

cam

usb

GNSS

usb

NUC .102

lan

Lidar

Can bus X-> right, Y->forward, Z

STM32

ระบบขับเคลื่อนล้อ

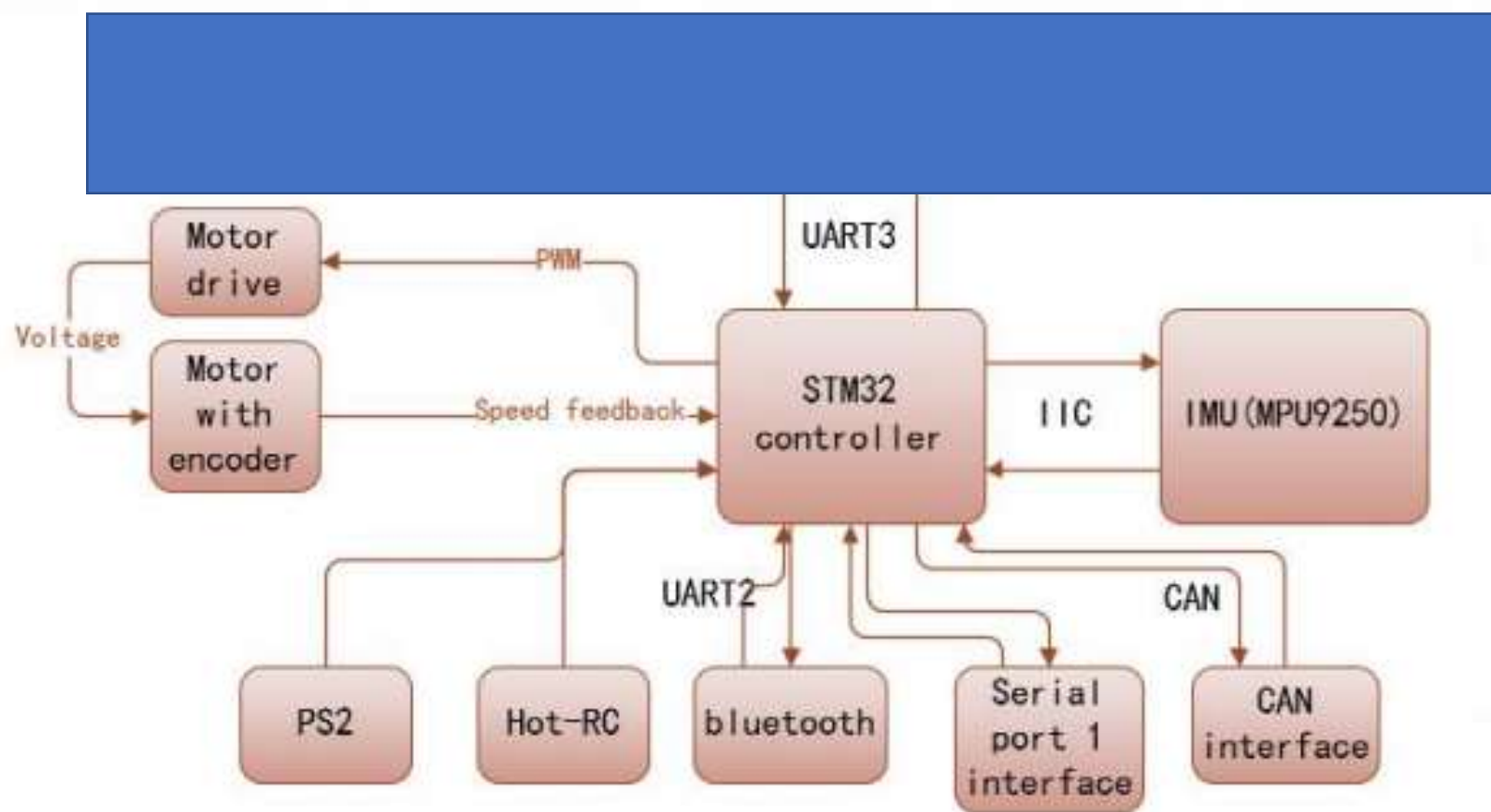
