# Dataflow analysis

### Dataflow analysis: what is it?

- A common framework for expressing algorithms that compute information about a program
- Why is such a framework useful?

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- A common framework for expressing algorithms that compute information about a program
- Why is such a framework useful?
- Provides a common language, which makes it easier to:
  - communicate your analysis to others
  - compare analyses
  - adapt techniques from one analysis to another
  - reuse implementations (eg: dataflow analysis frameworks)

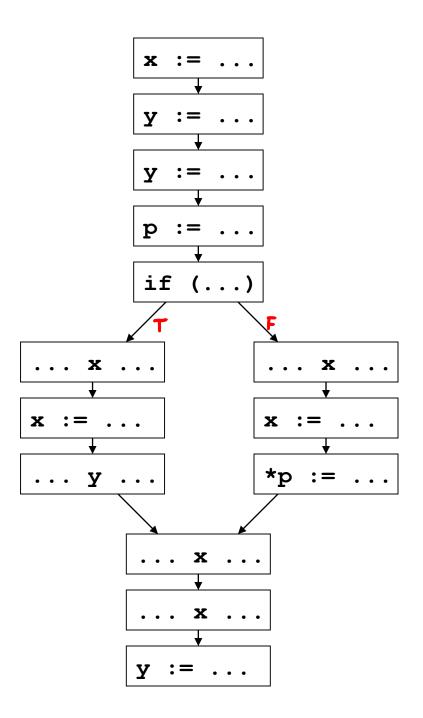
### **Control Flow Graphs**

- For now, we will use a Control Flow Graph representation of programs
  - each statement becomes a node
  - edges between nodes represent control flow

- Later we will see other program representations
  - variations on the CFG (eg CFG with basic blocks)
  - other graph based representations

