

Math 205 Exam 2 Answer key

1. Let A be the matrix

$$A = \begin{bmatrix} 1 & 2 & 0 & 3 & 4 \\ 3 & 6 & 1 & 10 & 14 \\ 7 & 14 & 2 & 23 & 33 \end{bmatrix}$$

A has reduced row-echelon form

$$R = \begin{bmatrix} 1 & 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

- (a) Find a basis for the nullspace of A .
- (b) Find a basis for the column space of A .

Solution:

Part (a)

The reduced row-echelon form corresponds to the following homogeneous linear system

$$\begin{aligned} x_1 + 2x_2 + 3x_4 &= 0 \\ x_3 + x_4 &= 0 \\ x_5 &= 0 \end{aligned}$$

The variables x_2 and x_4 are free variables and the solution set is

$$S = \left\{ \begin{bmatrix} -2x_2 - 3x_4 \\ x_2 \\ -x_4 \\ x_4 \\ 0 \end{bmatrix} \mid x_2, x_4 \in \mathbb{R} \right\}.$$

This yields a basis for the nullspace:

$$\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} \right\}$$

Part (a)

A basis for the column space is given by those columns of A which correspond to the columns with leading ones in a row echelon form (in this case the first, the third and the fifth):

$$\left\{ \begin{bmatrix} 1 \\ 3 \\ 7 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 14 \\ 33 \end{bmatrix} \right\}$$

Note that the column space of a reduced row-echelon form of A is in general different from the column space of A , which means that the columns need to be chosen in A !

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- (2) Let V be a 2-dimensional vector space with basis $\mathcal{B} = \{v_1, v_2\}$. Let $T : V \rightarrow V$ be a linear transformation with

$$T(v_1) = 3v_1 + 2v_2,$$

$$T(v_2) = 5v_1 - 4v_2.$$

- (a) (4 points) Find $T(2v_1 + v_2)$.

$$\begin{aligned} T(2v_1 + v_2) &= 2T(v_1) + T(v_2) \\ &= 2(3v_1 + 2v_2) + (5v_1 - 4v_2) \\ &= 11v_1 \end{aligned}$$

- (b) (4 points) Find $[T]_{\mathcal{B}}$, the matrix of T in the basis \mathcal{B} .

$$\begin{aligned} [T]_{\mathcal{B}} &= \left[[T(v_1)]_{\mathcal{B}} \mid [T(v_2)]_{\mathcal{B}} \right] \\ &= \left[[3v_1 + 2v_2]_{\mathcal{B}} \mid [5v_1 - 4v_2]_{\mathcal{B}} \right] \\ &= \begin{bmatrix} 3 & 5 \\ 2 & -4 \end{bmatrix}. \end{aligned}$$

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(3) Let

$$B = \left\{ \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 7 \\ 14 \end{bmatrix} \right\}.$$

We know that $W = \text{Span}(B)$ is a subspace of \mathbb{R}^3 , and then B is a basis of W .

Let

$$u_1 = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \quad \text{and} \quad u_2 = \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}.$$

(a) (4 points) Is u_1 in W ? If so, find the coordinate vector $[u_1]_B$.

$$u_1 \in W \Leftrightarrow u_1 = c_1 \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} + c_2 \begin{bmatrix} 3 \\ 7 \\ 14 \end{bmatrix}, \text{ and if this is so, } [u_1]_B = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

This gives the system with augmented matrix

$$\left[\begin{array}{cc|c} 1 & 3 & 2 \\ 2 & 7 & 3 \\ 4 & 14 & 4 \end{array} \right]$$

which reduces to $\left[\begin{array}{cc|c} 1 & 3 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & -2 \end{array} \right]$ which is inconsistent. Answer: No, $u_1 \notin W$.(b) (4 points) Is u_2 in W ? If so, find the coordinate vector $[u_2]_B$.We can see by inspection that $u_2 = v_1$ so $u_2 \in W$ and $[u_2]_B = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

If we don't notice that:

$$u_2 \in W \Leftrightarrow u_2 = c_1 \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} + c_2 \begin{bmatrix} 3 \\ 7 \\ 14 \end{bmatrix}, \text{ and if this is so, } [u_2]_B = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

This gives the system with augmented matrix

$$\left[\begin{array}{cc|c} 1 & 3 & 1 \\ 2 & 7 & 2 \\ 4 & 14 & 4 \end{array} \right]$$

which reduces to $\left[\begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$ with solution $\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, so Yes, $u_2 \in W$
and $[u_2]_B = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

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(4) Let

$$B = \left\{ \begin{bmatrix} 2 \\ 7 \end{bmatrix}, \begin{bmatrix} 3 \\ 10 \end{bmatrix} \right\} \Rightarrow P_{E \leftarrow B} = \begin{pmatrix} 2 & 3 \\ 7 & 10 \end{pmatrix}$$

B is a basis of \mathbb{R}^2 .

