

Quantum Chemistry by Levine

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1 Chapter 5 Angular Momentum

5.1

- (a) no.
 - (b) yes
 - (c) yes
 - (d) yes
 - (e) yes
- for all well-behaved functions

5.2

- (a) $[\hat{A}, \hat{B}] = \hat{A}\hat{B} - \hat{B}\hat{A} = -[\hat{B}, \hat{A}]$
- (b) $[\hat{A}, \hat{A}^n] = \hat{A}^{n+1} - \hat{A}^{n+1} = 0$
- (c) $[k\hat{A}, \hat{B}] = k\hat{A}\hat{B} - \hat{B}k\hat{A} = k[\hat{A}, \hat{B}]$
- (d) $[\hat{A}, \hat{B} + \hat{C}] = \hat{A}(\hat{B} + \hat{C}) - (\hat{B} + \hat{C})\hat{A} = [\hat{A}, \hat{B}] + [\hat{A}, \hat{C}]$
- (e) $[\hat{A}, \hat{B}\hat{C}] = \hat{A}\hat{B}\hat{C} - \hat{B}\hat{C}\hat{A}$

5.3

$$\begin{aligned} [\hat{x}, \hat{p}_x^3] &= p_x[\hat{x}, \hat{p}_x^2] + [\hat{x}, \hat{p}_x]\hat{p}_x^2 \\ &= -i\hbar \frac{\partial}{\partial x} (2\hbar^2 \frac{\partial}{\partial x}) + i\hbar (-\hbar^2 \frac{\partial^2}{\partial x^2}) \end{aligned}$$

5.4

for a harmonic oscillator:

$$\langle x \rangle = 0$$

for energy level $n = 0$, it has energy $E = \frac{\hbar\nu}{2}$

$$\text{from which } \langle T \rangle = \frac{\hbar\nu}{4}$$

$$\langle V \rangle = \frac{1}{2}kx^2 = \frac{\hbar\nu}{4}$$

$$\text{So } \langle x^2 \rangle = \frac{\hbar\nu}{2k} = \frac{\hbar}{8\pi^2\nu m}$$

$$(\Delta x)^2 = \langle x^2 \rangle - \langle x \rangle^2 = \frac{\hbar}{8\pi^2\nu m}$$

So:

$$\Delta x = \sqrt{\frac{\hbar}{8\pi^2\nu m}}$$

similarly:

$$\langle p_x \rangle = 0$$

$$\text{Given } \langle T \rangle = \frac{p_x^2}{2m} = \frac{h\nu}{4}$$

$$\langle p_x^2 \rangle = \frac{h\nu m}{2}$$

$$\Delta p_x = \sqrt{\langle p_x^2 \rangle - \langle p_x \rangle^2} = \sqrt{\frac{h\nu m}{2}}$$

So:

$$\Delta x \Delta p_x = \frac{h}{4\pi} = \frac{\hbar}{2}$$

5.5

Given the non-stationary state: $\Psi = \sqrt{105/l^7} x^2(l-x)$

We need to calculate 4 values: $\langle x \rangle, \langle x^2 \rangle, \langle p_x \rangle, \langle p_x^2 \rangle$

$$\langle x \rangle = \int_{-\infty}^{\infty} \Psi^* x \Psi d\tau = \frac{5l}{8}$$

$$\langle x^2 \rangle = \int_{-\infty}^{\infty} \Psi^* x^2 \Psi d\tau = \frac{5l^2}{12}$$

$$\langle p_x \rangle = \int_{-\infty}^{\infty} \Psi^* (-i\hbar \frac{\partial}{\partial x}) \Psi d\tau = 0$$

$$\langle p_x^2 \rangle = \int_{-\infty}^{\infty} \Psi^* (-i\hbar \frac{\partial}{\partial x})^2 \Psi d\tau = \frac{14\hbar^2}{l^2}$$

$$\Delta x = \sqrt{\langle x^2 \rangle - \langle x \rangle^2} = \sqrt{\frac{5}{192}} l$$

$$\Delta p_x = \sqrt{\langle p_x^2 \rangle - \langle p_x \rangle^2} = \sqrt{14} \frac{\hbar}{l}$$

So:

$$\Delta x \Delta p_x = \sqrt{\frac{5}{192}} l \sqrt{14} \frac{\hbar}{l} > \frac{\hbar}{2}$$