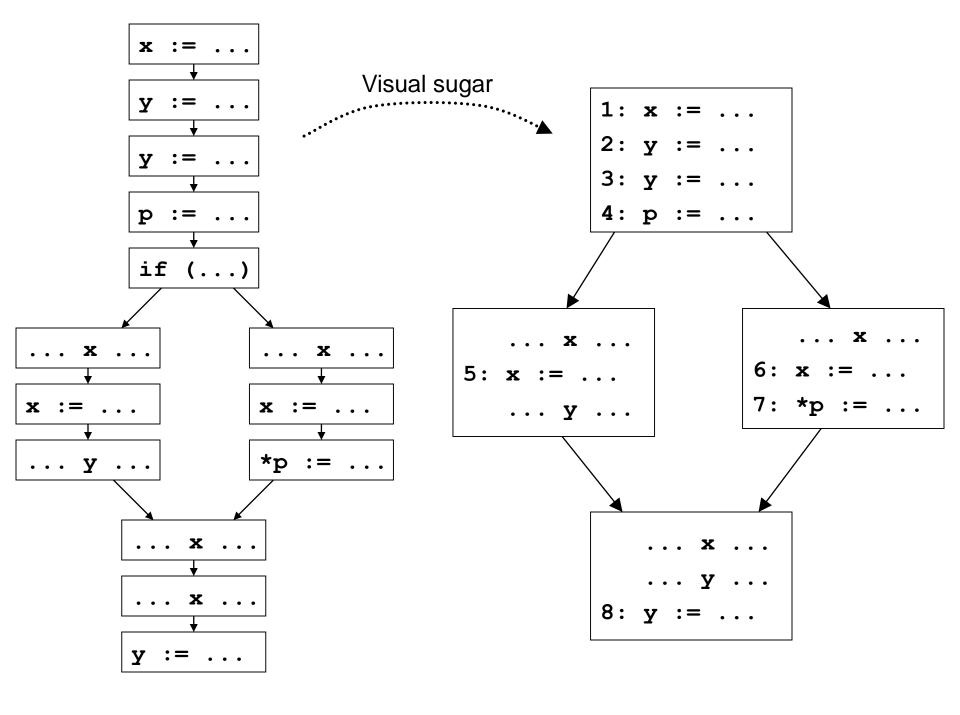
# **Example CFG**

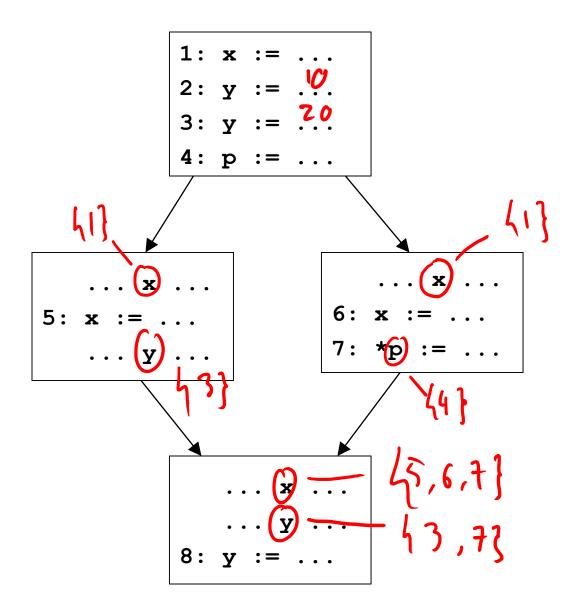
```
x := \dots
if (...) {
   ... x ...
   \mathbf{x} := \dots
   ... у ...
else {
    ... x ...
... x ...
```

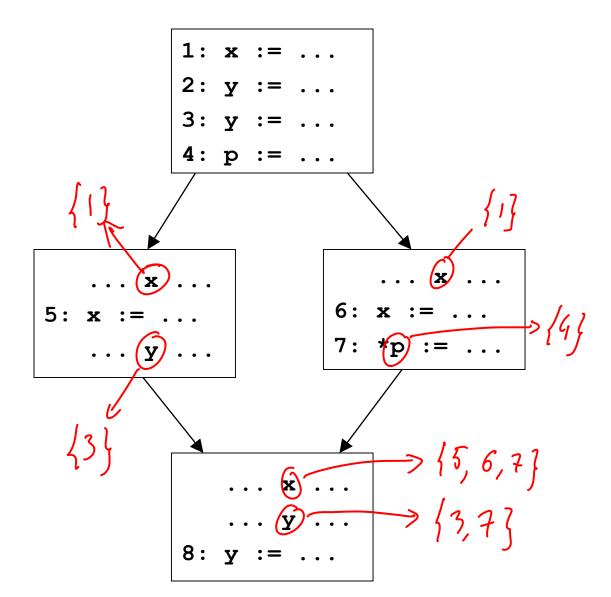


# An example DFA: reaching definitions

- For each use of a variable, determine what assignments could have set the value being read from the variable
- Information useful for:
  - performing constant and copy prop
  - detecting references to undefined variables
  - presenting "def/use chains" to the programmer
  - building other representations, like the DFG
- Let's try this out on an example







# Safety

- When is computed info safe?
- Recall intended use of this info:
  - performing constant and copy prop
  - detecting references to undefined variables
  - presenting "def/use chains" to the programmer
  - building other representations, like the DFG
- Safety:
  - can have more bindings than the "true" answer, but can't miss any

# Reaching definitions generalized

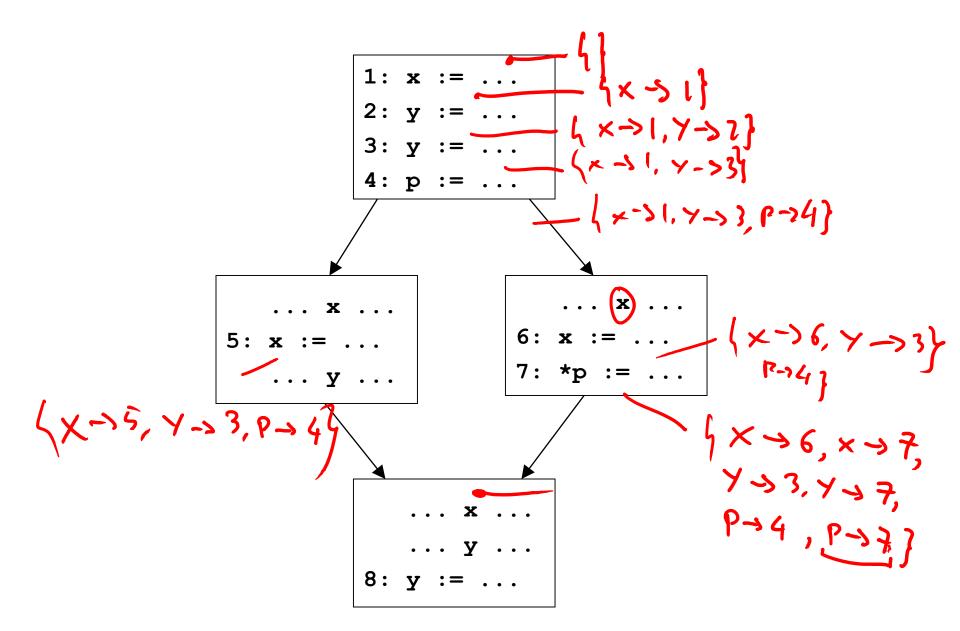
- DFA framework geared to computing information at each program point (edge) in the CFG
  - So generalize problem by stating what should be computed at each program point
- For each program point in the CFG, compute the set of definitions (statements) that may reach that point
- Notion of safety remains the same

