

The tail of the one-row colored $sl(3)$ Jones polynomial

and the Andrews - Gordon type identity

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RIMS, Kyoto Univ.
Wataru YUASA

§1 Quick Introduction to Quantum Invariants of Knots and Links

① Diagrammatic definition of knots & links

an ℓ -component link diagram D

\Leftrightarrow $D : \coprod S^1 \longrightarrow \mathbb{R}^2$, an generic
immersion

with over/under information

on intersection points.

i.e. intersection points



Reidemeister moves



the set of ℓ -component links

$:= \{ \ell\text{-component link diagrams} \}$

\backslash
(Ω1)

(Ω2)

(Ω3)

+ isotopy

i.e. $[D] = [D']$

D and D' are related by
a finite sequence of (Ω1), (Ω2), (Ω3)
+ isotopy

Oriented links

- link diagram + orientation on the image of S'
- equivalence : orientation preserving (Ω_1) (Ω_2) (Ω_3) moves

framed links

- equivalence : (Ω_0) (Ω_2) (Ω_3) moves



② Quantum invariants

of knots and links

a (k, l) -tangle diagram

\Leftrightarrow a generic immersion of arcs & loops
 $\underset{\text{def}}{\Leftrightarrow}$ a generic immersion of arcs & loops
 into $\mathbb{R} \times [0, 1]$

- s.t. • intersection point = \times
- $\partial\{\text{arcs}\} = \{(1, 0), (2, 0), \dots, (k, 0)\}$
 $\cup \{(1, 1), (2, 1), \dots, (l, 1)\}$



(5, 3)-tangle diagram

the set of framed (k, l) -tangles

$\coloneqq \{ (k, l)\text{-tangle diagram} \} / \begin{matrix} (\Omega_0), (\Omega_2), \\ (\Omega_3), \text{isotopy} \end{matrix}$

Fix a strict ribbon category \mathcal{C}

braiding $C_{V,W}: V \otimes W \rightarrow W \otimes V$

duality $\begin{cases} *: V \rightarrow V^* \\ b_V: 1 \rightarrow V \otimes V^* \\ d_V: V^* \otimes V \rightarrow 1 \end{cases}$

twist $\theta_V: V \rightarrow V$, isom.

a category of \mathcal{C} -colored framed tangles $\mathcal{T}_{\mathcal{C}}$

\Leftrightarrow $\text{Obj } \mathcal{T}_{\mathcal{C}}$: a finite sequence of $\text{Obj } \mathcal{C} \times \{+, -\}$
 $\circlearrowleft \emptyset$: the empty sequence.

$$\text{Obj } \mathcal{T}_{\mathcal{C}} \ni \eta_i = ((V_1, \varepsilon_1), (V_2, \varepsilon_2), \dots, (V_k, \varepsilon_k))$$

$$\eta_2 = ((W_1, \delta_1), (W_2, \delta_2), \dots, (W_\ell, \delta_\ell))$$

$\text{Mor}(\eta_1, \eta_2)$: an oriented framed (k, l) -tangle

s.t. • each component is colored by $\text{Obj } \mathcal{C}$

• $\begin{array}{c} (i, 1) \\ \downarrow \\ V_i \end{array}$ if $\varepsilon_i = +$, $\begin{array}{c} (i, 1) \\ \uparrow \\ V_i \end{array}$ if $\varepsilon_i = -$

$\begin{array}{c} W_i \\ \downarrow \\ \uparrow \end{array}$ if $\delta_i = +$, $\begin{array}{c} W_i \\ \uparrow \\ \downarrow \end{array}$ if $\delta_i = -$

Fix a strict ribbon category \mathcal{C}

braiding	$C_{V,W} : V \otimes W \rightarrow W \otimes V$
duality	$\begin{cases} * : V \rightarrow V^* \\ b_V : 1 \rightarrow V \otimes V^* \\ d_V : V^* \otimes V \rightarrow 1 \end{cases}$
twist	$\theta_V : V \rightarrow V$, isom.

