Sensory-motor transformations in vestibular processing

Linear Systems

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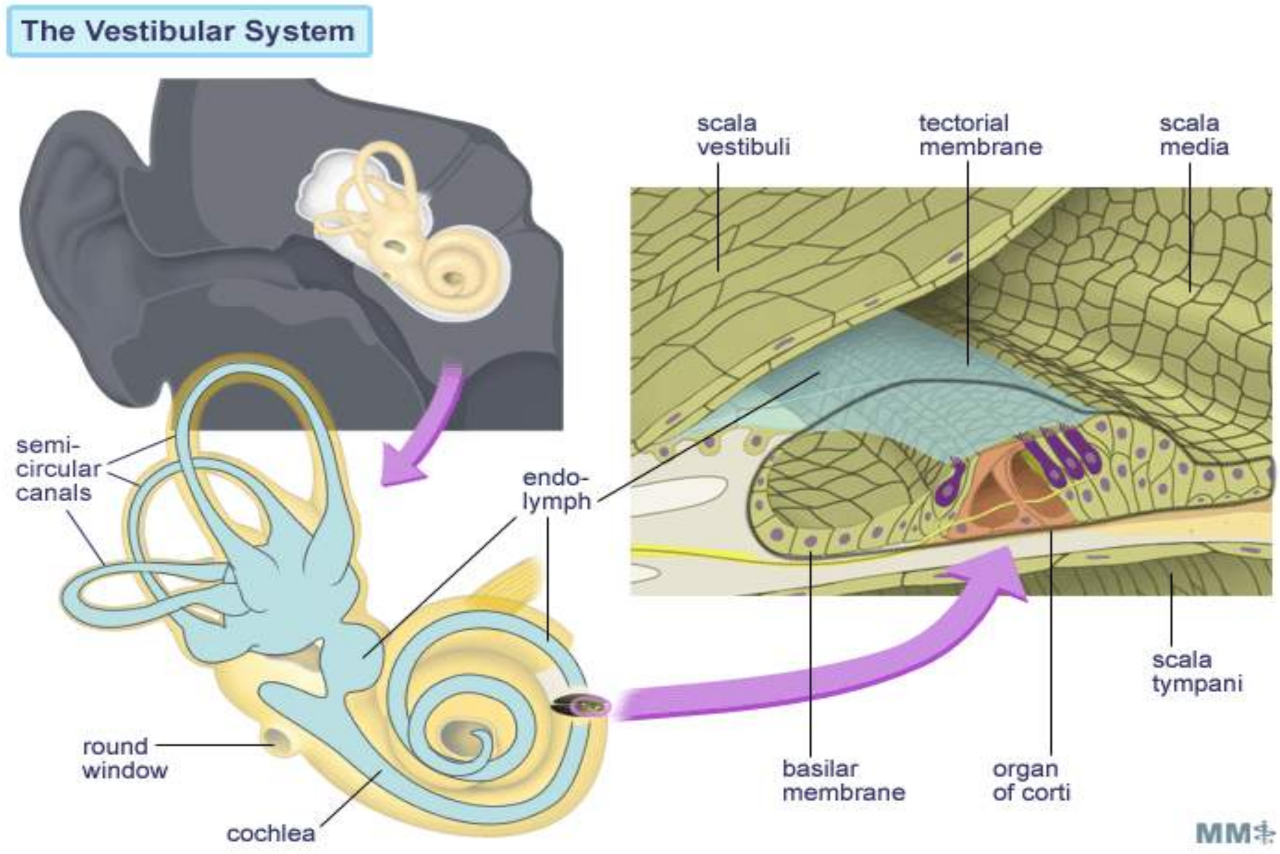
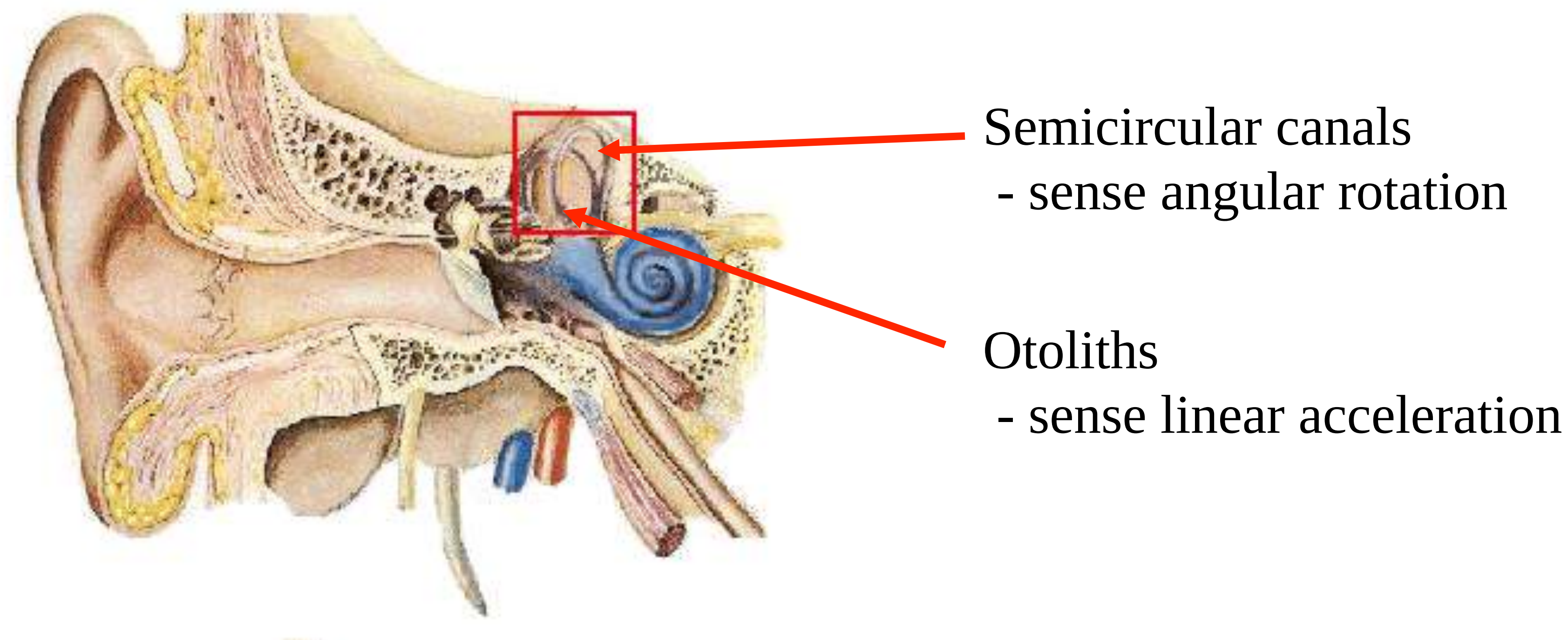
The Vestibular System

The vestibular system is phylogenetically the oldest part of the inner ear:

It is situated in the <u>petrous part</u> of the <u>temporal bone</u>, and is not only in close proximity to the cochlea but is continuous with the scala media.



Function of the Vestibular System

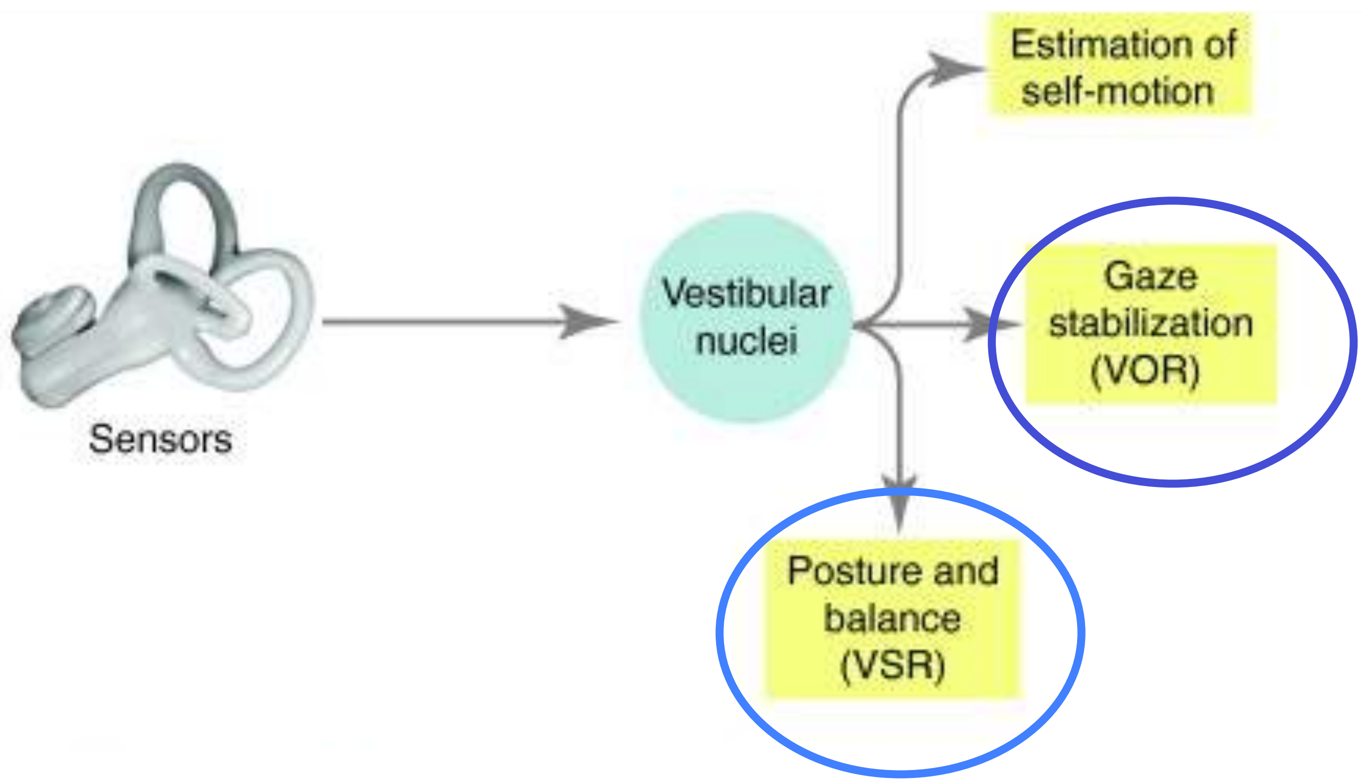


Provide information about head motion relative to space and gravity to:

1) Stabilize the visual axis (VOR)
2) Maintain head and body posture (VCR and vestibulospinal reflexes)
3) Compute spatial orientation or 'sense of balance'
4) Navigation

Function of the Vestibular System

i. The VOR,
ii. Posture and balance, and
iii. Higher order vestibular processing

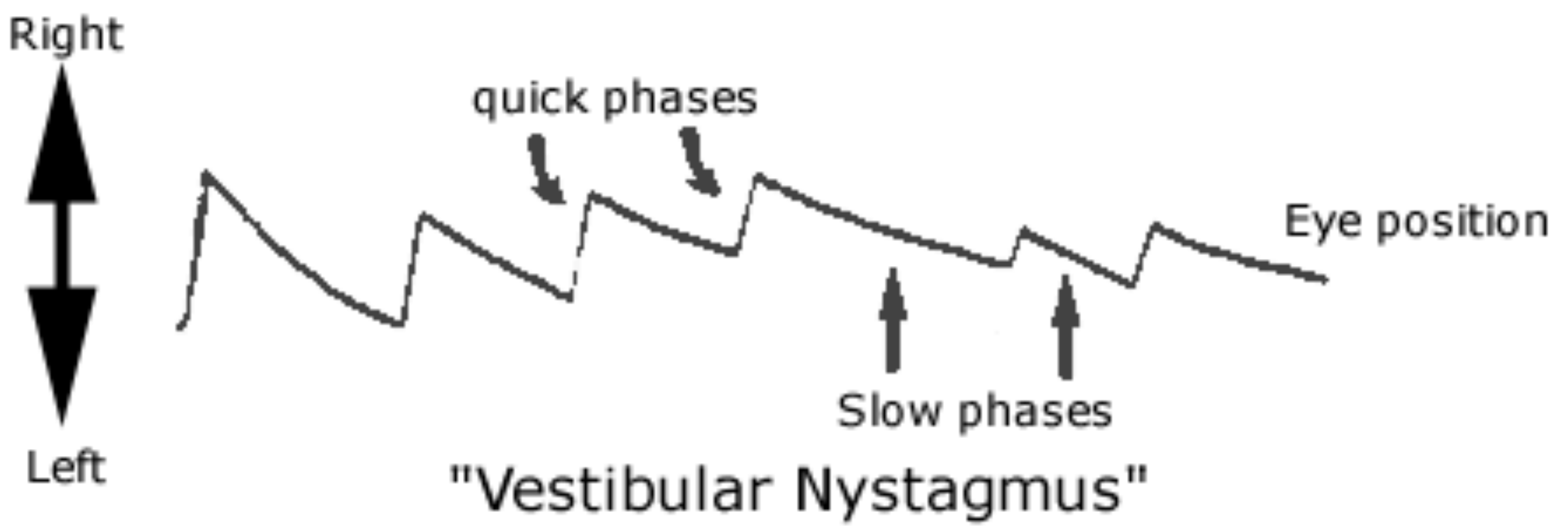


The Vestibulo-Ocular Reflex

(video)

Central Vestibular Processing for the VOR

Central Pathways: Vestibular Nuclei



Slow phase direction = left

Quick phase direction = right

So, head velocity direction = right

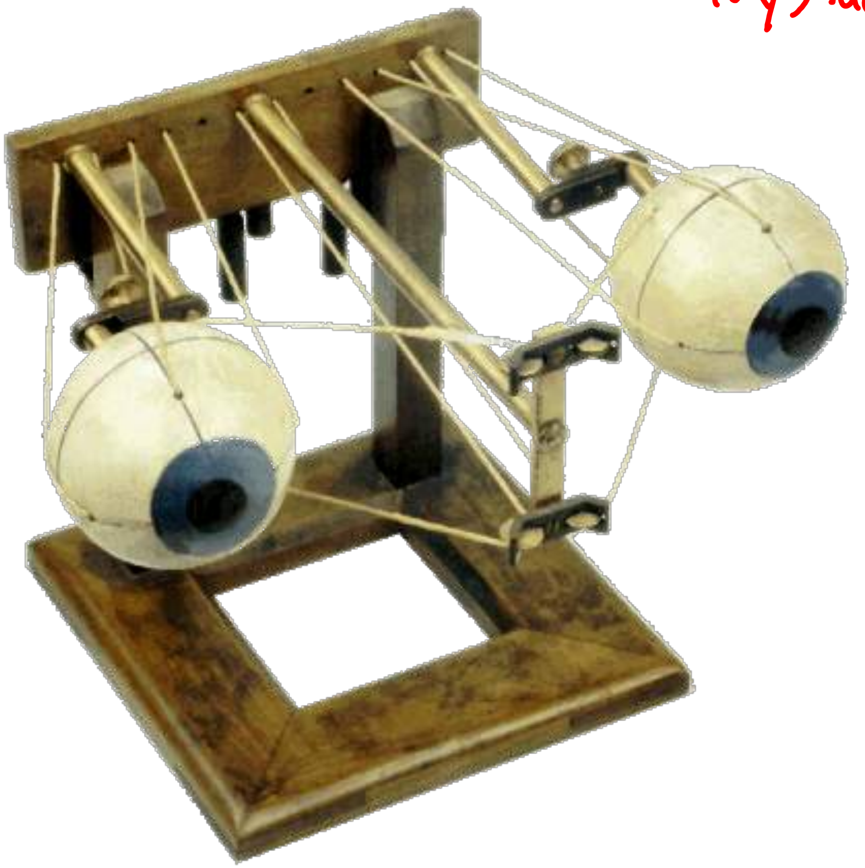
Sensorimotor transformations: VOR

1. Overview of Eye Movements - VOR
2. Motor Control of Eye Movements : Mechanical Constraints
3. The Vestibular System
    - 3.1) Signal Processing by Vestibular Sensors
        - i. Mechanical Analysis of the Semicircular Canals
        - ii. Hair Cells and Afferent responses
    - 3.2) Central Vestibular Processing for the VOR
        - i. Central Pathways (Vestibular Nuclei)
        - ii. Neuronal Pathway: Model of the VOR

How does the brain generate appropriate motor commands to move the eyes to align the axis of gaze with an object of interest?

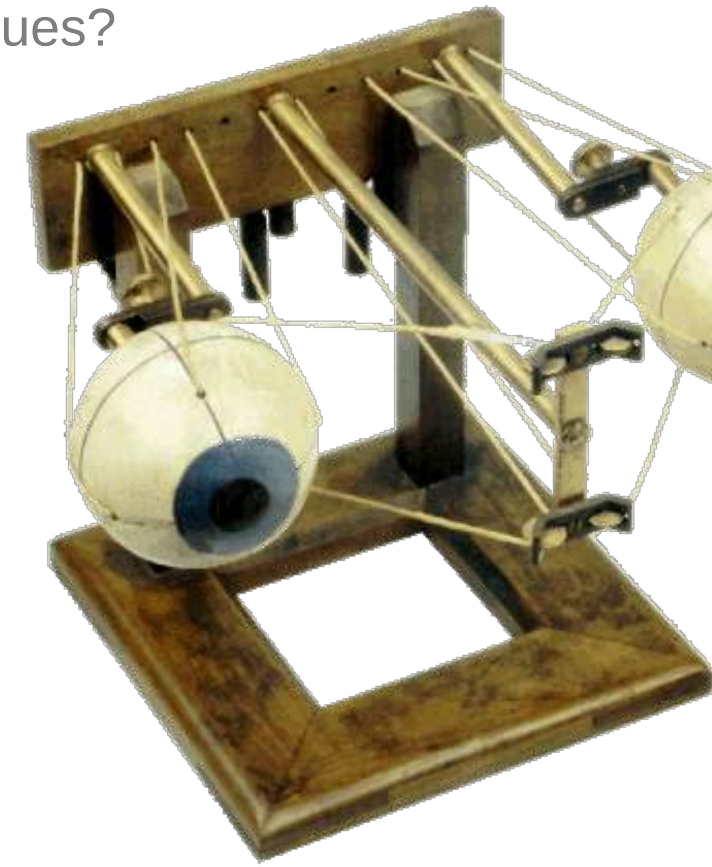
Reflex – Involuntary

Nystagmus



How does the brain generate appropriate motor commands to move the eyes to align the axis of gaze with an object of interest?

What are mechanical properties of the eye and surrounding tissues?



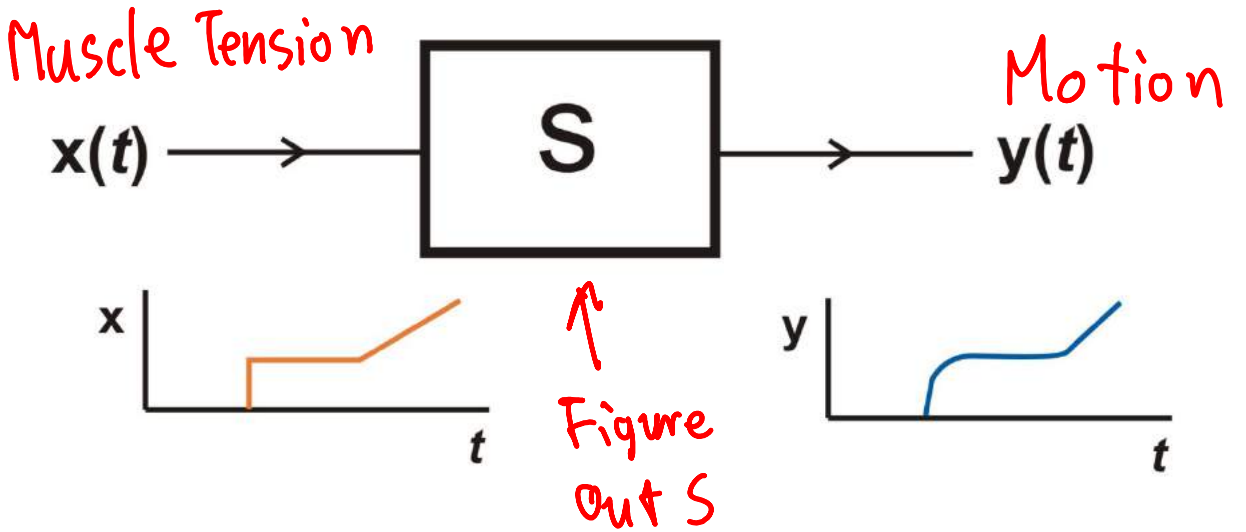
Why Study Eye Movements?
- No joints in system
- Constant inertia (negligible)

Mechanics of Eye Movements

What are the mechanics of the Oculomotor Plant?

Plant: devise which produces the final output

For eye movements = 1) eye muscles, 2) orbital tissues, 3) globe

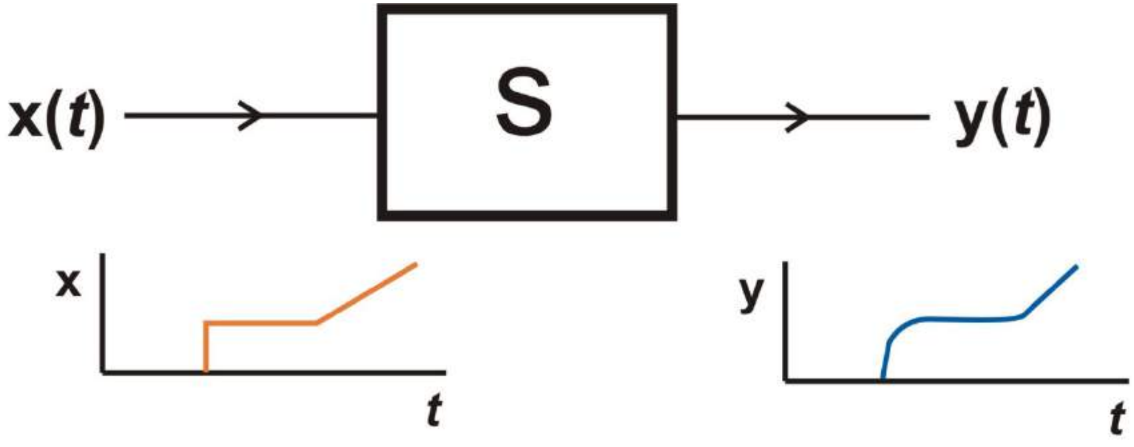


What is the output? Eye Movement

What is the input? Muscle tension

Control System Analysis

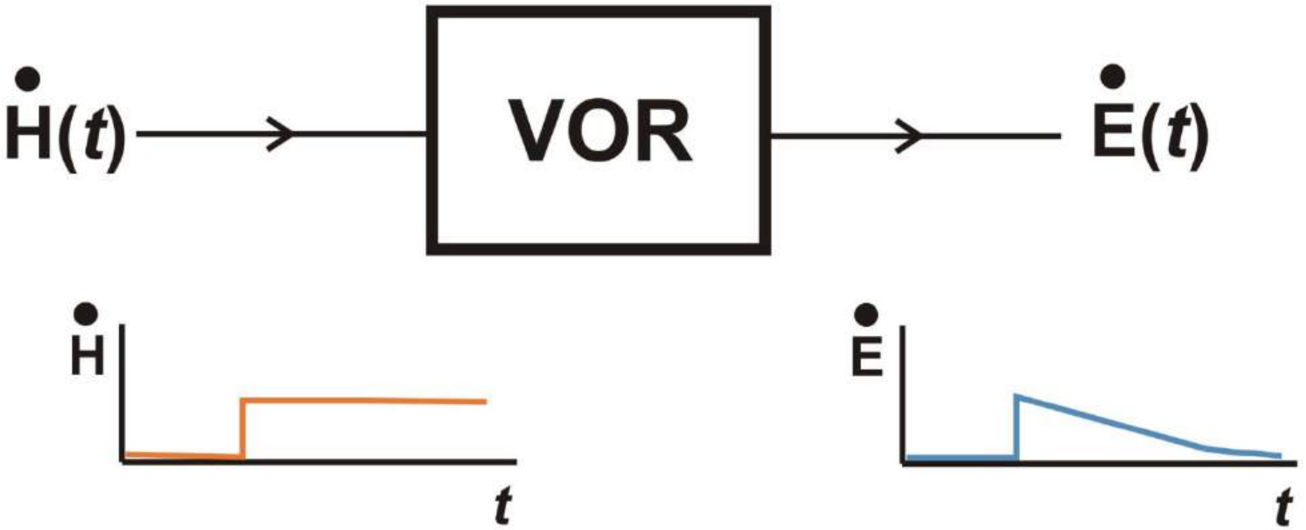
A system is represented as:



Where x(t) is the input, and y(t) is the output. These are signals that very as a function of time.

