PRACTICE CHAPTER 4

1. Simulating Robots Using ROS and Gazebo

sudo apt-get install ros-noetic-gazebo-ros-pkgs ros-noeticgazebo-msgs ros-noetic-gazebo-plugins ros-noetic-gazebo-roscontrol

Entah kenapa selalu tidak bisa menemukan lokasinya saat input command yang mengharuskan akses lokasi file

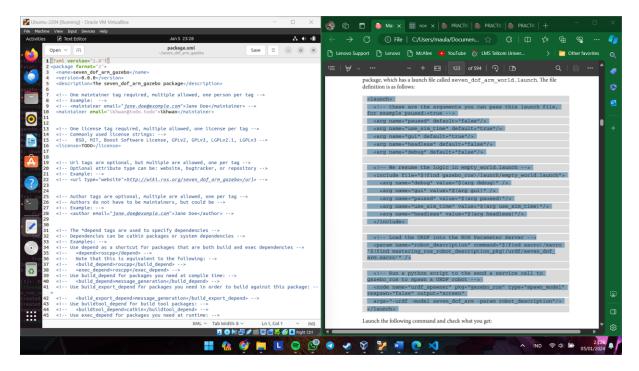
roscore & rosrun gazebo ros gazebo

2. Creating the robotic arm simulation model for Gazebo

```
catkin_create_pkg seven_dof_arm_gazebo gazebo_msgs gazebo_
plugins gazebo_ros gazebo_ros_control mastering_ros_robot_
description_pkg
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Launch the following command and check what you get:

roslaunch seven dof arm gazebo seven dof arm world.launch