- Composition

$$T_1 \circ T_2 := \boxed{\begin{array}{c} T_1 \\ \hline \dashdot \\ T_2 \end{array}}$$

- tensor product

$$T_1 \otimes T_2 := \boxed{\begin{array}{c|c} T_1 & T_2 \end{array}}$$

a category of \mathcal{C} -colored framed tangles $\mathcal{T}_{\mathcal{C}}$

- $\text{Obj } \mathcal{T}_{\mathcal{C}}$: a finite sequence of $\text{Obj } \mathcal{C} \times \{+, -\}$

\emptyset : the empty sequence.

$$\text{Obj } \mathcal{T}_{\mathcal{C}} \ni \eta_1 = ((V_1, \varepsilon_1), (V_2, \varepsilon_2), \dots, (V_k, \varepsilon_k))$$

$$\eta_2 = ((W_1, \delta_1), (W_2, \delta_2), \dots, (W_\ell, \delta_\ell))$$

- $\text{Mor}(\eta_1, \eta_2)$: an oriented framed (k, ℓ) -tangle

s.t. • each component is colored by $\text{Obj } \mathcal{C}$

$$\bullet \quad \begin{array}{c} (i, +) \\ \downarrow \\ \text{---} \\ \textcolor{blue}{V_i} \end{array} \quad \text{if } \varepsilon_i = +, \quad \begin{array}{c} (i, -) \\ \uparrow \\ \text{---} \\ \textcolor{blue}{V_i} \end{array} \quad \text{if } \varepsilon_i = -$$

$$\begin{array}{c} \textcolor{blue}{W_j} \\ \uparrow \\ \text{---} \\ \textcolor{blue}{W_j} \end{array} \quad \text{if } \delta_j = +, \quad \begin{array}{c} \textcolor{blue}{W_j} \\ \downarrow \\ \text{---} \\ \textcolor{blue}{W_j} \end{array} \quad \text{if } \delta_j = -$$

Theorem[Reshetikhin-Turaev, 1990]

$\exists! F_{\mathcal{C}} : \mathcal{T}_{\mathcal{C}} \rightarrow \mathcal{C}$, a \otimes -preserving functor

$$\text{s.t. } F((V, +)) = V, \quad F((V, -)) = V^*$$

$$\begin{array}{c} w \\ \nearrow \\ v \end{array} = C_{V,W} \quad \begin{array}{c} w \\ \nearrow \\ v \end{array} = C_{W,V}^{-1} \quad \begin{array}{c} w \\ \nearrow \\ v \end{array} = C_{W,V^*}^{-1} \quad \begin{array}{c} w \\ \nearrow \\ v \end{array} = C_{V^*,W}$$

$$\begin{array}{c} w \\ \nearrow \\ v \end{array} = C_{W^*,V}^{-1} \quad \begin{array}{c} w \\ \nearrow \\ v \end{array} = C_{V,W^*} \quad \begin{array}{c} w \\ \nearrow \\ v \end{array} = C_{V^*,W^*} \quad \begin{array}{c} w \\ \nearrow \\ v \end{array} = C_{W^*,V^*}^{-1}$$

$$\begin{array}{c} v \\ \downarrow \\ \textcolor{blue}{v} \end{array} = \text{id}_V \quad \begin{array}{c} v \\ \uparrow \\ \textcolor{blue}{v} \end{array} = \text{id}_{V^*} \quad \begin{array}{c} v \\ \downarrow \\ \textcolor{blue}{\theta} \end{array} = \theta_V \quad \begin{array}{c} v \\ \uparrow \\ \textcolor{blue}{\theta} \end{array} = \theta_V^{-1}$$

$$\begin{array}{c} v \\ \nearrow \\ \textcolor{blue}{w} \end{array} = d_V \quad \begin{array}{c} v \\ \nearrow \\ \textcolor{blue}{w} \end{array} = b_V \quad \left(\begin{array}{c} v \\ \nearrow \\ \textcolor{blue}{w} \end{array} = \begin{array}{c} v \\ \nearrow \\ \textcolor{blue}{w} \end{array}, \quad \begin{array}{c} v \\ \nearrow \\ \textcolor{blue}{w} \end{array} = \begin{array}{c} v \\ \nearrow \\ \textcolor{blue}{w} \end{array} \right)$$

