 1 \\ 1 & -3 & 1 \\ 1 & -3 & 1 \end{pmatrix} x = 0$$

$$\Rightarrow x_1 - 3x_2 + x_3 = 0$$

$$\left\{ \begin{pmatrix} 3x_2 - x_3 \\ x_2 \\ x_3 \end{pmatrix} : x_2, x_3 \in \mathbb{R} \right\}$$

# Example

$$i = \sqrt{-1}$$

Find the eigenvalues and the corresponding eigenvectors of

$$A = \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix}.$$

$$\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 2 \\ -2 & 1-\lambda \end{vmatrix} = (1-\lambda)^2 + 4 = 0$$

$$(1-\lambda)^2 = -4$$

$$\lambda - 1 = \pm \sqrt{-4} = \pm 2i$$

$$\lambda_1 = 1 + 2i \quad \lambda_2 = 1 - 2i$$

# Complex Eigenvalues of Real Matrices

- As  $p(\lambda)$  has degree  $n$ ,  $p(\lambda)$  can be factored into the product of  $n$  linear terms:

$$p(\lambda) = c(\lambda_1 - \lambda) \cdots (\lambda_n - \lambda), \quad (1)$$

where  $\lambda_i$  is the root of  $p(\lambda)$ .

- For real valued matrices,
  - Complex eigenvalues occur in **conjugate pairs**, i.e., if  $\lambda$  is an eigenvalue, so is  $\bar{\lambda}$ .
  - If  $\mathbf{z}$  is an eigenvector belonging to a complex eigenvalue  $\lambda$ , then  $\bar{\mathbf{z}}$  is an eigenvector belonging to  $\bar{\lambda}$ .

# Complex Eigenvalues of Real Matrices

- As  $p(\lambda)$  has degree  $n$ ,  $p(\lambda)$  can be factored into the product of  $n$  linear terms:

$$p(\lambda) = c(\lambda_1 - \lambda) \cdots (\lambda_n - \lambda), \quad (1)$$

where  $\lambda_i$  is the root of  $p(\lambda)$ .

- For real valued matrices,

$$Ax = \lambda x \Rightarrow \overline{Ax} = \overline{\lambda x}$$

- Complex eigenvalues occur in **conjugate pairs**, i.e., if  $\lambda$  is an eigenvalue, so is  $\bar{\lambda}$ .  
 $\lambda = a + bi \quad \bar{\lambda} = a - bi \quad \Rightarrow \quad \overline{Ax} = \bar{\lambda} \bar{x}$

- If  $\mathbf{z}$  is an eigenvector belonging to a complex eigenvalue  $\lambda$ , then  $\bar{\mathbf{z}}$  is an eigenvector belonging to  $\bar{\lambda}$ .

$(\lambda, x)$  is eigen-pair

$\Rightarrow (\bar{\lambda}, \bar{x})$  is another eigen-pair

# Contents

- Motivation
- Eigenvalues and Eigenvectors
- **Properties about Eigenvalues**
- Eigenvalue Decomposition
- Singular Value Decomposition



# Multiplicity of Eigenvalues

- We know that  $\lambda_1, \dots, \lambda_n$  may not be all distinct.
- Let  $\lambda_1, \dots, \lambda_p$  be the  $p$  distinct eigenvalues.
- The eigenvalue  $\lambda_k$  has *multiplicity*  $m_k$ . We know that  $\sum_k m_k = n$ .
- The characteristic polynomial can be written as

$$p(\lambda) = c(\lambda_1 - \lambda)^{m_1} \cdots (\lambda_p - \lambda)^{m_p}. \quad (2)$$

- Example: For  $p(\lambda) = (1 - \lambda)^2(4 - \lambda)^3$ , the multiplicity of 1 is 2 and the multiplicity of 4 is 3.

# Multiplicity of Eigenvalues

- We know that  $\lambda_1, \dots, \lambda_n$  may not be all distinct.
- Let  $\lambda_1, \dots, \lambda_p$  be the  $p$  distinct eigenvalues.
- The eigenvalue  $\lambda_k$  has *multiplicity*  $m_k$ . We know that  $\sum_k m_k = n$ .
- The characteristic polynomial can be written as

$$p(\lambda) = c(\lambda_1 - \lambda)^{m_1} \cdots (\lambda_p - \lambda)^{m_p}. \quad (2)$$

- Example: For  $p(\lambda) = (1 - \lambda)^2(4 - \lambda)^3$ , the multiplicity of 1 is 2 and the multiplicity of 4 is 3.

# Multiplicity of Eigenvalues

$$p(\lambda) = -\lambda(\lambda-1)^2$$

- We know that  $\lambda_1, \dots, \lambda_n$  may not be all distinct.
- Let  $\lambda_1, \dots, \lambda_p$  be the  $p$  distinct eigenvalues.
- The eigenvalue  $\lambda_k$  has *multiplicity*  $m_k$ . We know that  $\sum_k m_k = n$ .
- The characteristic polynomial can be written as

$$p(\lambda) = c(\lambda_1 - \lambda)^{m_1} \cdots (\lambda_p - \lambda)^{m_p}. \quad (2)$$

- Example: For  $p(\lambda) = (1 - \lambda)^2(4 - \lambda)^3$ , the multiplicity of 1 is 2 and the multiplicity of 4 is 3.

