



cam

usb

GNSS

usb

NUC .102

lan

Lidar

Can bus X-> right, Y->forward, Z

STM32

ระบบขับเคลื่อนล้อ

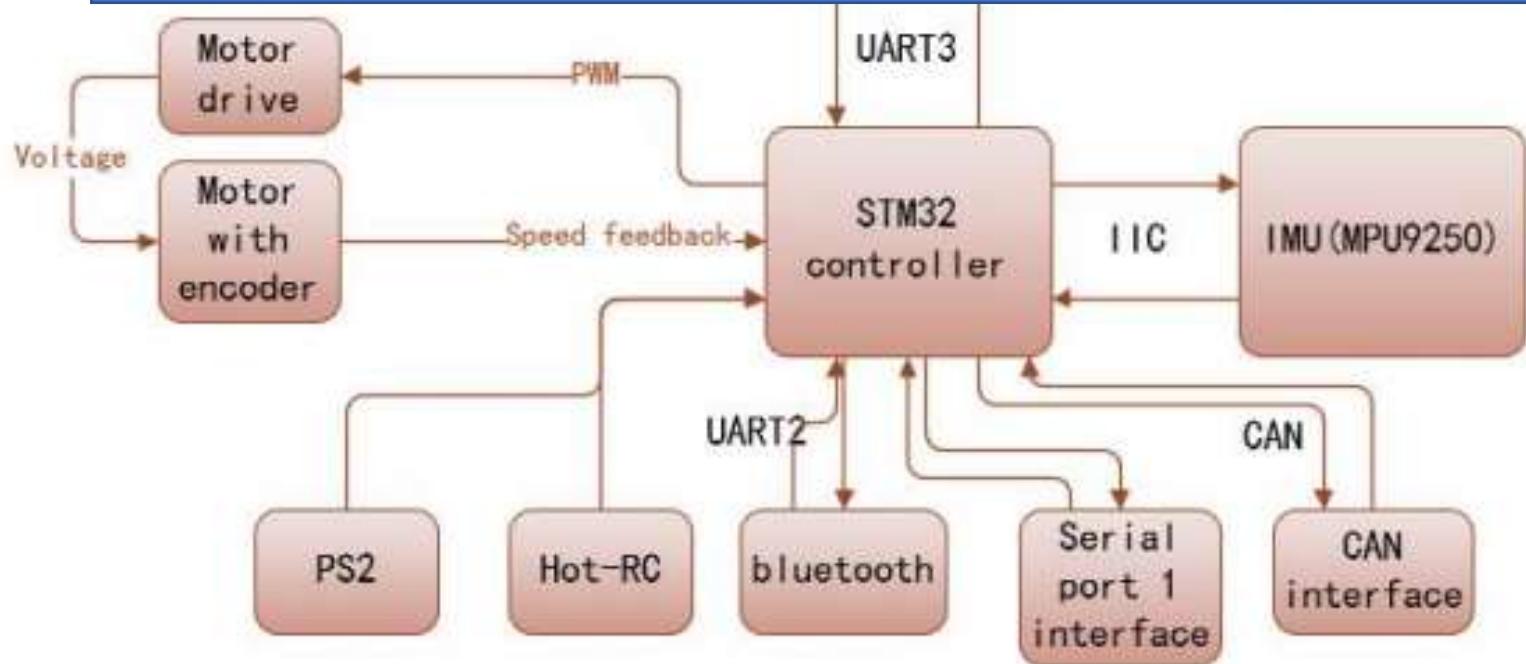


Figure 6-3 Robot controller connection diagram



Master mapviz .111

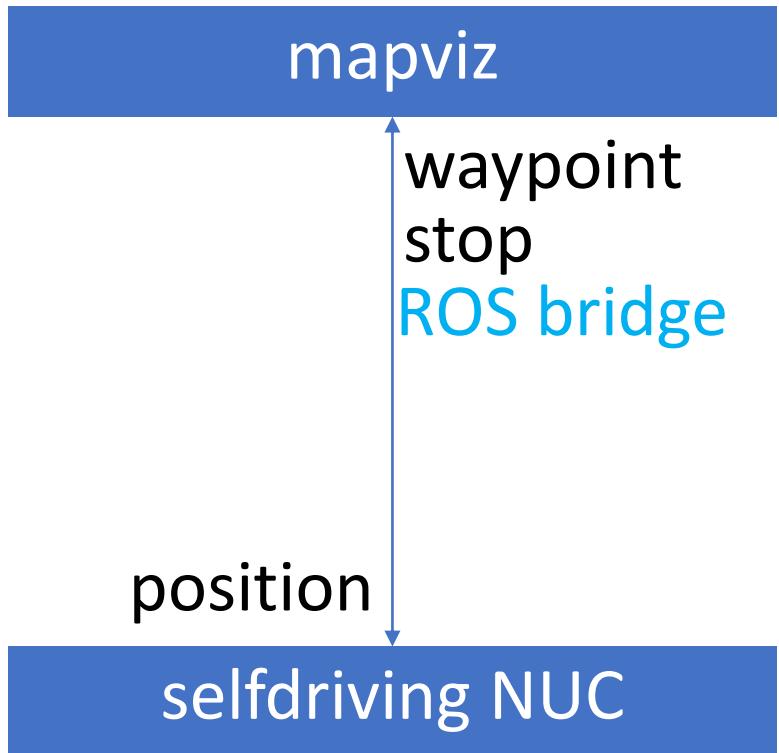
waypoint  
stop  
**ROS bridge wifi**

position

button

usb

Slave NUC .102



Can bus X-> right, Y->forward, Z-> XtoY