MUHAMMAD IKHWAN MAULANA

1103203219

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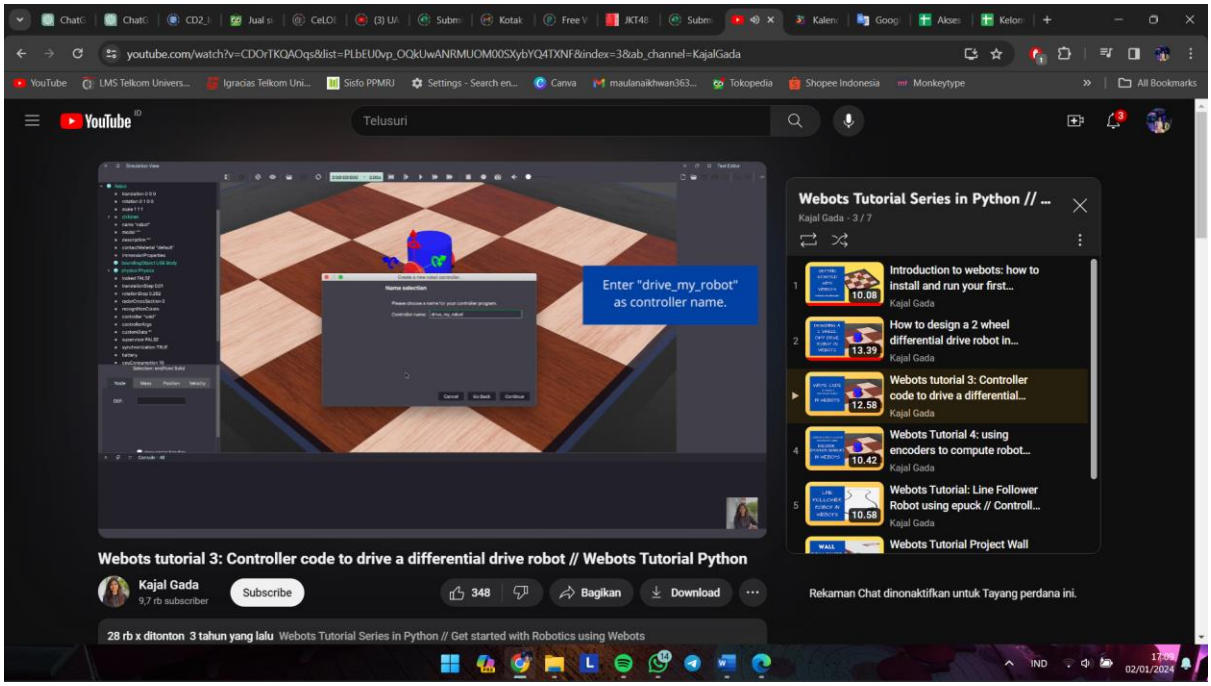
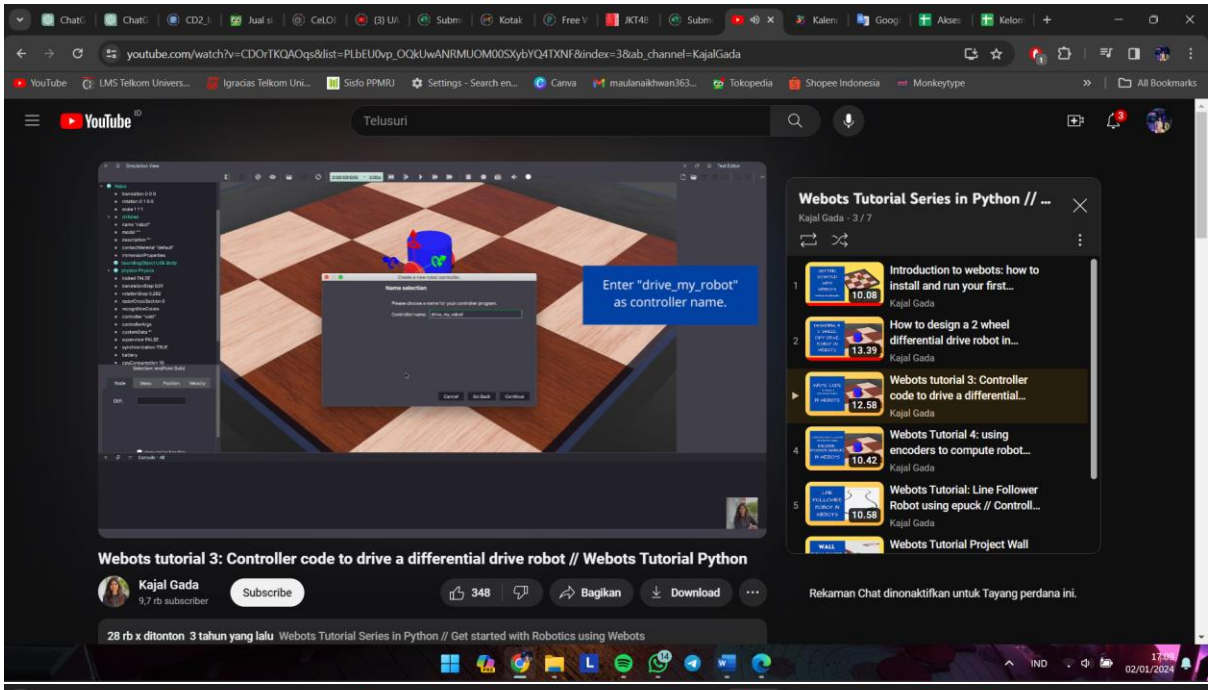