# Multiplicity of Eigenvalues

- We know that  $\lambda_1, \dots, \lambda_n$  may not be all distinct.
- Let  $\lambda_1, \dots, \lambda_p$  be the  $p$  distinct eigenvalues.
- The eigenvalue  $\lambda_k$  has *multiplicity*  $m_k$ . We know that  $\sum_k m_k = n$ .
- The characteristic polynomial can be written as

$$p(\lambda) = c(\lambda_1 - \lambda)^{m_1} \cdots (\lambda_p - \lambda)^{m_p}. \quad (2)$$

- Example: For  $p(\lambda) = (1 - \lambda)^2(4 - \lambda)^3$ , the multiplicity of 1 is 2 and the multiplicity of 4 is 3.

# Product and Sum of the Eigenvalues

- Consider an  $n \times n$  square matrix  $A = (a_{ij})$ .
- Let  $\lambda_1, \dots, \lambda_n$  be the  $n$  eigenvalues of  $A$ .
- $\prod_{i=1}^n \lambda_i = \det(A)$ .
- $\sum_{i=1}^n \lambda_i = \sum_{i=1}^n a_{ii}$ .
- Proof:

# Product and Sum of the Eigenvalues

① degree  $n$  term:

$$c(-\lambda)^n = (-\lambda)^n \Rightarrow c=1$$

③  $p(\lambda) = \det(A - \lambda I)$

$$p(0) = \det(A) = c \lambda_1 \cdots \lambda_n = \prod_{i=1}^n \lambda_i$$

② degree  $(n-1)$ -term:

$$c \sum \lambda_i (-\lambda)^{n-1} = \sum a_{ii} (-\lambda)^{n-1} \Rightarrow c \sum \lambda_i = \sum a_{ii} \Rightarrow \sum \lambda_i = \text{Tr}(A)$$

• Consider an  $n \times n$  square matrix  $A = (a_{ij})$ .

• Let  $\lambda_1, \dots, \lambda_n$  be the  $n$  eigenvalues of  $A$ .

•  $\prod_{i=1}^n \lambda_i = \det(A)$ .

•  $\sum_{i=1}^n \lambda_i = \sum_{i=1}^n a_{ii}$ .

• Proof:

$$p(\lambda) = c(\lambda_1 - \lambda) \cdots (\lambda_n - \lambda)$$

$$= \det(A - \lambda I) =$$

$$\begin{vmatrix} a_{11} - \lambda & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} - \lambda & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} - \lambda \end{vmatrix}$$

$$(a_{11} - \lambda) \cdots (a_{nn} - \lambda)$$

accounts for degree  $n$  and degree  $(n-1)$  terms

# Transpose and Inverse

- As  $|A - \lambda I| = |A^T - \lambda I|$ ,  $A$  and  $A^T$  have same characteristic polynomial, and hence the same eigenvalues.
- If  $A$  is singular, 0 is an eigenvalue of  $A$ .
- If  $A$  is invertible,  $\lambda$  is an eigenvalue of  $A$  if and only if  $\lambda^{-1}$  is an eigenvalue of  $A^{-1}$ .
- Proof:

# Transpose and Inverse

- As  $|A - \lambda I| = |A^T - \lambda I|$ ,  $A$  and  $A^T$  have same characteristic polynomial, and hence the same eigenvalues.
- If  $A$  is singular, 0 is an eigenvalue of  $A$ .  $Ax = 0 = 0 \cdot x$
- If  $A$  is invertible,  $\lambda$  is an eigenvalue of  $A$  if and only if  $\lambda^{-1}$  is an eigenvalue of  $A^{-1}$ .

- Proof:  $Ax = \lambda x$

$$x = A^{-1}(Ax) = A^{-1}(\lambda x) = \lambda A^{-1}x$$

$$\Rightarrow A^{-1}x = \lambda^{-1}x$$



# Stochastic Matrix

$$A = \begin{pmatrix} 0.3 & 0.2 \\ 0.7 & 0.8 \end{pmatrix}$$

- An  $n \times n$  matrix  $A$  is a stochastic matrix if

1. all the entries are non-negative ( $a_{ij} \geq 0$ );
2. the summation of each column is 1 ( $\mathbf{1}^\top A = \mathbf{1}^\top$ ).

$$A = [a_1, \dots, a_n]$$

- For any vector  $\mathbf{x} \in \mathbb{R}^n$ ,  $A\mathbf{x}$  and  $\mathbf{x}$  have the same sum.  $\mathbf{1}^\top A = [\mathbf{1}^\top a_1, \dots, \mathbf{1}^\top a_n]$

$$= [1, \dots, 1]$$

$$= \mathbf{1}^\top$$

- 1 is an eigenvalue of  $A$  (and  $A^\top$ ).

- All the eigenvalues  $\lambda$  of  $A$  have  $|\lambda| \leq 1$ .

- Proof:

$$\mathbf{1}^\top (A\mathbf{x}) = (\mathbf{1}^\top A)\mathbf{x} = \mathbf{1}^\top \mathbf{x}$$

$$A^\top \mathbf{1} = \mathbf{1} \Rightarrow A^\top \mathbf{1} = (1) \cdot \mathbf{1}$$

$$A^n \mathbf{x} = \lambda^n \mathbf{x}$$

LHS absolute values are bounded

# Contents

- Motivation
- Eigenvalues and Eigenvectors
- Properties about Eigenvalues
- **Eigenvalue Decomposition**
- Singular Value Decomposition

# Spectral Theorem

- If  $A$  is a real symmetric matrix, the spectral theorem shows that there exists an orthogonal matrix that diagonalize  $A$ .
- Every real symmetric matrix  $A$  can be factored into  $Q\Lambda Q^T$  where  $Q$  is an orthogonal matrix and  $\Lambda$  is a real diagonal matrix.
- ● The diagonal entries  $\lambda_i$  of  $\Lambda$  are eigenvalues of  $A$ .
- The columns  $\mathbf{q}_i$  of  $Q$  are eigenvectors belonging to  $\lambda_i$ , respectively.