Theorem[Reshetikhin-Turaev, 1990]

$\exists! F_e: \mathcal{T}_e \rightarrow \mathcal{C}$, a \otimes -preserving functor

s.t. $F((v,+)) = V, F((v,-)) = V^*$

$$\begin{array}{c} w \\ \nearrow v \\ \curvearrowright \end{array} = c_{v,w} \quad \begin{array}{c} w \\ \swarrow v \\ \curvearrowleft \end{array} = c_{w,v}^{-1} \quad \begin{array}{c} w \\ \nearrow v \\ \curvearrowleft \end{array} = c_{w,v^*}^{-1} \quad \begin{array}{c} w \\ \swarrow v \\ \curvearrowright \end{array} = c_{v^*,w}$$

$$\begin{array}{c} w \\ \swarrow v \\ \curvearrowleft \end{array} = c_{w,v}^{-1} \quad \begin{array}{c} w \\ \nearrow v \\ \curvearrowright \end{array} = c_{v,w^*} \quad \begin{array}{c} w \\ \nearrow v \\ \curvearrowleft \end{array} = c_{v,w^*} \quad \begin{array}{c} w \\ \swarrow v \\ \curvearrowright \end{array} = c_{w^*,v^*}^{-1}$$

$$v \downarrow = \text{id}_V \quad v \uparrow = \text{id}_{V^*} \quad v \downarrow \rho = \theta_V \quad v \uparrow \rho = \theta_V^{-1}$$

$$\begin{array}{c} v \\ \curvearrowright \\ \curvearrowleft \end{array} = d_V \quad \begin{array}{c} v \\ \curvearrowleft \\ \curvearrowright \end{array} = b_V$$

$\rightsquigarrow L$: an \mathcal{C} -colored framed link.

$\Rightarrow F_e(L) \in \text{End}(\mathbb{1})$

e.g (the quantum of invariant of framed links, the colored of Jones polynomial)

\mathfrak{g} : a simple Lie algebra

$\text{Rep}_f U_q(\mathfrak{g})$: the category of finite dimensional representations of the quantum group $U_q(\mathfrak{g})$. ($q = q^2$: a formal variable)

$L = L_1 \sqcup L_2 \sqcup \dots \sqcup L_e$: a framed link

$V_i \in \text{Rep}_f U_q(\mathfrak{g})$ is a coloring of L_i

the $(\mathfrak{g}, (V_1, \dots, V_e))$ -colored Jones polynomial

$J_L^{\mathfrak{g}}(V_1, V_2, \dots, V_e) \in \mathbb{C}(q^{\frac{1}{20}})$ is defined by

$$F_e(L)(1) = J_L^{\mathfrak{g}}(V_1, V_2, \dots, V_e) \cdot 1$$

($\because D$ is determined by \mathfrak{g})



§ 2 Stability of the Colored Jones Polynomial

① Properties of the CJP

Theorem [Lê, 2000] (Integrality)

$$J_L^g(V_{\lambda_1}, V_{\lambda_2}, \dots, V_{\lambda_k}) \in g^{\frac{p}{2}} \mathbb{Z}[g^{\pm 1}]$$

Theorem [Garoufalidis-Lê, 2005]

For a knot K ,

$\{J_K^g(\lambda)\}_\lambda$ is g -holonomic (except G_2)

$\{f_n(g) \in \mathbb{Z}((g))\}_n$ is g -holonomic

if $\exists d \in \mathbb{N}$, $\exists \alpha_\ell \in \mathbb{Z}[u, v]$ ($0 \leq \ell \leq d$)

s.t. $\sum_{\ell=0}^d \alpha_\ell(g, g^n) f_{n+\ell}(g) = 0$
 $(\forall n \geq 0)$

e.g. $K = \text{figure-eight knot}$ $\rightarrow (n+1)$ -dim. irrep.

