# Solve the ground state for He, Be and Ne atom

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#### Abstract

This survey presents an overview of

## 1 Introduction

Variational Monte Carlo (VMC) is a powerful method to solve the ground state of quantum manybody systems. In this paper, we will use VMC combined with self-consistent (SCF) theory to solve the ground state for He, Be and Ne atom. The Hamiltonian for an atomic system is

$$\hat{H} = \frac{1}{2} \sum_{i} \nabla_{i}^{2} - \sum_{i} \frac{Z}{r_{i}} + \frac{1}{2} \sum_{i \neq j} \frac{1}{|r_{i} - r_{j}|},\tag{1}$$

where

- first two terms are called single body term, representing electron-nucleus interaction;
- last term called many body term, representing electron-electron interaction, which can be then break down into direct term J and exchange term K;

Without it, system eigen states would be simply produced by Slater determinants. Otherwise, the system is not solvable analytically.

# 2 Principle

In this chapter we derive important conclusions and procedure that we used in the numerical calculation. For simplicity's sake, the system we only consider is a closed shell system where there are N/2 different spatial orbits given N electrons. Further discussions about open shell and closed shell please go to ??.

### 2.1 Hartree-Fock equations

The Hartree-Fock self-consistent field (SCF) theory is a method used in quantum chemistry to approximate the wave function and energy of a many-electron system. The theory is based on the Hartree-Fock approximation, which assumes that the many-electron wave function can be represented as a product of single-electron wave functions, or orbitals. The SCF method involves iteratively solving the Hartree-Fock equations to determine the orbitals and the energy of the system, and then using these solutions as the starting point for the next iteration. This process is repeated until the solutions converge to a self-consistent set of orbitals and energy, which represents the best approximation of the true wave function and energy of the system.

Adapted from original Hamiltonian 1(How?). Hartree-Fock equation for a closed-shell atomic system reads as follows: [?]

$$\hat{f}(r_i) = \hat{h}(r_i) + \sum_{a=1}^{N/2} (2\hat{J}_a(r_i) - \hat{K}_a(r_i))$$
(2)

where

- $\hat{f}(r_i)$ : Fock operator;
- $\hat{h}(r_i)$ : single body operator;
- $\hat{J}_a(r_i)$ : direct operator attributed to electron-electron coulomb repulsion;
- $\hat{K}_a(r_i)$ : exchange operator attributed to same-spin electron exchange effect. The factor is half of that of the direct operator.

Choose a set of normal basis (not necessarily orthogonal)  $\{\phi_1, ..., \phi_m\}$ . The Fock operator under the representation is:

$$F_{\mu\nu} = H_{\mu\nu}^{core} + \sum_{a=1}^{N/2} (2(\mu\nu|aa) - (\mu a|a\nu))$$
 (3)

where

- $F_{\mu\nu} = \int dr_1 \phi_{\mu}^*(r)$
- $(\mu\nu|aa)$ : direct operator;
- $(\mu a|a\nu)$ : exchange operator;

More formally, given  $X \subset \mathbb{R}^d$  of (r-1)(d+1)+1 points, there is a partition  $X=X_1\cup\cdots\cup X_r$  such that  $\bigcap_{j=1}^r \operatorname{conv} X_j \neq \emptyset$ . Such a partition is called a *Tverberg partition*. The number of points in this result is optimal, as a dimension-counting argument shows. In fact, if X is in general enough position and in the partition  $X=X_1\cup\ldots\cup X_r$  we have  $1\leq |X_j|\leq d+1$  for every j, then  $\bigcap_{j=1}^r \operatorname{aff} X_j$  is a single point if |X|=(r-1)(d+1)+1, and is empty if  $|X|\leq (r-1)(d+1)$ .

The last decade has seen an impressive sequence of results around Tverberg's theorem. The purpose of this survey is to give a broad overview of the current state of the field and point out key open problems. Other surveys covering different aspects of Tverberg's theorem can be found in [Eck79, Eck93, Mat02, BBZ16, DLGMM17, BZ17].

The paper is organized as follows. In sections 3 and 4 we describe the topological and colorful versions of Tverberg's theorem, which have received the most attention in recent years. In sections 5 and 6 we discuss a large number of variations and conjectures around Tverberg's theorem. In Section 7 we describe some applications of Tverberg's theorem. Finally, in Section 8 we present Tverberg-type results where the settings have changed dramatically, such as Tverberg for convexity spaces or quantitative versions. In that last section, we focus mostly on results which are related to geometry.

#### 2.2 Interlude: a short history of Tverberg's theorem

An early predecessor of Tverberg's theorem is Radon's lemma from 1921 [Rad21, Eck79]. Radon used it in his proof of Helly's theorem. It says that any set X of d+2 points in  $\mathbb{R}^d$  can be split into two sets whose convex hulls intersect. So it is the case r=2 of Tverberg's theorem. Its proof is simple: the d+2 vectors in X have a nontrivial affine dependence  $\sum_{x\in X} \alpha(x)x=0$  and  $\sum_{x\in X} \alpha(x)=0$ . The sets  $X_1=\{x\in X:\alpha(x)\geq 0\}$  and  $X_2=\{x\in X:\alpha(x)<0\}$  form a partition of X and their convex hulls intersect, as one can easily check.

Another result linked to this theorem is Rado's centerpoint theorem. This states that for any set X of n points in  $\mathbb{R}^d$ , there is a point p such that any closed half-space that contains p also contains at least  $\left\lceil \frac{n}{d+1} \right\rceil$  points of X. The standard proof of this result uses Helly's theorem. Tverberg's theorem implies it in few lines: setting  $r = \left\lceil \frac{n}{d+1} \right\rceil$ , there is a partition of X into r parts  $X_1, \ldots, X_r$  and a point  $p \in \mathbb{R}^d$  such that  $p \in \bigcap_{j=1}^r \operatorname{conv} X_j$ . Then p is a centerpoint of X: every closed halfspace containing p contains at least one point from each  $X_j$ .

In a paper entitled "On 3N points in a plane" Birch [Bir59] proves that any 3N points in the plane determine N triangles that have a point in common. His motivation was the (planar) centerpoint theorem. Actually, he proves more, namely the case d=2 of Tverberg's theorem and states the general case as a conjecture.

Tverberg's original motivation was also the centerpoint theorem and he learned about Birch's result and conjecture only later. He proved it first for d=3 in 1963, and in full generality in 1964. Here is, in his own words, how he found the proof: "I recall that the weather was bitterly cold in Manchester. I awoke very early one morning shivering, as the electric heater in the hotel room had gone off, and I did not have an extra shilling to feed the meter. So, instead of falling back to sleep, I reviewed the problem once more, and then the solution dawned on me!" [Tve01].

- 3 Topological versions
- 4 Colorful versions
- 5 The structure of Tverberg partitions
- 6 Universal Tverberg partitions
- 7 Applications of Tverberg's theorem
- 8 Tverberg-type results in distinct settings

### References

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