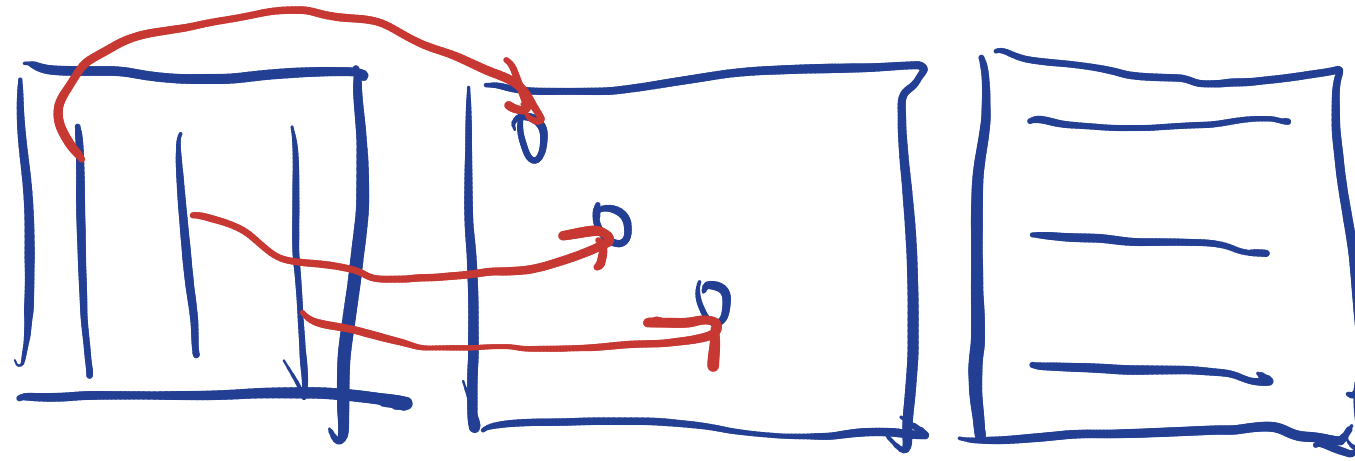
# Spectral Theorem

- If  $A$  is a real symmetric matrix, the spectral theorem shows that there exists an orthogonal matrix that diagonalize  $A$ .
- Every real symmetric matrix  $A$  can be factored into  $Q\Lambda Q^T$  where  $Q$  is an orthogonal matrix and  $\Lambda$  is a real diagonal matrix.
- ● The diagonal entries  $\lambda_i$  of  $\Lambda$  are eigenvalues of  $A$ .
- The columns  $\mathbf{q}_i$  of  $Q$  are eigenvectors belonging to  $\lambda_i$ , respectively.

# Spectral Theorem

$A$

$=$



1. Assume  $A$  is diagonalizable,

$$A = Q \Lambda Q^{-1}$$

2. Assume  $A$  is real-symmetric

$$A = Q \Lambda Q^T$$

$$A = Q \Lambda Q^T$$

- If  $A$  is a real symmetric matrix, the spectral theorem shows that there exists an orthogonal matrix that diagonalize  $A$ .

Lemma:  $Q$  is orthogonal, and square matrix,  $Q^T = Q^{-1}$  ( $Q^T Q = I$ )

- Every real symmetric matrix  $A$  can be factored into  $Q \Lambda Q^T$  where  $Q$  is an orthogonal matrix and  $\Lambda$  is a real diagonal matrix.

$$\det(Q^T Q) = \det^2(Q) = \det(I) = 1$$

- The diagonal entries  $\lambda_i$  of  $\Lambda$  are eigenvalues of  $A$ .
- The columns  $q_i$  of  $Q$  are eigenvectors belonging to  $\lambda_i$ , respectively.

Orthogonal matrix:  $Q \in \mathbb{R}^{n \times n}$   $Q^T Q = I_n = (\mathbf{q}_i^T \mathbf{q}_j)_{i,j}$

$$Q = [\mathbf{q}_1, \dots, \mathbf{q}_n] \quad Q^T Q = \begin{pmatrix} \mathbf{q}_1^T \\ \vdots \\ \mathbf{q}_n^T \end{pmatrix} (\mathbf{q}_1, \dots, \mathbf{q}_n) = \begin{pmatrix} \mathbf{q}_1^T \mathbf{q}_1 & \mathbf{q}_1^T \mathbf{q}_2 & \dots & \mathbf{q}_1^T \mathbf{q}_n \\ \vdots & \ddots & \ddots & \vdots \\ \mathbf{q}_n^T \mathbf{q}_1 & \dots & \dots & \mathbf{q}_n^T \mathbf{q}_n \end{pmatrix}$$

# Spectral Theorem

We can also write

$$A = \begin{bmatrix} \mathbf{q}_1 & \cdots & \mathbf{q}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \begin{bmatrix} \mathbf{q}_1^\top \\ \vdots \\ \mathbf{q}_n^\top \end{bmatrix}$$

$$= \begin{bmatrix} \mathbf{q}_1 & \cdots & \mathbf{q}_n \end{bmatrix} \begin{bmatrix} \lambda_1 \mathbf{q}_1^\top \\ \vdots \\ \lambda_n \mathbf{q}_n^\top \end{bmatrix}$$

$$= \sum_{i=1}^n \lambda_i \mathbf{q}_i \mathbf{q}_i^\top$$

$$\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n$$

$$\text{Tr}(\mathbf{q}_i \mathbf{q}_i^\top) = \text{Tr}(\mathbf{q}_i^\top \mathbf{q}_i) = \|\mathbf{q}_i\|_2^2 = 1$$

# Properties of $A^T A$

Let  $A$  be any  $m \times n$  matrix  $A$  of real numbers.