1) The goal of an engineer, is to design S, so that x results in y.
2) The Neurobiologist already has S, and controls x, observes y
   Then tries to guess what S is.

The VOR as an Example System



Head Velocity

Where:

$\dot{H}(t)$ is head velocity: here a step of velocity

and $\dot{E}(t)$ is slow-phase eye velocity

Eye Velocity

(note $\dot{H}(t)$ and $\dot{E}(t)$ are short hand for dH/dt, dE/dt)

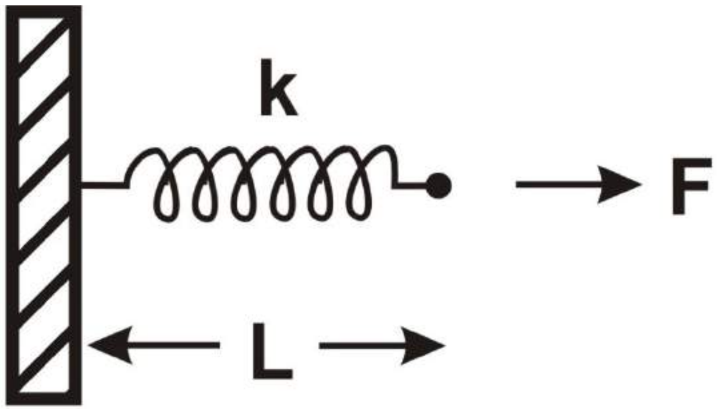
So in this case the problem, is to find S, for the VOR

Mechanical System Analysis

For example, to understand how you move your eye,

First, consider some examples of mechanics to relate force to eye movement:

1) Apply a force F to a spring of stiffness K, stretch it to length L.

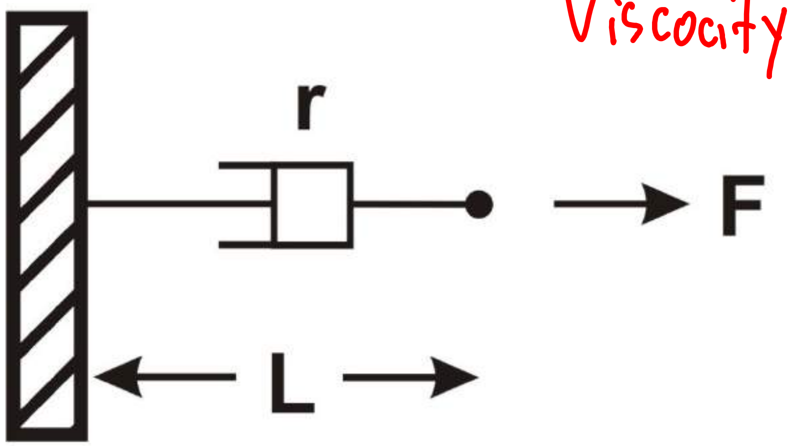


Hooks Law says: $F = kL$

Mechanical System Analysis

2) Apply a force (F) to a system characterized by a pure viscosity (of coefficient r). A good example is a hypodermic syringe.

Viscocity

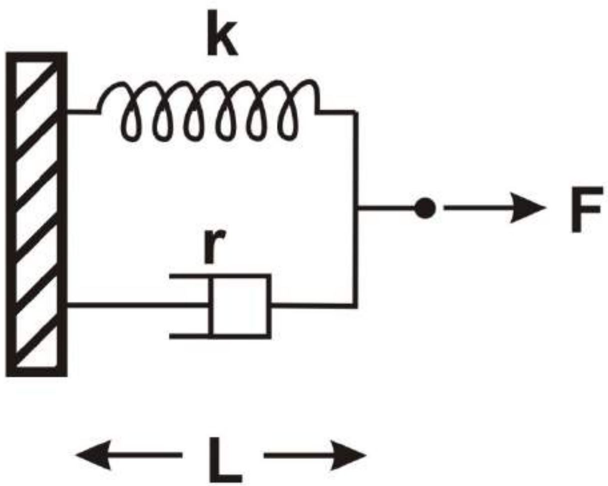


If you push at a constant force, the plunger moves at a constant velocity dL/dt, such that:

$$F = r \quad dL/dt$$

Mechanical System Analysis

3) Put these 2 elements in series (this is a simplified muscle model):



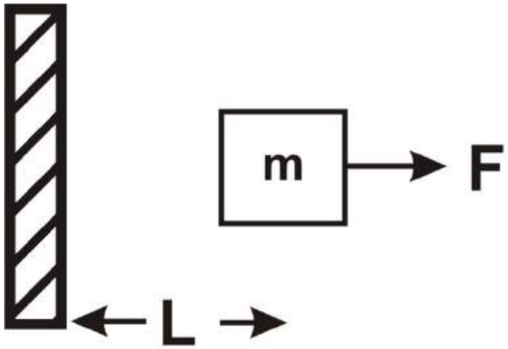
This is called a visco-elasticity. The force is shared by the elasticity (kL) and the viscosity ($r\ dL/dt$) so: $F = kL + r\ dL/dt$

First Order Differential Equation

This is a first order differential equation and if our "system" was a visco-elasticity, solving this equation for a given input should produce the observed output.

Mechanical System Analysis:

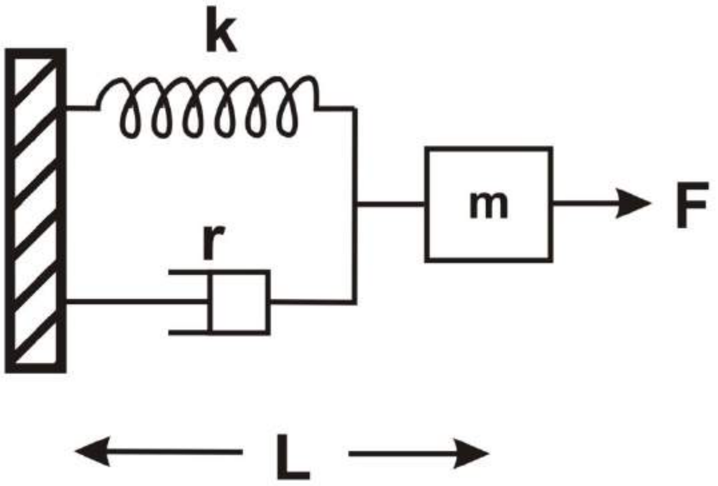
4) Now add a mass to the system:



From Newton's law of motion

$F = m\, d^2L/dt^2$, where d^2L/dt^2 is acceleration

$F = ma$



The system is now described by:

$$F = kL + r\ \ dL/dt + m\, d^2L/dt^2$$

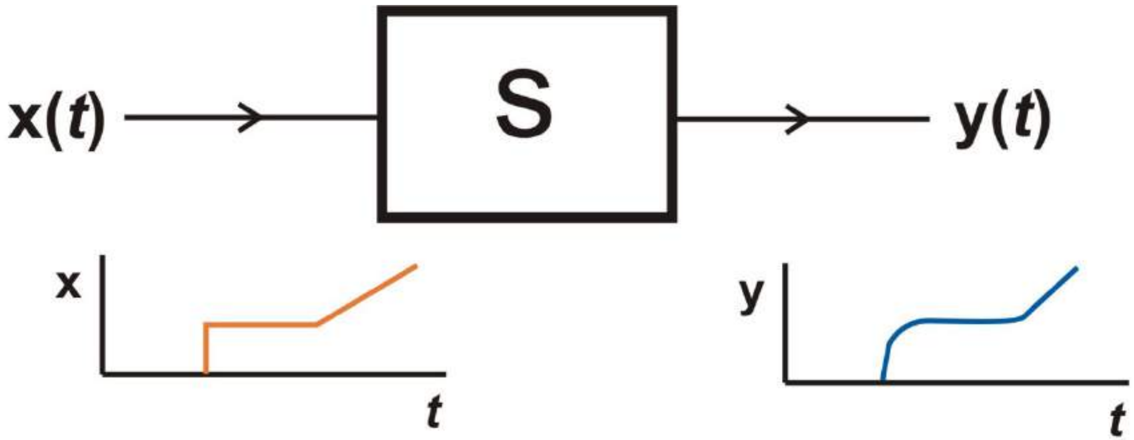
(i.e. a second order differential equation)

Mechanics of Eye Movements

How does mechanical analysis in the previous slides relate to the Oculomotor Plant?

Plant: devise which produces the final output

For eye movements = 1) eye muscles, 2) orbital tissues, 3) globe

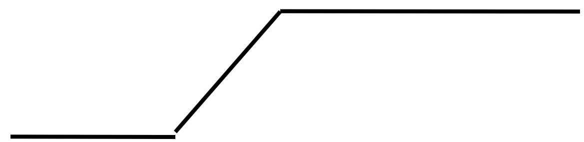


What is the output? Eye Movement

What is the input? Muscle tension, but hard to measure.

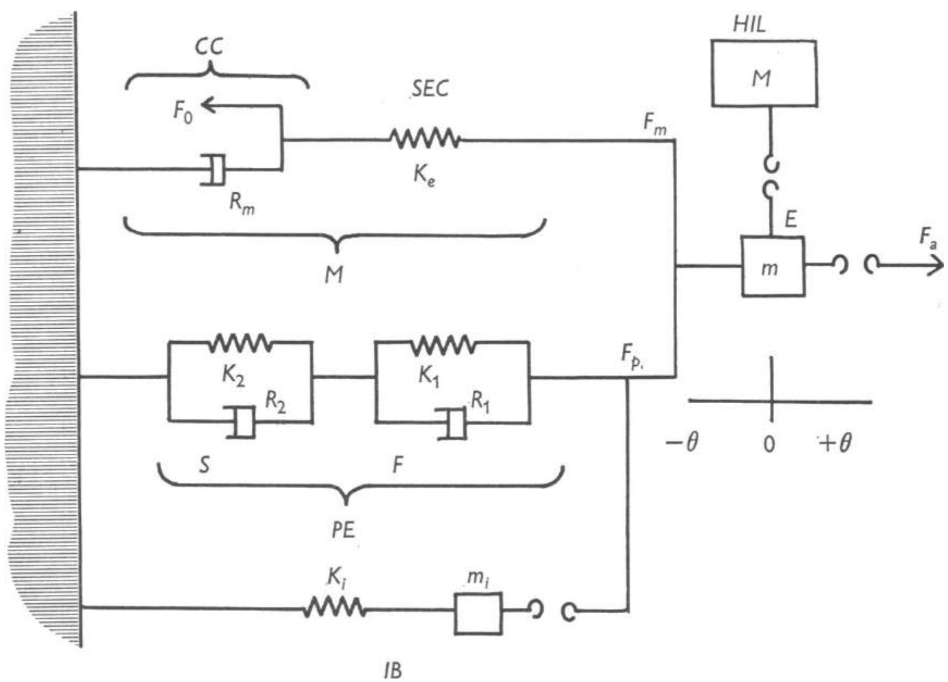
We can measure motoneuron drive to muscles

How does the brain generate appropriate motor commands to move the eyes to align the axis of gaze with an object of interest?



Step 1:
Record Eye movements

Suction contact lens used to apply forces and loads to the eye to understand the Mechanical properties of the eye and surrounding tissue.

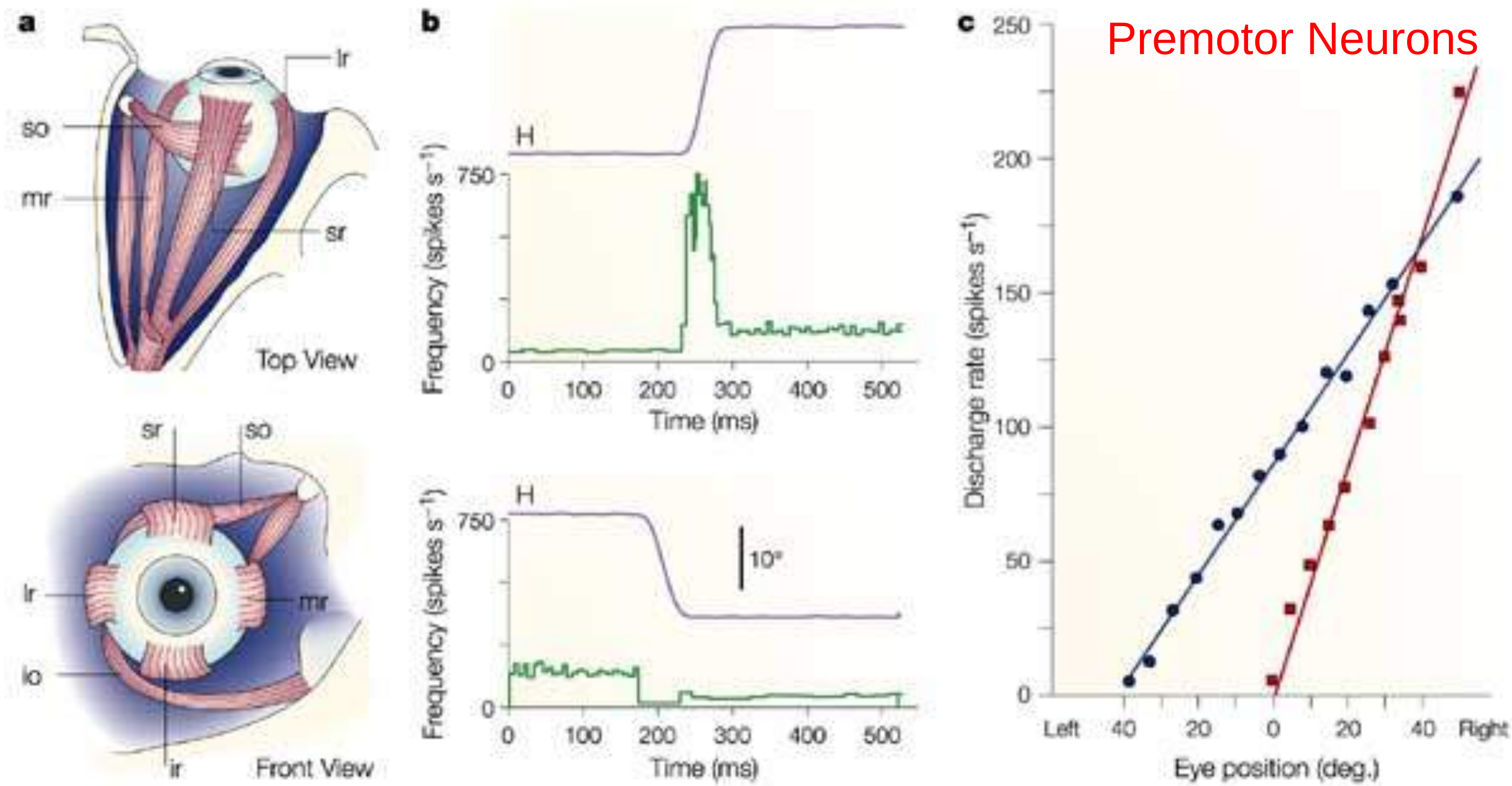


$$FR(t) = b + kE(t - t_d) + r\dot{E}(t - t_d) + u\ddot{E}(t - t_d) - cFR'$$

David Robinson 1964

How does the brain generate appropriate motor commands to move the eyes to align the axis of gaze with an object of interest?

Step 2:
Record Motor and Premotor Neurons



Nature Reviews | Neuroscience

Dave Sparks 2002

Standard Classification of 5 Types of Eye Movements

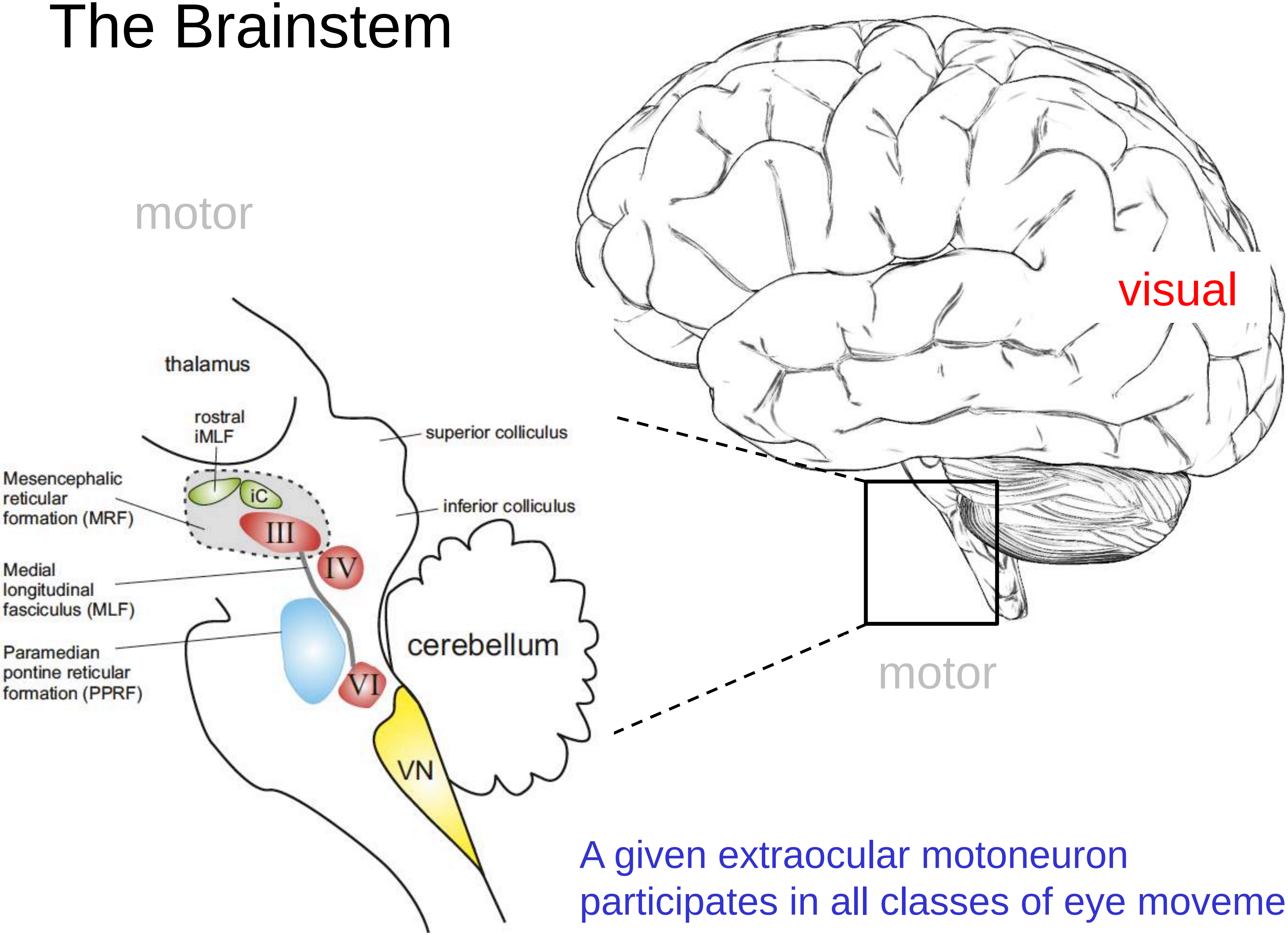
Eye movement classification		Function
Voluntary	Saccade	Fast redirection of gaze between stationary targets
	Pursuit	Slow eye movements used to track moving targets
	Vergence	Rotation of the eyes in opposite directions to fixation targets at different depths
Involuntary	Vestibulo-ocular	Uses vestibular inputs to hold images stationary on the retina as the head moves
	Optokinetic	Uses visual inputs to stabilize gaze in response to low frequency head movements

Classically eye movements grouped into 5 types

Extraocular motoneurons participate in all types of eye movements and their response dynamics can (largely) be predicted by the mechanics of the eye.

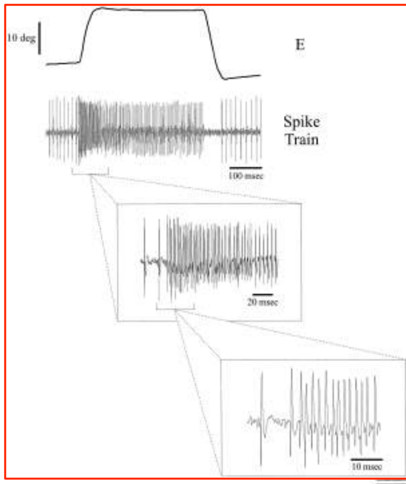
One plant can model them all

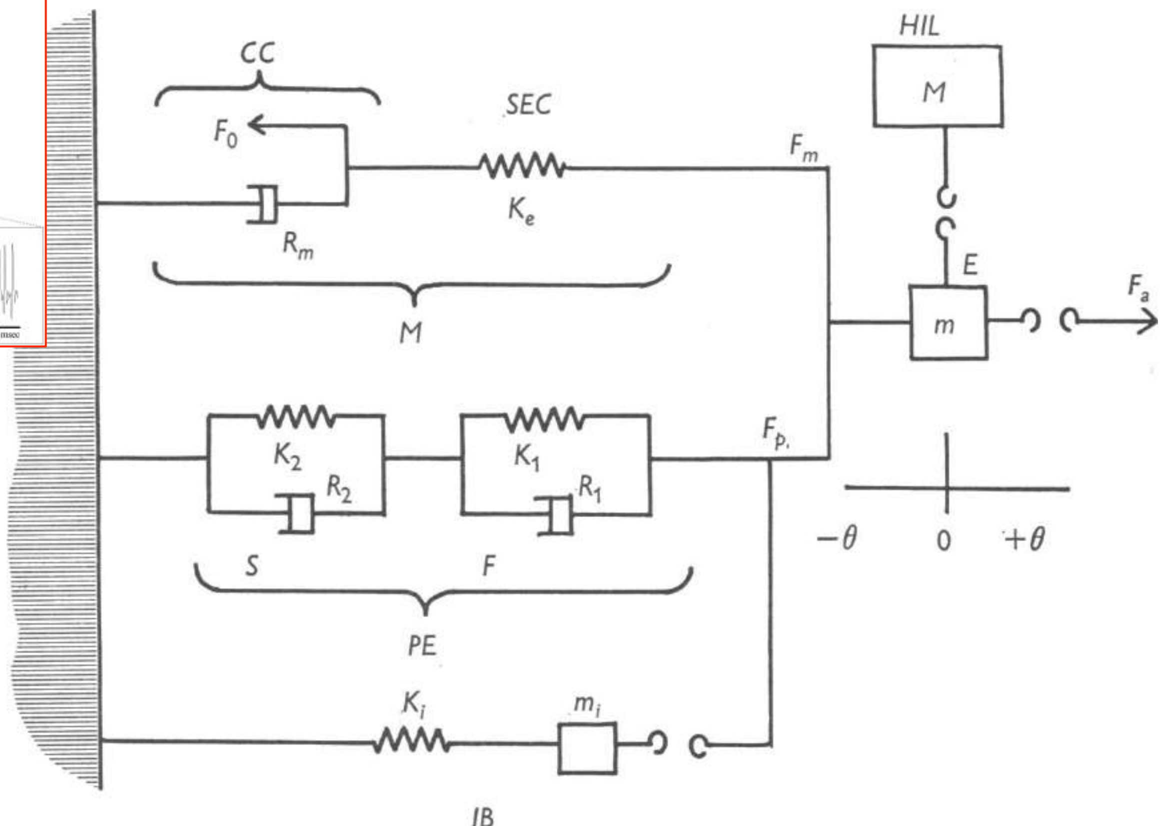
The Brainstem



A given extraocular motoneuron participates in all classes of eye movements
.

