

# **CSE-315 Microprocessor**

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# 1 Chapter-9 : 8086/8088 specification

- virtually no differences between these two microprocessors. Both are packaged in 40-pin dual in-line package.
- **8086**:16 bit microprocessor with a 16bit data bus(A0-A15)  
**8088**:16 bit microprocessor with a 8bit data bus(A0-A7)  
major difference between 8086 and 8088.
- Minor differences  
**8086**: $M/\overline{IO}$ ; **8088**: $IO/\overline{M}$   
PIN34:-**8086**: $\overline{BHE}$ /S7; **8088**:SS0
- power supply requirements:  
+5v with a supply voltage tolerance of  $\pm 10\%$   
both 32F to 180F  
8086 and 8088 have 340 and 360 mA.

**figures in the book**

## 1.1 Pin Connection

- **AD7-AD0**:
  - 8088 address/data bus lines
  - multiplexed address data bus
  - rightmost 8 bits of the memory address or I/O port whenever  $ALE=1$  or  $ALE=0$
  - high impedance state during hold acknowledge.

- **A15-A8:**
  - 8088 address bus
  - high impedance state during hold acknowledge.
- **AD15-AD8:**
  - 8086 address/data bus lines.
  - contains address bits when ALE=1
  - high impedance state during hold acknowledge.
- **A19/S6-A16/S3:**
  - multiplexed address/data bus lines
  - high impedance state during hold acknowledge.
- **S6:** always 0
- **S5:** indicated the condition of **IF** flag

S4	S3	indicate segment accessed during current bus cycle
0	0	extra segment
0	1	stack segment
1	0	code or no segment
1	1	data segment

- $\overline{RD}$  : if it is 0 then the data bus becomes receptive to data from memory or i/o devices connected to the system.
- high impedance state during hold acknowledge.
- **READY:**

- enters into wait state and remains idle if 0
- no effect on operations of microprocessor if this pin is in logic state 1.
- **INTR:**
  - used to request a h/w interrupt.
  - if INTR=1 when IF=1 then microprocessor enters an interrupt acknowledge cycle after completion of current instruction
- **NMI:**
  - non maskable interrupt pin.
  - similar to INTR except do not check IF flag.
- **$\overline{\text{TEST}}$  :**
  - an input that is tested by **wait** instruction. -if it is 0, the **WAIT** functions as **NOP**.
  - if 1 then **WAIT** waits for  **$\overline{\text{TEST}}$**  to become logic 0.

## 2 Chapter-9 : 8086/8088 specification

- **NMI:**
  - non-maskable interrupt pin
  - similar to INTR except that NMI does not check IF flag.
- **RESET:**
  - causes the microprocessor to reset if this pin remains high for a minimum of 4 clocking periods.
  - whenever the microprocessor gets reset, it begins executing instructions at memory location FFFF0H and disables future interrupts by clearing IF.
- **CLK:**
  - provides the base timing signal to the microprocessor.
  - clock signal must have at least 33% duty cycle(high for  $\frac{1}{3}$  rd and low for  $\frac{2}{3}$  of the period)
- **VCC**
  - power supply input
  - provides +5V
- **GND:-** 2 pins, both must be connected to ground.
- **MN/ $\overline{MX}$** :-selects either minimum mode or maximum mode operations of microprocessor.
- **$\overline{BHE}$ /**S7****-both high enable. -use in 8086 to enable the most significant data bus bits(D15-D8) during a read or write

-the state of S7 is always a logic1

## 2.1 Minimum Mode Pins

–  $\text{IO}/\overline{\text{M}}$  or  $\text{M}/\overline{\text{IO}}$

-selects memory or i/o -indicates that microprocessors address bus contains either a memory address or an i/o port address.  
-high impedance state during a hold acknowledge.

–  $\overline{\text{WR}}$ :

-indicates that microprocessor is outputting data to a memory or io device.  
-data bus contains valid data for memory or io during the time,  $\overline{\text{WR}}$  remains 0.

–  $\overline{\text{INTA}}$ :

-a response to the INTR input pin.  
-used to gate the interrupt vector number onto the data bus in response to an interrupt request.

–  $\overline{\text{ALE}}$ :

-address latch enable.  
-indicates that the microprocessor address/data bus contains address information.  
-the address can be a memory address or an i/o port.  
-does not float during a hold acknowledge.

–  $\text{DT}/\overline{\text{R}}$ : - data transmit or receive.

-indicates that microprocessors data bus is transmitting( $\text{DT}/\overline{\text{R}}=1$ )

or receiving( $DT/\overline{R}=(DT/\overline{R}=0)$ ) data.

-used to enable external data bus buffers.

– **DEN**:-data bus enable

-activates external data bus buffers.

– **HOLD**: - requests a direct memory access (DMA).

-if it is logic 1, microprocessor stops executing s/w and places its address, data and control bus at high impedance state.

-if it is a logic 0, the microprocessor executes s/w normally.