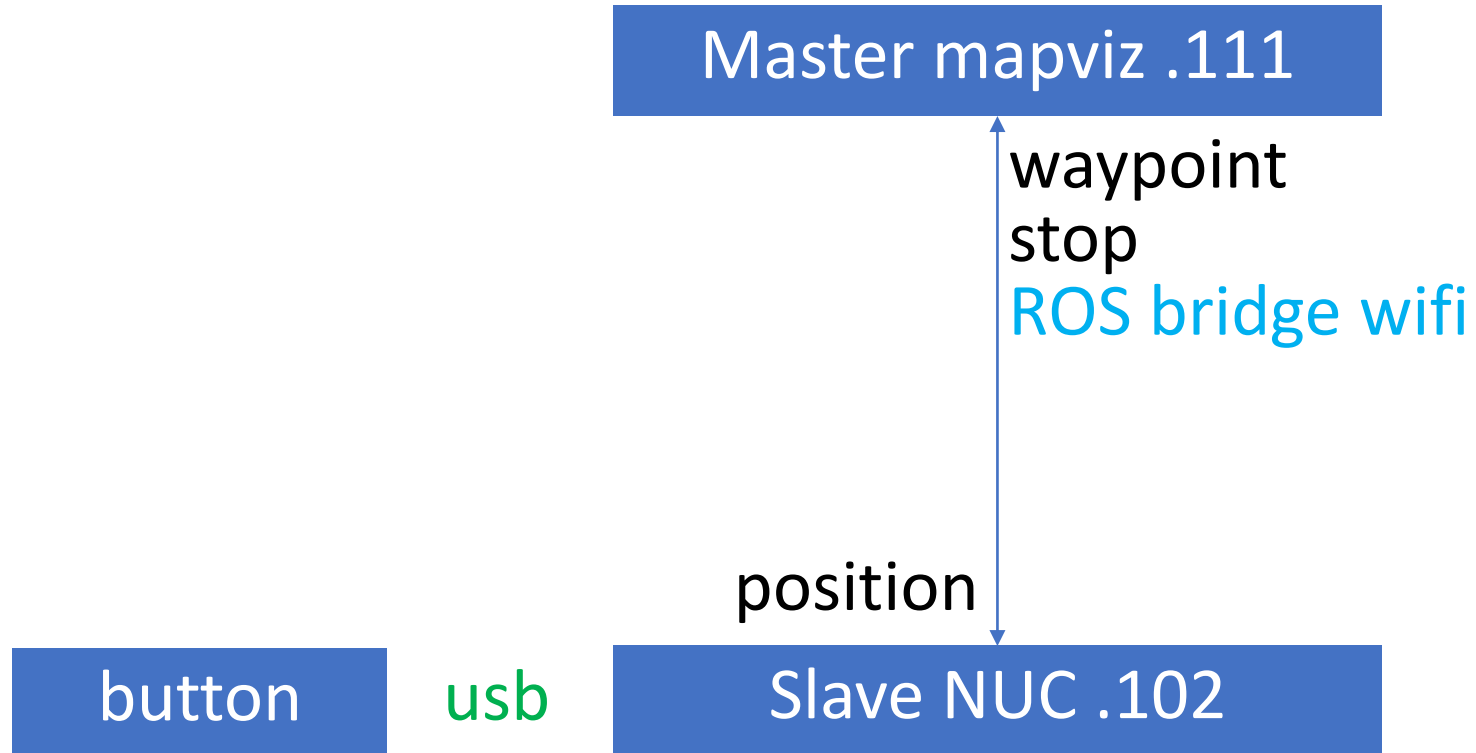
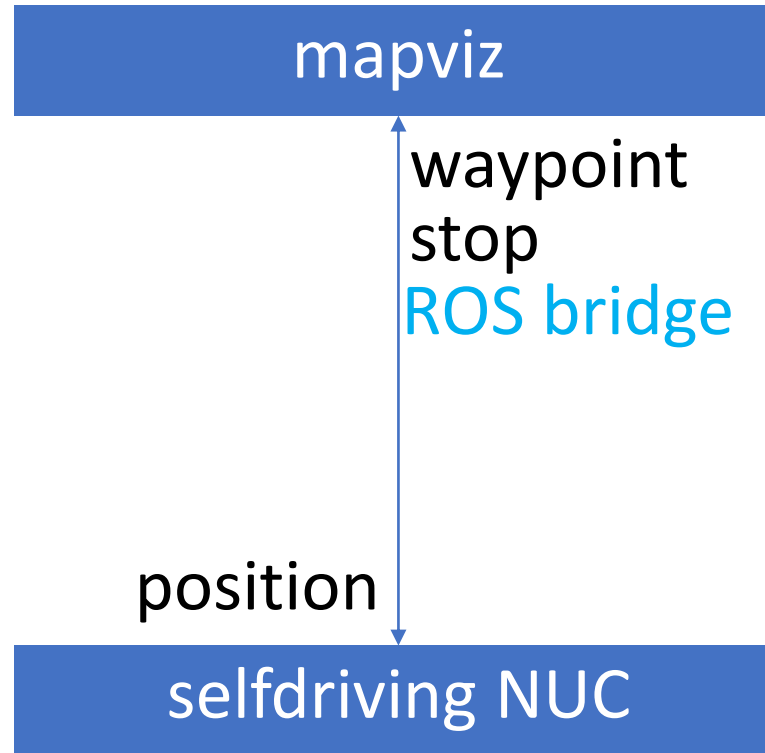


Figure 6-3 Robot controller connection diagram







Can bus X-> right, Y->forward, Z-> XtoY