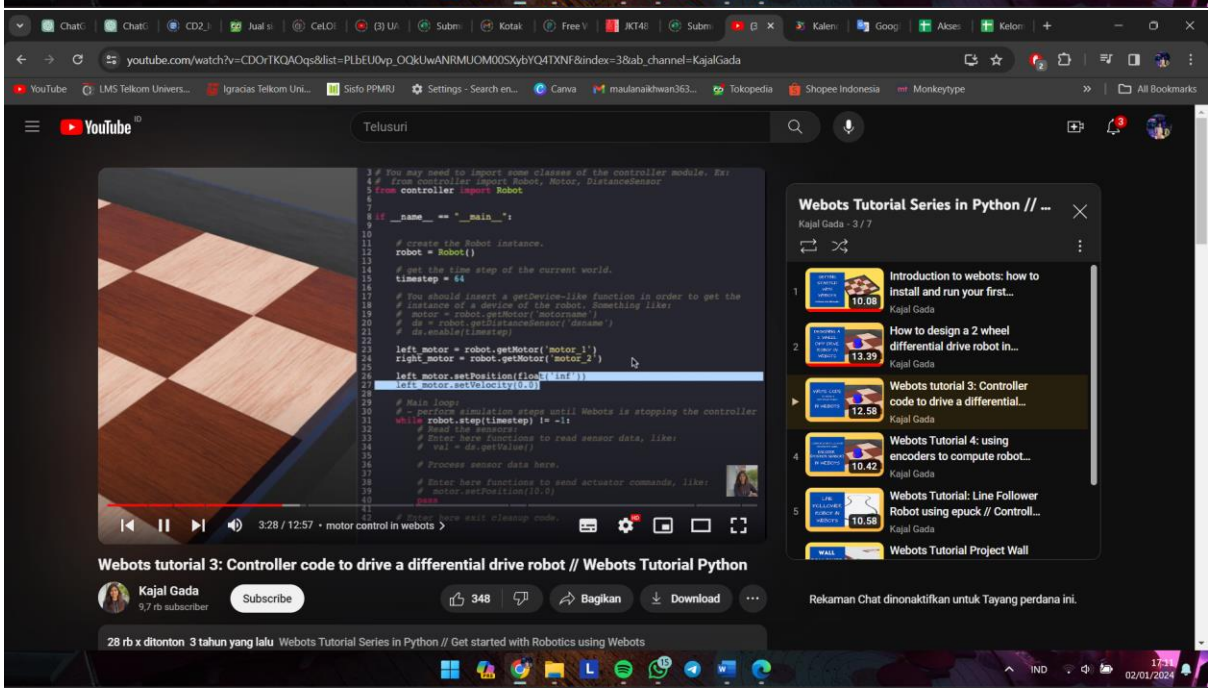
Webots tutorial 3: Controller code to drive a differential drive robot // Webots Tutorial Python

