# Starting laboratory session

Methods and tools for software quality

#### Antonio Martí Campoy



#### Goals



- Getting basic knowledge about the Integrated Development Environment (IDE) of IAR
  - IAR Embedded Workbench

#### Plan



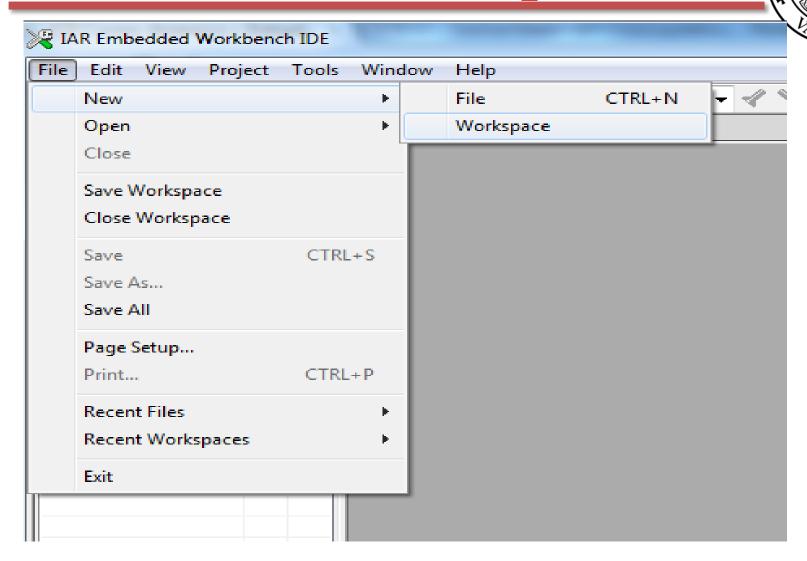
- Creating a new project.
- Setting options for the project.
- Adding robot\_library.
- Testing the project.
- Testing the hardware.

#### IAR Embedded Workbench





## Create a new workspace



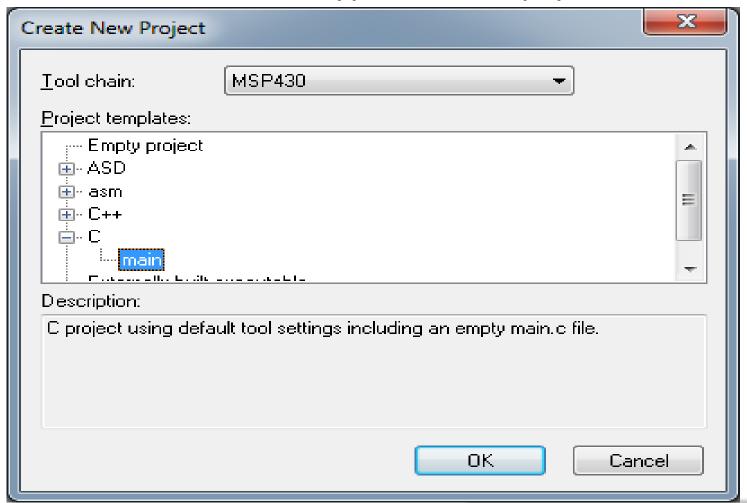
# Create a new project



IAR Embedded Workbench IDE		
File Edit View	Project Tools Window Help	
	Add Files	
Workspace	Add Group	
	Import File List	
Files	Edit Configurations	
	Remove	
	Create New Project	
	Add Existing Project	
	Options	
	Version Control System	
	Make	
	Compile	(
	Rebuild All	
	Clean	
	Batch build	
	Stop Build CTRL+INT	ER

