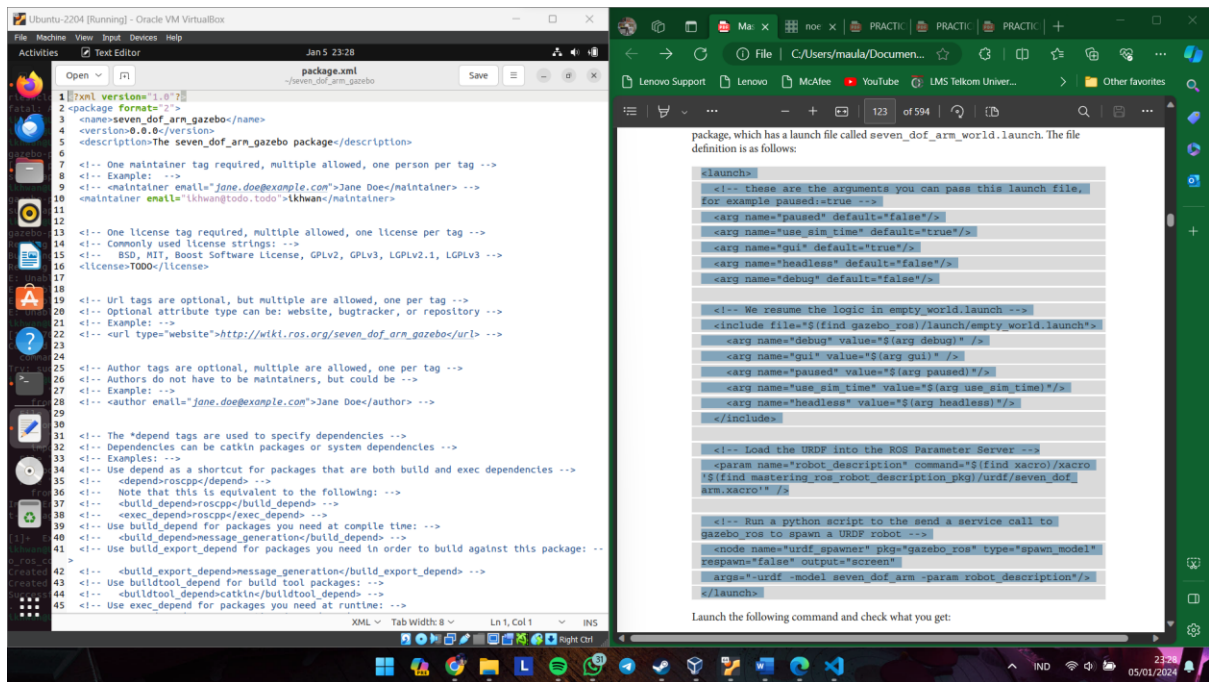


1103203219

1. Simulating Robots Using ROS and Gazebo

```
[1]+  Exit 1                  roscore
tkhwan@ubuntu-2204:~$ catkin_create_pkg seven_dof_arm_gazebo gazebo_msgs gazebo_plugins gazebo_ros gazebo
_ros_control mastering_ros_robot_description pkg
Created file seven_dof_arm_gazebo/package.xml
Created file seven_dof_arm_gazebo/CMakeLists.txt
Successfully created files in /home/tkhwan/seven_dof_arm_gazebo. Please adjust the values in package.xml
```



Launch the following command and check what you get:

```
roslaunch seven_dof_arm_gazebo seven_dof_arm_world.launch
```