How does the brain generate appropriate motor commands to move the eyes to align the axis of gaze with an object of interest?





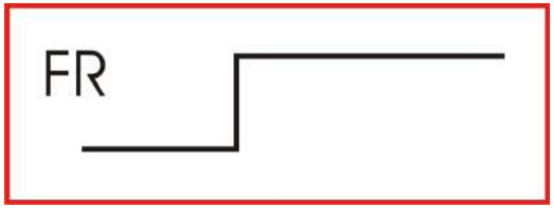
$FR(t) = b + kE(t - t_d) + r\dot{E}(t - t_d) + u\ddot{E}(t - t_d) - cFR'$

Van Gisbergen et al. 1981
Sylvestre and Cullen 1999

Description of MN discharge rate

Recall:

1) $Fr = Ro + KE + r\dot{E}$



$\downarrow$

In the Laplace domain:

Derivative: $\ell[\frac{df}{dt}] = sF(s) - f(0^+)$

$\downarrow$ $\dot{E} = sE$

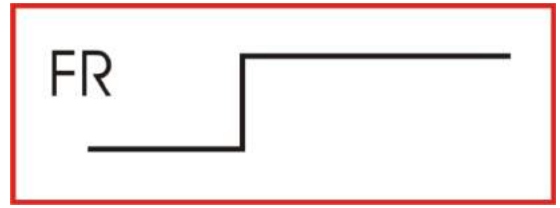
2) $Fr(s) = KE(s) + r\,s\,E(s)$

$H(s) = E(s)/Fr(s) = (1/K)/\ [(\mathbf{r/K})s + 1]$

The time constant: $\boldsymbol{\tau_e = {}^{r}/_{k}}$

Description of MN discharge rate

3) $Fr - Ro = KE + r\dot{E}$ if $\tau_e = {}^r/_k$



$$E(t) = R(1- e^{-t/\tau e})$$

$$E(t) = R(1- e^{-1}) \text{ if } t = \tau_e$$

$$= R(1 - {}^1/_e)$$

$$= R(1 - {}^1/2.7)$$

$$= R \times .63$$

If : $r = 1$, $K = 5$, then $\tau_e = 250$ ms

Consider a saccadic eye movement, the eye Dynamics with a step command of FR would be too slow. Saccades can be on target in less than 100ms.

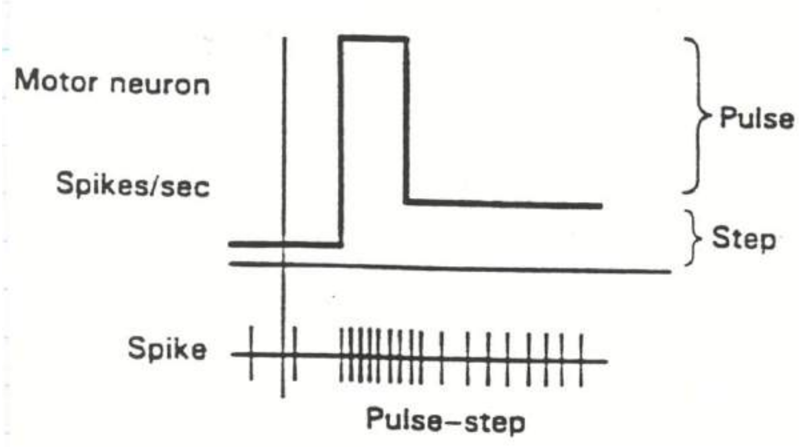
Analysis of Motoneuron Signals

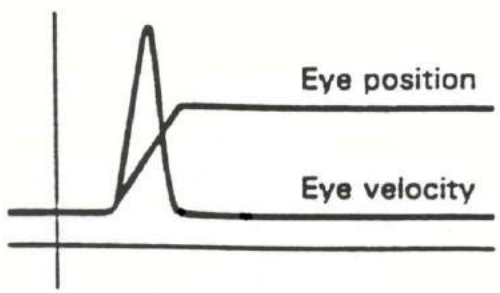
Pulse

Need an extra "burst" (pulse) in MN command signal in order to complete saccade in a shorter time (i.e. overcome viscous drag).

Step

Also need tonic activity after saccade (step) in order hold eye at new position (i.e. overcome elastic restoring forces).

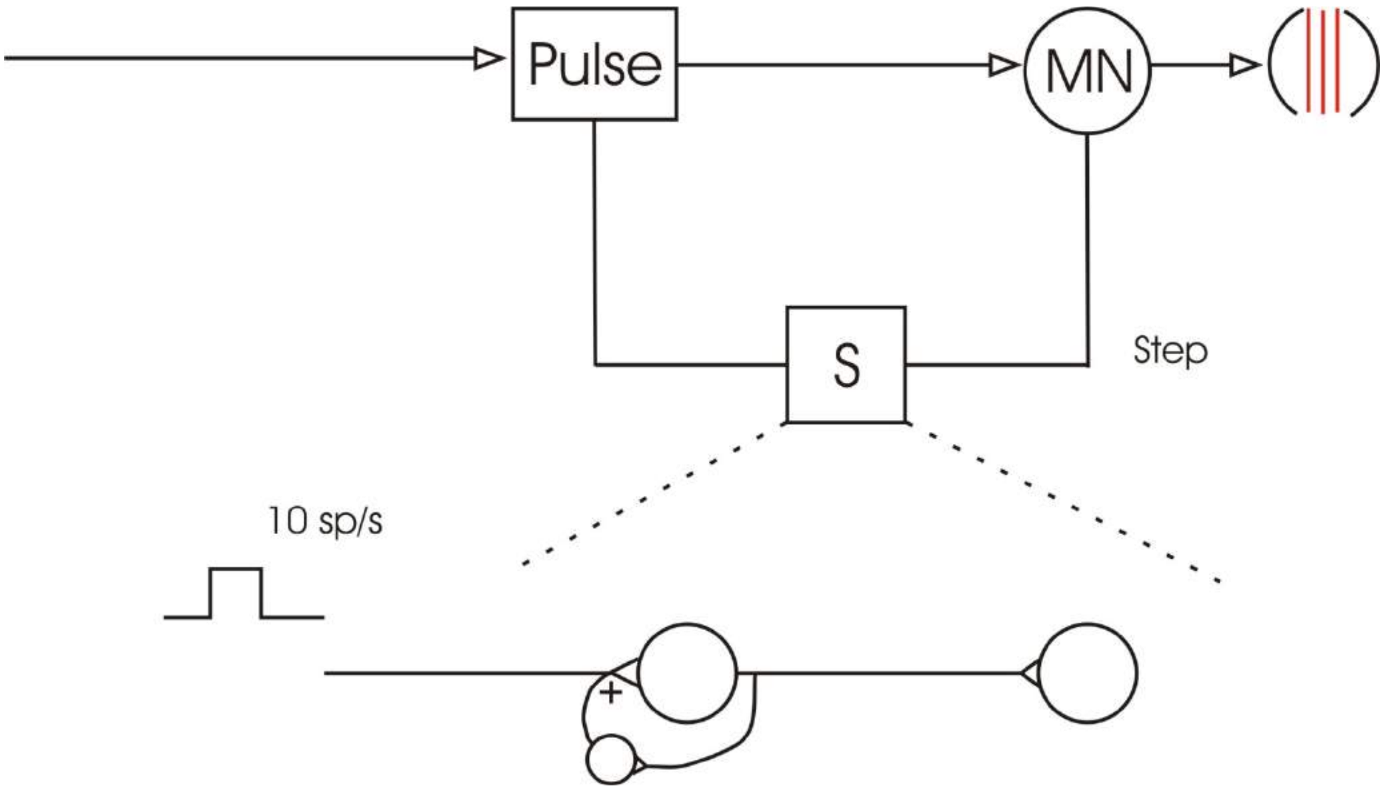




Note, The pulse resembles velocity + The step resembles position

Neural Circuit: Controlling Saccades

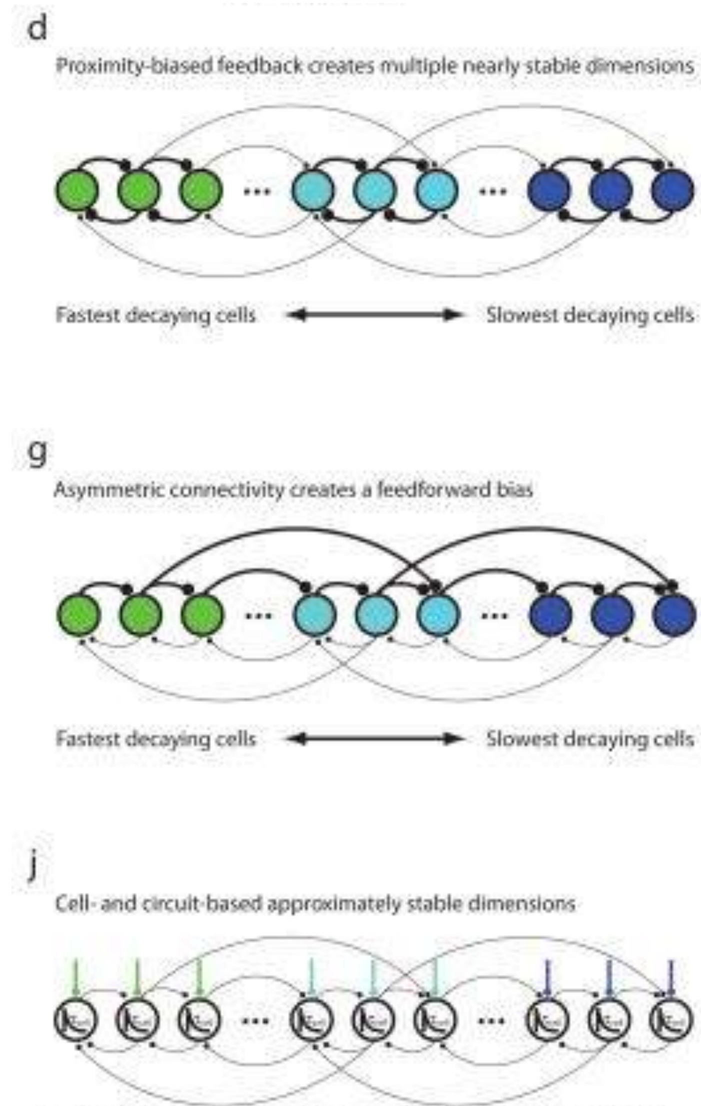
Tonic activity after saccade (step) generated by the oculomotor neural integrator



Neural Circuit: Controlling Saccades

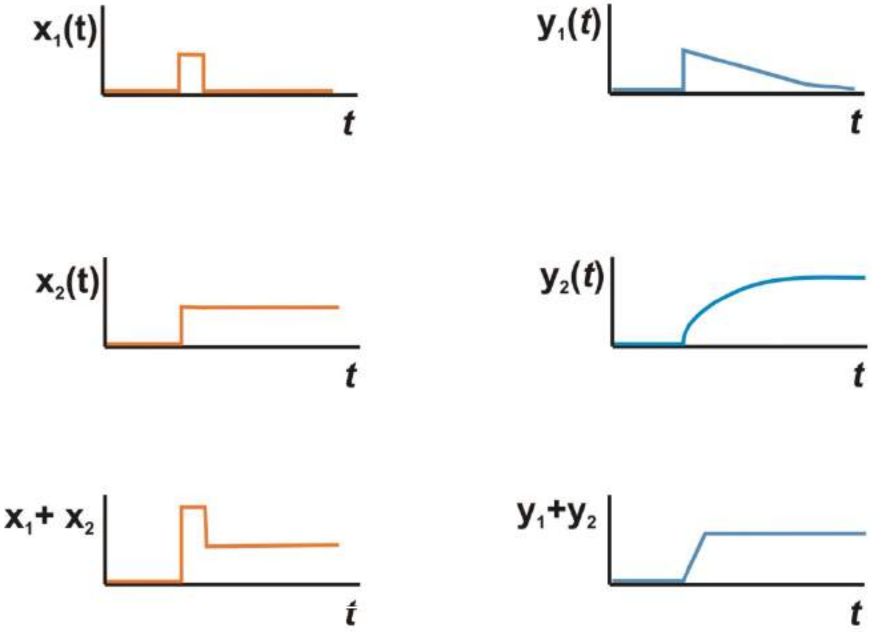
Tonic activity after saccade (step) generated by the oculomotor neural integrator

Current model of the neural integrator based on experimental findings in Species ranging from monkeys to Zebrafish.



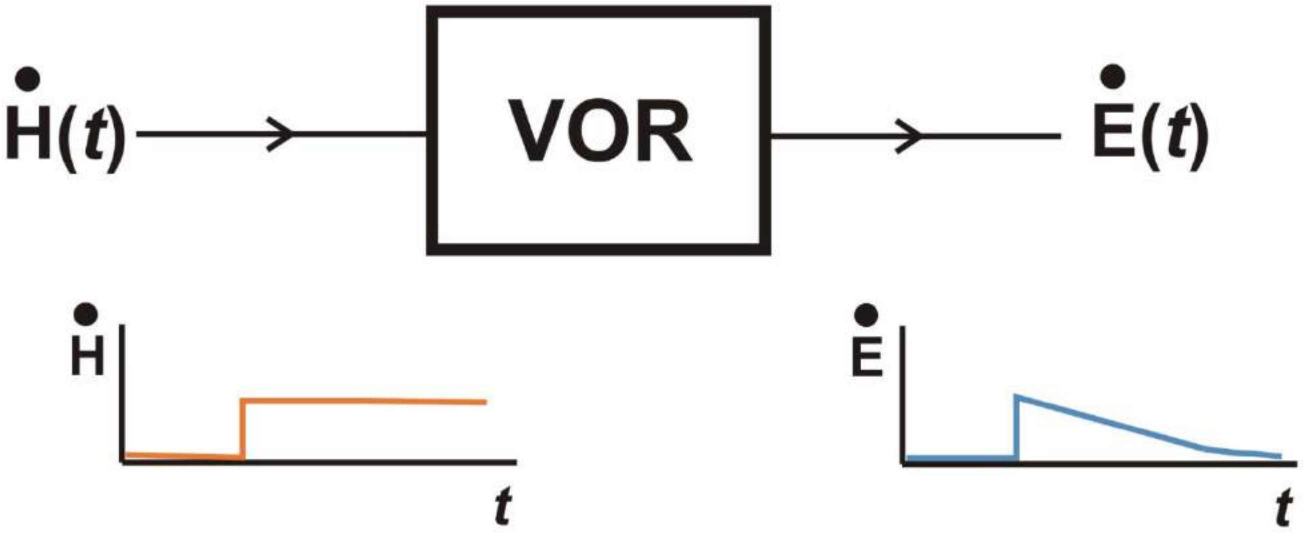
Miri et al,
Nature NS., 2011

Linearity and Superposition:



For example, the MN equation added the results from 3 experiments, together. *Assumption: The system is linear*. If we put in 2 signals, the output is the same as as the sum of the response of each alone.

The VOR as an Example System



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So in this case the problem, is to find S, for the VOR

Sensorimotor transformations: VOR

So, far we have considered

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2. Motor Control of Eye Movements : Mechanical Constraints
3. The Vestibular System
    - 3.1) Signal Processing by Vestibular Sensors
        - i. Mechanical Analysis of the Semicircular Canals
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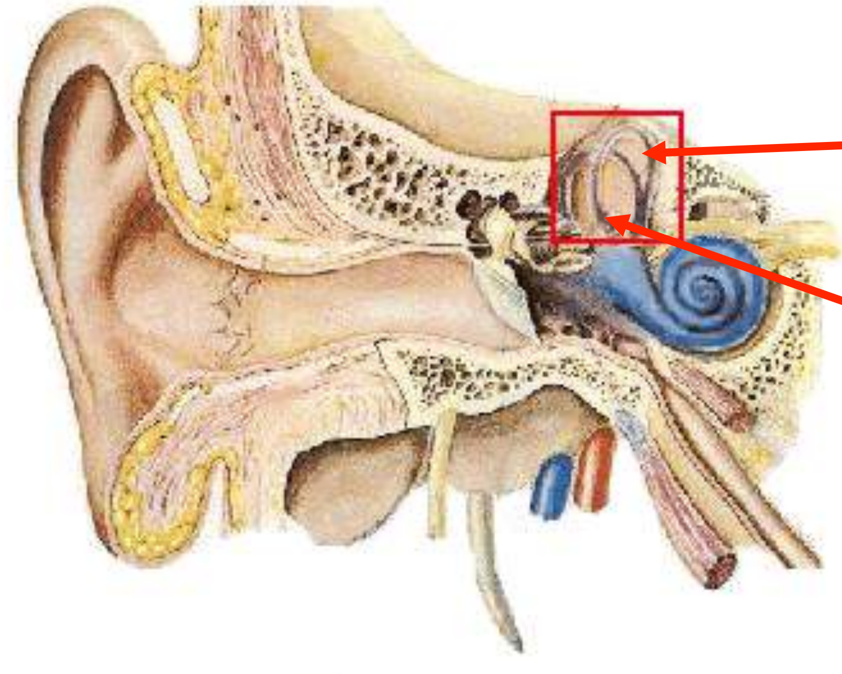
Function of the Vestibular System



Semicircular canals
- sense angular rotation

Otoliths
- sense linear acceleration

Provide information about head motion relative to space and gravity to:

1) Stabilize the visual axis (VOR)
2) Maintain head and body posture (VCR and vestibulospinal reflexes)
3) Compute spatial orientation or 'sense of balance'
4) Navigation

Organization of the Vestibular System

Anatomy: there are 2 types of sensors on each side of the head.

Linear

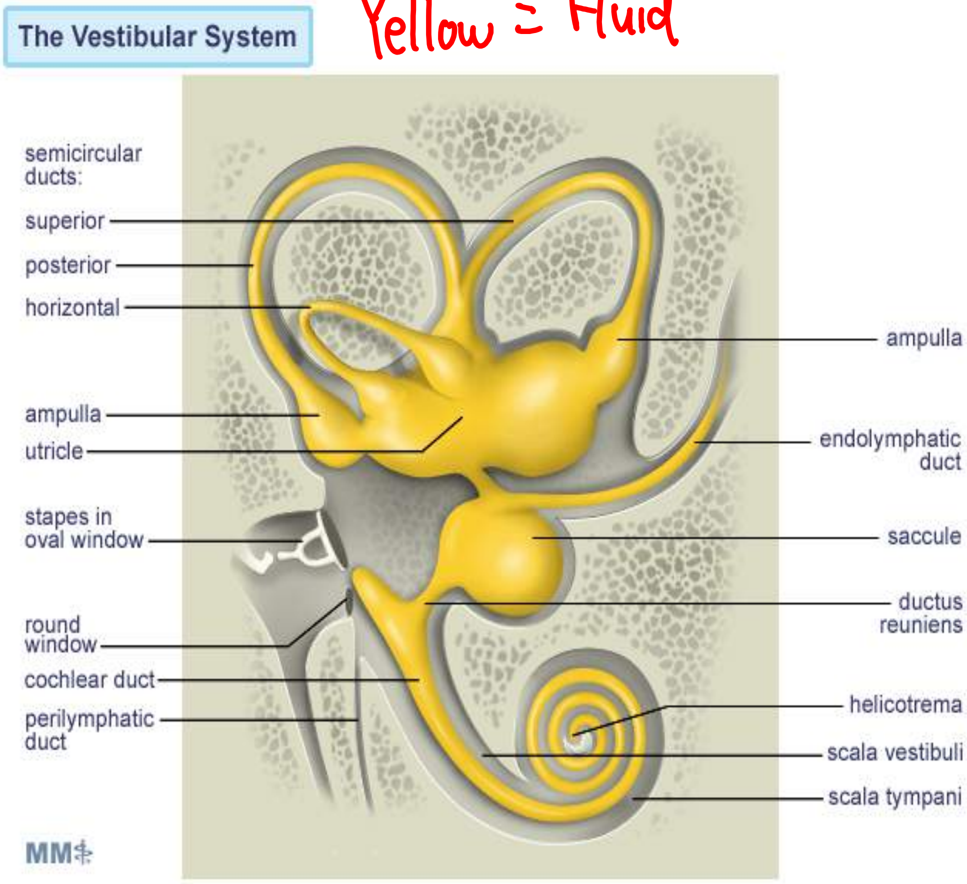
1) Otoliths (linear acceleration)
   → saccule
   → utricle

Macula

2) Semicircular canals
   (angular acceleration) Angular
   → horizontal
   → superior
   → posterior

Ampula
(crista)

Yellow = Fluid



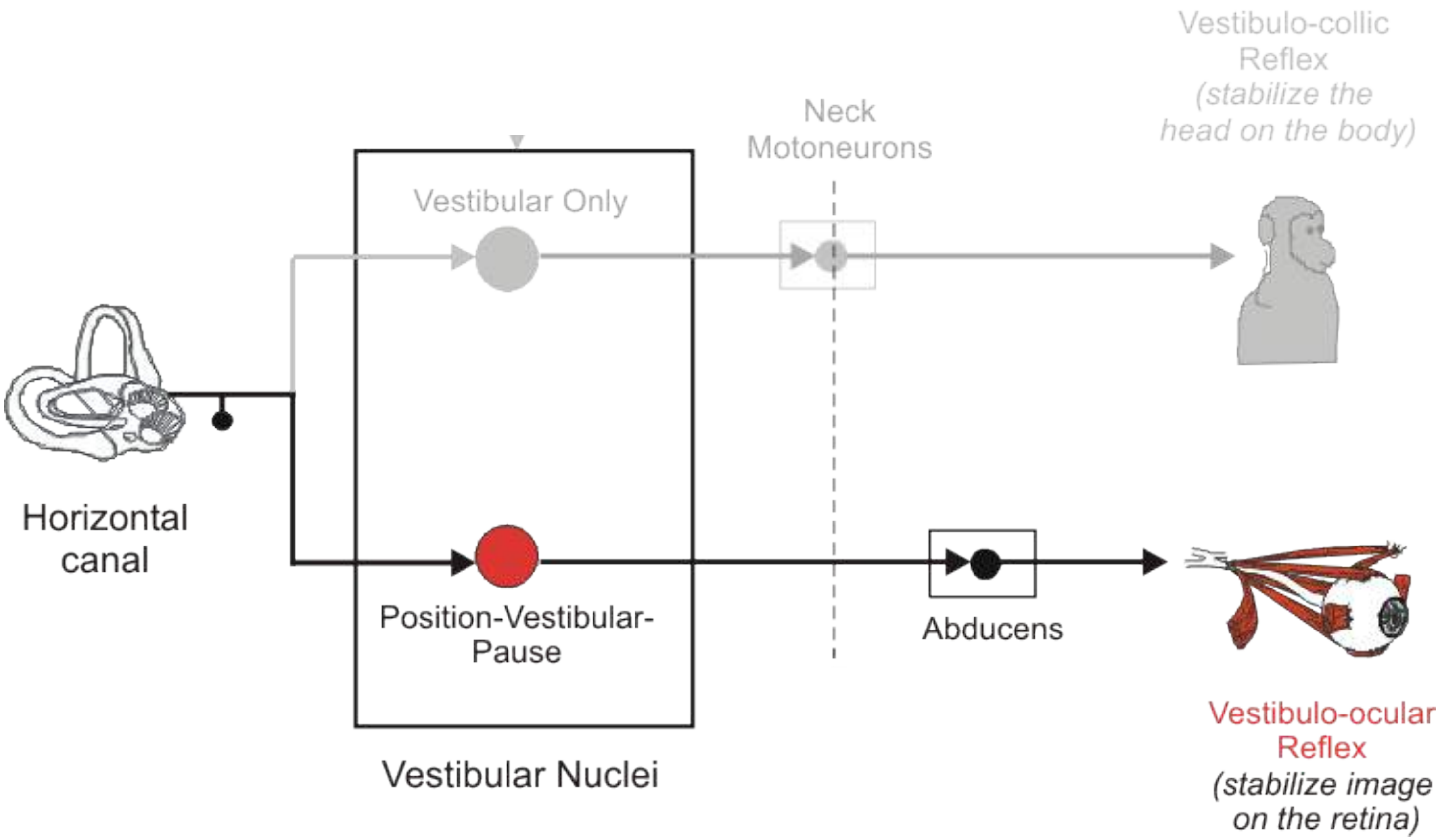
Note: Entire system is continuous with scala media of the cochlea via the ductus reunions.