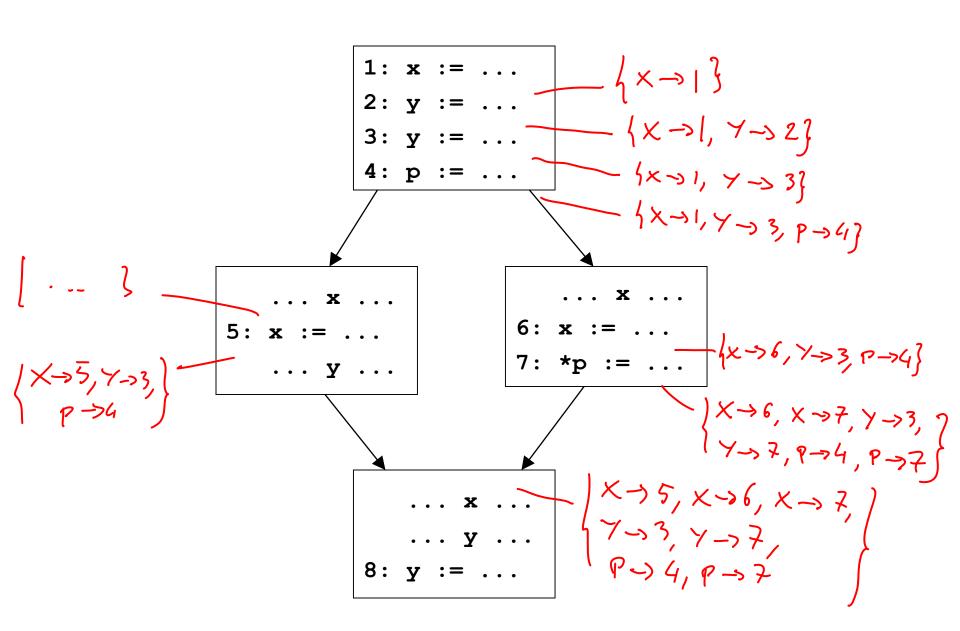
# Reaching definitions generalized

- Computed information at a program point is a set of var → stmt bindings
  - eg:  $\{x \rightarrow s_1, x \rightarrow s_2, y \rightarrow s_3\}$
- How do we get the previous info we wanted?
  - if a var x is used in a stmt whose incoming info is in, then:

# Reaching definitions generalized

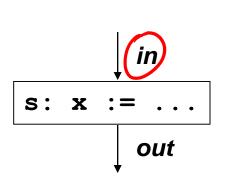
- Computed information at a program point is a set of var → stmt bindings
  - eg:  $\{x \rightarrow s_1, x \rightarrow s_2, y \rightarrow s_3\}$
- How do we get the previous info we wanted?
  - if a var x is used in a stmt whose incoming info is in, then:  $\{s \mid (x \rightarrow s) \in in\}$
- This is a common pattern
  - generalize the problem to define what information should be computed at each program point
  - use the computed information at the program points to get the original info we wanted