$$J_K^{al_2}(n) = \frac{g^{-\frac{n-1}{2}}}{1-g^{-1}} \sum_{k=0}^{n-1} (1-g^{-n})(1-g^{1-n}) \cdots (1-g^{k-n})$$

then,

$$J_K^{al_2}(n-1) = \frac{g^{n-1} + g^{4-4n} - g^{-n} - g^{1-2n}}{g^{\frac{1}{2}}(g^{n-1} - g^{2-n})} J_K^{al_2}(n)$$

$$+ \frac{g^{4-4n} - g^{3-2n}}{g^{2-n} - g^{n-1}} J_K^{al_2}(n+1)$$

- \mathfrak{g} - holonomic

$$\rightsquigarrow \delta_k(n) := \max \deg_{\mathfrak{g}} (J_k^{\mathfrak{gl}_2}(n))$$

$$\delta_k^*(n) := \min \deg_{\mathfrak{g}} (J_k^{\mathfrak{sl}_2}(n))$$

are quadratic quasi-polynomials

$$\text{i.e. } \delta_k^*(n) = a_k^*(n)n^2 + b_k^*(n)n + c_k^*(n)$$

$$\text{s.t. } a_k(n), b_k(n), c_k(n)$$

are periodic functions
for $n \gg 0$

\rightsquigarrow (strong) slope conjecture

$$``\{a_k(n)\} \cup \{a_k^*(n)\}"$$

$$\subset \{ \text{slopes of } \partial\Sigma \text{ s.t. } \Sigma \subset S^3 \setminus K \}$$

$$``\{b_k(n)\} \cup \{b_k^*(n)\}" \subset \{ X(\Sigma) / |\partial\Sigma| \}$$

Notation

- For $\underline{\lambda} = (\lambda_1, \lambda_2, \dots, \lambda_e)$

$$J_{L,\underline{\lambda}}^{\mathfrak{g}}(\mathfrak{g}) := J_L^{\mathfrak{g}}(V_{\lambda_1}, V_{\lambda_2}, \dots, V_{\lambda_e})$$

$$\delta_L^*(\underline{\lambda}) := \min \deg J_{L,\underline{\lambda}}^{\mathfrak{g}}(\mathfrak{g})$$

$$\hat{J}_{L,\underline{\lambda}}^{\mathfrak{g}}(\mathfrak{g}) := \pm g^{-\delta_L^*(\underline{\lambda})} J_{L,\underline{\lambda}}^{\mathfrak{g}}(\mathfrak{g}) \in \mathbb{Z}[\mathfrak{g}]$$

$$= \underbrace{a_0}_{\checkmark 0} + a_1 \mathfrak{g} + a_2 \mathfrak{g}^2 + \dots$$

② Stability for $\{\hat{J}_{L,n}^{sl_2}(q)\}_n$

conjectured by Dasbach - Lin
 & proved by { Armond
 Garoufalidis - Lê }

e.g. $K = \text{Diagram}$

- table of the coefficients of $\hat{J}_{K,n}^{sl_2}(q)$ for $n=2, 3, 4$

$q^0 q^1 q^2 \dots$

$n=2$	1 -1 -1 0 2 0 -2 0 3 0 -3 0 3 0 -3 0 ...
$n=3$	1 -1 -1 0 0 3 -1 -1 -1 5 -1 -2 -2 -1 6 ...
$n=4$	1 -1 -1 0 0 1 2 0 -2 -1 -1 3 1 -2 -3 ...