- $A^T A$  is symmetric.
- $A^T A$  is diagonalizable by an orthogonal matrix, and the eigenvalues of  $A^T A$  are real.

Proof:

Let's assume  $x \in N(A)$

$$\Rightarrow Ax = 0 \Rightarrow A^T Ax = 0 \Rightarrow x \in N(A^T A)$$

$$N(A) \subseteq N(A^T A)$$

- $N(A^T A) = N(A)$ .

- $\text{rank}(A) = \text{rank}(A^T A)$ .

Let's assume  $x \in N(A^T A)$

$$\Rightarrow A^T Ax = 0 \Rightarrow x^T A^T Ax = 0$$

$$\Leftrightarrow \|Ax\|_2^2 = 0$$

$$N(A^T A) \subseteq N(A)$$

$$\Rightarrow Ax = 0 \\ \Rightarrow x \in N(A)$$

$$A^T Ax = \lambda x$$

$$\Rightarrow x^T A^T Ax = \lambda x^T x$$

$$\Rightarrow \|Ax\|_2^2 = \lambda \|x\|_2^2$$

# Contents

- Motivation
- Eigenvalues and Eigenvectors
- Properties about Eigenvalues
- Eigenvalue Decomposition
- Singular Value Decomposition



# Singular Value Decomposition

The **singular-value decomposition (SVD)** of an  $m \times n$  matrix  $A$  of real numbers is a factorization of the form  $U\Sigma V^\top$ , where

- $U$  is an  $m \times m$  orthogonal matrix;
- $V$  is an  $n \times n$  orthogonal matrix;
- $\Sigma$  is an  $m \times n$  matrix whose off-diagonal entries are all 0's, and whose diagonal entries  $\sigma_i$ ,  $i = 1, \dots, n$ , called the **singular values** satisfy

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n \geq 0.$$

$$\Sigma = \begin{bmatrix} \sigma_1 & & 0 \\ & \ddots & \\ 0 & & \sigma_n \\ 0 & & 0 \end{bmatrix}$$

Here singular values  $\sigma_k = 0$  if  $k > \min\{m, n\}$ .

**SVD exists for any real matrix.**

$$\Sigma = \begin{bmatrix} \sigma_1 & & 0 & & 0 \\ & \ddots & & & \\ 0 & & \sigma_n & & 0 \\ & & 0 & & 0 \\ & & & \ddots & \end{bmatrix}$$

# Linear Transformation View

- Suppose  $A$  has the SVD:  $A = U\Sigma V^T$ .  $A \in \mathbb{R}^{m \times n} : \mathbb{R}^n \rightarrow \mathbb{R}^m$
- The columns of  $U$  form an orthonormal basis of  $\mathbb{R}^m$ . e.g.,  $A \in \mathbb{R}^{2 \times 3}$
- The columns of  $V$  form an orthonormal basis of  $\mathbb{R}^n$ .  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$
- The linear transformation  $L(\mathbf{x}) = A\mathbf{x}$  has the matrix representation  $\Sigma$  with respect to the above bases of  $\mathbb{R}^m$  and  $\mathbb{R}^n$ .
- In other words,

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\Sigma = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix}$$

$$\Sigma A \mathbf{x} = \begin{pmatrix} 4a \\ 2b \end{pmatrix}, \quad \mathbf{x} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$\Sigma A = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 2 & 0 \end{pmatrix}$$

$$L(\mathbf{x}) = U\Sigma V^T \mathbf{x}$$

$$[L(\mathbf{x})]_U = \Sigma[\mathbf{x}]_V$$

$$L(\mathbf{x}) = U$$

$$[\mathbf{x}]_V = V^T \mathbf{x}$$

$$\boxed{\begin{matrix} \mathbf{x} = \begin{pmatrix} a \\ b \\ c \end{pmatrix} \\ A\mathbf{x} = \begin{pmatrix} a \\ b \end{pmatrix} \end{matrix}}$$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\mathbf{x} = \begin{pmatrix} a \\ b \end{pmatrix}$$

$$A\mathbf{x} = \begin{pmatrix} a \\ b \\ 0 \end{pmatrix}$$

# Linear Transformation View

- Suppose  $A$  has the SVD:  $A = U\Sigma V^\top$ .
- The columns of  $U$  form an orthonormal basis of  $\mathbb{R}^m$ .
- The columns of  $V$  form an orthonormal basis of  $\mathbb{R}^n$ .
- The linear transformation  $L(\mathbf{x}) = A\mathbf{x}$  has the matrix representation  $\Sigma$  with respect to the above bases of  $\mathbb{R}^m$  and  $\mathbb{R}^n$ .
- In other words,