(a) (4 points) If $[w]_B = \begin{bmatrix} 5 \\ 6 \end{bmatrix}$, find w .

where $E = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$ is the standard basis for \mathbb{R}^2 .

$$[w]_E = P_{E \leftarrow B} [w]_B = \begin{pmatrix} 2 & 3 \\ 7 & 10 \end{pmatrix} \begin{pmatrix} 5 \\ 6 \end{pmatrix} = \begin{pmatrix} 28 \\ 95 \end{pmatrix}$$

$$\boxed{\text{Alternatively, } 5 \begin{pmatrix} 2 \\ 7 \end{pmatrix} + 6 \begin{pmatrix} 3 \\ 10 \end{pmatrix} = \begin{pmatrix} 28 \\ 95 \end{pmatrix}}$$

(b) (4 points) If $v = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, find $[v]_B$.

$$[v]_B = P_{B \leftarrow E} [v]_E = (P_{E \leftarrow B})^{-1} [v]_E = \begin{pmatrix} 2 & 3 \\ 7 & 10 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} -10 & 3 \\ 7 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} -4 \\ 3 \end{pmatrix}$$

$$\boxed{\text{Alternatively, } \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \alpha \begin{pmatrix} 2 \\ 7 \end{pmatrix} + \beta \begin{pmatrix} 3 \\ 10 \end{pmatrix} \Rightarrow \alpha = -4, \beta = 3}$$

(c) (8 points) Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear transformation $T(x) = Ax$, where A is the matrix

$$A = \begin{bmatrix} 11 & 13 \\ 17 & 19 \end{bmatrix}.$$

Find $[T]_B$. (You may leave your answer expressed as a product of matrices and their inverses.)

$$[T]_B = P_{B \leftarrow E} [T]_E P_{E \leftarrow B} = \begin{pmatrix} 2 & 3 \\ 7 & 10 \end{pmatrix}^{-1} \begin{pmatrix} 11 & 13 \\ 17 & 19 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ 7 & 10 \end{pmatrix}$$

Problem 5

A has the characteristic polynomial $-(\lambda - 1)(\lambda - 2)(\lambda - 4)$, so the eigenvalues are $\lambda_1 = 1$, $\lambda_2 = 2$ and $\lambda_3 = 4$.

- For $\lambda_1 = 1$, we solve $(A - \lambda_1 I)\mathbf{v} = \mathbf{0}$.

$$\begin{aligned} A - \lambda_1 I &= \begin{bmatrix} 2 & 0 & 2 \\ 1 & 2 & 1 \\ 0 & 1 & 0 \end{bmatrix} \xrightarrow{P_{12}} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 0 & 2 \\ 0 & 1 & 0 \end{bmatrix} \xrightarrow{A_{12}(-2)} \begin{bmatrix} 1 & 2 & 1 \\ 0 & -4 & 0 \\ 0 & 1 & 0 \end{bmatrix} \\ &\xrightarrow{P_{23}} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 0 \\ 0 & -4 & 0 \end{bmatrix} \xrightarrow{A_{23}(4)} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}. \end{aligned}$$

Hence, $v_3 = t$ is a free variable, we may obtain $v_2 = 0$ and $v_1 = -t$. Hence,

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

Therefore, the eigenspace E_1 is spanned by $\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$.

- For $\lambda_2 = 2$, we solve $(A - \lambda_2 I)\mathbf{v} = \mathbf{0}$.

$$A - \lambda_2 I = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \xrightarrow{A_{12}(-1)} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 0 & 1 & -1 \end{bmatrix} \xrightarrow{A_{23}(-1)} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}.$$

Hence, $v_3 = s$ is a free variable, we may obtain $v_2 = s$ and $v_1 = -2s$. Hence,

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = s \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}.$$

Therefore, the eigenspace E_2 is spanned by $\begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$.

- For $\lambda_3 = 4$, we solve $(A - \lambda_3 I)\mathbf{v} = \mathbf{0}$.

$$\begin{aligned} A - \lambda_3 I &= \begin{bmatrix} -1 & 0 & 2 \\ 1 & -1 & 1 \\ 0 & 1 & -3 \end{bmatrix} \xrightarrow{M_1(-1)} \begin{bmatrix} 1 & 0 & -2 \\ 1 & -1 & 1 \\ 0 & 1 & -3 \end{bmatrix} \xrightarrow{A_{12}(-1)} \begin{bmatrix} 1 & 0 & -2 \\ 0 & -1 & 3 \\ 0 & 1 & -3 \end{bmatrix} \\ &\xrightarrow{M_2(-1)} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 1 & -3 \end{bmatrix} \xrightarrow{A_{23}(-1)} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{bmatrix}. \end{aligned}$$

Hence, $v_3 = r$ is a free variable, we may obtain $v_2 = 3r$ and $v_1 = 2r$.
Hence,

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = r \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}.$$

Therefore, the eigenspace E_3 is spanned by $\begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}$.