## New project settings

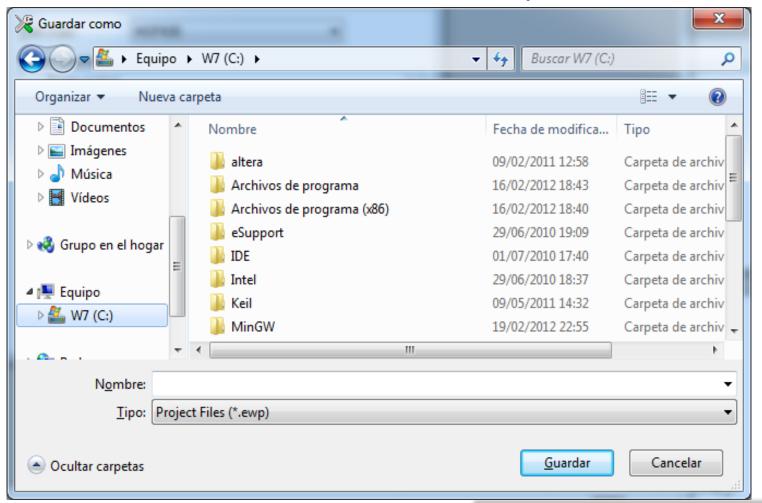
MSP430 toolchain, C type with empty main file



## "Save as" for the project



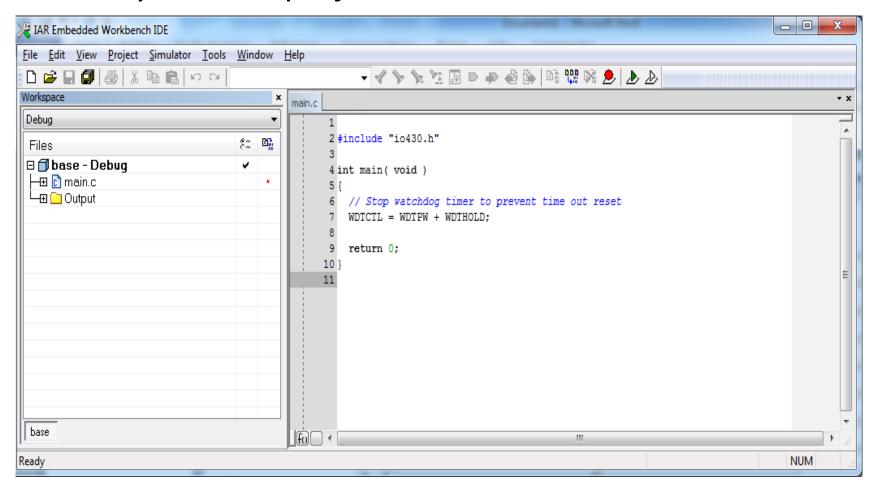
Create a new folder and save a .ewp file