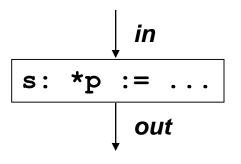


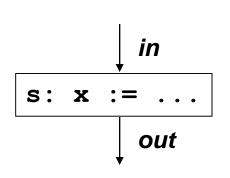
#### Using constraints to formalize DFA

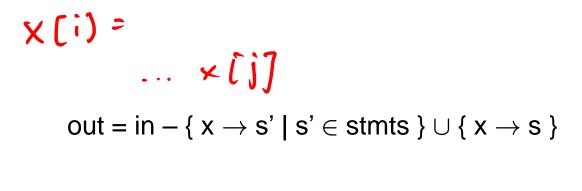
- Now that we've gone through some examples, let's try to precisely express the algorithms for computing dataflow information
- We'll model DFA as solving a system of constraints
- Each node in the CFG will impose constraints relating information at predecessor and successor points
- Solution to constraints is result of analysis

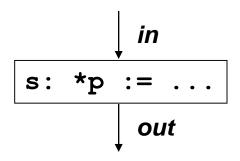


$$4a > 5, b > 10, b > 11, ... }$$
out =  $im - 4 \times > * \} \cup 4 \times > s }$ 







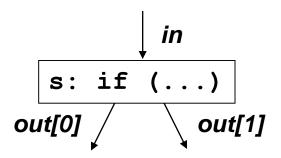


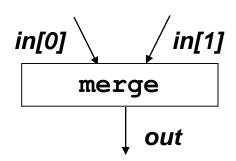
Using may-point-to information:

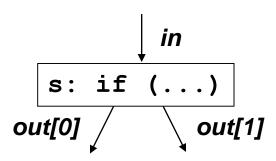
out = in 
$$\cup$$
 {  $x \rightarrow s \mid x \in may\text{-point-to(p)}$  }

Using must-point-to aswell:

out = in 
$$- \{ x \rightarrow s' \mid x \in \text{must-point-to(p)} \land s' \in \text{stmts} \}$$
  
 $\cup \{ x \rightarrow s \mid x \in \text{may-point-to(p)} \}$ 

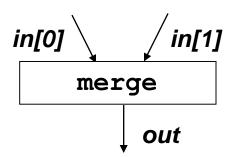






$$out [ 0 ] = in \land out [ 1 ] = in$$

more generally:  $\forall i$  . out [i] = in



$$out = in [0] \cup in [1]$$

more generally:  $out = \bigcup_i in[i]$ 

#### Flow functions

- The constraint for a statement kind s often have the form: out = F<sub>s</sub>(in)
- F<sub>s</sub> is called a flow function
  - other names for it: dataflow function, transfer function
- Given information in before statement s, F<sub>s</sub>(in) returns information after statement s
- Other formulations have the statement s as an explicit parameter to F: given a statement s and some information in, F(s,in) returns the outgoing information after statement s

#### Flow functions, some issues

 Issue: what does one do when there are multiple input edges to a node?

 Issue: what does one do when there are multiple outgoing edges to a node?

#### Flow functions, some issues

- Issue: what does one do when there are multiple input edges to a node?
  - the flow functions takes as input a tuple of values,
     one value for each incoming edge
- Issue: what does one do when there are multiple outgoing edges to a node?
  - the flow function returns a tuple of values, one value for each outgoing edge
  - can also have one flow function per outgoing edge

#### Flow functions

- Flow functions are a central component of a dataflow analysis
- They state constraints on the information flowing into and out of a statement

- This version of the flow functions is local
  - it applies to a particular statement kind
  - we'll see global flow functions shortly...

### Summary of flow functions

- Flow functions: Given information in before statement s, F<sub>s</sub>(in) returns information after statement s
- Flow functions are a central component of a dataflow analysis
- They state constraints on the information flowing into and out of a statement

# Back to example

1: x := ... 2: y := ... 3: y := ... 4: p := ... if(...)

 $d_0$  $d_1 = F_a(d_0)$  $d_2 = F_b(d_1)$  $d_3 = F_c(d_2)$  $d_4 = F_d(d_3)$  $d_5 = F_e(d_4)$  $d_5$  $d_6 = F_g(d_5)$  $d_6 \quad d_7 = F_h(d_6)$  $d_8 = F_i(d_7)$ 

$$\begin{aligned} d_{10} &= F_j(d_9) \\ d_{11} &= F_k(d_{10}) \begin{array}{l} d_{10} \\ d_{11} \end{array} \\ d_{12} &= F_l(d_{11}) \end{array}$$

 $d_9$ 

 $d_9 = F_f(d_4)$ 

merge

 $d_{13} = F_m(d_{12}, d_8)$   $d_{13} \quad d_{14} = F_n(d_{13})$   $d_{14} \quad d_{15} = F_o(d_{14})$   $d_{15} \quad d_{16} = F_p(d_{15})$ 

 $d_8$ 

How to find solutions for d<sub>i</sub>?

