

EXAMPLE

Calibrated by: Auto-Calibrated on Thu Oct 22 06:59:31 2015

Calibration Equation: $\lambda \text{ (nm)} = C_0 + C_1 \cdot p + C_2 \cdot p^2 + C_3 \cdot p^3$

Where 'p' is pixel index, and:

Coefficient **C0** = 8.03432E+02

Coefficient **C1** = 1.42142E-01

Coefficient **C2** = -5.63408E-06

Coefficient **C3** = -8.94574E-09

Calibration Equation: $\lambda \text{ (nm)} = C_0 + C_1 \cdot p + C_2 \cdot p^2 + C_3 \cdot p^3$

Where 'p' is pixel index, and:

Coefficient **C0** = 8.03432E+02

Coefficient **C1** = 1.42142E-01

Coefficient **C2** = -5.63408E-06

Coefficient **C3** = -8.94574E-09

EXAMPLE

Calibrated by: Auto-Calibrated on Thu Oct 22 06:59:31 2015

Calibration Equation: $y(mm) = C_0 + C_1 \cdot x + C_2 \cdot x^2 + C_3 \cdot x^3$

Where 'x' is pixel index, and:

Coefficient $C_0 = 8.03435E+05$

Coefficient $C_1 = 1.45145E-01$

Coefficient $C_2 = -5.63408E-06$

Coefficient $C_3 = -8.94524E-09$

EXAMPLE

Calibrated by: Auto-Calibrated on Thu Oct 22 06:29:31 2015

Calibrated by: Auto-Calibrated on Thu Oct 22 06:59:31 2015

EXAMPLE

Coefficient C0 = 8.03432E+02
Coefficient C1 = 1.42142E-01
Coefficient C2 = -5.63408E-06
Coefficient C3 = -8.94574E-09

Where 'p' is pixel index, and:

Calibration Equation: $\lambda (nm) = C_0 + C_1 \cdot p + C_2 \cdot p^2 + C_3 \cdot p^3$

Calibrated by: Auto-Calibrated on Thu Oct 22 06:59:31 2015





to-Calibrated on Thu Oct 22 06:11



3. d. 82 -



to-Calibrated on Thu Oct 22 01

EXAMPLE

Calibrated by: Auto-Calibrated on Thu Oct 22 06:59:31 2015

Calibration Equation: $\lambda \text{ (nm)} = C_0 + C_1 \cdot p + C_2 \cdot p^2 + C_3 \cdot p^3$

Where 'p' is pixel index, and:

Coefficient **C0** = 8.03432E+02

Coefficient **C1** = 1.42142E-01

Coefficient **C2** = -5.63408E-06

Coefficient **C3** = -8.94574E-09