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PRACTICE CHAPTER 6

1. The MoveIt! Architecture

```
sudo apt-get install ros-noetic-moveit ros-noetic-moveit-
plugins ros-noetic-moveit-planners
```


Tidak dapat menemukan lokasi paket

2. Generating a MoveIt! configuration package using the Setup Assistant tool

Step 1 – Launching the Setup Assistant tool

To start the MoveIt! Setup Assistant tool, we can use the following command:

```
roslaunch moveit_setup_assistant setup_assistant.launch
```


Error ketika menginputkan command