• 0-stability (the tail of K)

$$n=2 \quad 1 -1 -1 0 2 0 -2 0 3 0 -3 0 3 0 -3 0 \dots$$

$$n=3 \quad 1 -1 -1 0 0 3 -1 -1 -1 5 -1 -2 -2 -1 6 \dots$$

$$n=4 \quad 1 -1 -1 0 0 1 2 0 -2 -1 -1 3 1 -2 -3 \dots$$

$\downarrow \lim$

$$\Phi_0 \quad 1 -1 -1 0 0 1 0 1 0 0 0 0 -1 0 0 -1 \dots$$

tail of $\{\hat{J}_{K,n}^{sl_2}(q)\}_n$

• 1-stability

$$n=2 \quad 0 0 2 -1 -2 -1 3 0 -3 0 4 0 -3 1 \dots$$

$$n=3 \quad 0 0 2 -1 -2 -1 -1 5 -1 -5 -2 -1 7 \dots$$

$$n=4 \quad 0 0 2 -1 -2 -1 -1 1 4 1 -2 -2$$

$$\Phi_1 \quad 0 0 2 -1 -2 -1 -1 1 \dots$$

Theorem[Armond, 2013]

L : an A - adequate link.

then, $\exists \mathcal{J}_L^{al_2}(g) \in \mathbb{Z}[[g]]$ s.t

$$\hat{\mathcal{J}}_{L,n}^{al_2}(g) - \mathcal{J}_L^{al_2}(g) \in g^{n+1} \mathbb{Z}[[g]]$$

tail of $\{\hat{\mathcal{J}}_{k,n}^{al_2}(g)\}$

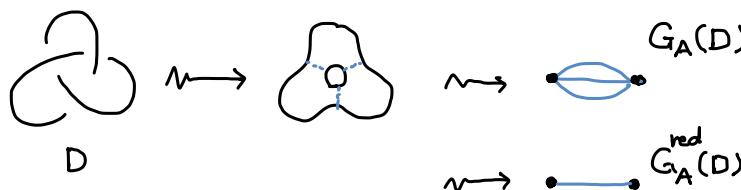
Theorem[Armond-Dasbach, 2016]

L : an A - adequate link

D : an A-adequate link diagram of L

then, $\mathcal{J}_L^{al_2}(g)$ only depends on $G_A^{\text{red}}(D)$

e.g.



Theorem[Garoufalidis-Lê, 2015]

L : an alternating link.

then $\{\hat{\mathcal{J}}_{L,n}^{al_2}(g)\}$ is k-stable ($\forall k \geq 0$)

- $\{f_n(g) \in \mathbb{Z}[[g]]\}_n$ is k-stable

if $\exists \Phi_0(g), \dots, \exists \Phi_k(g) \in \mathbb{Z}((g))$

$$\text{s.t. } \lim_{n \rightarrow \infty} g^{-kn(n+1)} (f_n(g) - \sum_{j=0}^k \Phi_j(g) g^{j(n+1)}) = 0$$

- $\lim_{n \rightarrow \infty} f_n(g) = \Phi(g)$

$\overset{\text{def}}{\iff} \forall m \in \mathbb{N}, \exists N_m \in \mathbb{N}$

$$\text{s.t. } f_{N_m}(g) - \Phi(g) \in g^m \mathbb{Z}[[g]]$$

Theorem [Garoufalidis-Vuong, 2017]

K : a torus knot

\mathfrak{g} : a rank 2 simple Lie algebra.

then, $\{J_{k,n,\lambda}^{\mathfrak{g}}(\mathfrak{g})\}_n$ is k -stable ($\forall k$)

$$\text{sl}_3 \quad \lambda = (s, t) \quad s, t \in \mathbb{Z}_{\geq 0}$$

$$\{(ns, nt)\}$$

$$\{(n, o)\}_n$$

Theorem [Y.]