$$L(\mathbf{x}) = U\Sigma V^\top \mathbf{x}$$

$$[L(\mathbf{x})]_U = \Sigma [\mathbf{x}]_V$$

$$L(\mathbf{x}) = U [L(\mathbf{x})]_U$$

$$[\mathbf{x}]_V = V^\top \mathbf{x}$$

$$rk(S) \leq k$$

$$\Leftrightarrow B = V^\top S V$$

$$rk(B) \leq k$$

$$B = \begin{pmatrix} B_{1,1} & B_{1,2} \\ B_{2,1} & B_{2,2} \end{pmatrix}$$

# Visualization of SVD

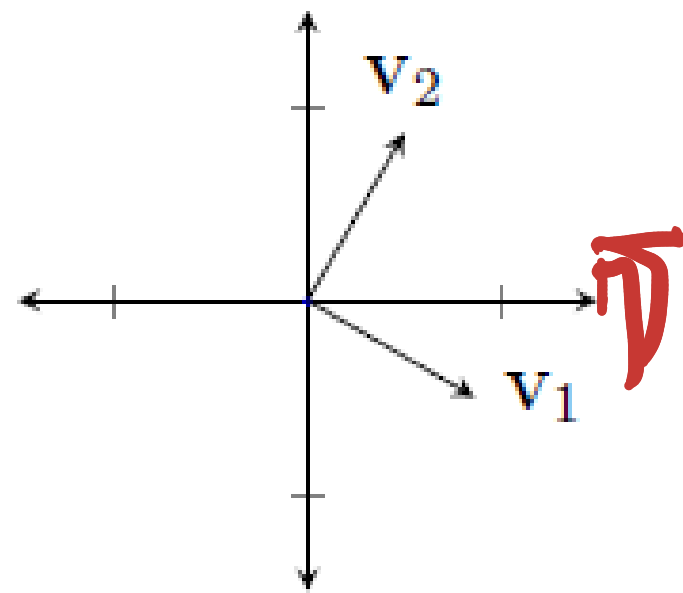
$$A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$A = U \Sigma V^T$$