# How to find solutions for d<sub>i</sub>?

- This is a forward problem
  - given information flowing in to a node, can determine using the flow function the info flow out of the node
- To solve, simply propagate information forward through the control flow graph, using the flow functions
- What are the problems with this approach?

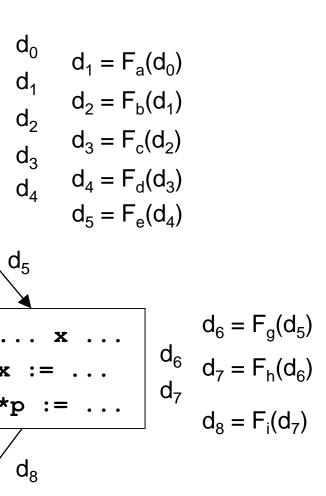
# First problem

em

1: 
$$x := ...$$
2:  $y := ...$ 
3:  $y := ...$ 
4:  $p := ...$ 

$$d_9 = F_f(d_4)$$

$$d_9$$



$$\begin{aligned} d_{10} &= F_j(d_9) \\ d_{11} &= F_k(d_{10}) \begin{array}{l} d_{10} \\ d_{11} \end{array} \\ d_{12} &= F_l(d_{11}) \end{array}$$

$$5: \mathbf{x} := \dots$$

$$0 \quad d_{12}$$

merge ... x ...

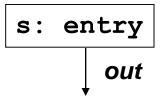
 $d_{13} = F_{m}(d_{12}, d_{8})$   $d_{13} = d_{14} = f_{n}(d_{13})$   $d_{14} = d_{15} = d_{15} = d_{15}$   $d_{15} = d_{16} = d_{15}$ 

What about the incoming information?

### First problem

- What about the incoming information?
  - d<sub>0</sub> is not constrained
  - so where do we start?
- Need to constrain d<sub>0</sub>
- Two options:
  - explicitly state entry information
  - have an entry node whose flow function sets the information on entry (doesn't matter if entry node has an incoming edge, its flow function ignores any input)

# Entry node

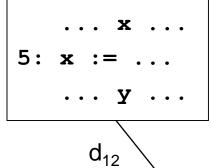


out = 
$$\{ x \rightarrow s \mid x \in Formals \}$$

# Second problem

```
d_{0} = F_{entry}()
d_{1} = F_{a}(d_{0})
d_{2} = F_{b}(d_{1})
d_{3} = F_{c}(d_{2})
d_{4} = F_{d}(d_{3})
d_{5} = F_{e}(d_{4})
```

$$\begin{aligned} d_{10} &= F_j(d_9) \\ d_{11} &= F_k(d_{10}) \begin{array}{l} d_{10} \\ d_{11} \end{array} \\ d_{12} &= F_l(d_{11}) \end{array}$$

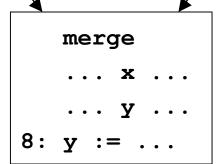


 $d_9$ 

 $d_9 = F_f(d_4)$ 

$$d_6 = F_g(d_5)$$
 $d_6 = F_g(d_5)$ 
 $d_7 = F_g(d_7)$ 

Which order to process nodes in?



$$d_{13} = F_m(d_{12}, d_8)$$

$$d_{13} = d_{14} = f_n(d_{13})$$

$$d_{14} = d_{15} = d_{15} = d_{15}$$

$$d_{15} = d_{16} = d_{15}$$

 $d_8$ 

### Second problem

Which order to process nodes in?

- Sort nodes in topological order
  - each node appears in the order after all of its predecessors
- Just run the flow functions for each of the nodes in the topological order

What's the problem now?

### Second problem, prime

- When there are loops, there is no topological order!
- What to do?
- Let's try and see what we can do

```
1: x := ...
2: y := ...
3: y := ...
4: p := ...
```

... x ...

5: x := ...

... у ...

... x ...