L : a "minus-adequate" oriented link.

$$\exists J_L^{\text{sl}_3}(\mathfrak{g}) \in \mathbb{Z}[[\mathfrak{g}]] \quad \text{s.t.}$$

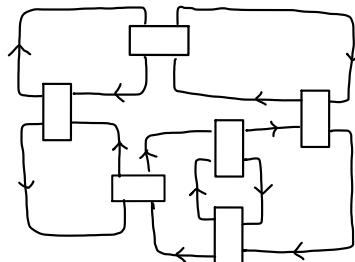
$$\hat{J}_{L,(n,o)}^{\text{sl}_3}(\mathfrak{g}) - J_L^{\text{sl}_3}(\mathfrak{g}) \in \mathfrak{g}^{n+1} \mathbb{Z}[[\mathfrak{g}]]$$

i.e. $\{J_{L,(n,o)}^{\text{sl}_3}(\mathfrak{g})\}$ is zero stable

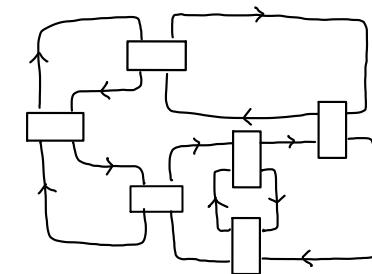
e.g. (minus-adequate)

- Consider an adequate 4-valent graph with oriented edges

s.t. vertex =  or  or 



adequate

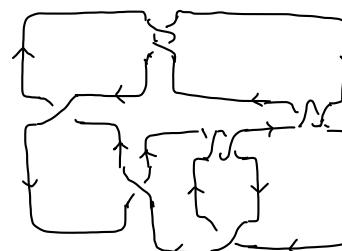


inadequate

- Replace

$$\begin{array}{ccc} \text{---} & \longrightarrow & \text{---} \\ | & & | \\ \vdots & & \vdots \\ | & & | \end{array} \quad \left. \begin{array}{l} p \text{ crossings} \\ (p \in \mathbb{Z}_{\geq 1}) \end{array} \right\}$$

e.g.



§ 3 Tails and Andrews - Gordon Type Identities

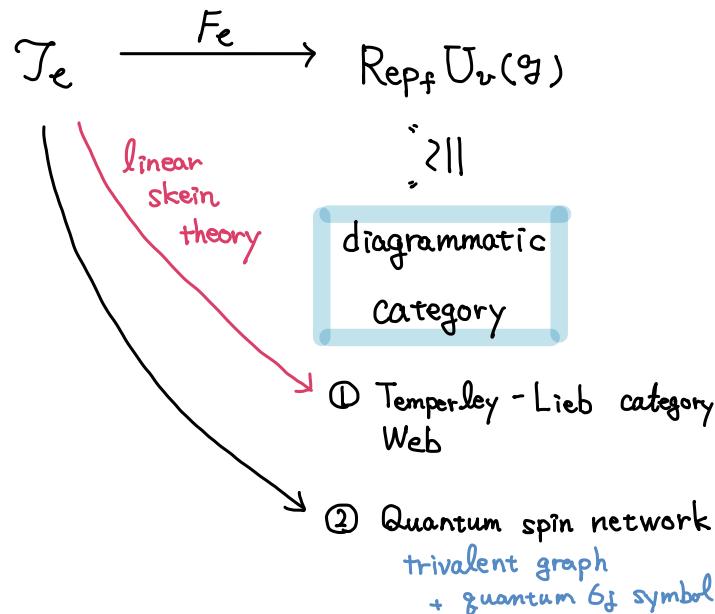
① Graphical Calculus

Problem

Compute the colored Jones polynomial
and its tail.

$$\mathcal{L} = \text{Rep}_f U_q(\mathfrak{g})$$

$T_e = \mathcal{L}$ -colored framed tangles



"Linear skein theory"

= a functor from T_e to
a diagrammatic representation
of $\text{FunRep}_f U_q(\mathfrak{g})$
or
 $\text{Kar}(\text{FunRep}_f U_q(\mathfrak{g}))$

the Kauffman bracket ($\mathfrak{g} = sl_2$)

(Notation) $| = |^1 = \downarrow_{V_2 \cong V_2^*}$
the 2-dim.
irreducible rep.