$$(V^T x) ?$$

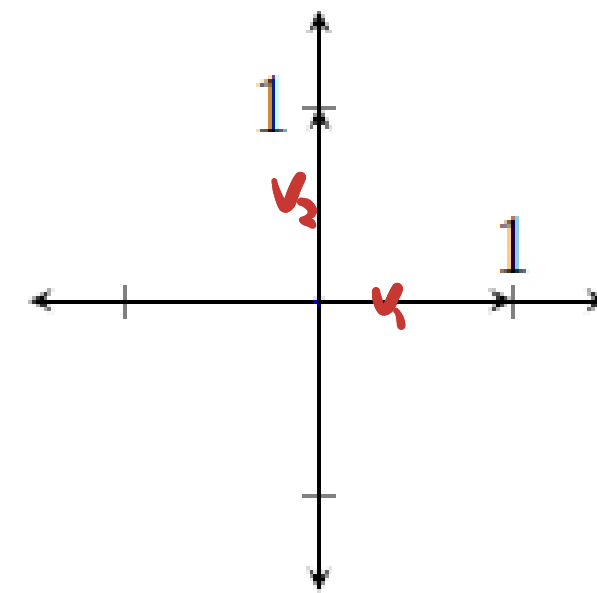
$$V = (v_1, v_2)$$

$V^T x$ : rotate right singular vectors to standard basis

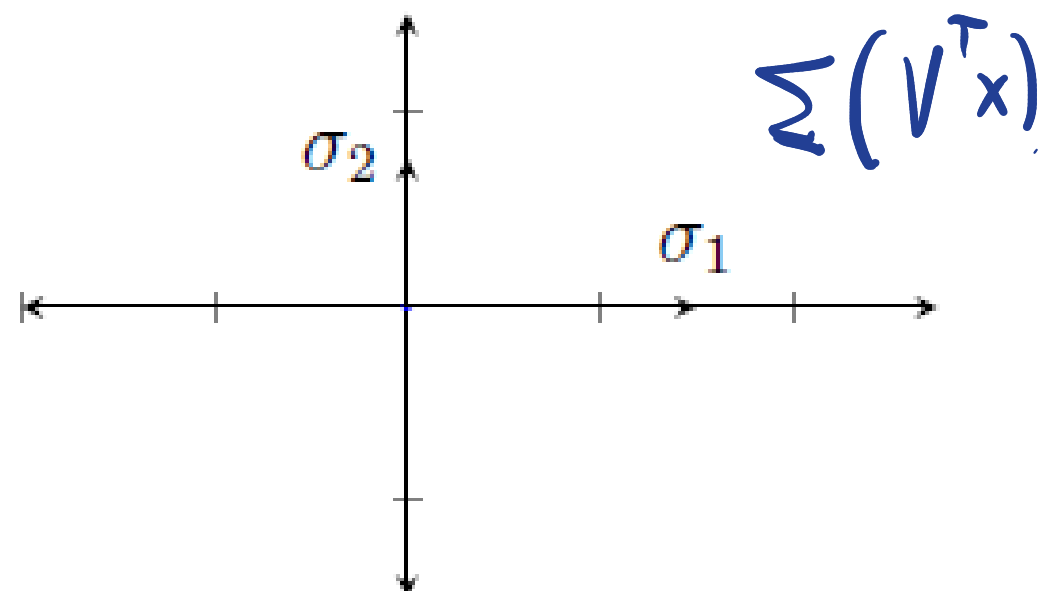


(a) standard axis

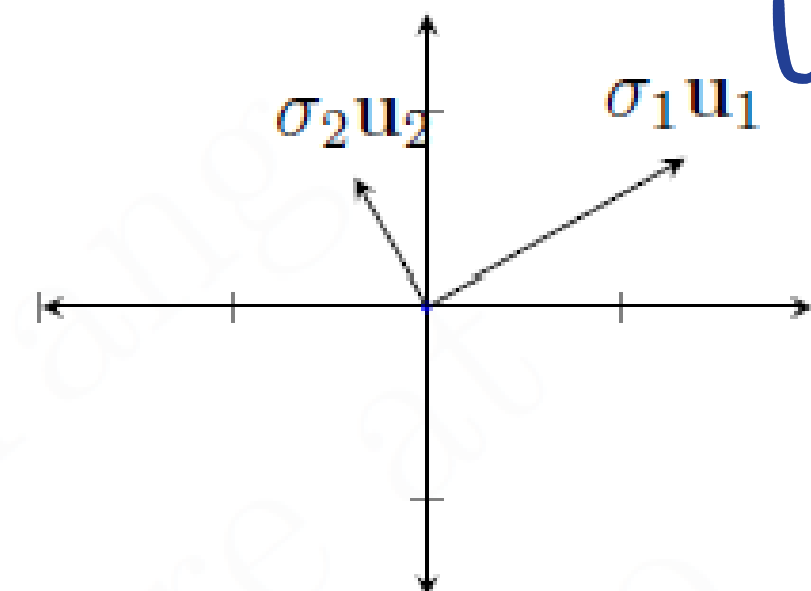
$$V^T x$$



(b)  $(v_1, v_2)$  axis



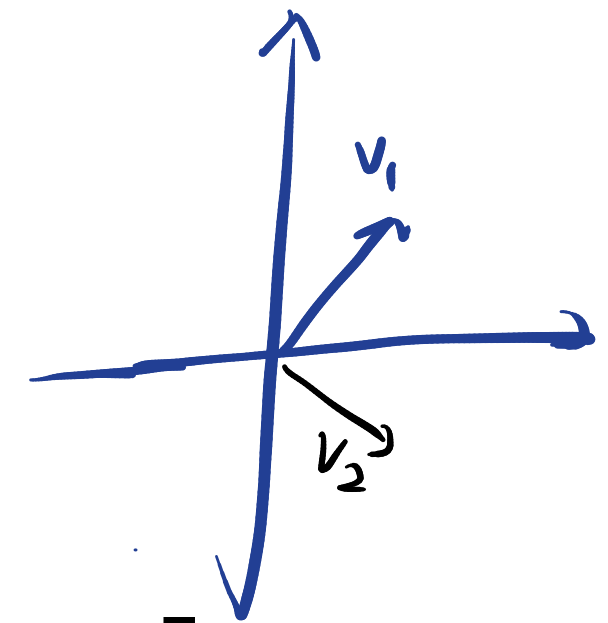
(c) scaled by  $\sigma_1$  and  $\sigma_2$ ,  $(u_1, u_2)$  axis



(d) standard axis

$U(\Sigma V^T x)$ : rotate standard basis to left singular vectors

# Example



1.

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

2.

$$\begin{bmatrix} 2 & 5 & 4 \\ 6 & 3 & 0 \\ 6 & 3 & 0 \\ 2 & 5 & 4 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} 12 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ -\frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ \frac{1}{3} & -\frac{2}{3} & \frac{2}{3} \end{bmatrix}$$

# Example

1.

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

2.

$$\begin{bmatrix} 2 & 5 & 4 \\ 6 & 3 & 0 \\ 6 & 3 & 0 \\ 2 & 5 & 4 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} 12 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ -\frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ \frac{1}{3} & -\frac{2}{3} & \frac{2}{3} \end{bmatrix}$$

# SVD and Rank

- If  $A = U\Sigma V^\top$ , then the rank of  $A$  is equal to the number of **nonzero singular values**.

$$A \in \mathbb{R}^{m \times n}$$

$$U = \left[ \begin{pmatrix} u_1 & \dots & u_m \end{pmatrix} \right] \quad V = \left[ \begin{pmatrix} v_1 & \dots & v_n \end{pmatrix} \right]$$

- Proof Technique:

- Let  $r$  be the number of nonzero singular values of  $A$ .
- Let  $U_r$  and  $V_r$  be the first  $r$  columns of  $U$  and  $V$ , respectively.
- Let  $\Sigma_r = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_r)$ .

We have  $U_r^\top U_r = V_r^\top V_r = I_r$  and

$$A = U_r \Sigma_r V_r^\top \Rightarrow \text{rk}(A) = \# \text{ of nonzero singular values.} \quad (3)$$

$$A = U_r \Sigma_r V_r^\top \Rightarrow \text{rk}(A) \leq \text{rk}(U_r)$$

$$A V_r = U_r \Sigma_r \Rightarrow A V_r \Sigma_r^{-1} = U_r \Rightarrow \text{rk}(U_r) \leq \text{rk}(A)$$

# Outer Product Expansion

$$\begin{aligned} A &= U_r \Sigma_r V_r^T \\ &= \begin{bmatrix} \mathbf{u}_1 & \cdots & \mathbf{u}_r \end{bmatrix} \begin{bmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \end{bmatrix} \begin{bmatrix} \mathbf{v}_1^\top \\ \vdots \\ \mathbf{v}_r^\top \end{bmatrix} \\ &= \begin{bmatrix} \mathbf{u}_1 & \cdots & \mathbf{u}_r \end{bmatrix} \begin{bmatrix} \sigma_1 \mathbf{v}_1^\top \\ \vdots \\ \sigma_r \mathbf{v}_r^\top \end{bmatrix} \\ &= \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^\top \end{aligned}$$



# Eigenvalues vs Singular Values

- For an  $n \times n$  square matrix  $A$  with SVD and rank  $r$

$$A\mathbf{v}_i = \sigma_i \mathbf{u}_i, i = 1, \dots, r.$$

- The rank of a matrix is always the same as the number of non-zero singular values.

# Eigenvalues vs Singular Values

- If  $A$  is diagonalizable, i.e.,  $A$  has  $n$  linearly independent eigenvectors  $\mathbf{x}_i$

$$A\mathbf{x}_i = \lambda_i\mathbf{x}_i, i = 1, \dots, n$$

then the rank of the matrix is equal to the number of non-zero eigenvalues.

- But this may not be the case when the matrix is not diagonalizable.