– **HLDA**: - hold acknowledge

-indicates that the microprocessor has entered the hold state.

–  $\overline{SS0}$  - equivalent to the S0 pin in the maximum mode operation.

-it is combined with  $IO/\overline{M}$  and  $DT/\overline{R}$  to decode function of the current bus cycle.

$IO/\overline{M}$	$DT/\overline{R}$	$\overline{SS0}$	function
0	0	0	interrupt acknowledge
0	0	1	memory card
0	1	1	memory write
0	1	1	halt
1	0	0	opcode fetch
1	0	1	I/O read
1	1	0	I/O write
1	1	1	passive/inactive

Table 1: bus cycle status(8088)[minimum mode]



$\overline{IS2}$	$\overline{S1}$	$\overline{S0}$	<b>function</b>
0	0	0	interrupt acknowledge
0	0	1	I/O card
0	1	1	I/O write
0	1	1	halt
1	0	0	opcode fetch
1	0	1	memory read
1	1	0	memory write
1	1	1	passive

Table 2: bus control functions generated by the bus controller 8088[maximum mode]

### 3 8086/8088 hardware specifications

**Maximum Mode Pins:** for using with external co-processors

- $\overline{S2}, \overline{S1}, \overline{S0}$  - indicate the function of current bus cycle.  
-normally decoded 8288 bus controller.
- $\overline{R1}/\overline{GT1}$  and  $\overline{R0}/\overline{GT0}$  - request/grant pins  
-requests direct memory access(DMA)  
-used to both request and grant DMA operation.
- $\overline{LOCK}$  - used to lock peripheral off the system.
- **OS1 and OS2** - queue status bit.  
-show status of the internal instruction queue.  
-accessed by numeric co-processor(8087)

QS1	QSA	Function
0	0	queue is idle
0	1	first byte of opcode
1	0	queue is empty
1	1	subsequent byte of opcode

### 3.1 clock generator-8284A

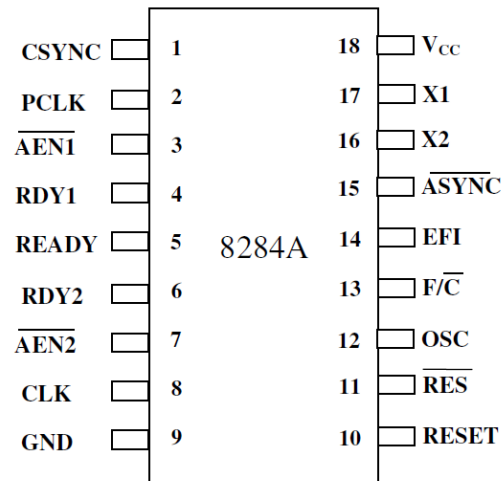


Fig1. Pin diagram of the 8284A clock generator

Figure 1: 8284A clock generator

- **Basic functions:**

- clock generation
- RESET synchronization
- READY synchronization
- TTL-level peripheral clk signals

- **pin functions**

- **AEN1 and AEN2 (address enable)** - qualify the bus ready signals RDY1 and RDY2 respectively.
- wait states are generated by the READY pin of microprocessor, which is controlled by  $\overline{AEN1}$  and  $\overline{AEN2}$

- **RDY1 and RDY2** - Bus ready inputs.
  - cause wait states in conjunction with  $\overline{AEN1}$  and  $\overline{AEN2}$  pins.
- **$\overline{ASync}$**  : - READY synchronization.
  - selects either one or two stages of synchronization for RDY1 and RDY2 inputs.
- **READY** - an output pin that connects to microprocessors READY input.
  - synchronized with RDY1 and RDY2 inputs.
- **X1 and X2:** - crystal oscillator pins.
  - connect to an external crystal which is used as the timing source for the clock generator and all its functions.
- **F/ $\overline{C}$**  - Frequency/crystal select input.
  - chooses the clocking source.
  - if it is held high, an external clock is provided to the EFI pin.
  - if it is held low, the internal crystal oscillator provides the timing signal.
- **EFI:** - External Frequency Input.
  - supplies timing whenever F/ $\overline{C}$  is held high.
- **CLK:** - clock output pin, which provides clock input to microprocessor and other components.
  - output signal is  $\frac{1}{3}$  of crystal or EFI input freq. and has a duty cycle of 33%(as required by 8086/8088).

- **PCLK:** - peripheral clock.
  - $\frac{1}{6}$  of the crystal or EFI input freq. and has a 50% duty cycle.
- **OSC:** - oscillator output.
  - at same freq. as the crystal or EFI input.
  - provides an EFI input to other 8284A in a multi-processor system.
- **$\overline{\text{RES}}$ :** - reset input.
  - often connected to an RC network that provides power on resetting.
- **RESET:** - reset output.
  - connected to microprocessors RESET input pin.
- **CSYNC:** - clock synchronization.
  - used whenever the EFI input provides synchronization in a multi-processor system.
  - if the internal oscillator is used, this pin must be grounded.