Function of the Vestibular System

i. The VOR,

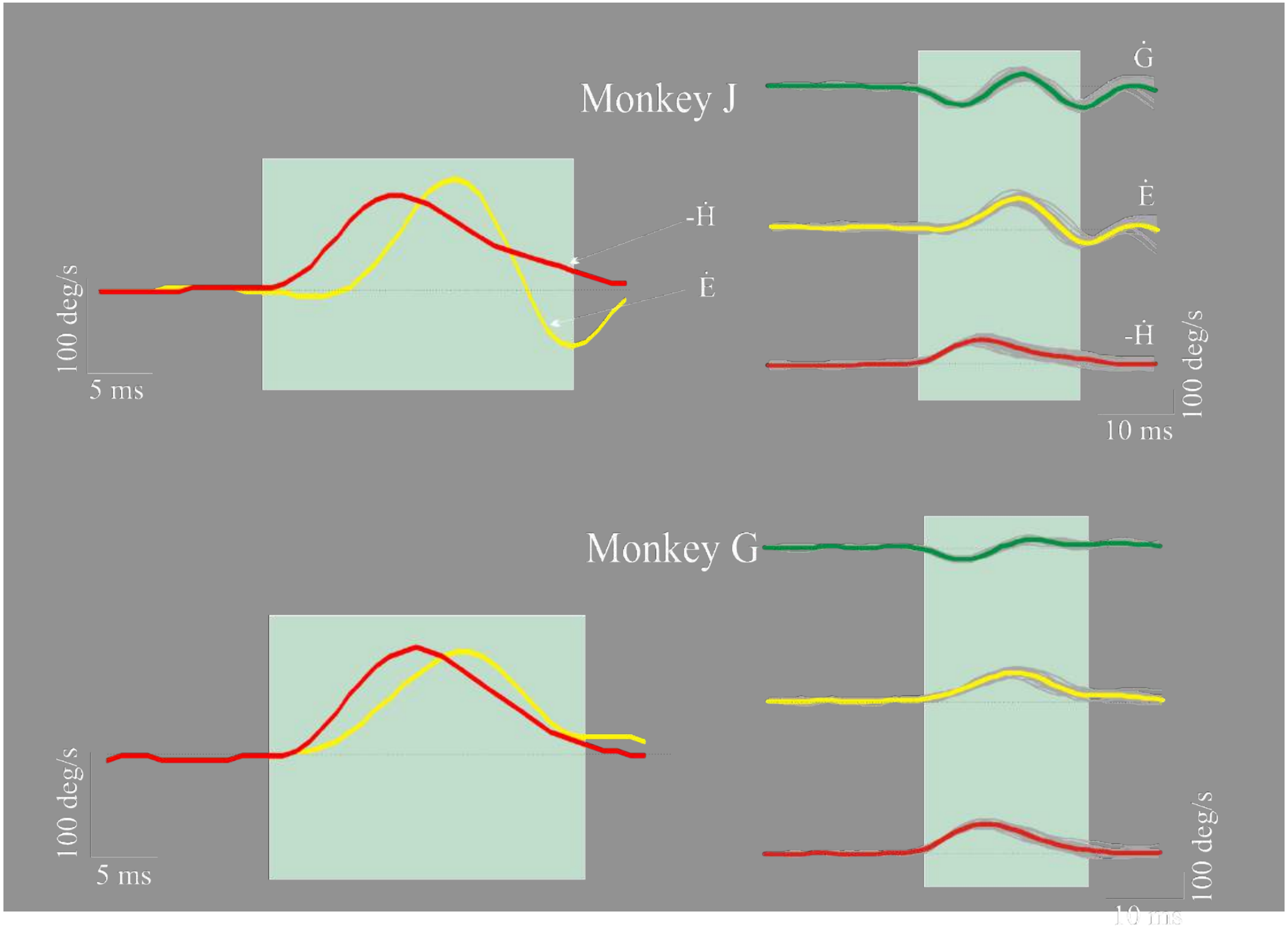
ii. Posture and balance, and

iii. Higher order vestibular processing



Function of the VOR

Gaze Stabilization via the Vestibulo-ocular Reflex



More effective than vision since response latency is very short!

Huterer and Cullen, *J. Neurophys.*, 2002

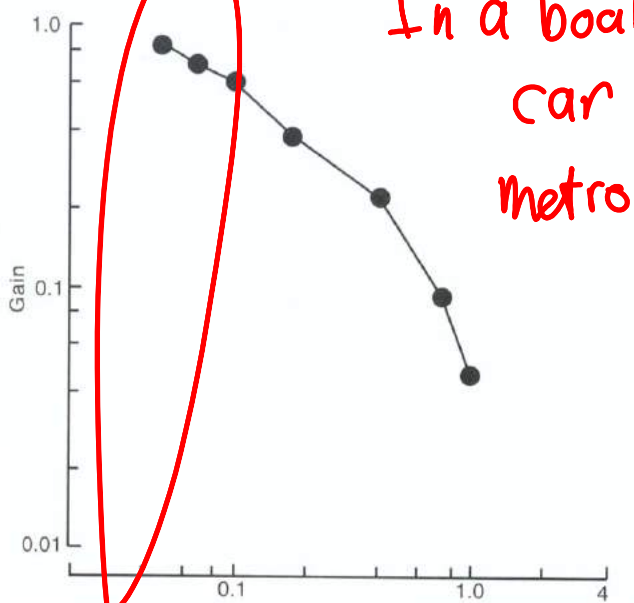
Function of the VOR

Gaze Stabilization via the Vestibulo-ocular Reflex

$$\text{Gain} = \frac{\text{Eye Velocity}}{\text{Head Velocity}}$$

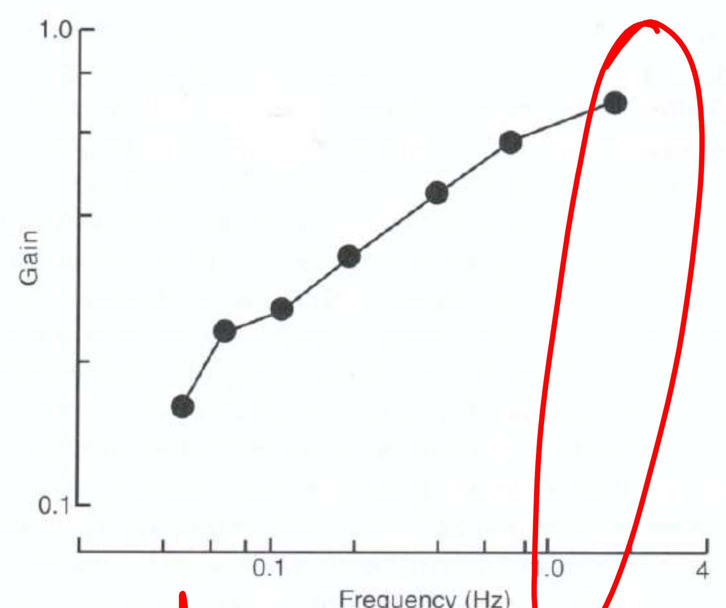
OKN Gain

VOR Gain



In a boat
car
metro

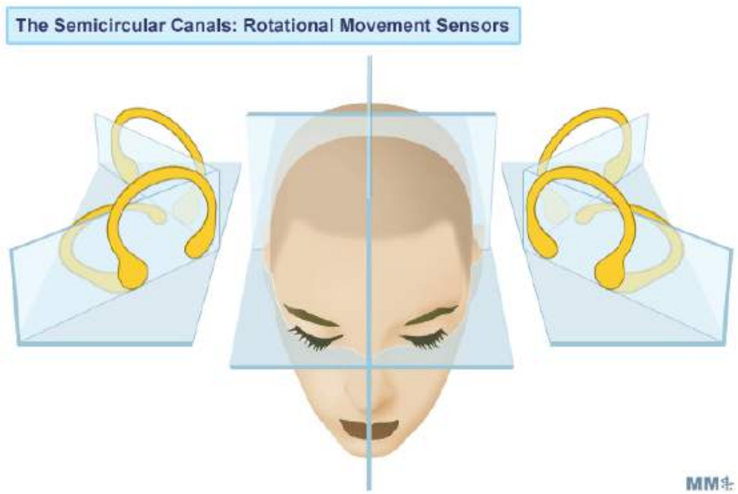
low F



Good with high F

Accordingly, VOR is more effective than visually driven OKN at higher frequenceis

Mechanical Analysis of the Semicircular Canals



- The 3 canals are ~ at right angles to each other.
- Each of the 3 planes lie approximately in the pulling direction of one of the pairs of extraocular muscles

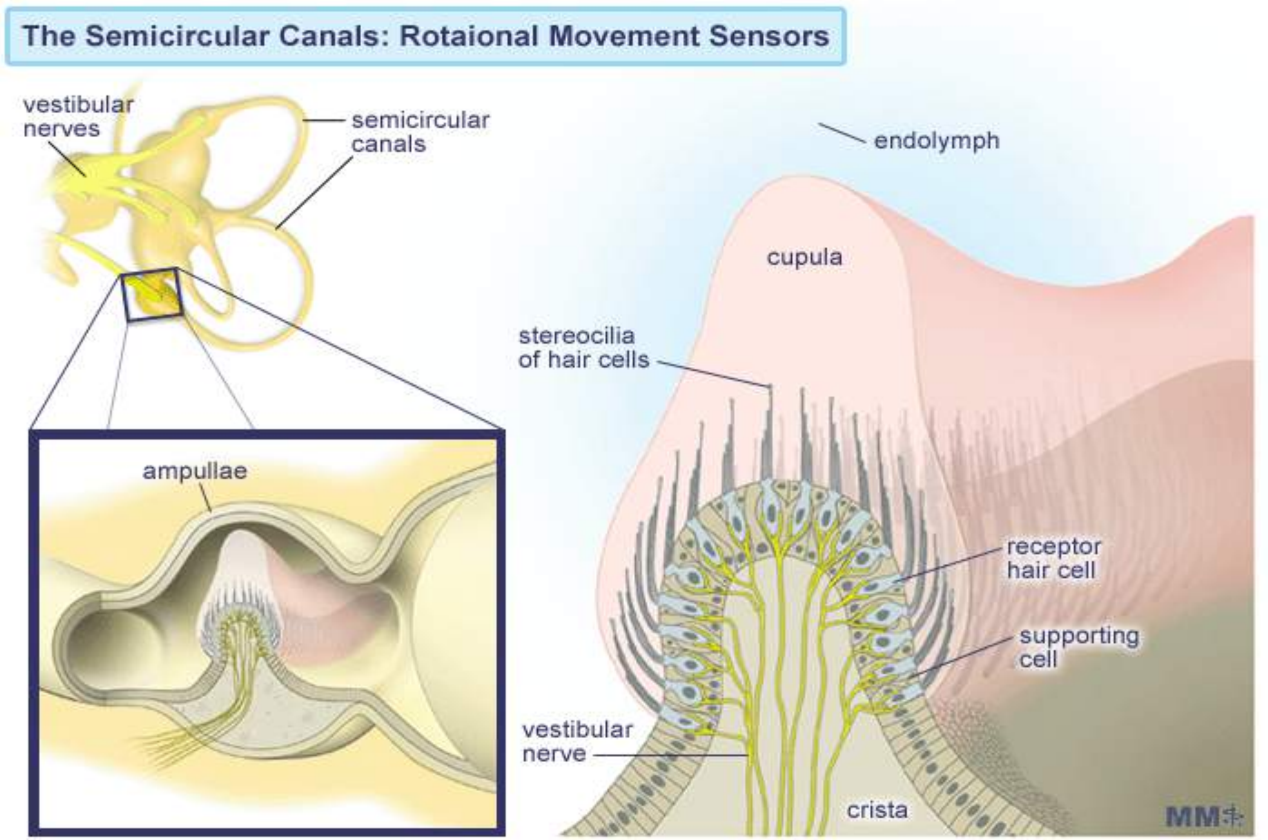
Horizontal → horizontal for normal resting posture.

Superior
Posterior → subtend 45^o relative to the sagittal and frontal plane.

Each canal consists of

1) A circular fluid path
2) <u>2) Ampulla</u> → crista – hair cells
→ cupula – elastic membrane (water tight)

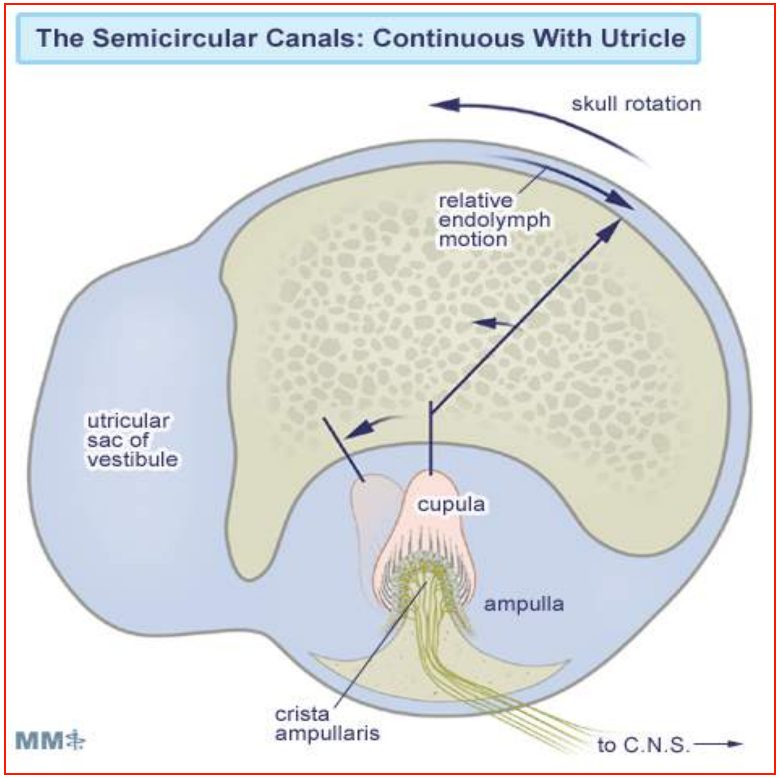
Mechanical Analysis of the Semicircular Canals



Receptor Cells
All hair cells are oriented in the same direction for each canal.

Mechanism: Head rotates
→ fluid is left behind
→ ampulla pushes against it
→ bends cilia.

Mechanical Analysis of the Semicircular Canals



The cupula is deflected by the movement of the endolymph, which occurs during head motion. The following sequence of events occurs:

1) the head turns
2) the endolymph tends to remain stationary due to inertial forces
3) therefore the endolymph moves relative to the canal
(in the opposite direction of head motion).

Mechanical Analysis of the Semicircular Canals

Stimulus = Angular acceleration

But Over the frequency range of normal head movements (i.e. > .01Hz).

The very small diameter (0.3mm) → ↑viscous properties of the fluid

This is mathematically equivalent to ∫ (integration)

Head Acceleration

↓

Head Velocity

↓

Thus, the system functions as an angular speedometer

(hair cell output ⟶ rotational speed)

CNS → 3 canals = speed of head in 3D

Hydrodynamic analysis of the canals predicted that the relationship between the angular displacement of the endolymph ($\varepsilon(t)$) and the head's angular acceleration ($\alpha(t)$) is:

$$\theta d\, \varepsilon^2/dt^2 + \Pi\, d\, \varepsilon(t)/dt + \Delta\, \varepsilon(t) = \theta\alpha(t)$$

Acceleration Velocity Position

Where: θ is the effective moment of inertia of the endolymph.

Π is a damping constant that reflects the viscous drag exerted by the canal wall as the endolymph flows past it, and

Δ Is a elastic restoring factor related

The dynamics of this equation are governed by two time constants,

1) a long one ($\tau 1= \Pi / \Delta = 5s$) and
2) a short one ($\tau 2= \theta / \Pi = .004s$).

Hydrodynamic analysis of the canals predicted that the relationship between the angular displacement of the endolymph ($\varepsilon(t)$) and the head's angular acceleration ($\alpha(t)$) is:

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In the Laplace domain:

Derivative: $\ell[\frac{df}{dt}] = sF(s) - f(0^+)$

$$\ell[\frac{d^2 f}{dt^2}] = s^2 F(s) - s\ f^1(0^+) - f^0(0^+)$$

$$H(s) = E(s)/\alpha(s)$$

$$H(s) = 1/ [(\Pi / \Delta)\, s+1]\, [(\theta / \Pi)\, s+1]$$

Where: θ is the effective moment of inertia of the endolymph.

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Δ Is a elastic restoring factor related

The dynamics of this equation are governed by two time constants,

1) a long one ($\tau 1 = \Pi / \Delta = 5$s) and
2) a short one ($\tau 2 = \theta / \Pi = .004$s).

This equation says that the movement of the endolymph in the canals is opposed by two frictional forces

1) one which arises from the viscosity of the endolymph and
2) a second which is due to the elasticity of the cupula.

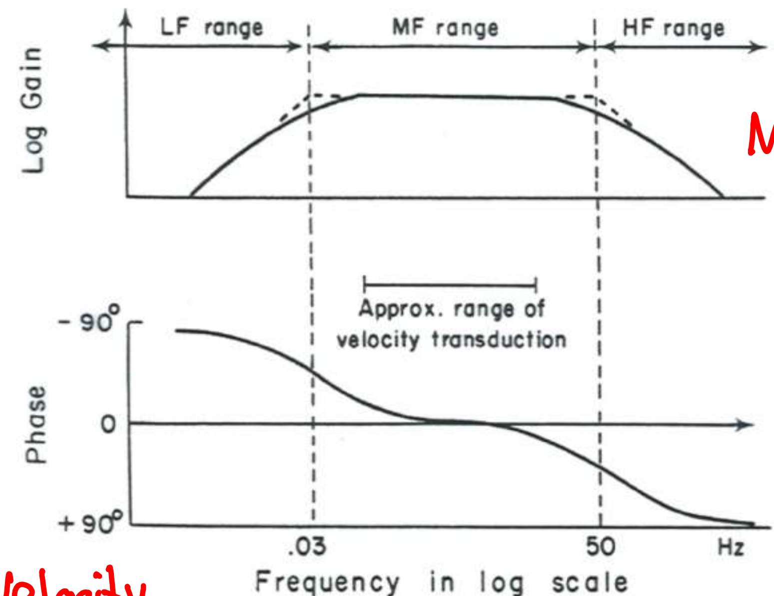
These opposing forces cause the movement of the endolymph (relative to the cupula) to *lag* head acceleration (as would be the case if the only the inertia of the endolymph were significant). • •

Thus the receptor cells which deflect the movement of the cupula are primarily sensitive to head velocity (rather than acceleration) during most natural head movements (i.e. frequency = 0.05-20Hz).

- This is shown in the next slide……………

Mechanical Analysis of the Semicircular Canals

Frequency Response



No Acceleration
No frequency

Velocity

Most head movements fall in here

System is characterized in terms of gain and phase (Bode Plots).

Note, in this graph a phase of 0 deg is in phase with velocity, and -90 and +90 deg are in phase with acceleration and position.

Sensorimotor transformations: VOR

So, far we have considered

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        - i. Mechanical Analysis of the Semicircular Canals
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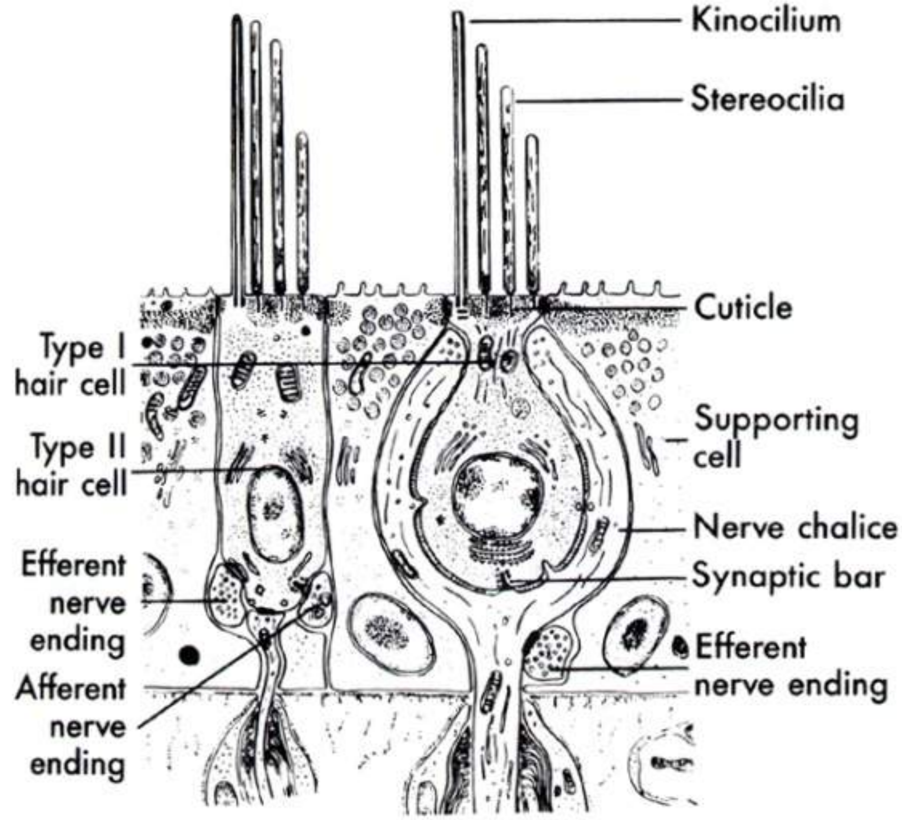
Hair Cells and Afferent Responses

Two types of Hair cells

Type I Hair Cells
Characterized by calyx like endings of the sensory fibers.

Type II Hair Cells
Characterized by more conventional (bulbous) cell fiber synapses.