#### The project

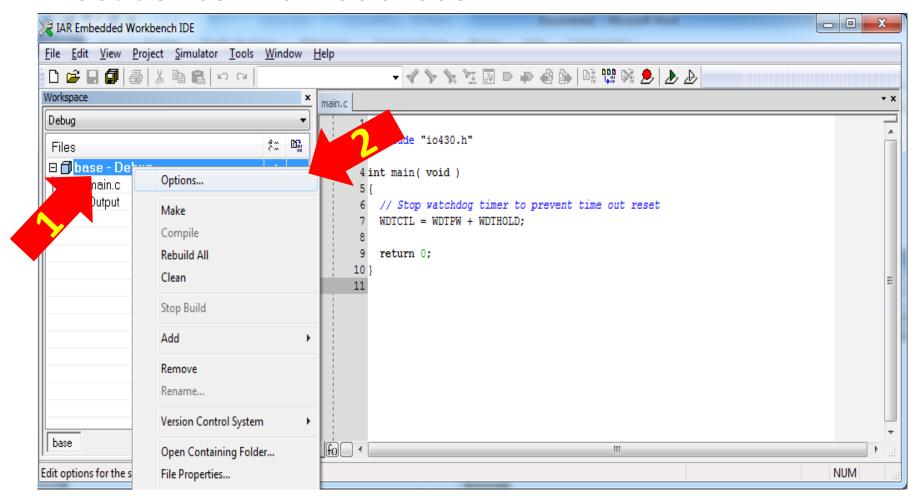


Here your new project



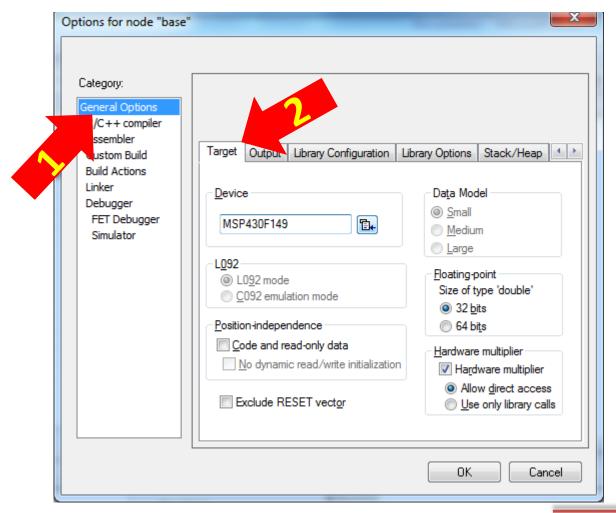


Set device: MSP430G2553



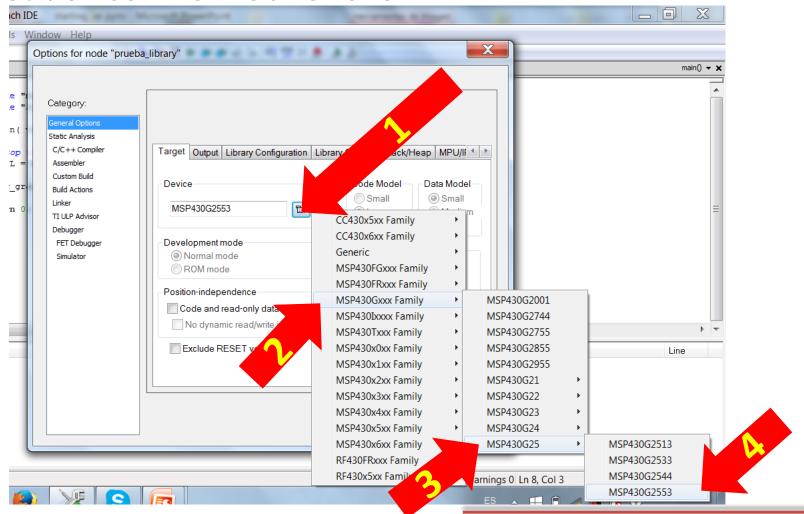


Set device: MSP430FG4619



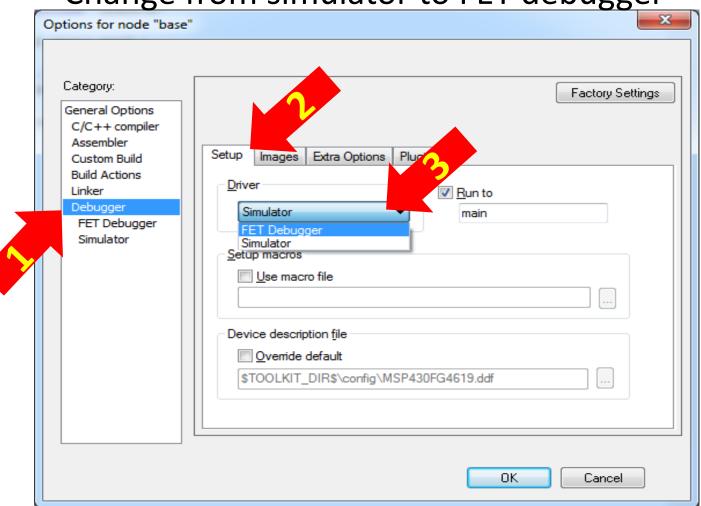


Set device: MSP430FG4619





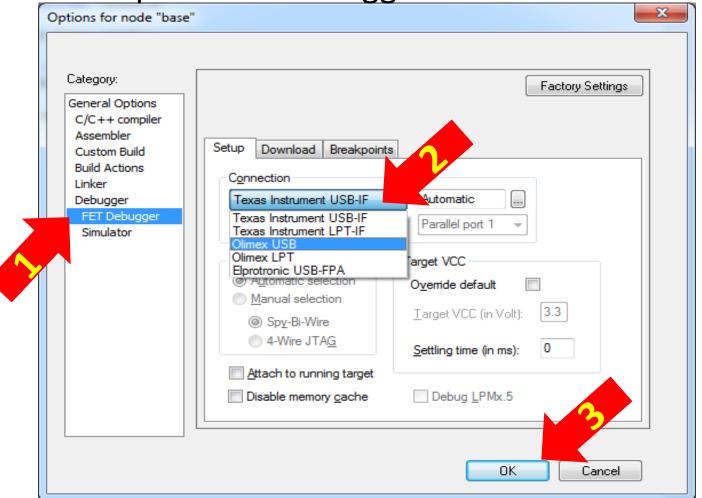
Change from simulator to FET debugger





\* ALENCIA

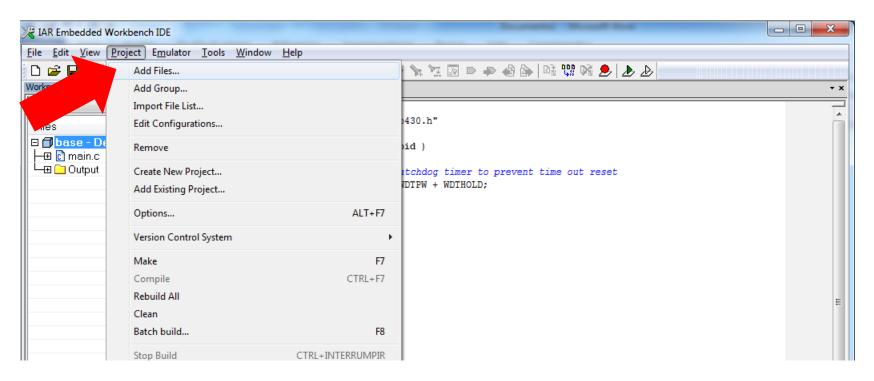
Setup the FET debugger to Texas Instruments USB-TF



- Replace the generic microcontroller header file with the actual microcontroller header:
  - Replace #include "io430.h" with #include "msp430G2553.h"
- Download file "robot\_library.zip" from moodle: ent.esigelec.fr
  - Extract files in the folder of your workspace/project

#### Setup the project

- Add header files "stdint.h" and "intrinsics.h" to have access to standard types and low level functions.
- Add the robot\_library to the project: robot\_library.r43



#### Setup the project

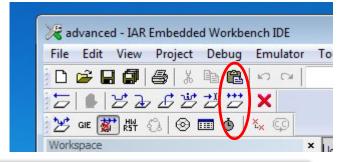
 Add in the main function sentences to disable the watchdog and initialise the Clock System

```
// Stop watchdog timer to prevent time out reset
WDTCTL = WDTPW + WDTHOLD;
Clock_graceInit_DCO_12M(); //from robot_library.r43
```

• To use the function *Clock\_graceInit\_DCO\_12M()* you have to include header "system.h"

#### Test the project

- \* HENCLA\*
- Now, before adding your new code, test if everything is ok compiling the project:
- Compile all files and link them with F7 (Make) or "Project → Make" (you will be prompted to save the workspace before)
  - Expected result is warnings: 0 errors:0
- Download and activate debug with "Project → Download and debug"
- 3. Run program with "Debug  $\rightarrow$  Go"
  - The program does nothing



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