## 4 Chapter-9 : 8086/8088 specification

### 4.1 internal block diagram of 8284A clock generator

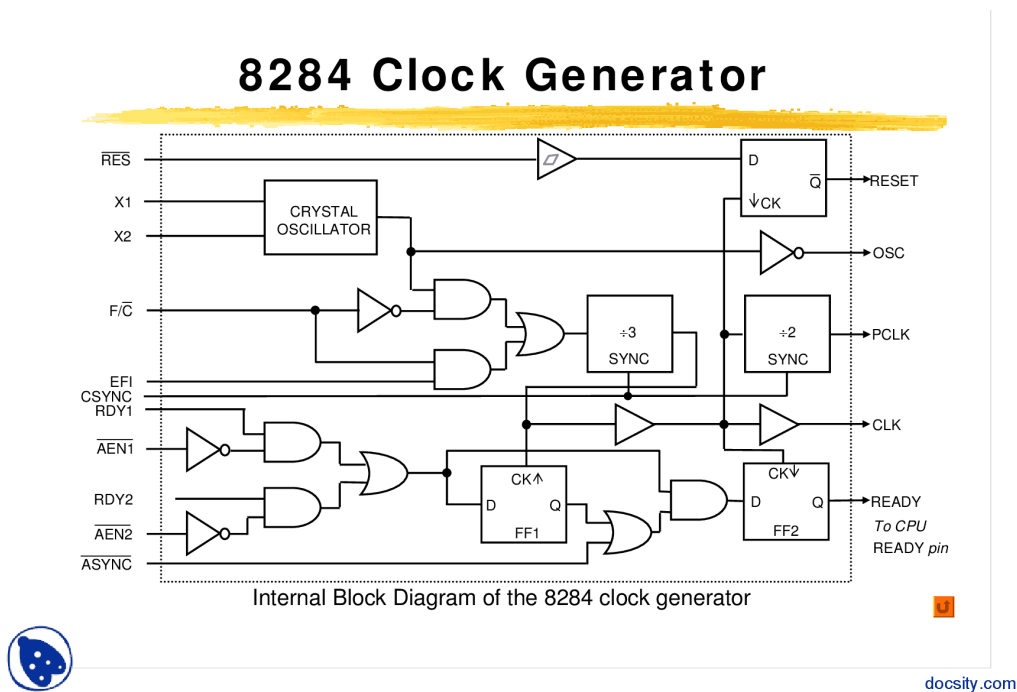


Figure 2: internal block diagram of 8284A clock generator

- if a crystal is attached to X1 and X2, the oscillator generates a square wave signal at the same frequency of the crystal.

- $CLK = \frac{frequency}{3}$ ;  $PCLK = \frac{frequency}{6}$

## 4.2 operation of the RESET section

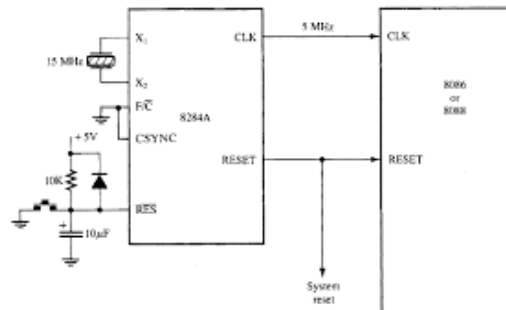


Figure 3: RESET operation of 8284A clock generator

- $\overline{\text{RES}}$  goes through a **Schmitt Trigger** and a **D-type** flip-flop, which ensures meeting timing requirements of microprocessors RESET input.
- the circuit applies RESET to microprocessor at a negative edge(1- $\rightarrow$ 0) and the microprocessor samples the RESET the signal at the positive edge(0- $\rightarrow$ 1).
- when power is first applied to the system, the RC circuit provides a logic 0 to  $\overline{\text{RES}}$
- after a short time  $\overline{\text{RES}}$  becomes logic 1, as the capacitor charges to +5v through the resistor.
- a push button allows the microprocessor to be reset by an operator.
- correct RESET timing requires the RESET input to become a logic 1 no later than 4 clock cycles after the power is applied, and held high for at least 50 micro-seconds.

- RESET goes high in 4 clock by FF. RESET stays high for 50 microseconds by RC.

### 4.3 Bus buffering and latching

- the address/data bus on the microprocessor is multiplexed(shared) to reduce the # of pins, which, on the other hand, burdens with the task of extracting or de-multiplexing info from these pins.
- Why not leave the buses multiplexed??  
memory and i/o require that the address remains valid and stable throughout a read or write cycle. If the buses are multiplexed , the address can get changed causing read or write in wrong locations.
- All computer systems have 3 types of buses:
  1. Address bus: provides memory address or i/o port of #s
  2. Data bus: transfers data between microprocessor and memory and i/o.
  3. control bus: provides control signals to memory and i/o.