5.6

Given Ψ is the eigenfunction, the only measurement value can be eigenvalue a

So it is expected there is no deviation.

$$\Delta A = \langle A^2 \rangle - \langle A \rangle^2$$

where:

$$\langle A^2 \rangle = \int_{-\infty}^{\infty} \Psi^* A^2 \Psi d\tau = a^2$$

$$\langle A \rangle^2 = a^2$$

$$\text{So: } \Delta A = \sqrt{\langle A^2 \rangle - \langle A \rangle^2} = 0$$

5.7

$$(\Delta A)^2 = \int_{-\infty}^{\infty} \Psi (A - \langle A \rangle)^2 \Psi d\tau$$

$$= \int_{-\infty}^{\infty} \Psi A^2 \Psi d\tau - 2 \langle A \rangle \int_{-\infty}^{\infty} \Psi A \Psi d\tau + \langle A \rangle^2 = \langle A^2 \rangle - \langle A \rangle^2$$

5.8

All the combinations HH, HT, TH, TT

So $\langle w \rangle = 1$

where w takes value 2, 1, 0

w^2 can take 4, 1, 0 at different possibilities

$$\langle w^2 \rangle = 4 * \frac{1}{4} + 1 * \frac{1}{2} + 0 * \frac{1}{4} = 1.5$$

So:

$$\sigma w = \sqrt{\langle w^2 \rangle - \langle w \rangle^2} = \sqrt{0.5}$$

5.9

- (a) vector
- (b) vector
- (c) scalar
- (d) scalar
- (e) vector
- (f) scalar

5.10

$$A = (3, -2, 6), B = (-1, 4, 4)$$

$$|A| = 7, |B| = \sqrt{33}$$

$$A + B = (-2, 3, 10), A - B = (4, -6, 2)$$

$$AB = 13$$

$$A * B = (-32, -18, 10)$$

$$\cos\theta = \frac{AB}{|A||B|} = \frac{13}{7\sqrt{33}}$$

5.11

two diagonal lines are $(1, 1, 1), (-1, 1, -1)$

$$\cos\theta = \frac{-1}{3}$$

5.13

$$\text{grad } f = \vec{i}(4x - 5yz) + \vec{j}(-5xz) + \vec{k}(-5xy + 2z)$$

$$\nabla f = 4 + 0 + 2 = 6$$

5.14

$$(a) \text{div} \cdot \text{grad } g(x, y, z) = \text{div}(\vec{i}(\frac{\partial}{\partial x}) + \vec{j}(\frac{\partial}{\partial y}) + \vec{k}(\frac{\partial}{\partial z}))$$

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

$$(b) \text{div} \cdot \vec{r} = (\vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z})(\vec{i}x + \vec{j}y + \vec{k}z) = 1 + 1 + 1 = 3$$

5.15

$$(a) |B| = \sqrt{13}$$

(b) with each axis:

$$\cos\alpha = \frac{(3, -2, 0, 1)(1, 0, 0, 0)}{\sqrt{13}} = \frac{3}{\sqrt{13}}$$

$$\cos\alpha = \frac{(3, -2, 0, 1)(0, 1, 0, 0)}{\sqrt{13}} = \frac{-2}{\sqrt{13}}$$

$$\cos\alpha = \frac{(3,-2,0,1)(0,0,1,0)}{\sqrt{13}} = 0$$

$$\cos\alpha = \frac{(3,-2,0,1)(0,0,0,1)}{\sqrt{13}} = \frac{1}{\sqrt{13}}$$

5.16

- (a) no
 (b) yes
 (c) yes
 (d) yes
- $$[\hat{L}_x^2, \hat{L}^2] = \hat{L}_x[\hat{L}_x, \hat{L}^2] + [\hat{L}_x, \hat{L}^2]\hat{L}_x = 0$$