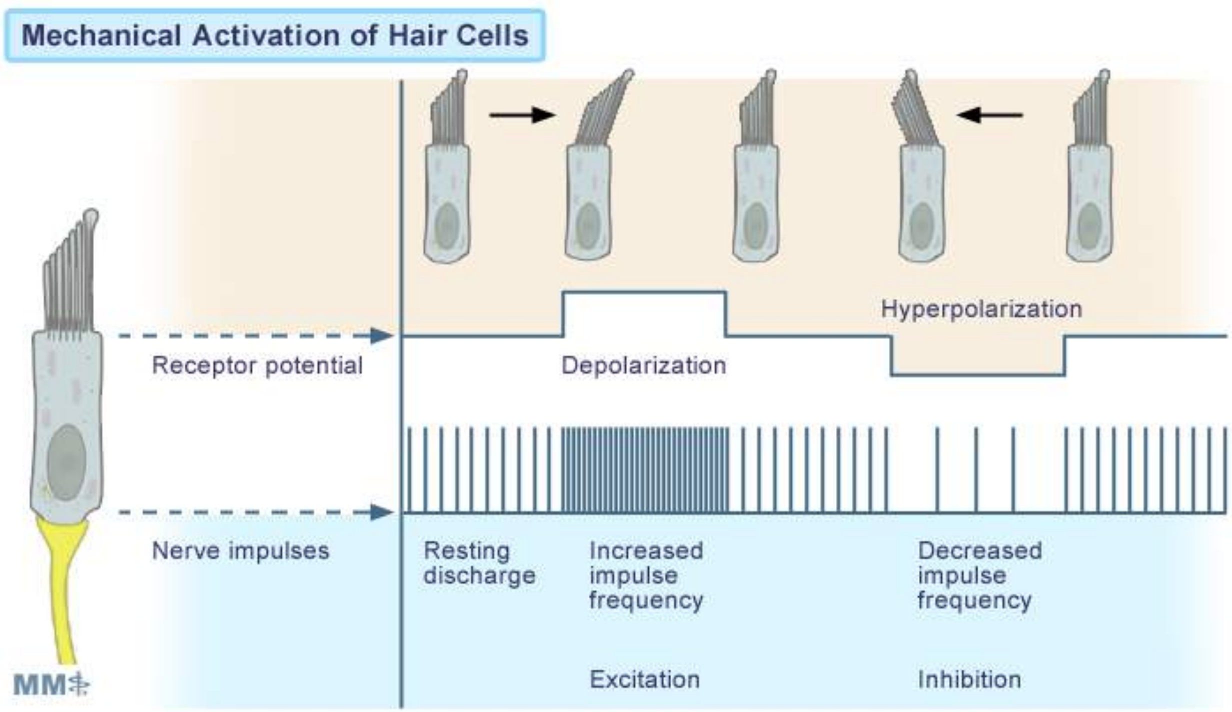


Hair Cells and Afferent Responses

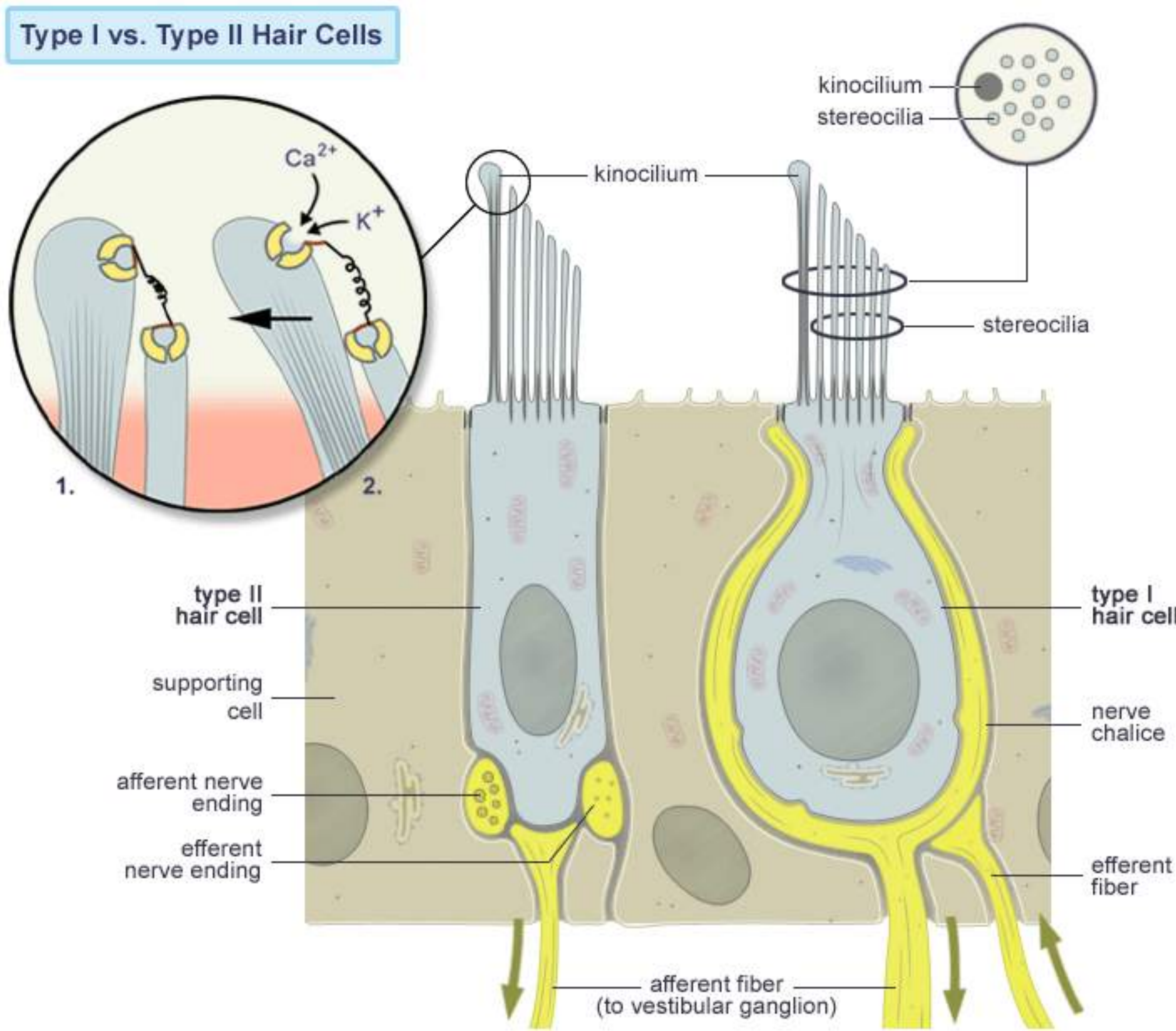
Exhibit a constant resting discharge when not stimulated

1) Bending cilia <u>towards</u> kinocilia
excites hair cell: ↑ action potential, VIII nerve.

2) Bending cilia <u>away from</u> kinocilia
inhibits hair cell: ↓ action potential, VIII nerve.



Thus, the resting discharge (spontaneous discharge) allows the CNS
to sense stimulation in 2 directions (opposite via the <u>change</u> in activity).



Mechanism of Mechano-Neural Transduction: similar to auditory system Role of Efferent system: not yet understood

Hair Cells and Afferent Responses

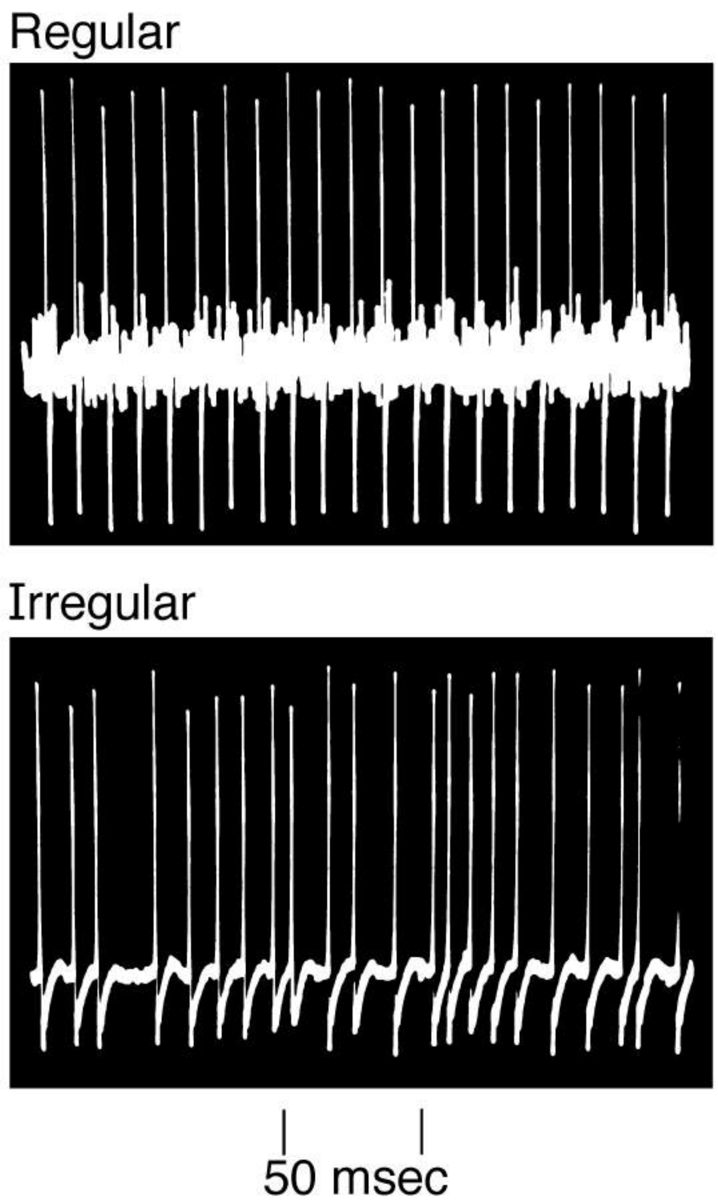
Regular Versus Irregular Afferents

Afferent innervation patterns
  type II haircells - regular afferents
  type I haircells - irregular affernts

Regulars:

- More regular action potentials spacing
- Lower Afferent gain and phase
- Lower Efferent response magnitude
- Lower Galvanic sensitivity

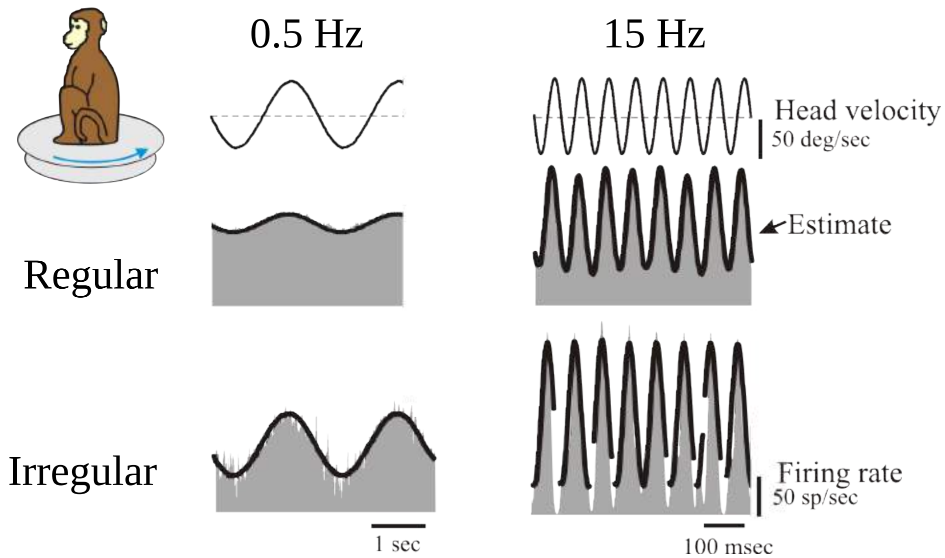
Prosthetics, Affecting Irregular more

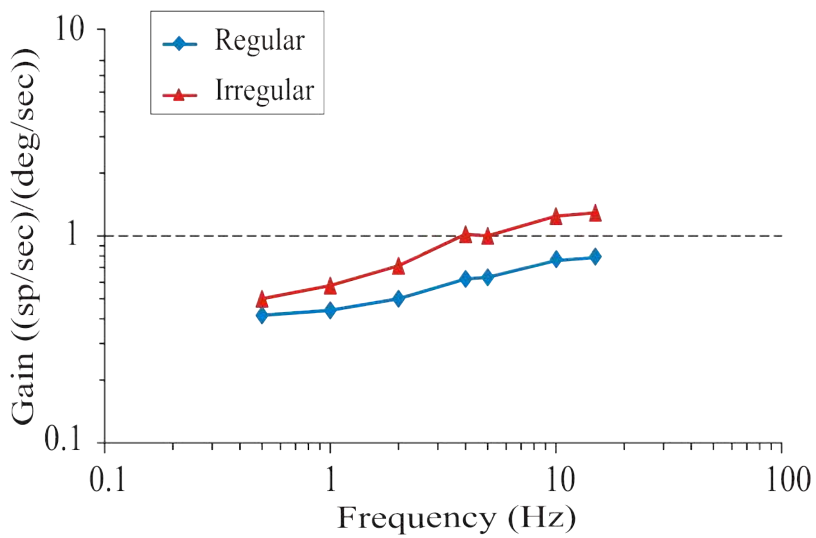


Vestibular afferent Dynamics:

Afferents show a response gain increase with frequency

Gain

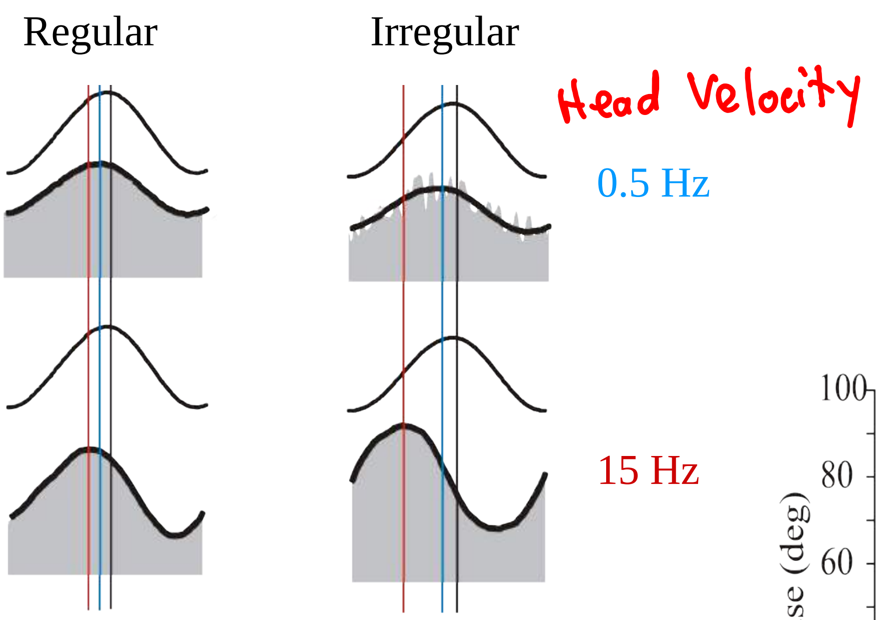


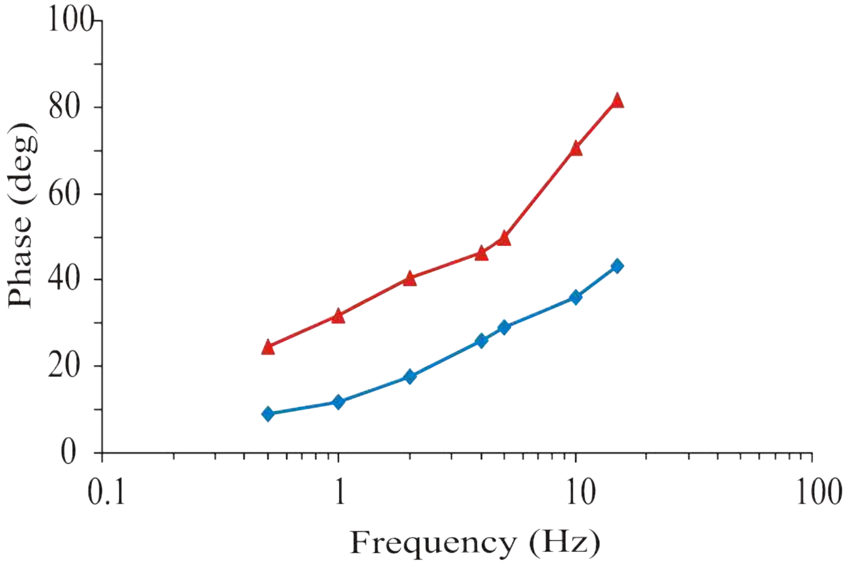


Sadeghi, Minor, and Cullen; J Neurophys, 2007

Vestibular afferent Dynamics:

Afferents (particularly irregular afferents) also show a response phase increase with frequency

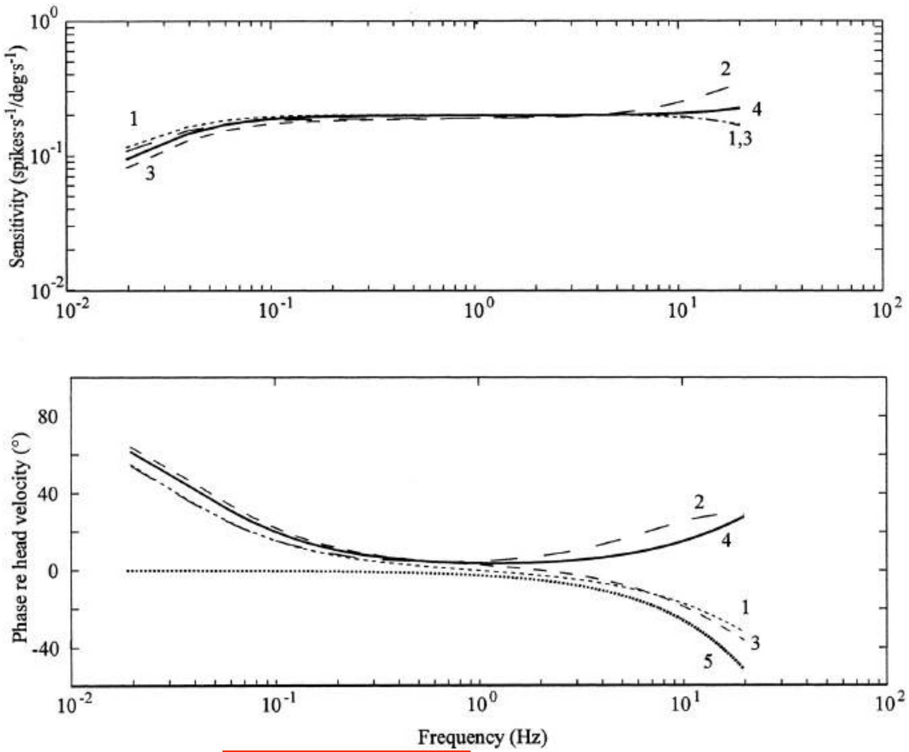




Sadeghi, Minor, and Cullen; J Neurophys, 2007

Vestibular-Nerve Afferents:

Response to Sinusoidal Rotation



1. Torsion pendulum $\dfrac{1}{(5.7s+1)(0.003s+1)}$

2. Squirrel monkey $\dfrac{s(1+0.015s)}{(1+5.7s)(1+0.003s)}$

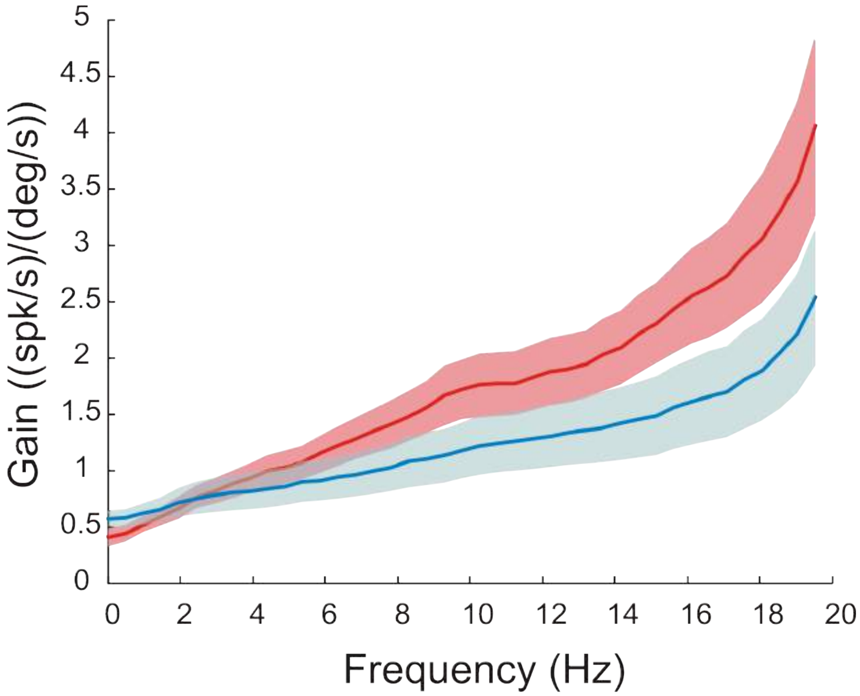
3. Baird, et al. chinchilla $\dfrac{s(0.2s+1)^{0.056}}{(3.96s+1)(0.007s+1)}$

4. Present study chinchilla $\dfrac{s(0.0042s+1)}{4.4s+1}$

5. 7 millisecond lag

Hullar, T. E. et al. J Neurophysiol 82: 2000-2005 1999

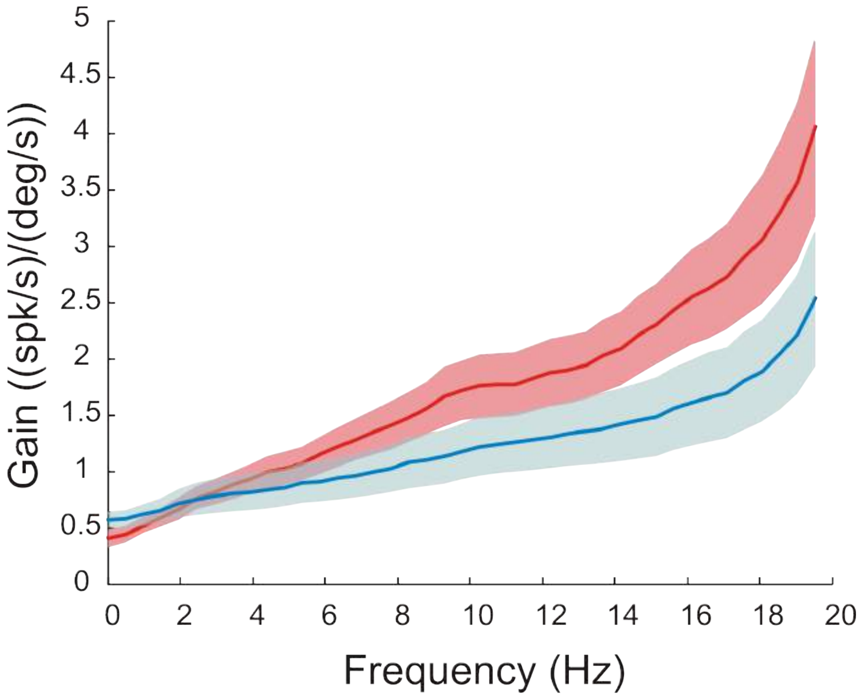
Vestibular-Nerve Afferents:
Response to broadband stimulus



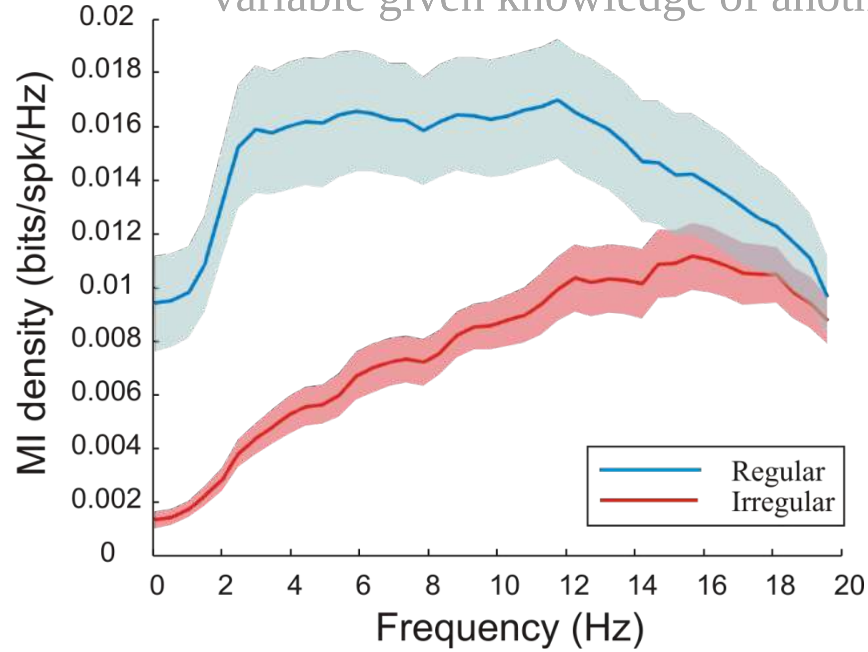
$G(f)=|P_{rs}(f)/P_{ss}(f)|$

Sadeghi, Chacron, Taylor, and Cullen, *J. Neurosci*, *2007*
Massot, Schneider, Chacron, Cullen, *Plos Biology*, *2012*

