

# BST: Find Next Node Strategy

## Find “Successor” node (if exists):

Given a Node on the tree:

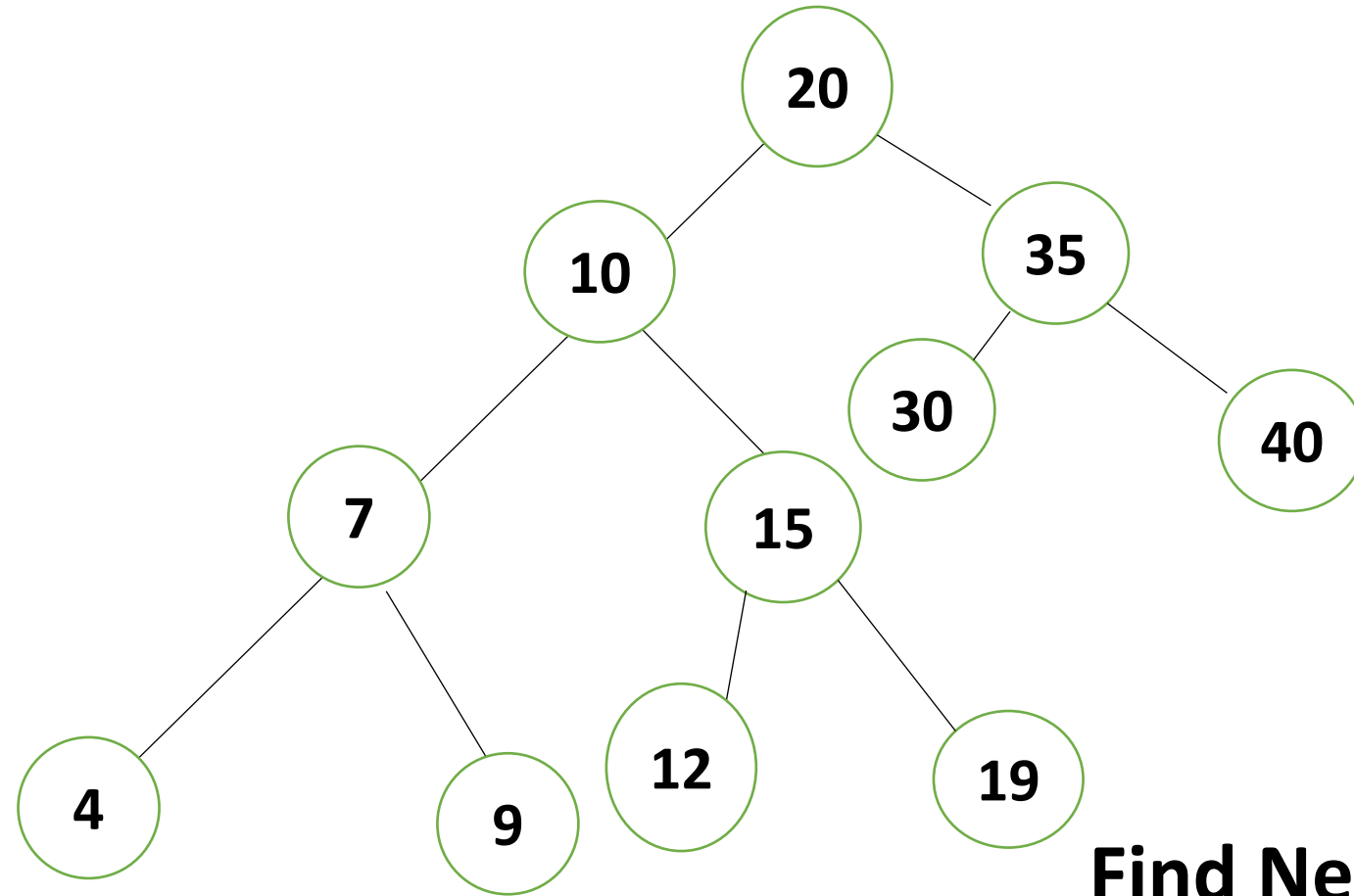
How do we find the “next node”?

Starting at:

Node 10?

Node 12?

Node 19?



