

中国种学院大学

University of Chinese Academy of Sciences

3. Evaluate the Frobenius matrix norm, 1-norm, 2-norm, and -norm for each

matrix below.
$$A = \begin{pmatrix} 1 & -2 \\ -1 & z \end{pmatrix}$$
 $B\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$ $C = \begin{pmatrix} 4 & -2 & 4 \\ -2 & 1 & -2 \\ 4 & -2 & 4 \end{pmatrix}$

$$A: A^{\mathsf{T}}A = \begin{pmatrix} 1 & -1 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} 1 & -2 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 2 & -4 \\ -4 & 8 \end{pmatrix}$$

$$AE-ATA = \begin{vmatrix} \lambda-2 & 4 \\ 4 & \lambda-8 \end{vmatrix} = A-2(\lambda-8)-16 = A-2(\lambda-8)-16 = A-2(\lambda-8)$$

B:
$$B^TB = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$
 BTB的特征同量 $\lambda_{max} = 1$

$$||B||_{\mathcal{E}} = \sqrt{3} ||B||_{1} = ||B||_{2} = ||B||_{2$$

$$C: C^{T}C = \begin{bmatrix} 4 & -2 & 4 \\ -2 & 1 & -2 \\ 4 & -2 & 4 \end{bmatrix} \begin{bmatrix} 4 - 2 & 4 \\ -2 & 1 & -2 \\ 4 & -2 & 4 \end{bmatrix} \begin{bmatrix} 4 - 2 & 4 \\ 4 & -2 & 4 \end{bmatrix} = \begin{bmatrix} 36 & -18 & 36 \\ -18 & 9 & -18 \\ 36 & -18 & 26 \end{bmatrix}$$

$$\frac{|\lambda E - C^T C|}{|\lambda - 36|} = \frac{|\lambda - 36|}{|\lambda - 9|} = \frac{|\lambda - 36|}{|\lambda - 9|} = \frac{|\lambda - 36|}{|\lambda - 9|} = \frac{|\lambda - 36|}{|\lambda - 36|} = \frac{$$

$$40.12. (a) A = \begin{pmatrix} 1 & 0 & -1 \\ 1 & 2 & 1 \\ 1 & 1 & -3 \end{pmatrix} b = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$



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(a) 求矩阵A的QR分解

$$K=1: r_{11}=||a_{1}||=J_{3}$$
 $q_{1}=\frac{a_{1}}{||a_{1}||}=(\frac{1}{J_{3}},\frac{1}{J_{3}},\frac{1}{J_{3}},0)^{T}$

$$k=2: h_2=\langle a_1^{\dagger} l_1 \rangle = a_1^{\top} \cdot l_1 = \overline{l_3} \quad g_2 = \frac{a_2 - h_2 g_1}{\|a_1 - h_2\|} = (-\frac{1}{13}, \frac{1}{13}, 0, \overline{13})^{\top} h_2 = \overline{l_3}$$

$$k=3$$
 $r_{13}=\langle a_3|g_1\rangle=a_3^{T}g_1=-J_3$ $r_{23}=\langle a_3|g_2\rangle=a_3^{T}g_2=J_3$

$$q_2 = \frac{a_3 - r_{13}q_1 - r_{23}q_2}{\|a_3 - r_{13} - q_1 - r_{23}q_2\|} = \left(\frac{1}{16}, \frac{1}{16}, -\frac{2}{16}, 0\right)^T$$

$$\frac{q_{3}}{\sqrt{2}} = \frac{a_{3} - h_{3}q_{1} - h_{23}q_{2}}{\sqrt{2}} = (\frac{1}{16}, \frac{1}{16}, \frac$$

(6) 式AX=6 的最小二乘解

$$Ax=b \Rightarrow QRX=b$$
 因为Q是正交矩阵,则有QT=Q-1

$$Rx = Q^{T}b$$
, 得 J_{3} J_{3} J_{5} $J_$

$$= (53 \frac{3}{5} 0)^{T} 解復 (X_1, X_2, X_3)^{T} = (\frac{2}{5}, \frac{1}{5}, 0)$$



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4. 以方向的投影矩阵为:

$$P_{H} = \frac{\mu \cdot \mu^{T}}{\mu^{T} \cdot H} = \frac{1}{15} \cdot \begin{pmatrix} 4 & -2 & -6 & 2 \\ -2 & 1 & 3 & -1 \\ -6 & 3 & 9 & -3 \\ 2 & -1 & -3 & 1 \end{pmatrix}$$

少为有的投影和好多为

$$P_{v} = \frac{v \cdot v^{T}}{v^{T} \cdot v} = \frac{1}{18} \cdot \begin{vmatrix} 1 & 4 & 0 & -1 \\ 4 & 16 & 0 & -4 \\ 0 & 0 & 0 & 0 \\ -1 & -4 & 0 & 1 \end{vmatrix}$$

(a)
$$P_{v} \cdot u = \frac{1}{18}(3, 12, 0, -3)^{7} = (\frac{1}{6}, \frac{2}{3}, 0, -\frac{1}{6})^{7}$$

(c)
$$v_{u} \cdot u = (I - P_{v}) \cdot u = u - P_{v} \cdot v = (-\frac{13}{6}, \frac{1}{3}, -3, \frac{5}{6})^{T}$$

(d)
$$P_{u1} \cdot v = (I - P_{up}) \cdot v = v - P_{u} \cdot v = (\overline{\xi}, \frac{12}{5}, -\overline{\xi}, -\overline{\xi}, \frac{4}{5})^{T}$$