



西南大學

含弘光大 · 繼往開來

Relaxation-Free Deep Hashing via Policy Gradient

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Made by Godder

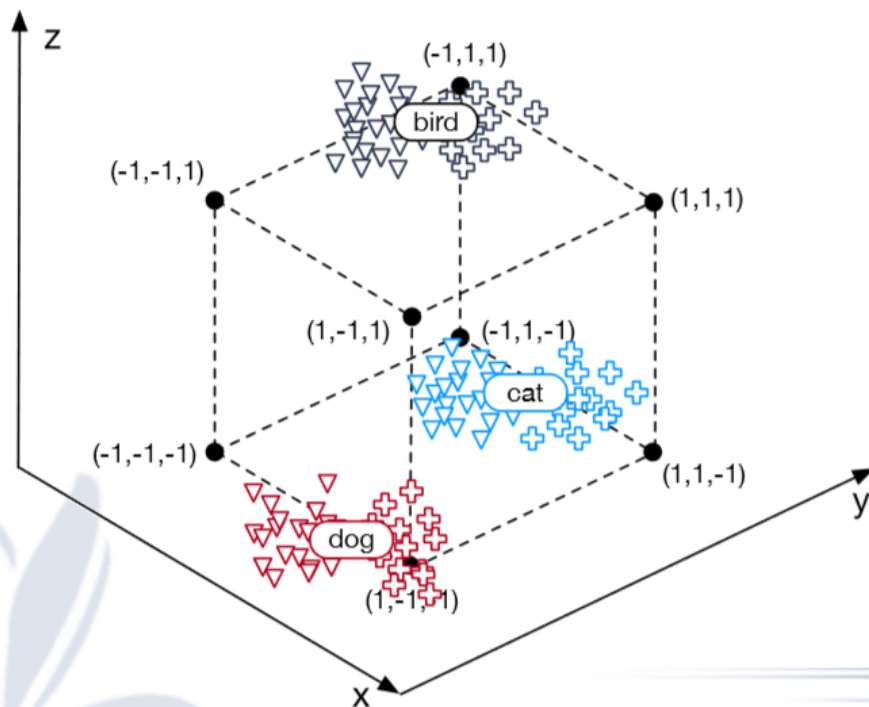
2019/10/25

SOUTHWEST
UNIVERSITY



introduction

- Hash evaluate
 - Hamming distance





introduction

- Hash evaluate
 - Hamming distance
 - cosine





introduction

- European space to Hamming distance.
 - Sign function

$$\text{sign}(x) = \begin{cases} 1 & x \geq 0 \\ -1 & x < 0. \end{cases}$$





introduction

- European space to Hamming distance.
 - Sign function
 - relaxation





introduction

- European space to Hamming distance.
 - Sign function
 - relaxation
 - Probability





Related work

- Unsupervised
 - SH: **graph** partition
 - AGH: neighborhoods by tractable **graph**
 - DH: neural network & non-linear function
 - ITQ: iterative manner to learn a rotation matrix
 - MH: cluster center & dimensionally reduction
 - DGH: optimization method for discrete code space.





Related work

- Machine learning Supervised
 - KSH: inner product for hamming distance
 - FSH: decision tree.
 - SDH: auxiliary variable & kernel based.
 - SEDH: learn multi-layer function by label information





Related work

- Deep learning Supervised
 - CNNH: two stages strategy.
 - <1> learn hash code
 - <2> learn network by hash code
 - DNNH: CNNH with simultaneous feature learning.
 - DSH: DNNH + max-margin loss + quantization loss
 - HashNet: non-smooth sign activation.