1. Setelah projek yang sudah dibuat sebelumnya, sekarang menambahkan kontroler pada robot.

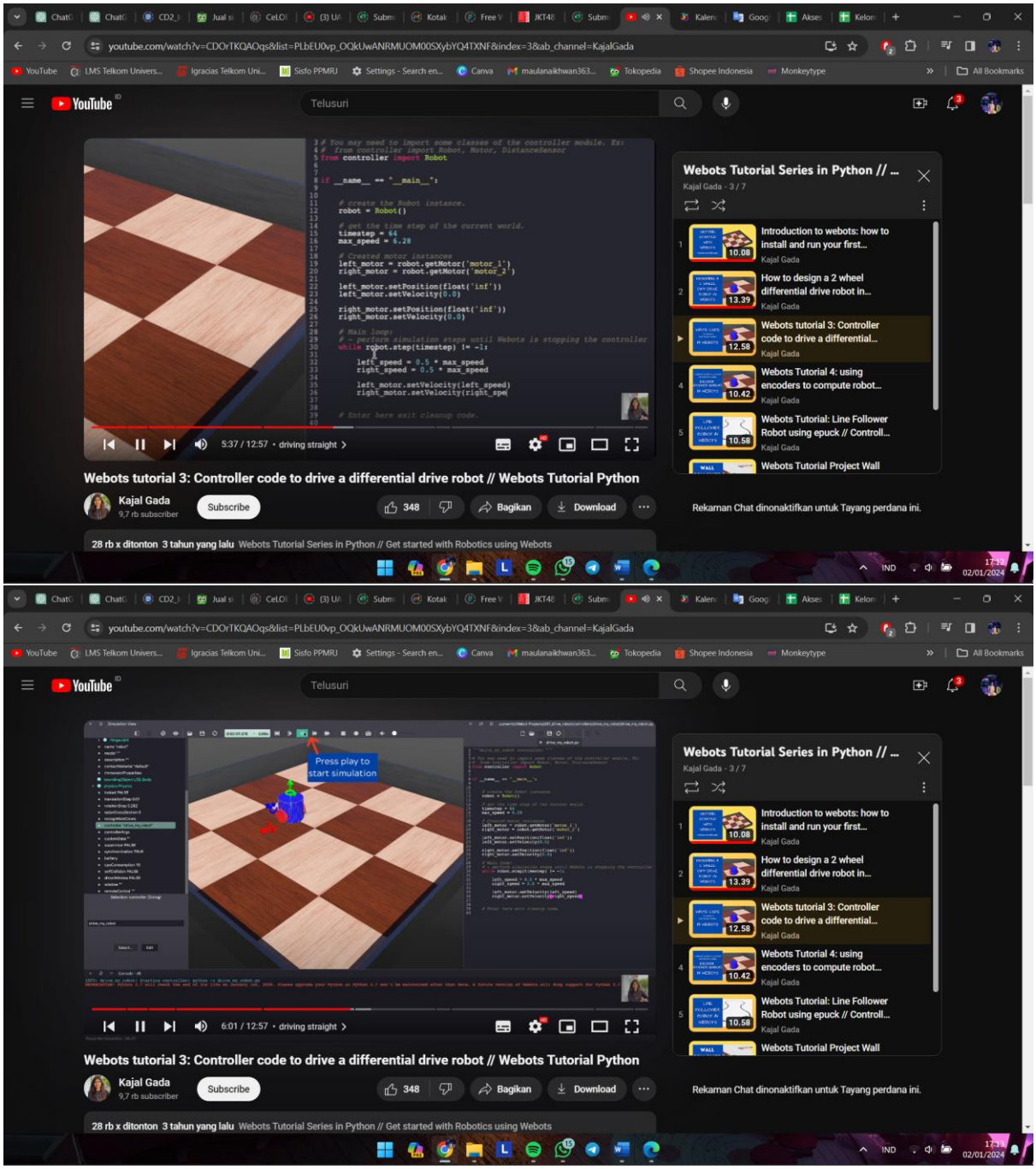