Vestibular-Nerve Afferents:
Response to broadband stimulus



Mutual Information: reduction in uncertainty about one random variable given knowledge of another



$G(f)=|P_{rs}(f)/P_{ss}(f)|$

$MI=[-\log_2(1-C(f)]$

$C(f)=|P_{rs}(f)|^2/[P_{ss}(f)P_{rr}(f)]$

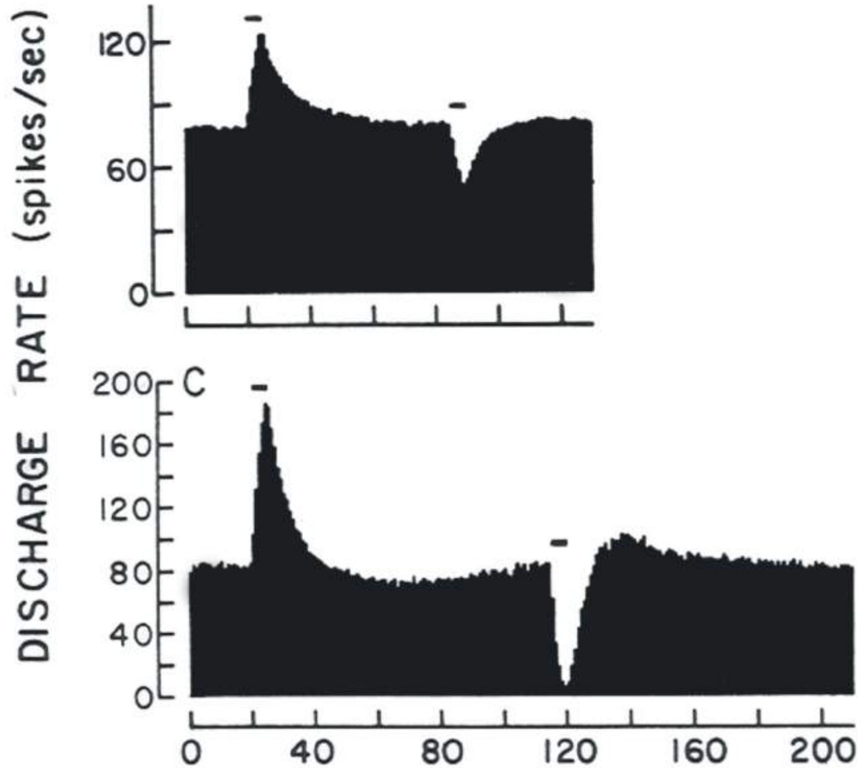
Sadeghi, Chacron, Taylor, and Cullen, *J. Neurosci*, *2007*
Massot, Schneider, Chacron, Cullen, *Plos Biology*, *2012*

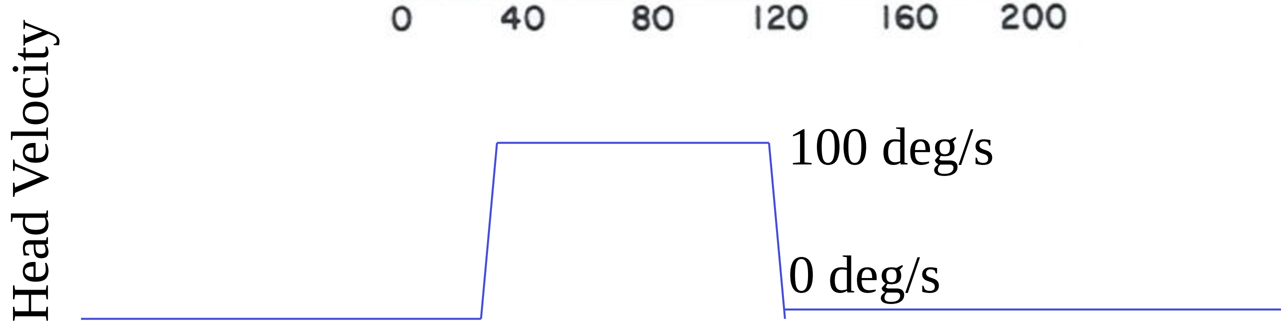
Vestibular afferents response to “velocity trapezoid” inputs as predicted by the torsion-pendulum model

$$\theta d\, \varepsilon 2/dt2 + \Pi\, d\, \varepsilon(t)/dt + \Delta\, \varepsilon(t) = \theta\alpha(t)$$

Dominant time constant is 5 sec

In contrast, the VOR has a time constant of ~20 s.





Sensorimotor transformations: VOR

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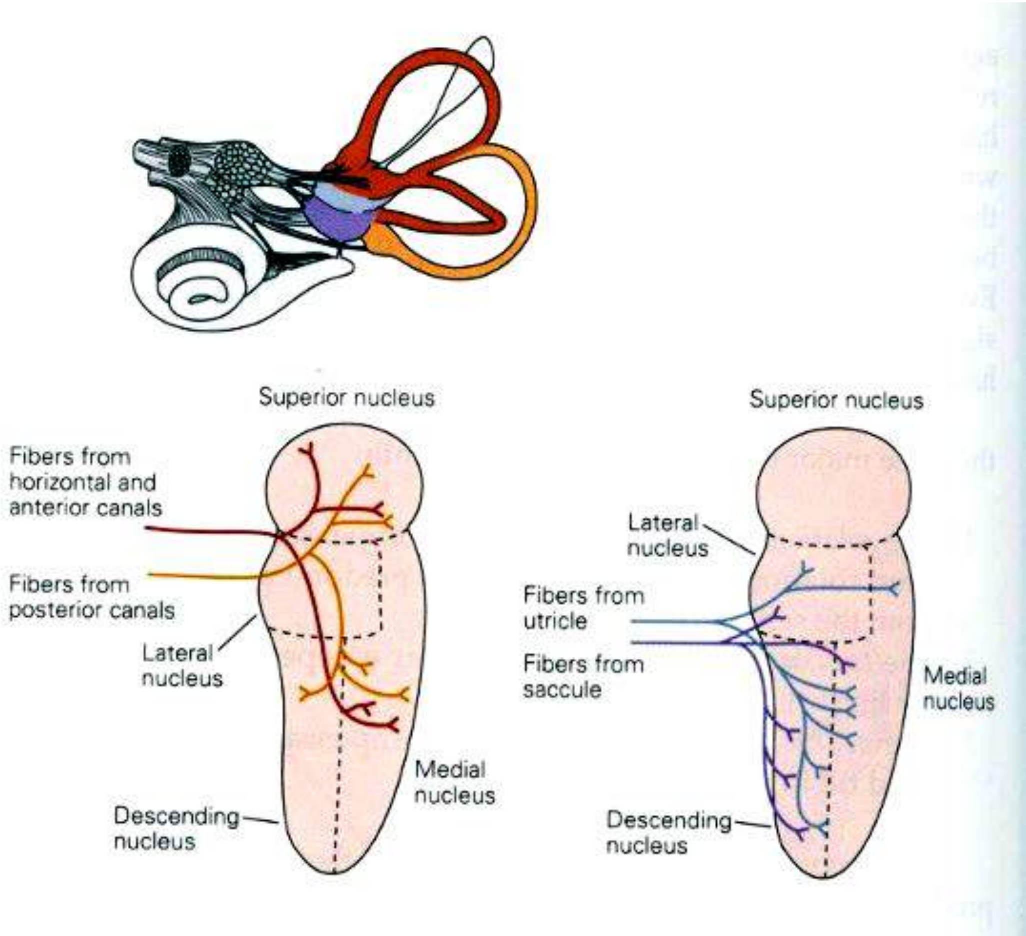
Central Vestibular Processing for the VOR

Central Pathways: Vestibular Nuclei



4 subdivisions:

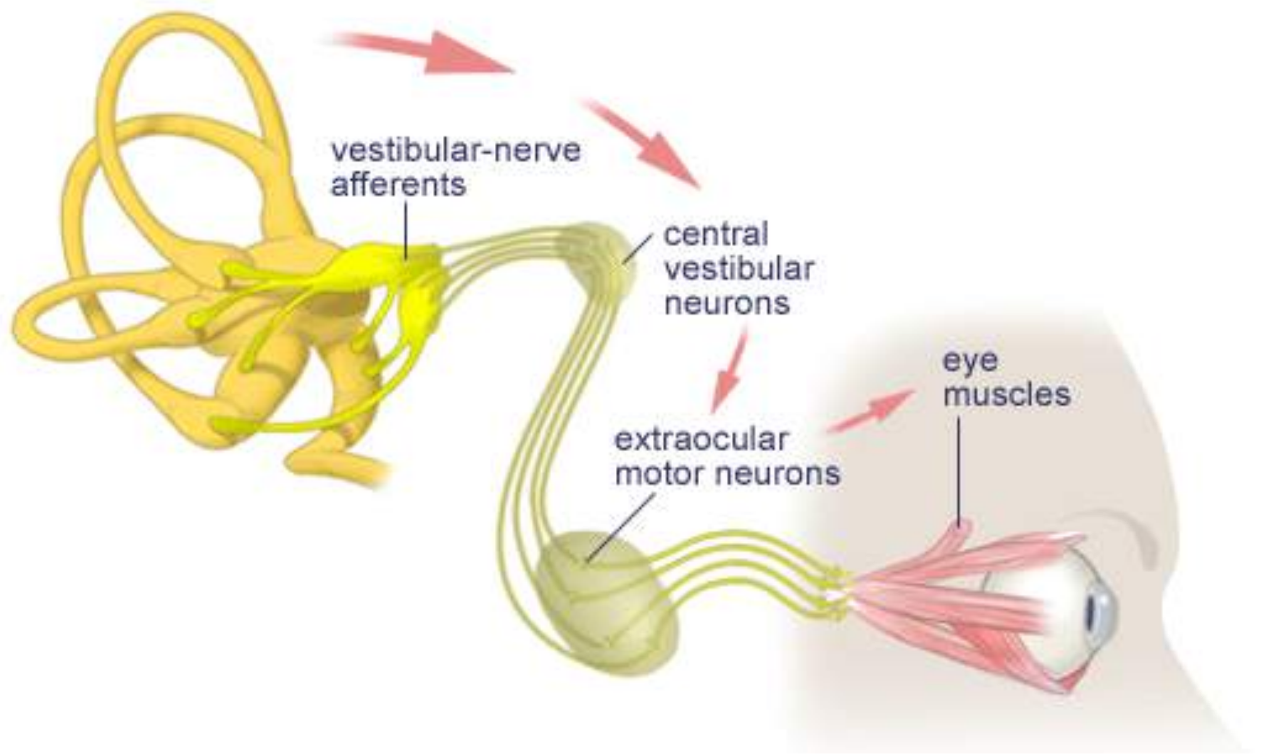
Superior/Medial
- predominantly canal

Lateral
- canal and otolith

Descending
- predominantly otolith

Central Vestibular Processing for the VOR

Central Pathways: Vestibular Nuclei



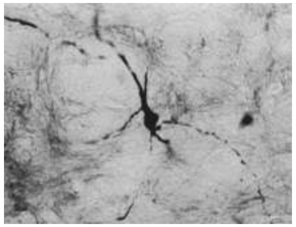
For the Horizontal rotational VOR:

Afferents project to neurons in the vestibular nuclei which in turn project to the

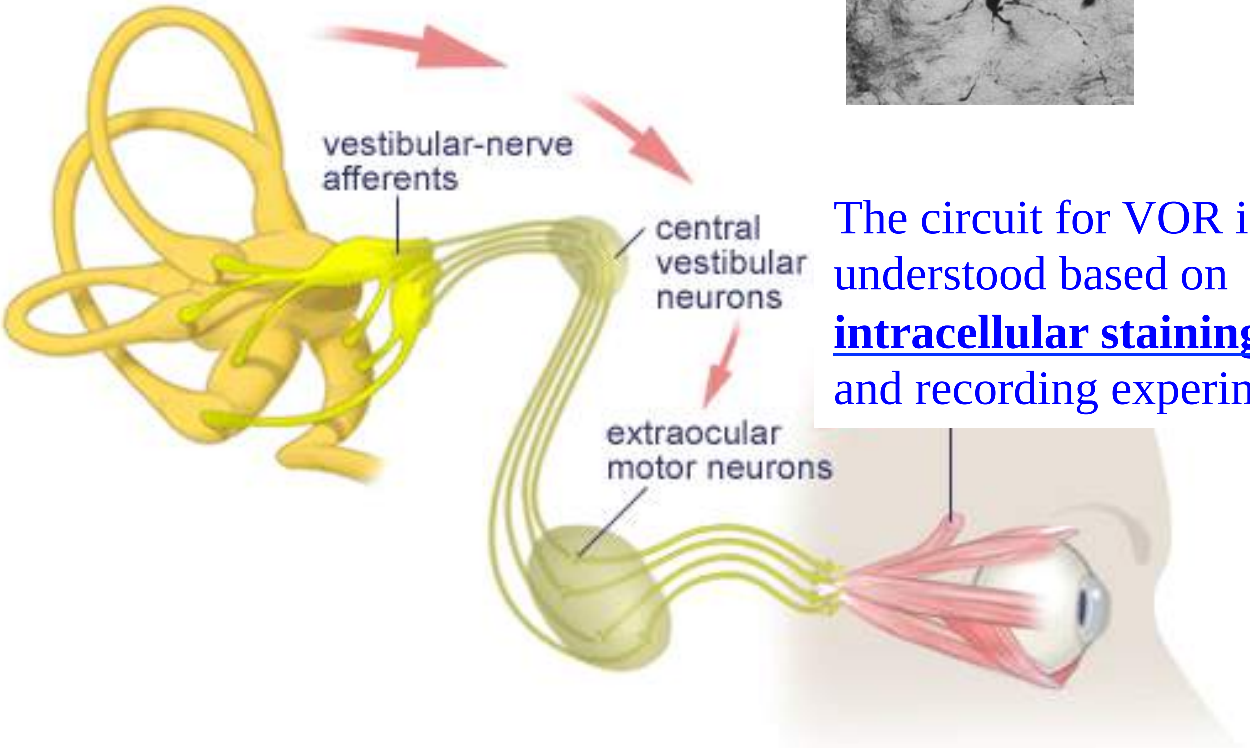
1) Abducens and
2) Medial Rectus subdivision of the oculomotor nucleus

Central Vestibular Processing for the VOR

Central Pathways: Vestibular Nuclei



The circuit for VOR is well understood based on **intracellular staining** and recording experiments.



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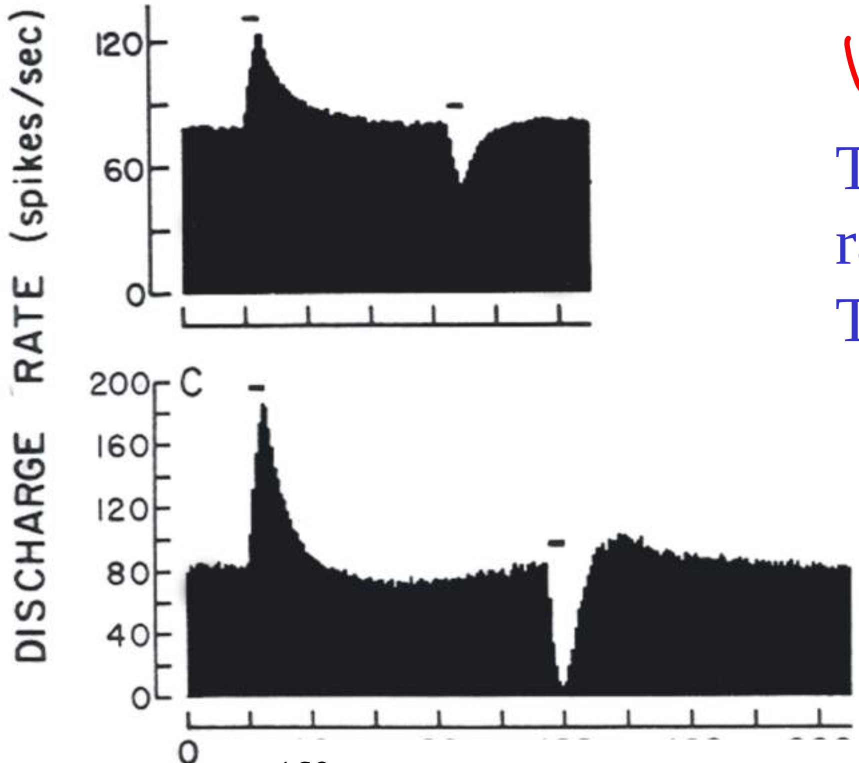
Central Vestibular Processing for the VOR

Central Pathways: Vestibular Nuclei

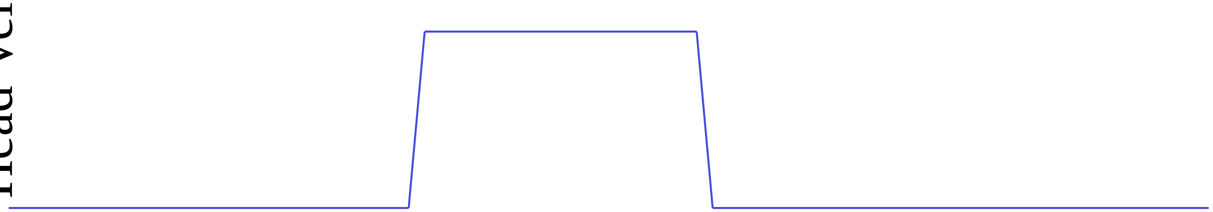


160ms

Velocity Storage

Time constant is ~20 sec rather than 5 sec as for The Vestibular Afferents.

Head Velocity



100 deg/s

0 deg/s

Central Vestibular Processing for the VOR

Central Pathways: Vestibular Nuclei and Velocity Storage

The slow time constant of the canals (5s) is represented in the discharges of vestibular afferents.

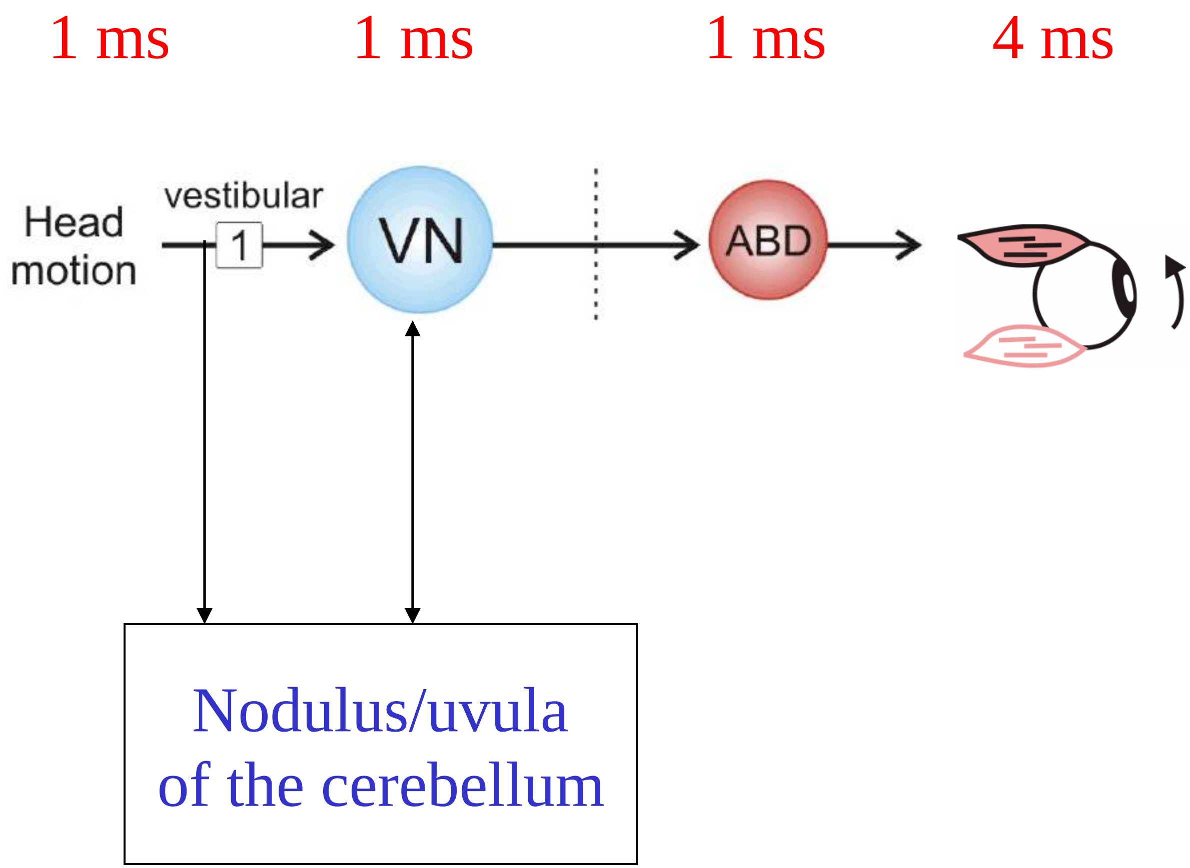
But for rotation in the dark at a constant velocity –
slow phase eye velocity is initially compensatory, but then goes to zero with a time constant of 21 sec not 5 sec, as predicted by the dynamics of the afferents.

1) The central mechanism responsible for lengthening the afferent time course is referred to as "velocity storage".

2) Reciprocal projections between the cerebellum and vestibular nuclei mediate velocity storage. After lesions of the cerebellar uvula and nodulus the VOR decay time constant (as well as the response of central vestibular neurons) returns to 5 ms.