Related work

- Deep learning hash code generation
discrete hash code is **non-differentiable**





Related work

- Deep learning hash code generation
discrete hash code is non-differentiable
- Continuous relaxation by a quantization function





Related work

- Deep learning hash code generation
discrete hash code is non-differentiable
- Continuous relaxation by a quantization function

quantization loss is np-hard, the loss is **disconvergent**





Related work

- Deep learning hash code generation
 - discrete hash code is non-differentiable
- Continuous relaxation by a quantization function
- Replace sign function with sigmoid or tanh function





Related work

- Deep learning hash code generation
discrete hash code is non-differentiable
- Continuous relaxation by a quantization function
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Model learning difficult, relaxation becomes more non-smooth





PGDH

- Hash representation

$$p(a_{i,k}) = \begin{cases} \pi_{\mathbf{x}_i, \theta}^{(k)}, & \text{if } a_{i,k} = 1 \\ 1 - \pi_{\mathbf{x}_i, \theta}^{(k)}, & \text{if } a_{i,k} = 0 \end{cases}$$





PGDH

- Hash representation to discrete hash codes

$$b_q^k = \begin{cases} +1, & \text{if } \pi_{\mathbf{x}_q, \theta}^{(k)} > 0.5 \\ -1, & \text{otherwise} \end{cases}$$

$$b_q^k = \begin{cases} +1, & \text{with probability } \pi_{\mathbf{x}_q, \theta}^{(k)} \\ -1, & \text{with probability } 1 - \pi_{\mathbf{x}_q, \theta}^{(k)} \end{cases}$$





PGDH

- Hash constraint

$$b_i = 2 * (a_i - 0.5)$$

$$r(a_i) = -\frac{1}{2} \sum_{j=1}^n \hat{s}_{ij} (K - b_i^T \hat{b}_j)$$

$$s.t. \quad b_i, \hat{b}_j \in \{-1, +1\}^K \quad (4)$$

$$\hat{s}_{ij} = \begin{cases} \beta, & \text{if } s_{ij} = 1 \\ \beta - 1, & \text{otherwise} \end{cases}$$



PGDH

- Objective function

$$\mathcal{L}(\theta) = - \sum_i \mathbb{E}_{\mathbf{a}_i \sim P_\theta(\mathbf{x}_i)} [r(\mathbf{a}_i)]$$





PGDH

- Policy gradient

$$\nabla_{\theta} \mathcal{L}(\theta) = - \sum_i \mathbb{E}_{\mathbf{a}_i \in \mathcal{A}_i} [r(\mathbf{a}_i) \nabla_{\theta} \log(P_{\theta}(\mathbf{a}_i | \mathbf{x}_i))]$$

where \mathcal{A}_i is the set of all possible actions for i -th input data in the minibatch

T -samples Monte Carlo on \mathbf{a}_i

$$\mathcal{A}_i = \{\mathbf{a}_i^1, \mathbf{a}_i^2, \dots, \mathbf{a}_i^T\} = MC^{P_{\theta}(\mathbf{a}_i | \mathbf{x}_i)}(T)$$

$$\nabla_{\theta} \mathcal{L}(\theta) \approx - \frac{1}{T} \sum_i \sum_t [r(\mathbf{a}_i^t) \nabla_{\theta} \log(P_{\theta}(\mathbf{a}_i^t | \mathbf{x}_i))]$$



PGDH

- REINFORCE

$$\nabla_{\theta} \mathcal{L}(\theta) \approx -\frac{1}{T} \sum_i \sum_t [(r(\mathbf{a}_i^t) - r') \nabla_{\theta} \log(P_{\theta}(\mathbf{a}_i^t | \mathbf{x}_i))] \quad (10)$$

r' the average of all rewards in each mini-batch.

$$\sum_i \mathbb{E}_{\mathbf{a}_i \in \mathcal{A}_i} [r' \nabla_{\theta} \log(P_{\theta}(\mathbf{a}_i^t | \mathbf{x}_i))] = \sum_i r' \nabla_{\theta} \sum_{\mathbf{a}_i} P_{\theta}(\mathbf{a}_i^t | \mathbf{x}_i) = \sum_i r' \nabla_{\theta} 1 = 0$$

$$\theta \leftarrow \theta - \lambda \nabla_{\theta} \mathcal{L}(\theta) \quad (11)$$





PGDH

Algorithm 1: PGDH

Input: Training set: $\mathbf{X} = \{\mathbf{x}_i\}_{i=1}^n$, pairwise labels: $\mathcal{S} = \{s_{ij}\}$ and codebook update interval $R > 1$.