2. Kontroler yang ditambahkan bisa di kode menggunakan bahasa python sesuai kebutuhan.

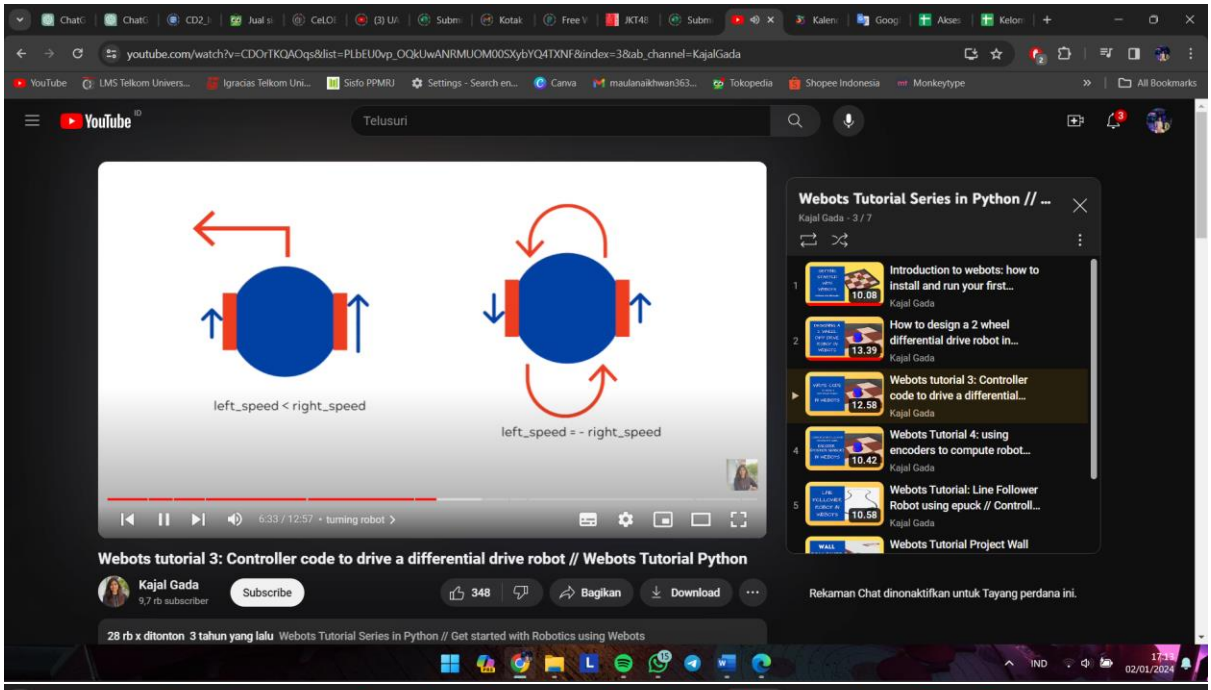