In summary, letting

$$P = \begin{bmatrix} -1 & -2 & 2 \\ 0 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix},$$

we have $P^{-1}AP = D$.

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(6) (36 points) Solve each of the following differential equations/initial value problems:

(a) $y'''' + 2y''' - 5y'' - 6y' = 0$.

(In operator notation, this is the differential equation $(D^4 + 2D^3 - 5D^2 - 6D)y = 0$. Note that $D^4 + 2D^3 - 5D^2 - 6D = D(D+1)(D-2)(D+3)$.)

The auxiliary equation is
 $\lambda(\lambda+1)(\lambda-2)(\lambda+3)=0$.

The solutions are

$$\lambda=0, \quad \lambda=-1, \quad \lambda=2, \quad \lambda=-3$$

Therefore, the solution is

$$y = C_1 + C_2 e^{-x} + C_3 e^{2x} + C_4 e^{-3x}$$

where C_1, C_2, C_3, C_4 are constants.

(b) $y'''' - 13y''' + 60y'' - 122y' + 64y = 0$.

(In operator notation, this is the differential equation $(D^4 - 13D^3 + 60D^2 - 112D + 64)y = 0$.

Note that $D^4 - 13D^3 + 60D^2 - 112D + 64 = (D-1)(D-4)^3$.)

The auxiliary equation is
 $(\lambda-1)(\lambda-4)^3=0$.

The solutions are $\lambda=1, \lambda=4$.

Therefore, the solution of the differential equation is

$$y = C_1 e^x + C_2 e^{4x} + C_3 x e^{4x} + C_4 x^2 e^{4x}$$

where C_1, C_2, C_3, C_4 are real constants.

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(c) $y'' - 4y' + 29y = 0$.

(In operator notation, this is the differential equation $(D^2 - 4D + 29)y = 0$.)

The auxiliary equation is

$$\lambda^2 - 4\lambda + 29 = (\lambda - 2)^2 + 5^2 = 0.$$

The solutions are $\lambda = 2 \pm 5i$.

Therefore, the solution is

$$y = C_1 e^{2x} \cos(5x) + C_2 e^{2x} \sin(5x),$$

where C_1 and C_2 are real constants.

(d) $y'' - 4y' + 3y = 0$, $y(0) = 3$, $y'(0) = 7$.

(In operator notation, this is the differential equation $(D^2 - 4D + 3)y = 0$. Note that $(D^2 - 4D + 3) = (D - 1)(D - 3)$.)

It is very easy to find the solution

$$y = C_1 e^x + C_2 e^{3x} \quad \text{Let us}$$

compute the derivative. We have

$$y' = C_1 e^x + 3C_2 e^{3x} \quad \text{Now let}$$

us use the initial conditions.

$$3 = y(0) = C_1 + C_2$$

$$7 = y'(0) = C_1 + 3C_2$$

So $C_1 = 1$ $C_2 = 2$ Therefore,

$$y = e^x + 2e^{3x}$$

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(e) $y'' + 4y' + 3y = 60e^{2x}$.

(In operator notation, this is the differential equation $(D^2 + 4D + 3)y = 60e^{2x}$. Note that $(D^2 + 4D + 3) = (D + 1)(D + 3)$.)

The complementary solution is

$$y_c(x) = C_1 e^{-x} + C_2 e^{-3x}$$

Suppose that $y_p(x) = Ae^{2x}$ is a particular solution. Then

$$y_p'' + 4y_p' + 3y_p = 15Ae^{2x} = 60e^{2x}$$

So $A = 4$. Therefore, the general solution is

$$y(x) = C_1 e^{-x} + C_2 e^{-3x} + 4e^{2x}$$

(f) $y'' - 4y = 12e^{2x}$.

(In operator notation, this is the differential equation $(D^2 - 4)y = 12e^{2x}$. Note that $(D^2 - 4) = (D - 2)(D + 2)$.)

The complementary solution is

$$y_c(x) = C_1 e^{2x} + C_2 e^{-2x}$$

Suppose that $y_p(x) = Axe^{2x}$ is a particular solution. Then

$$y_p''(x) = 4Axe^{2x} + 4Ae^{2x}$$

$$y_p''(x) - 4y_p = 4Ae^{2x} = 12e^{2x}$$

So $A = 3$. Therefore,

$$y(x) = C_1 e^{2x} + C_2 e^{-2x} + 3xe^{2x}$$