5.18

$$[\hat{L}_x^2, \hat{L}_y] = \hat{L}_x[\hat{L}_x, \hat{L}_y] + [\hat{L}_x, \hat{L}_y]\hat{L}_x$$

$$= i\hbar(\hat{L}_x\hat{L}_z + \hat{L}_z\hat{L}_x)$$

5.19

coordinate conversion

$$(x, y, z) \rightarrow (r, \theta, \phi)$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \cos^{-1}\left(\frac{z}{r}\right)$$

$$\phi = \tan^{-1}\left(\frac{y}{x}\right)$$

(a) given (1, 2, 0)

$$r = \sqrt{5}$$

$$\theta = \frac{\pi}{2}$$

$$\phi = \tan^{-1}2$$

(b) given (-1, 0, 3)

$$r = \sqrt{10}$$

$$\theta = \cos^{-1}\left(\frac{3}{\sqrt{10}}\right)$$

$$\phi = \tan^{-1}0 = \pi$$

(c) given (3, 1, -2)

$$r = \sqrt{14}$$

$$\theta = \cos^{-1}\left(\frac{-2}{\sqrt{14}}\right)$$

$$\phi = \tan^{-1}\left(\frac{1}{3}\right)$$

(d) given (-1, -1, -1)

$$r = \sqrt{3}$$

$$\theta = \cos^{-1}\left(\frac{-1}{\sqrt{3}}\right)$$

$$\phi = \tan^{-1}(1) = \frac{5}{4}\pi$$

5.20

Coordinate conversion:

$$x = r\sin\theta\cos\phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

$$(a) \text{ given } r = 1, \theta = \pi/2, \phi = \pi$$

$$x = -1, y = 0, z = 0$$

$$(b) \text{ given } r = 2, \theta = \pi/4, \phi = 0$$

$$x = \sqrt{2}, y = 0, z = \sqrt{2}$$

5.21

(a) sphere

(b) cone

(c) plane perpendicular to xy plane

5.22

the volume is:

$$V = \int_0^{2\pi} \int_0^\pi \int_0^r r^2 \sin \theta dr d\theta d\phi = \frac{4}{3} \pi r^3$$

5.23

the shape of \vec{L} is a cone

So the eigenvalue of $c = \vec{L}_z = m\hbar$

the eigenvalue of $b = \vec{L}^2 = l(l+1)\hbar^2$

$$\cos \theta = \frac{c}{\sqrt{b}} = \frac{m}{\sqrt{l(l+1)}}$$

given $l = 2$

$$m = -2, -1, 0, 1, 2$$

$$\text{then } \cos \theta = \frac{-2}{\sqrt{6}}, \frac{-1}{\sqrt{6}}, 0, \frac{1}{\sqrt{6}}, \frac{2}{\sqrt{6}}$$

5.24

$$\text{Given } \cos \theta = \frac{c}{\sqrt{b}} = \frac{m}{\sqrt{l(l+1)}}$$

when $m = -l, -l+1, \dots, l-1, l$

when $m = l, \cos^2 \theta = \frac{l}{l+1}$

when $l- > \inf$ then $\cos \theta- > 1, \theta = 0$

5.28

$$\hat{L}^2 Y_2^0 = 2 * (2+1) Y_2^0$$

5.29

$$\hat{L}_z^3 Y_l^m = (m\hbar)^3 Y_l^m$$

5.30

$$\hat{L}_x^2 + \hat{L}_y^2 = \hat{L}^2 - \hat{L}_z^2$$

So the eigenvalue is $l(l+1)\hbar^2 - m^2\hbar^2$

5.31

(a) given $l = 2$, $m = -2, -1, 0, 1, 2$

the measured value $m\hbar = -2\hbar, -\hbar, 0, \hbar, 2\hbar$

(b) given $l = 3$

the measured value $m\hbar = -3\hbar, -2\hbar, -\hbar, 0, \hbar, 2\hbar, 3\hbar$

5.32

similar to \hat{L}_z , $[\hat{L}^2, \hat{L}_y] = 0$

the eigenvalue is also $-\hbar, 0, \hbar$

5.33

the other parameters are not important since it is time term

Given Y_2^1

the measurement of $\hat{L}^2 = l(l+1)\hbar = 6\hbar$

the measurement of $\hat{L}_z = m\hbar = \hbar$

5.35

$$\hat{L}_- Y_1^1 = Y_1^0$$

$$\hat{L}_-^2 Y_1^1 = Y_1^{-1}$$

$$\hat{L}_-^3 Y_1^1 = 0$$

5.37

(a) true

(b) false

(c) true

(d) true

(e) true

(f) false

it is possible to find an eigenfunction, but not a set of eigenfunction