3. Setelah itu, kita coba mengontrol robot agar berjalan lurus.



4. Robot bisa digerakkan sesuai kehendak kita, entah itu kecepatan dan arahnya.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left_speed < right_speed
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6:33 / 12:57 • turning robot >
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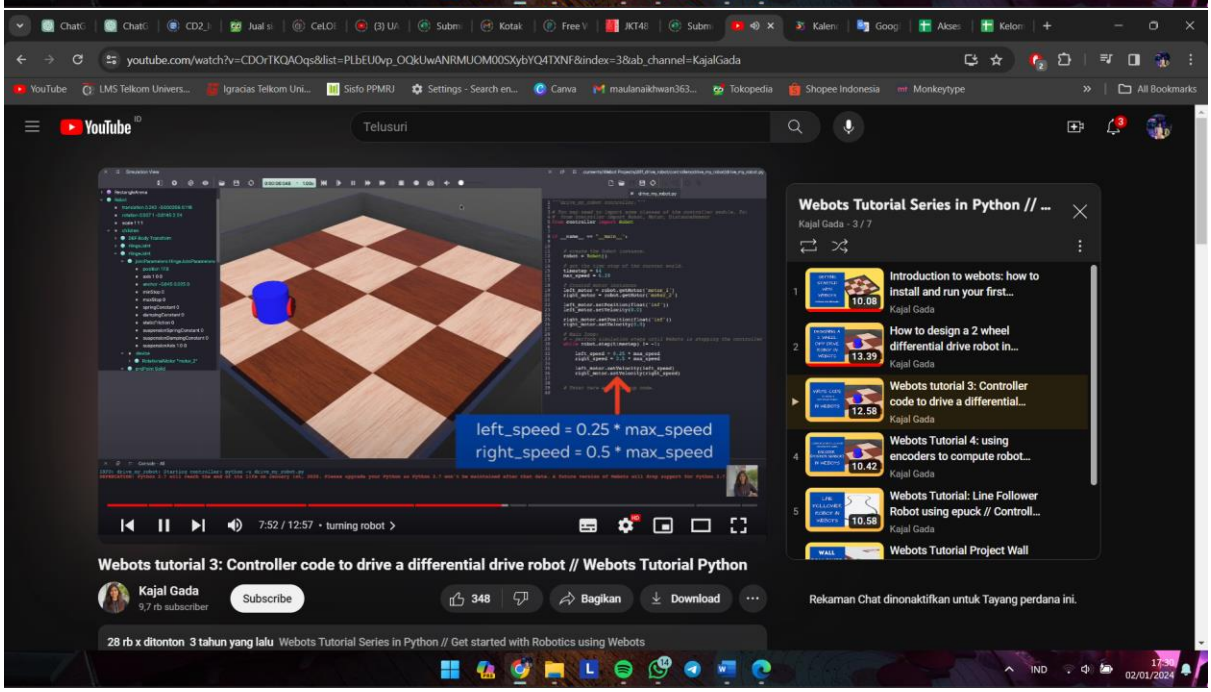