Consider  $M = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

# Property of SVD

Let an  $m \times n$  matrix  $A$  having SVD  $U\Sigma V^T$ . Then

- $\sigma_i = \sqrt{\lambda_i}$ ,  $i = 1, \dots, n$ , where  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n \geq 0$  are eigenvalues of  $A^T A$ .  $A^T A = V \Sigma^T U^T U \Sigma V^T = V \Sigma^T \Sigma V^T$ .
- $V$  diagonalizes  $A^T A$ , and hence  $\mathbf{v}_j$ 's are eigenvectors of  $A^T A$ .
- the columns of  $U$  satisfy:

$$\mathbf{u}_j = \frac{1}{\sigma_j} A \mathbf{v}_j, \quad j = 1, \dots, r = \text{rank}(A)$$

$$A^T \mathbf{u}_j = \mathbf{0}, \quad j = r + 1, \dots, m.$$

Exercise.

$$A = U \Sigma V^T$$

$$A V = U \Sigma V^T V = U \Sigma$$

$$V = (\mathbf{v}_1, \dots, \mathbf{v}_n)$$

$$A \mathbf{v}_j = \sigma_j \mathbf{u}_j \Rightarrow \mathbf{u}_j = (A \mathbf{v}_j) / \sigma_j$$

# Matrix Norm

$$\|A\|_F^2 = \sum_{i,j} |a_{ij}|^2 = \text{Tr}(A^T A) = \text{Tr}(AA^T)$$

- Matrix norm  $\|A\|_F = \sqrt{\sum_{i,j} |a_{ij}|^2}$ , which is also called *Frobenius* norm.

- If  $A = U\Sigma V^T$ , then  $\|A\|_F^2 = \sigma_1^2 + \dots + \sigma_n^2$ .

$$\|A\|_F^2 = \|U\Sigma V^T\|_F^2 = \|\Sigma V^T\|_F^2 = \|\Sigma\|_F^2 = \sigma_1^2 + \dots + \sigma_n^2$$

Lemma

If  $Q$  is an orthogonal matrix, then  $\|QA\|_F = \|A\|_F$ .

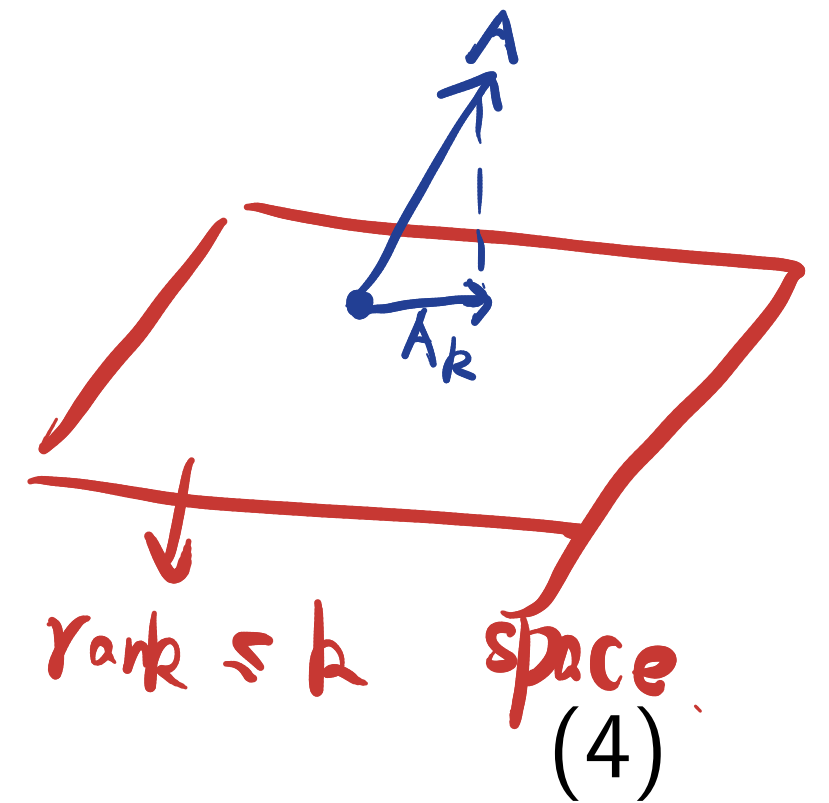
proof of lemma:

$$\begin{aligned} \|QA\|_F^2 &= \text{Tr}(QAA^TQ^T) \\ &= \text{Tr}(AA^TQ^TQ) = \text{Tr}(AA^T) = \|A\|_F^2 \end{aligned}$$

$$\Sigma = \text{diag}(\sigma_1, \dots, \sigma_n)$$

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n$$

## Low rank approximation



For a fixed  $m \times n$  matrix  $A$  and an integer  $k$ , solve

$$\min_{\text{rank}(S) \leq k} \|A - S\|_F.$$

Theorem

$$U^T S V = \Sigma_k \Rightarrow S^* = U \Sigma_k V^T$$

Let  $A = U \Sigma V^T$  be an  $m \times n$  matrix and let  $A_k = U \Sigma_k V^T$  where  $\Sigma_k$  is same as  $\Sigma$  except that the  $(j, j)$  entry is 0 for  $j > k$ . Then

$$\min_{\text{rank}(S) \leq k} \|A - S\|_F = \|A - A_k\|_F = (\sigma_{k+1}^2 + \dots + \sigma_n^2)^{1/2}.$$

