PRACTICE CHAPTER 5

1. Setting up CoppeliaSim with ROS

```
tar vxf CoppeliaSim_Edu_V4_2_0_Ubuntu20_04.tar.xz

mv CoppeliaSim_Edu_V4_2_0_Ubuntu20_04 CoppeliaSim

echo "export COPPELIASIM_ROOT=/path/to/CoppeliaSim/folder >>
~/.bashrc"
```

```
Indubuntu-2204:-$ roslaunch seven_dof_arm_gazebo seven_dof_arm_world.launch

Toack (most recent call last):

"/usr/bin/roslaunch", line 34, in <module>

import roslaunch

"/usr/lib/python3/dist-packages/roslaunch/_init__.py", line 62, in <module>

on .scriptapi import ROSLaunch

"/usr/lib/python3/dist-packages/roslaunch/scriptapi.py", line 42, in <module>

import roslaunch.parent

File "/usr/lib/python3/dist-packages/roslaunch/parent.py", line 54, in <module>

import roslaunch.server

File "/usr/lib/python3/dist-packages/roslaunch/server.py", line 80, in <module>

from rosgraph_msgs.msg import Log

ImportError: cannot import name 'Log' from 'rosgraph_msgs.msg' (/opt/ros/humble/local/lib/python3.10/dist-packages/rosgraph_msgs/msg/__init__.py)

ikhwangibuntu-2204:~$ tar vxf CoppeliaSim_Edu_V4_2_0_ubuntu20_03.tar.xz

tar: CoppeliaSim_Edu_V4_2_0_ubuntu20_03.tar.xz: Cannot open: No such file or directory

tar: Fror is not recoverable: exiting now
```

Terjadi error

2. Simulating a robotic arm using CoppeliaSim and ROS

```
rosrun xacro seven_dof_arm.xacro > /path/to/csim_demo_pkg/
urdf/seven_dof_arm.urdf
```

```
ikbwsn@Jbuntu-2204:-$ rosrun xacro seven_dof_arm.xacro > /path/to/csim_demo_pkg/urdf/seven_dof_arm.urdf
basis /path/to/csim_demo_pkg/urdf/seven_dof_arm.urdf: No such file or directory
```

File dan directori tidak ada