Output: Learning model θ and codebook \mathbf{C}

```
1: Initialize  $p_\theta$  and  $\mathbf{C}$ ;  
2: for  $iter = 1, 2, \dots, M$  do  
3:   Sample random minibatch from  $\mathbf{X}$ ;  
4:   Compute the action probability by feeding minibatch to the model;  
5:   Compute the rewards for MC samples of the minibatch according to Eq. (4)  
6:   Compute policy gradient according to Eq. (10);  
7:   Update the model  $\theta$  according to Eq. (11);  
8:   if  $iter \% R = 0$  then  
9:     Update codebook  $\mathbf{C}$ ;  
10:  end if  
11: end for  
12: return model  $\theta$  and codebook  $\mathbf{C}$ ;
```



Experiments

- Dataset

	CIFAR10	NUSWIDE	ImageNet
category number	10	21	100
Train set	500×10	500×21	100×100
Query set	100×10	100×21	Validation set
Retrieval set	All - query	All - query	100 categories





Experiments

- Evaluate
 - MAP
 - RP
 - HLP@2 (Hamming lookup precision within radius $r=2$)





Experiments

- Hash code generation method

Training Epochs	1	5	10	40	50	60	70	80	90	100	
Deterministic	24.51	47.18	66.56	72.13	74.73	74.78	74.77	75.17	75.50	75.54	√
Stochastic	10.10	18.18	58.32	73.54	74.18	74.93	75.12	75.18	74.90	75.21	





Experiments

- Setting
 - Hyper-parameter

β	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
CIFAR-10	10.12	18.38	20.08	49.43	73.65	70.32	75.23	75.12	34.12
NUS-WIDE	31.32	43.65	54.13	66.12	77.95	76.12	77.32	79.18	78.80
ImageNet	1.14	1.14	33.12	43.64	69.65	68.69	70.32	70.11	70.03

R = 5, Monte Carlo samples T = 10

- Network: AlexNet pretrained on ImageNet.
- Optimizer: Adam with lr=0.005
- Batch-size: 128

