10/5 Review

(B) B: burglary, E: earthquake, A: alarm, J: John calls, M: Mary calls. * Belief network BN = DAG + CPTs * Conditional independence $P(X_1 \mid X_1, X_2, \dots, X_{1+1}) = P(X_1 \mid pa(X_1))$ * Representing CPTs lookup tables logical AND/OR noisy - OR sigmoid * Conditional independence - A node Xi is conditionally independent of its non-parent ancestors given its parents: $P(X_1 \mid pa(X_1)) = P(X_1 \mid X_1, \dots, X_{1+1})$ - More generally: Let X, Y and E refer to sets of nodes in BN. When is X conditionally independent of Y given evidence E? When is P(X|E,Y) = P(X|E)? P(X,Y|E) = P(X|E) P(Y|E)?

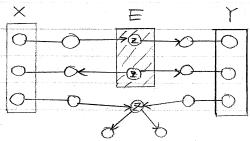
d-separation

"direction - dependent"

Relates conditional independence to graph-theoretic properties.

P(X,Y|E) = P(X|E) P(Y|E) if and only if every undirected path from a node in X to any node in Y is "d-separated" by E.

Def: a path TT is d-separated if there exists a node ZETT for which one of three conditions hold:



Intuition

(I) $Z \in E$ with $\rightarrow (Z) \rightarrow is$ "intervening" event in a causal chain. (I) ZEE with (2) is a common cause/explanation.

(II) $Z \notin E$ with $\longrightarrow E$ and all descendants $(Z) \notin E$.

sis an unobserved common effect.

Ex: B A

I) P(B|A,M) = P(B|A)?

true: A is an intermediate cause.

 \mathbb{T} , $P(\mathcal{J}, M \mid A) = P(\mathcal{J} \mid A) P(M \mid A)$?

true : A is a common cause or explanation.

 \mathbb{I}) P(B,E) = P(B)P(E)?

true: A is an unobserved common effect.

P(B, E|A) = P(B|A) P(E|A)? Not true. Path B→A←E fails all three conditions.

- * Proof that d-sep \(\infty \) conditional independence is hard.
- * Algorithms exist for efficient tests of d-separation.

Inference

* Problem

E = set of evidence nodes

Q = set of query nodes

How to compute posterior distribution P(Q(E)?

* Types of inference



- diagnostic reasoning (from effects to causes) e.g., P(B=1 | M=1)
- causal reasoning (from causes to effects) e.g., PCM=1 | B=1)
- explaining away (about multiple causes) e.g., PCB=1 | A=1, E=1)
- mixed (causes and effects) e.g., PCB=1, M=1 | A=1, J=1)

- When can inference be done efficiently?

(i.e., polynomial time in size of DAG and CPTs)

Polytrees !!

Polytrees

* A polytree is a graph without loops

- a singly connected network (at most one undirected path between any two nodes)

*Goal: compute P(X=x/E)

Node X

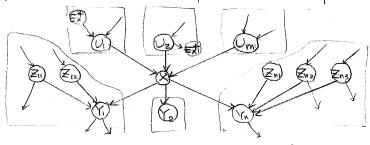
Evidence E

Parents U: (1-1, ", m # parents)

Children & J=1,..., n # children)

Parents of children Zjk

(excluding X)



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* Note: Boxes don't overlap for polytrees - otherwise, there are loops
* Types of evidence:
 Ext = evidence "above" X connected thru parents
  Ex = evidence "below" X connected thru children.
  Assume X € E. (otherwise trivial).
 E = Ex U Ex
* General strategy: recursion
  P(X=x|E) = P(X=x|E_x,E_x^+)
                  = P(E_x^-|X=x,E_x^+) P(X=x|E_x^+)
                                                                     generalized
                                                                     Bayes rule
                 = \frac{P(E_x^-|X=x)P(X=x|E_x^+)}{P(E_x^-|E_x^+)}
                                                                      d-separation case I
                                                                       X = intermediate event
* Plan of attack
 - compute numerator up to constant factor. (independent of little "x").
 - compute denominator by P(E_x^{-1}|E_x^{+}) = \sum_{\alpha} P(E_x^{-1}|X=\alpha) P(X=\alpha |E_x^{+})
 - constant factors will divide out of ratio.
                                                                              by normalization.
* Upstream recursion
 P(X|E_X^{\dagger}) = \sum_{i=1}^{n} P(X_i, \vec{U} = \vec{u} \mid E_X^{\dagger}) marginalization
               = = P(X | U= t, Ext) P(U=t | Ext) product rule.
               = \sum_{i=1}^{n} P(X|\vec{U}=\vec{u}) P(\vec{U}=\vec{u}|\vec{E}_{x}^{+}) \qquad d-separation I \text{ or } \vec{I}
                = \sum_{i=1}^{n} P(X | \vec{U} = \vec{u}) \prod_{i=1}^{n} P(U_i = u_i | E_X^{+}) d-separation III X = u_i observed
 Notation Euix = evidence connected to Ui except via path thrux.
                    (evidence in its own box)
               = \frac{F}{F}(X|\(\pi = \pi\)) \frac{m}{T} P(\pi_1 = u_1 | \E u_1 \chi) d-separation case \frac{m}{T}
                                               recurse on parents
                          (given)
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