Central Vestibular Processing for the VOR

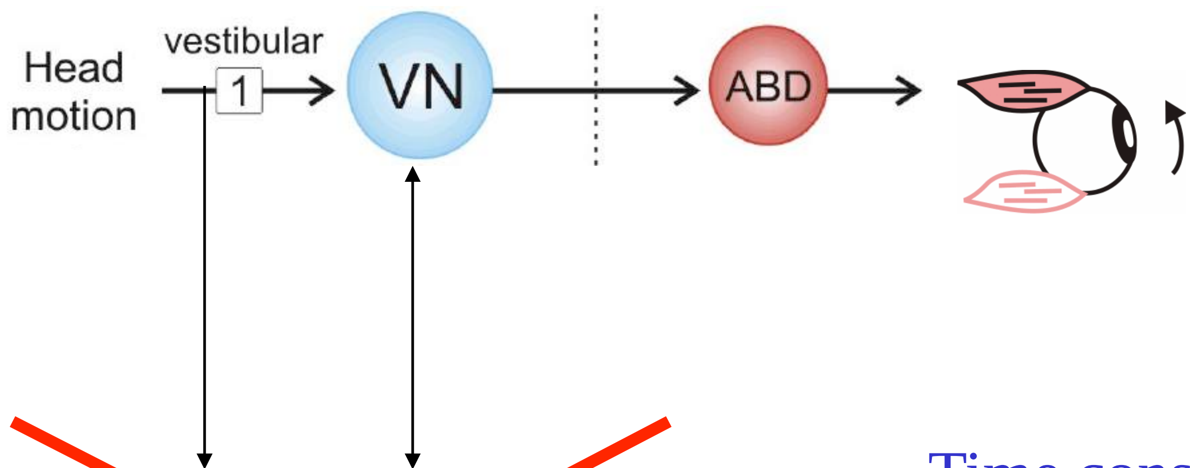
Central Pathways: Vestibular Nuclei and Velocity Storage



Central Vestibular Processing for the VOR

Central Pathways: Vestibular Nuclei and Velocity Storage

1 ms 1 ms 1 ms 4 ms = 7 ms delay

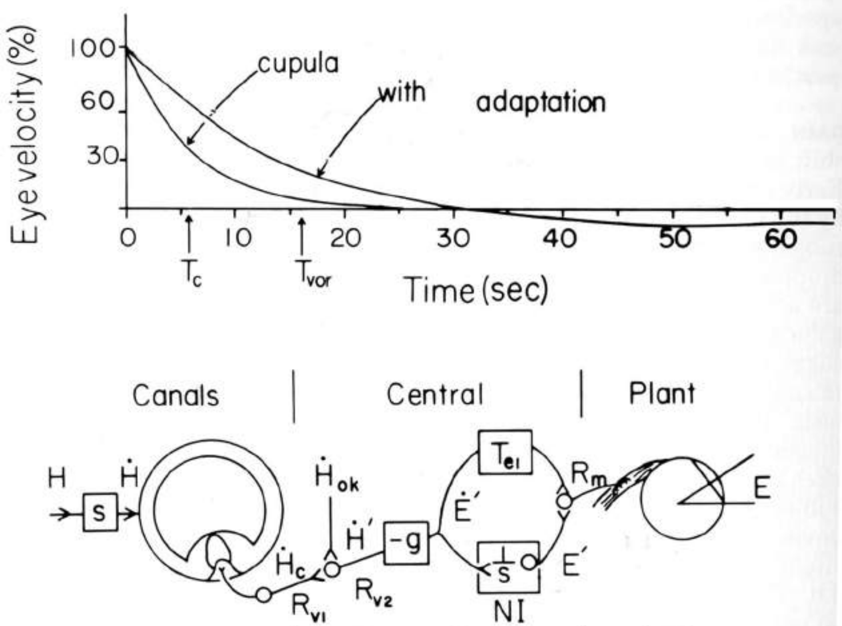


~~Nodulus/uvula of the cerebellum~~

Time constant returns to ~5 s.

Central Vestibular Processing for the VOR

Neuronal Pathway: Model of the VOR



$$s\frac{sT_c}{(sT_c+1)}\frac{sT_a}{(sT_a+1)}(sT_z+1) \quad -g\frac{T_{vor}}{(sT_{vor}+1)}\frac{(sT_c+1)}{T_c} \quad T_{e1}+\frac{1}{s} \quad \frac{e^{-s\tau}}{(sT_{e1}+1)(sT_{e2}+1)}$$

$$-gs\frac{sT_{vor}}{(sT_{vor}+1)}\frac{sT_a}{(sT_a+1)}(sT_z+1) \qquad \frac{e^{-s\tau}}{s\,(sT_{e2}+1)}$$

$$\frac{E(s)}{H(s)} = -g\frac{sT_{vor}}{(sT_{vor}+1)}\frac{sT_a}{(sT_a+1)}\left[\frac{(sT_z+1)}{(sT_{e2}+1)}e^{-s\tau}\right]$$

Working with this

IV (plant transfer function)

$Fr = Ro + kE + r\dot{E}$

Last week

Sensorimotor transformations: VOR

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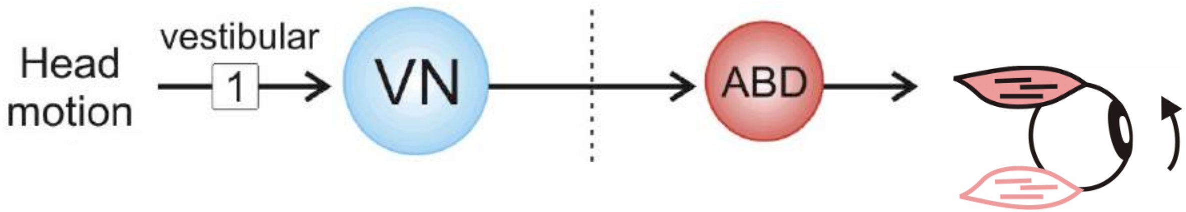
            - System Dynamics and Levels of Analysis
            - 1) Behavior, 2) Neural Circuits, 3) Neurons.

Neuronal Processing for the VOR

Central Pathways: Intrinsic Cellular Properties

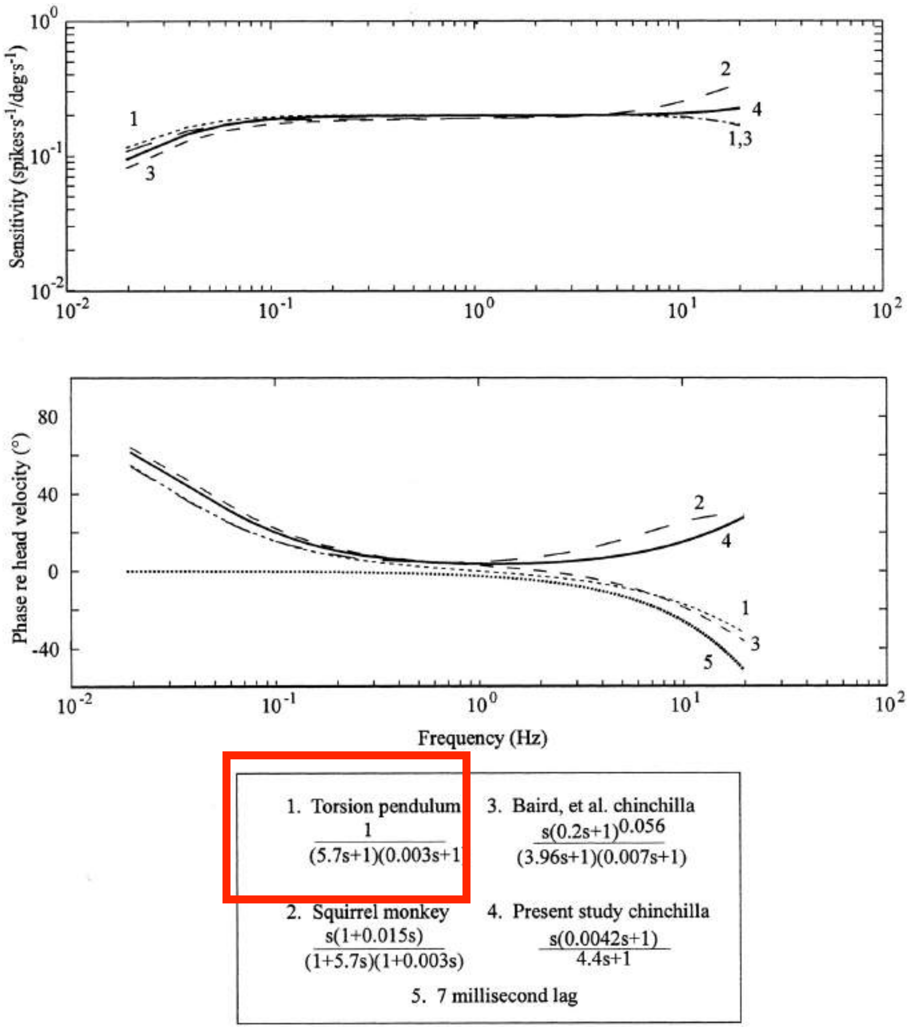
1 ms 1 ms 1 ms 4 ms



Considerations:

1) Neuronal dynamics and limits (cut-off and saturation)
2) Intrinsic Processing and Membrane Properties
3) Compensation for pathway delays

Vestibular-Nerve Afferents:
Response to Sinusoidal Rotation

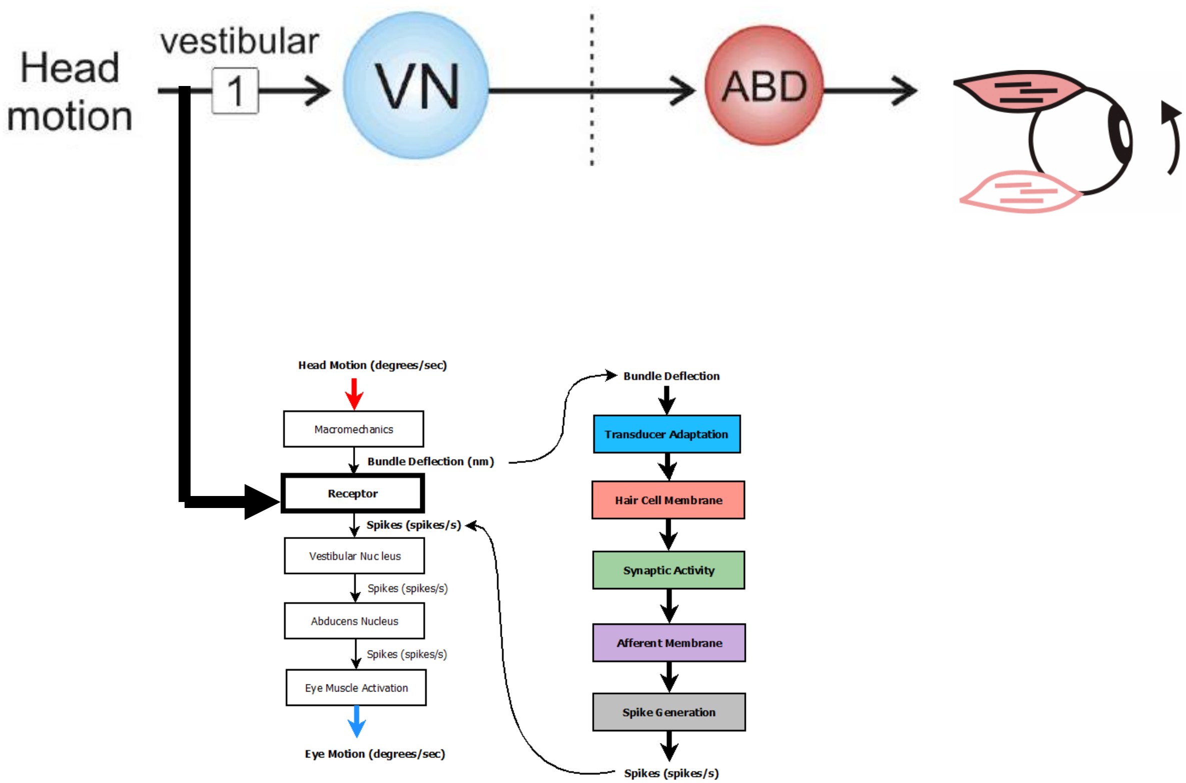


Hullar, T. E. et al. J Neurophysiol 82: 2000-2005 1999

Neuronal Processing for the VOR

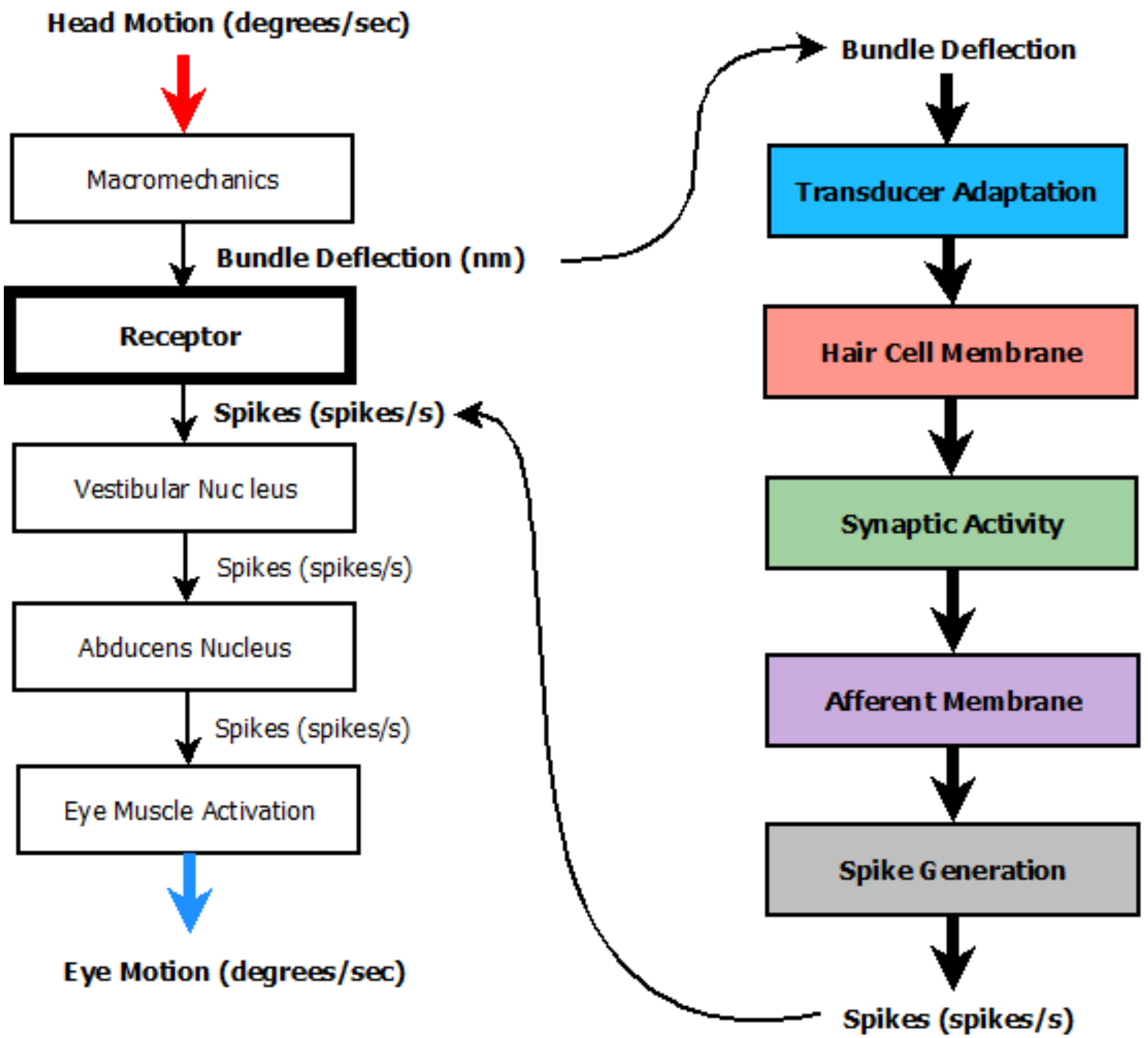
Central Pathways: Intrinsic Processing and Membrane Properties

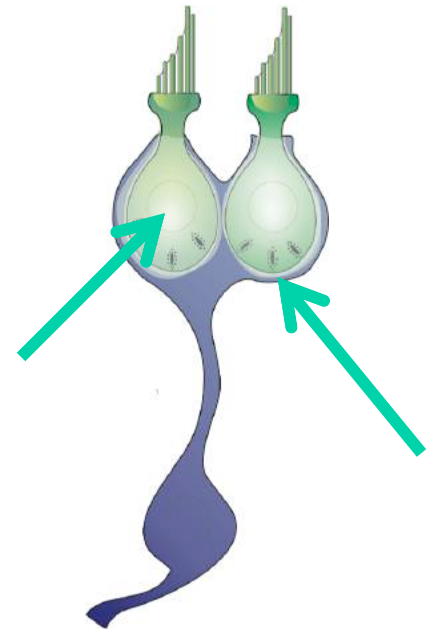
1 ms　1 ms　1 ms　4 ms



Neuronal Processing for the VOR

Central Pathways: Intrinsic Processing and Membrane Properties





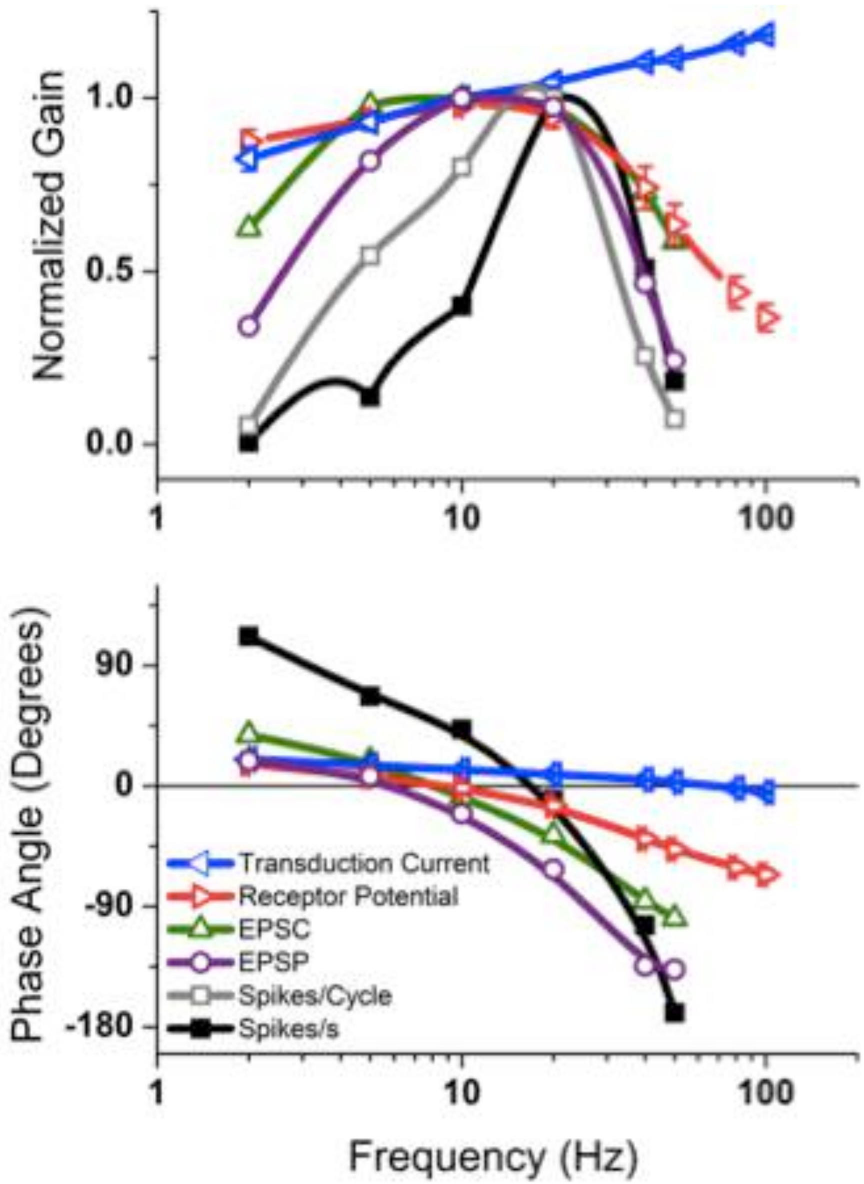
Neuronal Processing for the VOR

Dynamics of Mechanical-Neural Transduction

Bode Plots reveal:

1) Tuning narrows at each stage

2) Increased phase lag > 20 Hz at each stage; spiking adds a large phase lead below 20 Hz

