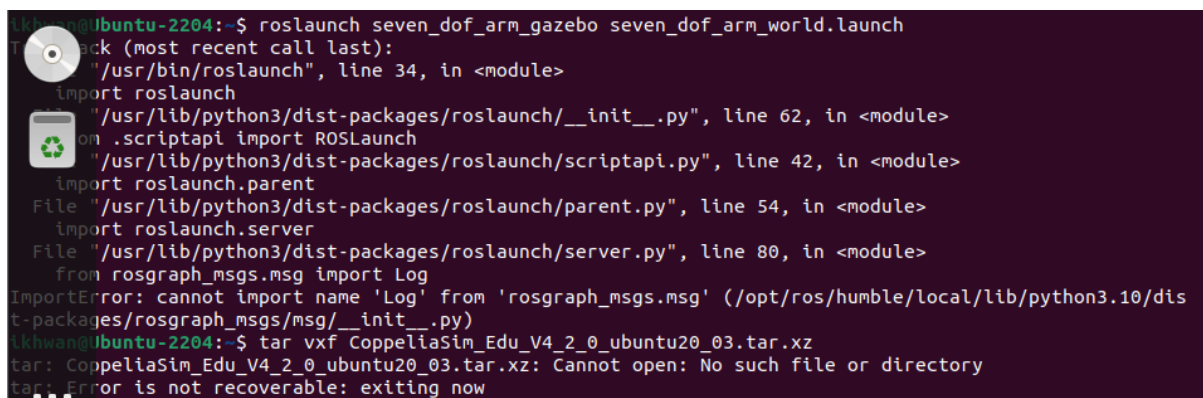MUHAMMAD IKHWAN MAULANA

1103203219

PRACTICE CHAPTER 5

1. Setting up CoppeliaSim with ROS

```
tar vxf CoppeliaSim_Edu_V4_2_0_Ubuntu20_04.tar.xz
```

```
mv CoppeliaSim_Edu_V4_2_0_Ubuntu20_04 CoppeliaSim
```

```
echo "export COPPELIASIM_ROOT=/path/to/CoppeliaSim/folder >>
~/.bashrc"
```
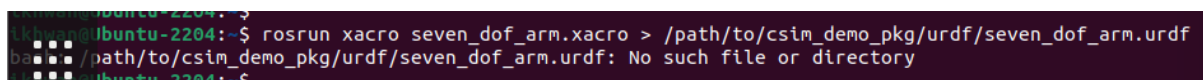

Terjadi error

2. Simulating a robotic arm using CoppeliaSim and ROS

```
rosrun xacro seven_dof_arm.xacro >  /path/to/csim_demo_pkg/
urdf/seven_dof_arm.urdf
```


File dan directori tidak ada