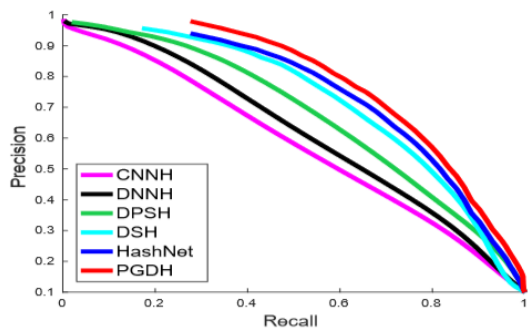


Experiments

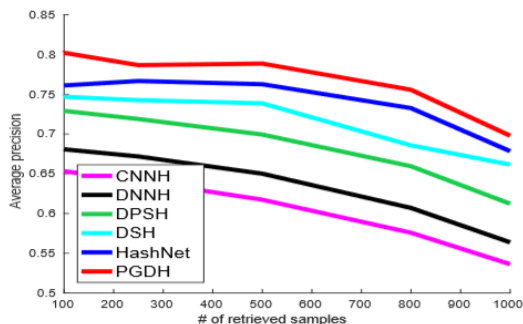
Methods	CIFAR-10 (%)				NUS-WIDE (%)				ImageNet (%)			
	16	32	48	64	16	32	48	64	16	32	48	64
LSH [8]	12.9	15.2	16.9	17.8	40.3	49.2	49.3	55.1	10.1	23.5	30.1	34.9
SH [40]	12.2	13.5	12.1	12.6	47.9	49.1	49.8	51.5	20.8	32.7	39.5	42.0
ITQ [9]	21.3	23.4	23.8	25.3	56.7	60.3	62.2	62.6	32.5	46.2	51.3	55.6
CCA-ITQ [9]	31.4	36.1	36.6	37.9	50.9	54.4	56.8	67.6	26.6	43.6	54.8	58.0
KSH [25]	35.6	40.8	53.1	44.1	40.6	40.8	38.7	39.8	16.0	28.8	34.2	39.4
FastH [19]	45.3	46.1	48.7	50.3	51.9	61.0	64.7	65.2	22.8	44.7	51.7	55.6
SDH [30]	40.2	42.0	44.9	45.6	53.4	61.8	63.1	64.5	29.9	45.1	54.9	59.3
CNNH [42]	48.8	51.2	53.4	53.6	61.2	62.3	62.1	63.7	28.8	44.7	52.8	55.6
DNNH [17]	55.5	55.8	58.1	62.3	68.1	71.3	71.8	72.0	29.7	46.3	54.0	56.6
DPSH [18]	64.6	66.1	67.7	68.6	71.5	72.6	73.8	75.3	32.6	54.6	61.7	65.4
DSH [22]	68.9	69.1	70.3	71.6	71.8	72.3	74.2	75.6	34.8	55.0	62.9	66.5
HashNet [2]	70.3	71.1	71.6	73.9	73.3	75.2	76.2	77.6	50.6	62.9	66.3	68.4
PGDH	73.6	74.1	74.7	76.2	76.1	78.0	78.6	79.2	51.8	65.3	70.7	71.6



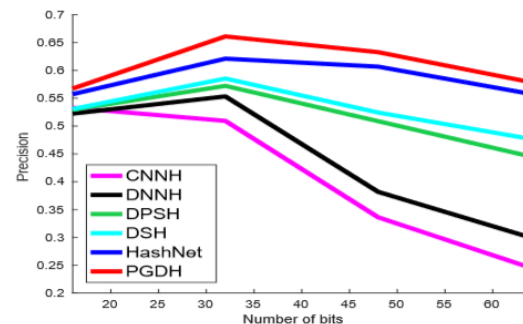
Experiments



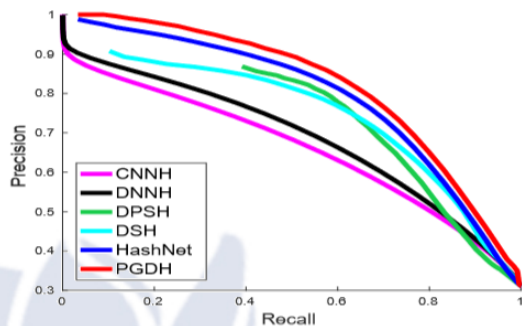
(a) P-R curve at 64 bits



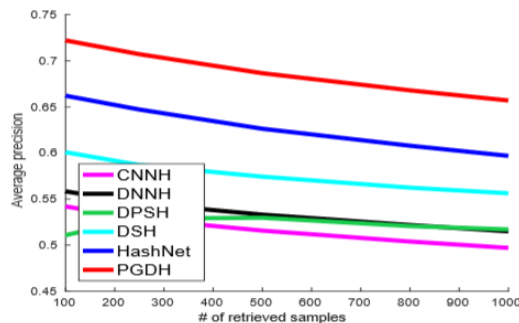
(b) P@N at 64 bits



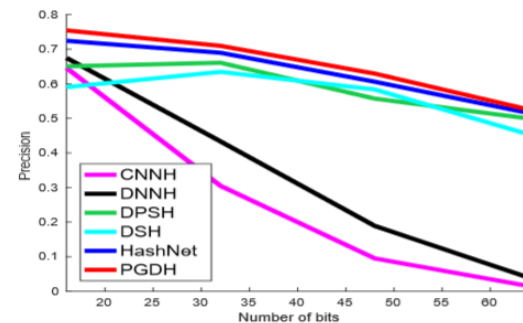
(c) HLP@2 at 64 bits



(a) P-R curve at 64 bits



(b) P@N at 64 bits



(c) HLP@2 at 64 bits



Reference

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