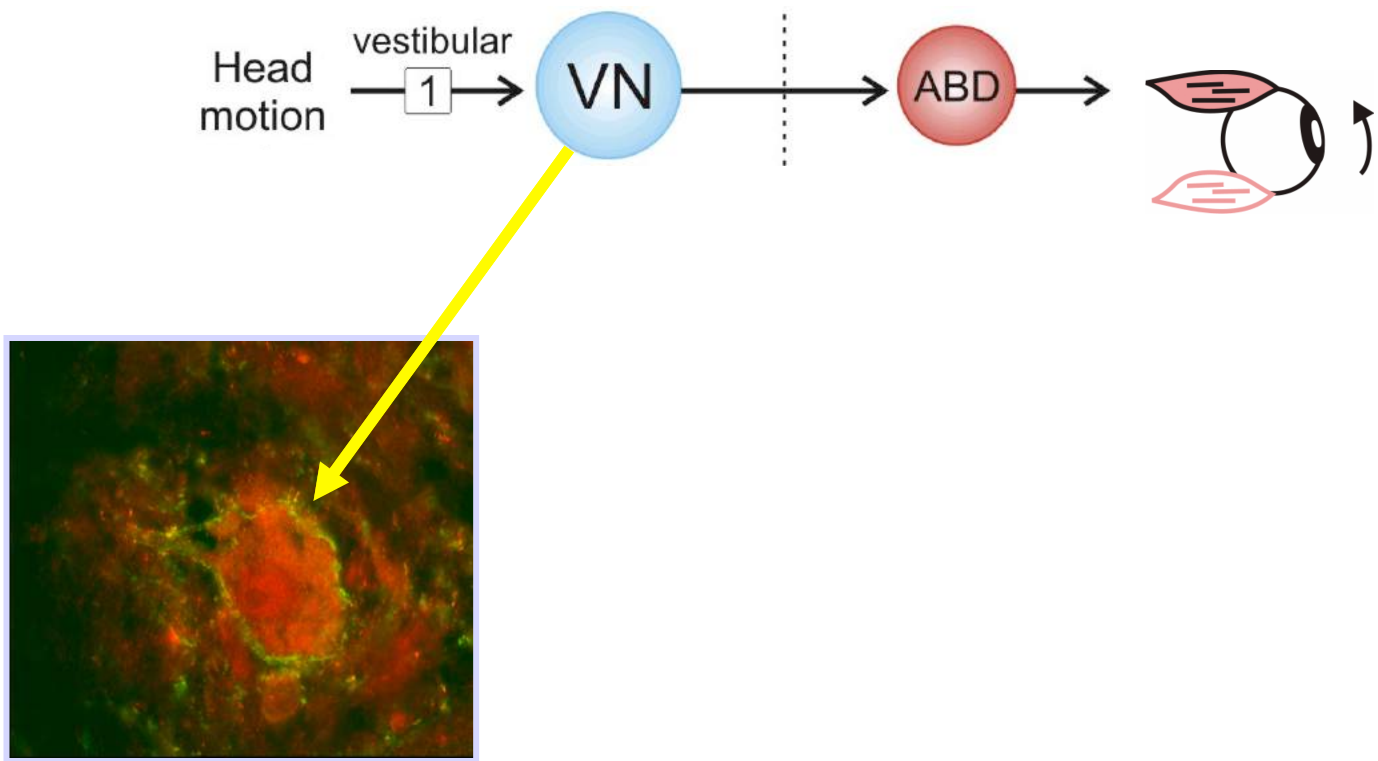


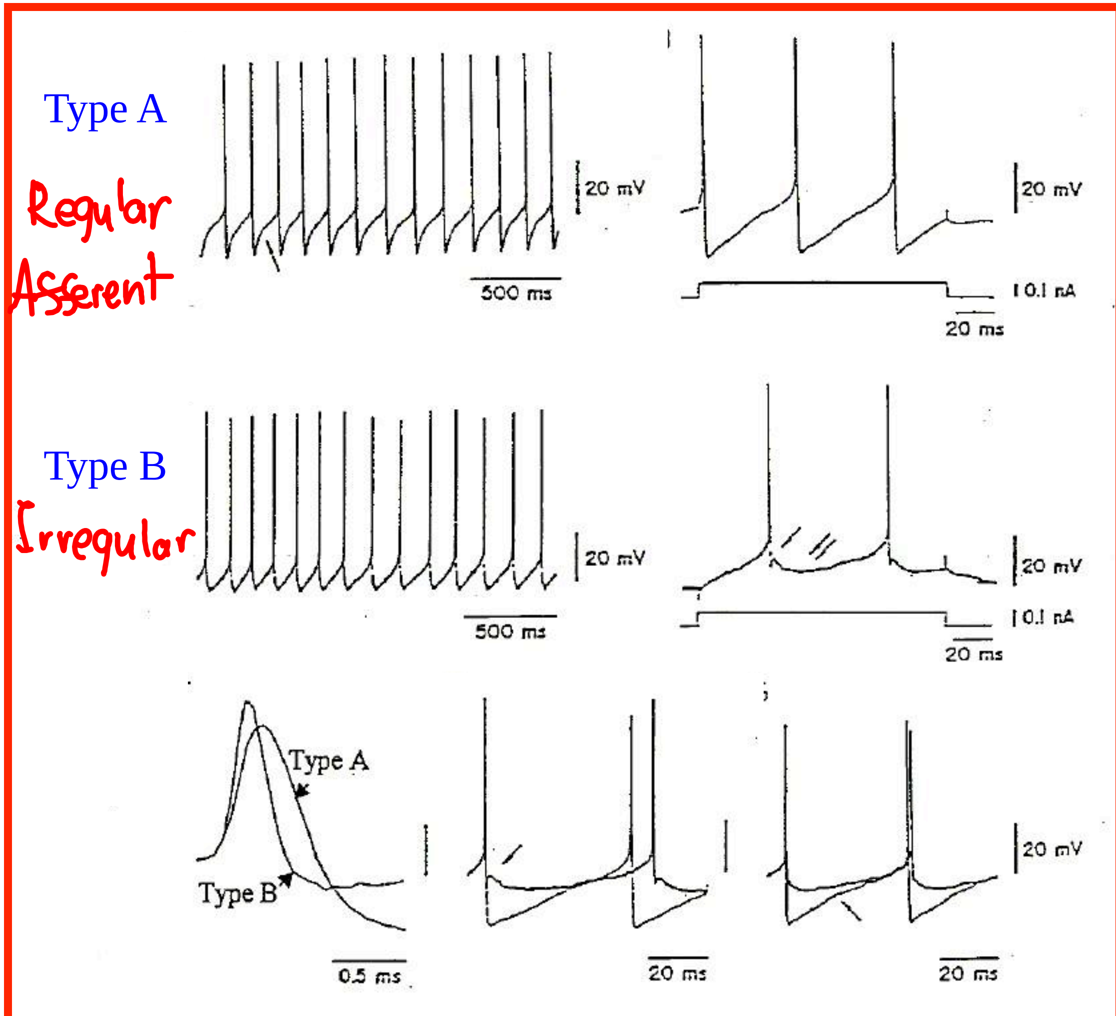
Songer and Eatock, JNS 2013

Central Vestibular Processing for the VOR

Central Pathways: Intrinsic Cellular Properties

1 ms 1 ms 1 ms 4 ms





Serafin et al. 1991a,b

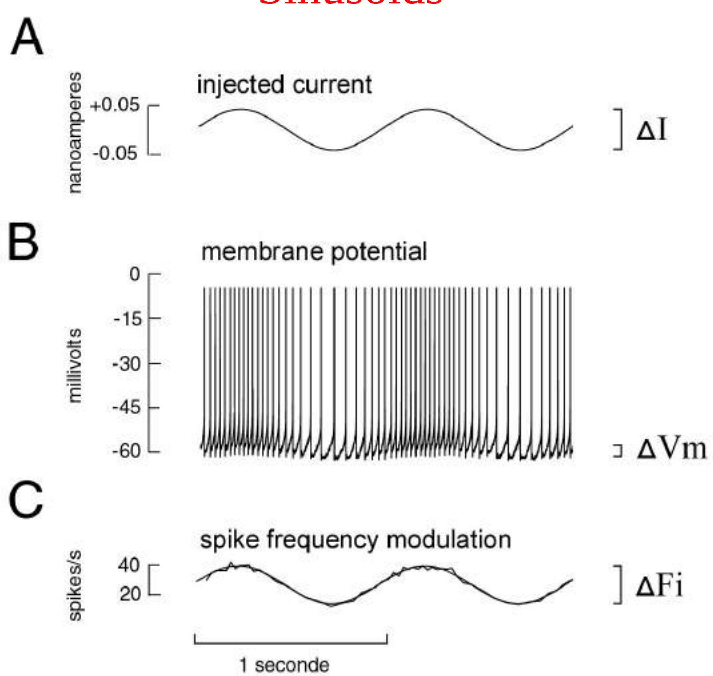
Summarized properties of 170 MVN neurones

Type A neurones 32.3%	• Wide action potential • Large single AHP • Single range firing • A-type rectification • Small high threshold calcium ($HT-Ca^{2+}$) spikes
Type B neurones 47.1%	• Thin action potential • Early fast and delayed slower AHP • Secondary range in the first intervals • Large $HT-Ca^{2+}$ spikes and Ca^{2+} plateau potentials • And – 55.0% Na^+ plateau potentials (Na(P)) – 16.5% Low threshold Ca^{2+} spikes (LTS) – 16.5% LTS and Na (P) – 12.0% Absence of LTS and Na (P)
Type C neurones 20.6%	

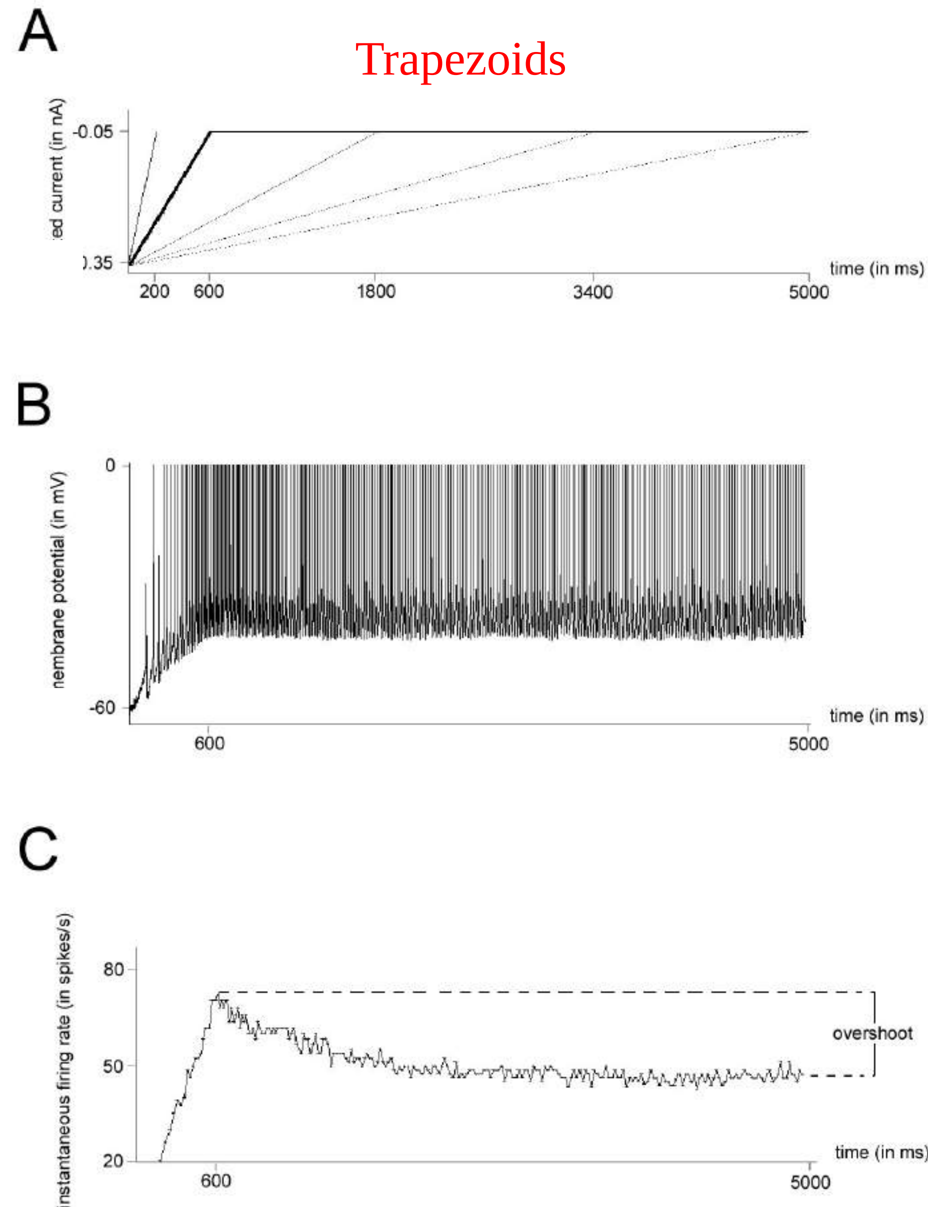
Central Vestibular Processing for the VOR

Intrinsic Cellular Properties: Input-Output Analysis

Sinusoids



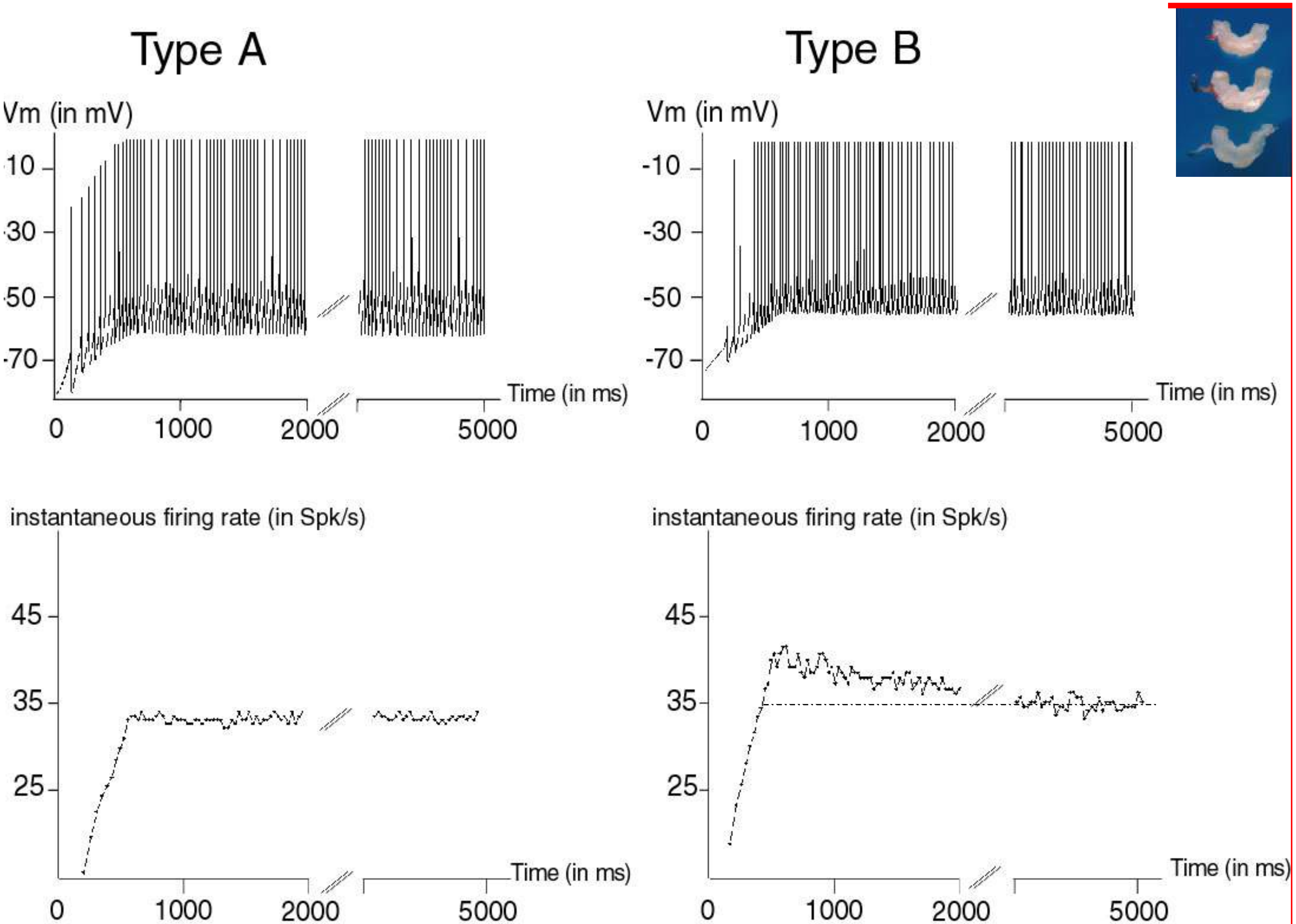
Trapezoids



Ris et al. 2001

Central Vestibular Processing for the VOR

Intrinsic Cellular Properties: Input-Output Analysis



Ris et al. 2001

Central Vestibular Processing for the VOR

Central Pathways: Intrinsic Cellular Properties

Type A Vestibular Nuclei Neurons are modulators

More linear

Less sensitive to current

Less phase lead, regular

follow up mode

Type B Vestibular Nuclei Neurons are detectors

Non linear (more overshoot, FRA)

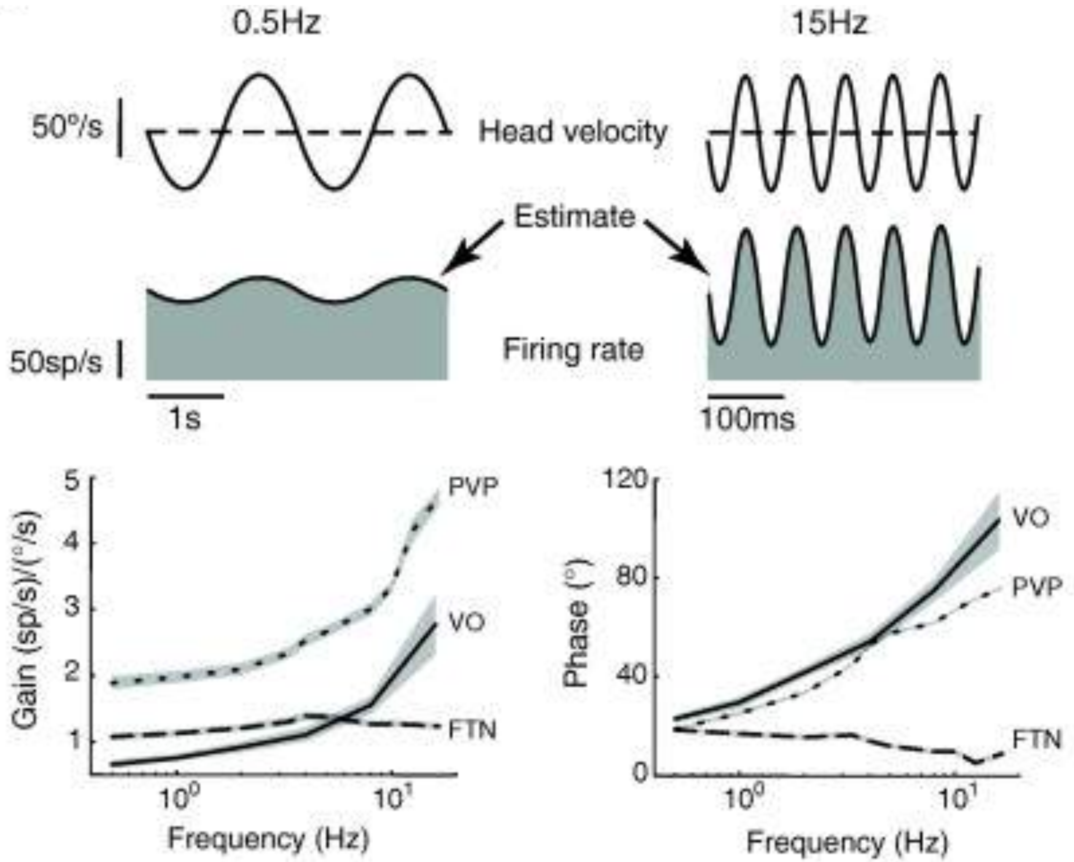
Very sensitive to current,

Phase Lead , Irregular

trigger mode

Vestibular Nuclei Neuron Dynamics:

Afferents show a response gain increase with frequency



Type B

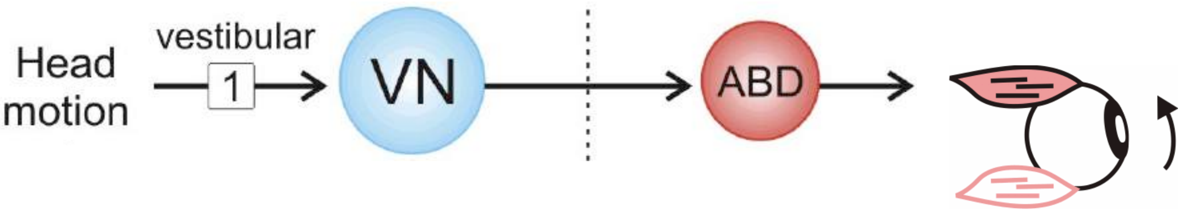
Type A

Cullen, TINs 2012

Central Vestibular Processing for the VOR

Central Pathways: Pathway Delays – Phase compensation

1 ms 1 ms 1 ms 4 ms

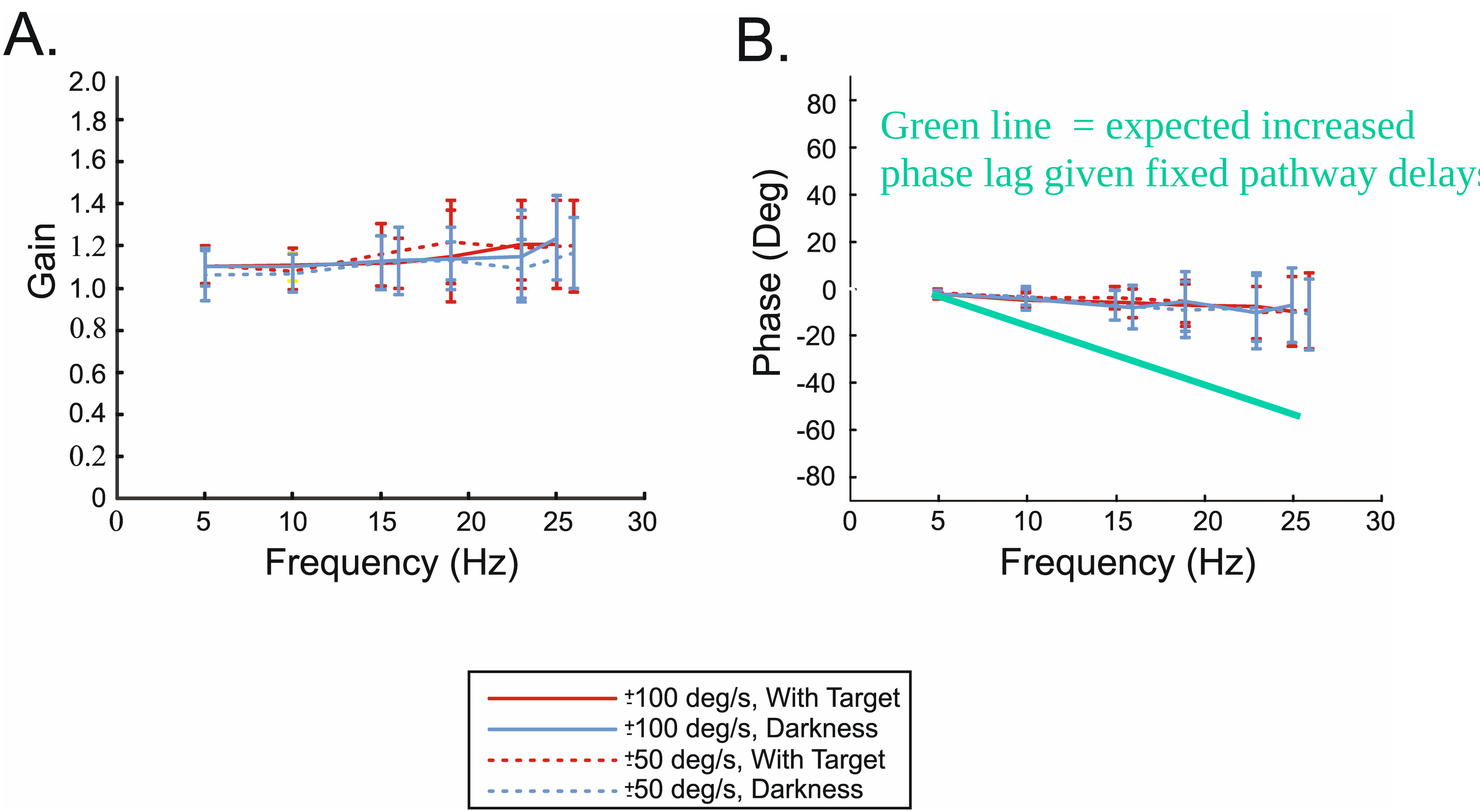


Considerations:

1) Neuronal limits (cut-off and saturation)
2) Intrinsic Processing and Membrane Properties
3) Compensation for pathway delays

Vestibulo-ocular reflex (VOR) Dynamics:

The VOR is compensatory over a wide frequency range



Huterer and Cullen, JNP 2000

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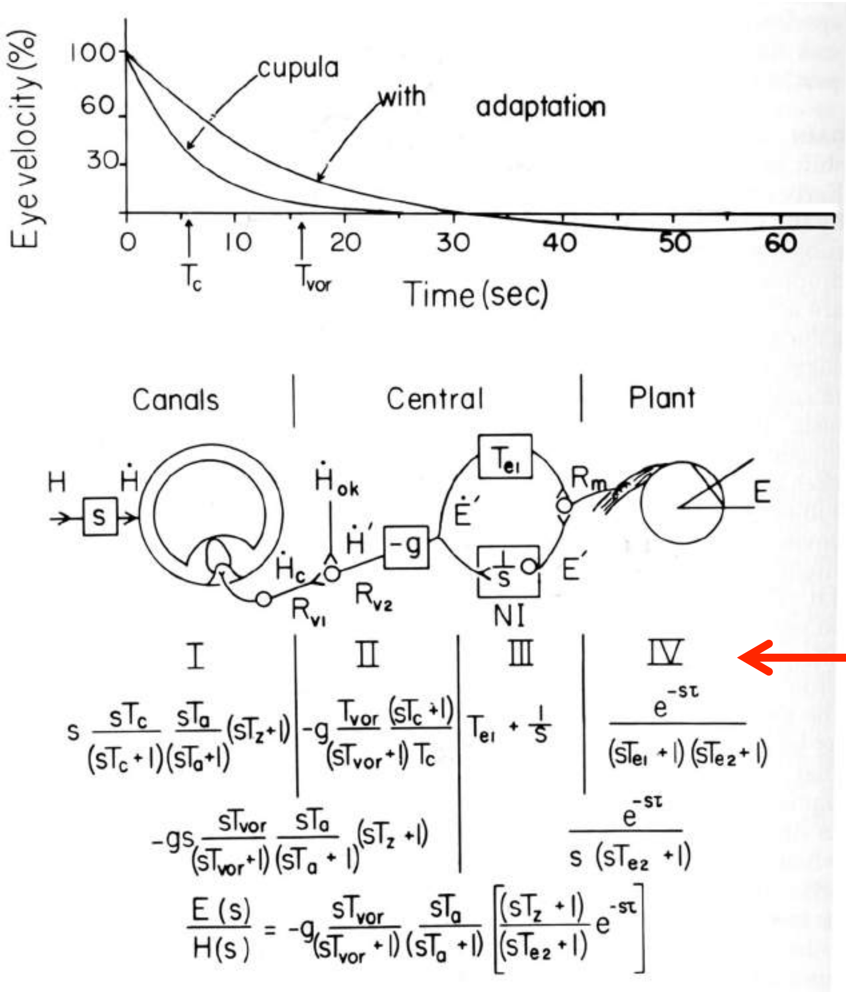
        - ii. Neuronal Pathway: Model of the VOR
            - Intrinsic membrane properties as well as inputs shape response dynamics

Central Vestibular Processing for the VOR

Neuronal Pathway: Model of the VOR



IV (plant transfer function)

$Fr = Ro + kE + r\dot{E}$