In other words,  $A_k$  is the best rank  $k$  approximation of  $A$  in Frobenius

norm. Proof: For  $S$  with  $\text{rk}(S) \leq k$ ,  $\|A - S\|_F = \|U \Sigma V^T - S\|_F$

$$\Leftrightarrow \text{It suffices to find } B \triangleq U^T S V \text{ s.t. } \text{rk}(B) \leq k, \quad \| \Sigma - B \|_F \text{ is minimized} \Rightarrow B = \Sigma_k$$

$$= \| U^T (U \Sigma V^T - S) V \|_F = \| \Sigma - U^T S V \|_F$$

In the proof, we used the fact that "there is no better  $k$ -rank approximation for  $\Sigma$  than

$$\Sigma_k = \text{diag}(b_1, \dots, b_k, 0, \dots, 0)$$

Justification:

Consider  $\min_{B: \text{rank}(B) \leq k} \|B - \Sigma\|_F^2 = \sum_{i=1}^r (B_{ii} - b_i)^2 + \sum_{i \neq j} B_{ij}^2$

• If optimal  $B$  has any nonzero off-diagonal entry,

Set it to zero  $\Rightarrow$  obtain better optimal solution  
 $\Rightarrow$  Contradiction

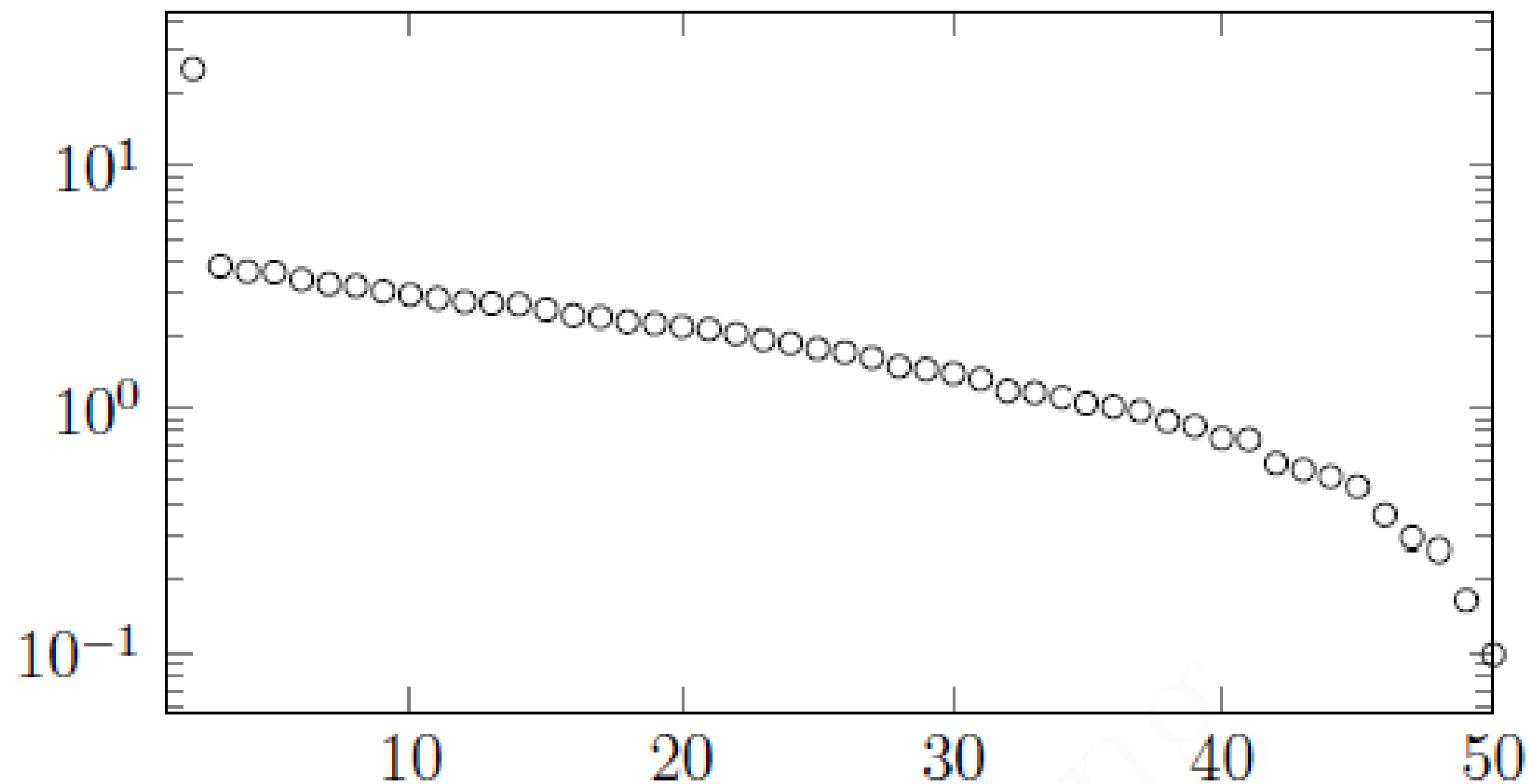
• Hence,  $B$  must be diagonal matrix, i.e.,  $B = \text{diag}(b_1, \dots, b_r)$

$$\|B - \Sigma\|_F^2 = \sum_{i=1}^r (B_{ii} - b_i)^2$$

$$\Rightarrow B^* = \text{diag}(b_1, \dots, b_k, 0, \dots, 0)$$

# Example

- Generate a random  $50 \times 50$  matrix  $A$  using Julia
- Check the rank of matrix  $A$ , which should be ~~50~~ most of the case.  
50
- Plot the singular values:



# Applications

$$\text{Tr}(AB) = \text{Tr}(BA)$$

$$\begin{aligned} \text{Tr}(QA \underbrace{A^T Q^T}_B) \\ = \text{Tr}(AA^T(Q^T Q)) \end{aligned}$$

$$= \text{Tr}(AA^T)$$

- Eigenvalues with PCA;
- Eigenvalues for extracting information from graph;
- SVD with recommender systems.