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left_speed = 0.25 * max_speed
right_speed = 0.5 * max_speed
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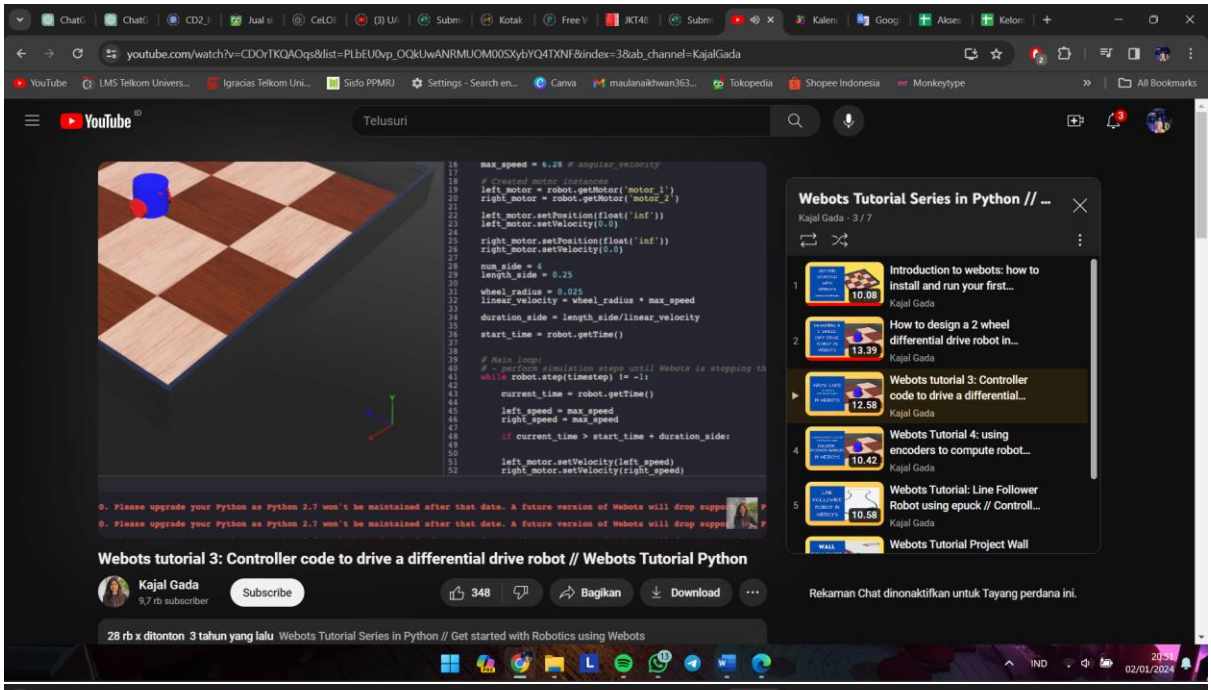
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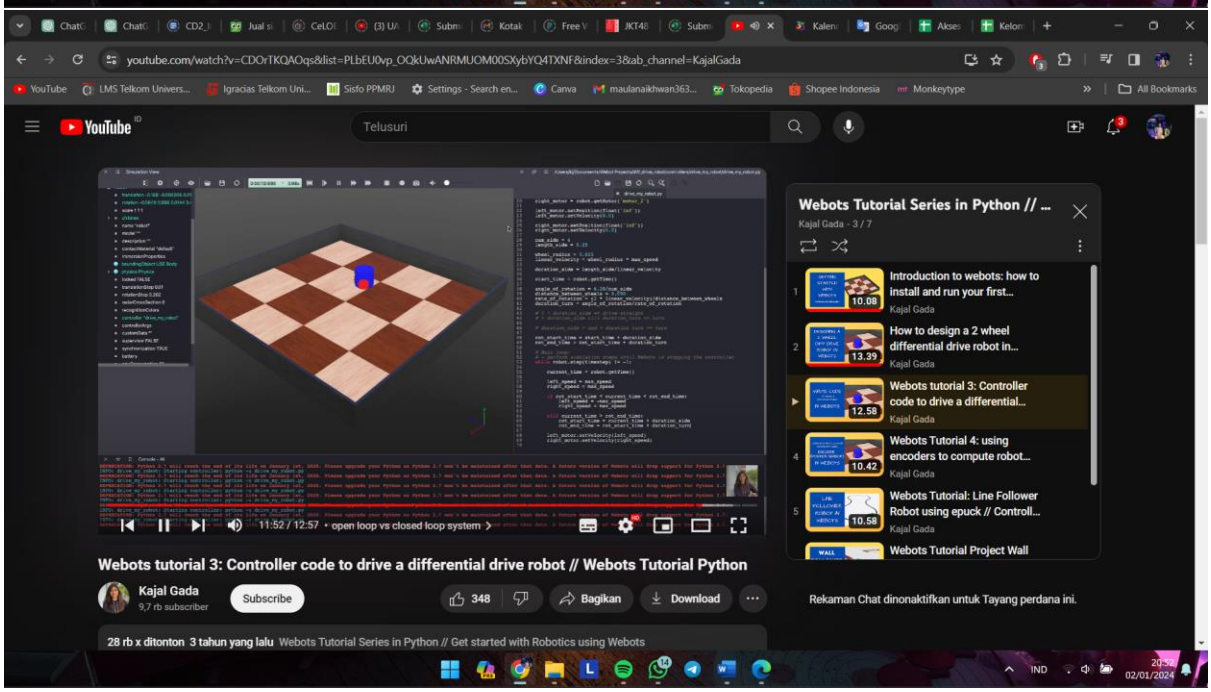
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