## Find Next: Tree Walking Rules:

Next Node Starting at:

(10)? **If RHC exists, Go RHC, walk down all LHC's to Leaf (12)**

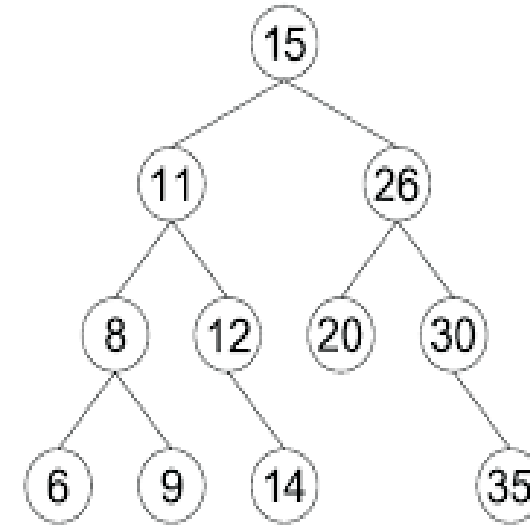
(12)? **Else If LHC of Parent, return Parent (15)**

(19)? **Else, Walk-up Parents till Parent X LHC of GParent Y. Use Y (20)**

# “Get Next Node” Code

## Finding “next” node (if exists): Not-recursive)

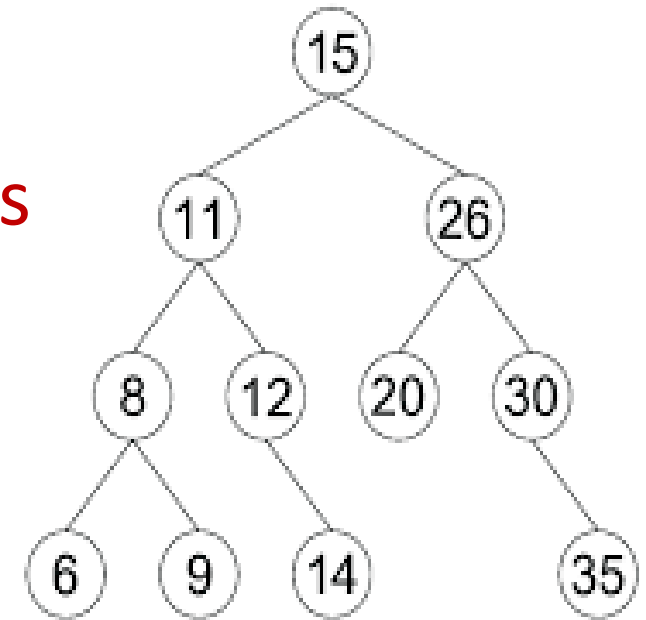
```
Node*BST:: getNext (Node* from) { // Returns next node
    Node *currNode = from→parent;
    if (from→RHC) { // If RHC, find leftmost leaf (15→20)
        currNode = from→RHC;
        while (currNode→LHC) { currNode = LHC ; }
        return (currNode); }
    //No RHC. Is this node the Root. If so, return error (end of line)
    If (from == toRoot) return (NULL); // Root and no right hand child. Done.
    // No RHC and not Root? Is this Node an LHC of Parent? If so, return Parent
    if (from == from→Parent→LHC))
        return (from→Parent);
    // No RHC, not Root, not an LHC of Parent.
    // Climb tree until parent is LHC of Gparent. Return Gparent (14→15). Note: Currnode is from's parent
    while (currnode == currnode→Parent→RHC) { // Keep climbing
        if (!(currNode = currnode→Parent)) // Keep climbing. If new parent is Root, we are done
            break; }
    return (currNode→Parent); } // Return first Gparent with LHS or Root (where all descent was RHC)
```



# Homework 3: Get Previous Node

## Deliverables:

1. **List of** “Find Previous Node” Tree Walking rules
2. **Code for:** `Node* BST::getPrevious (Node* from)`



## Finding the “Preceding” node (if exists):

`Node* getPrevious (Node* from) { // Returns previous node or Null (if lowest value)  
// Null should be returned only for Node 6 in example`

Node 15 → 14

Node 20 → 15