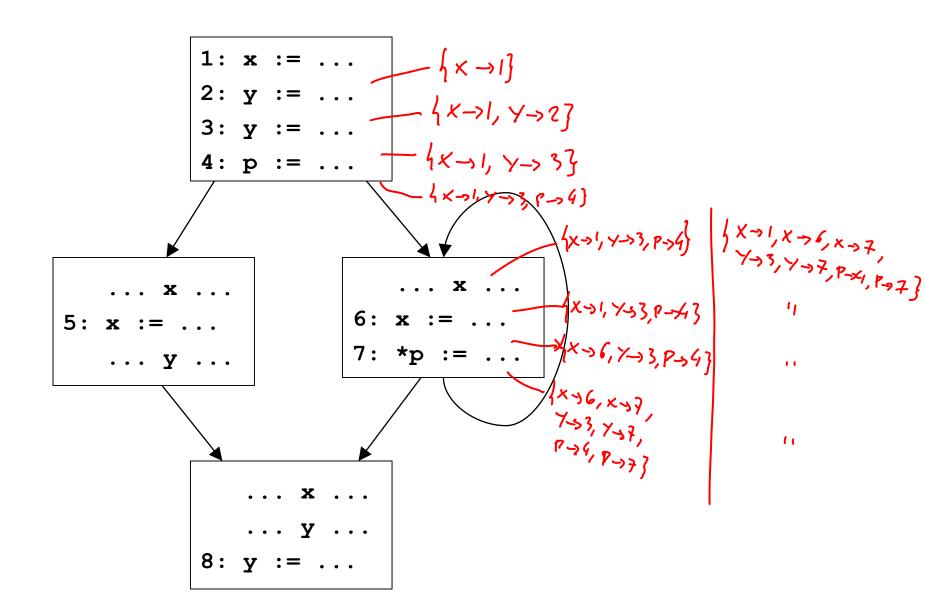
6: **x** := ...

7: \*p := ...

... x ...

... у ...

8: y := ...



# Worklist algorithm

- Initialize all d<sub>i</sub> to the empty set
- Store all nodes onto a worklist
- while worklist is not empty:
  - remove node n from worklist
  - apply flow function for node n
  - update the appropriate d<sub>i</sub>, and add nodes whose inputs have changed back onto worklist

### Worklist algorithm

```
let m: map from edge to computed value at edge
let worklist: work list of nodes
for each edge e in CFG do
   m(e) := \emptyset
for each node n do
   worklist.add(n)
while (worklist.empty.not) do
   let n := worklist.remove any;
   let info in := m(n.incoming edges);
   let info out := F(n, info in);
   for i := 0 .. info out.length-1 do
      if (m(n.outgoing edges[i]) ≠ info out[i])
         m(n.outgoing edges[i]) := info out[i];
         worklist.add(n.outgoing edges[i].dst);
```

# Issues with worklist algorithm

# Two issues with worklist algorithm

- Ordering
  - In what order should the original nodes be added to the worklist?
  - What order should nodes be removed from the worklist?
- Does this algorithm terminate?

#### Order of nodes

- Topological order assuming back-edges have been removed
- Reverse depth-first post-order
- Use an ordered worklist

```
1: x := ...
2: y := ...
3: y := ...
4: p := ...
```

... x ...

5: x := ...

... у ...

... x ...

6: **x** := ...

7: \*p := ...

... x ...

... у ...

8: y := ...

#### **Termination**

- Why is termination important?
- Can we stop the algorithm in the middle and just say we're done...
- No: we need to run it to completion, otherwise the results are not safe...

#### **Termination**

 Assuming we're doing reaching defs, let's try to guarantee that the worklist loop terminates, regardless of what the flow function F does

```
while (worklist.empty.not) do
  let n := worklist.remove_any;
  let info_in := m(n.incoming_edges);
  let info_out := F(n, info_in);
  for i := 0 .. info_out.length-1 do
    if (m(n.outgoing_edges[i]) ≠ info_out[i])
      m(n.outgoing_edges[i]) := info_out[i];
    worklist.add(n.outgoing_edges[i].dst);
```

#### **Termination**

 Assuming we're doing reaching defs, let's try to guarantee that the worklist loop terminates, regardless of what the flow function F does

#### Structure of the domain

 We're using the structure of the domain outside of the flow functions

 In general, it's useful to have a framework that formalizes this structure

We will use lattices