$$| ^n = \underbrace{| \dots |}_n = |_{V_2 \otimes \dots \otimes V_2}$$

the Kauffman bracket ($\mathcal{G} = \text{sl}_2$)

$$\times = q^{\frac{1}{4}}) (+ q^{-\frac{1}{4}} \cup$$

$$\circ = -[2] \emptyset = (q^{\frac{1}{2}} + q^{-\frac{1}{2}}) \emptyset$$

• construction of the color $|_{V_{n+1}}$

= the Jones - Wenzl projector $\boxed{}^n$

i.e. $\boxed{}^n = \boxed{}^{n-1} : V_2^{\otimes n} \rightarrow \text{Sym}^n V_2 \hookrightarrow V_2^{\otimes n}$

Diagrammatic definition

$$\boxed{}^n = \boxed{}^{n-1} | + \frac{[n-1]}{[n]} \begin{array}{c} \boxed{}^{n-1} \\ \downarrow \\ \boxed{}^{n-2} \\ \downarrow \\ \boxed{}^1 \end{array}$$

$$([n] = \frac{q^{\frac{n}{2}} - q^{-\frac{n}{2}}}{q^{\frac{1}{2}} - q^{-\frac{1}{2}}})$$

$$\rightsquigarrow K = \text{?}$$

then, $\text{?} = J_{K,n}^{\text{sl}_2}(q) \emptyset$

the A_2 bracket ($\mathcal{G} = \text{sl}_3$)

(Notation) $\uparrow = \uparrow_{V_{0,0}} = \downarrow_{V_{0,1}}$

$$\times = q^{\frac{1}{3}} \} \{ - q^{-\frac{1}{6}} \text{?}$$

$$\times = q^{-\frac{1}{3}} \} \{ - q^{\frac{1}{6}} \text{?}$$

$$\boxed{} = \boxed{} + \boxed{} \{$$

$$\circ = [2] \uparrow, \quad \circ = \circ = [3] \emptyset$$

$$\boxed{}^n = \boxed{}^{n-1} \uparrow - \frac{[n-1]}{[n]} \begin{array}{c} \boxed{}^{n-1} \\ \uparrow \\ \boxed{}^{n-2} \\ \uparrow \\ \boxed{}^1 \end{array}$$

$\searrow V_{(n,0)}$

$$\boxed{}^{m,n} = \sum_{k=0}^{\min\{m,n\}} (-1)^k \frac{[m][n]}{[m+n+1]} \begin{array}{c} m \uparrow n \downarrow \\ \boxed{} \\ m+k \uparrow k \downarrow \\ m \quad n-k \end{array}$$

$\searrow V_{(m,n)}$

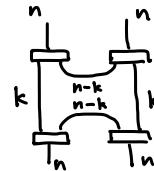
$$\rightsquigarrow \text{?} = J_{K,(m,n)}^{\text{sl}_3}(q) \emptyset$$

② Twist formulas ($\mathfrak{g} = \mathfrak{sl}_2$)

Theorem[Yamada, 1989]

$$\text{Diagram: Two strands labeled } n \text{ with a twist between them.}$$

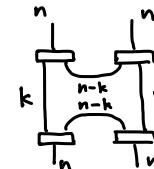
$$= \sum_{k=0}^n q^{\frac{1}{4}(-n^2+2k)} \frac{(\mathfrak{g})_n}{(\mathfrak{g})_k (\mathfrak{g})_{n-k}}$$



Theorem[Masbaum, 2003]

$$\text{Diagram: Two strands labeled } n \text{ with a more complex twist involving a loop.}$$

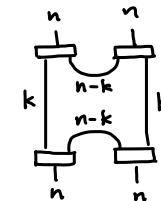
$$= \sum_{k=0}^n (-1)^{n-k} q^{\frac{1}{2}(-n^2-n+2k^2+k)} \frac{(\mathfrak{g})_n^2}{(\mathfrak{g})_k^2 (\mathfrak{g})_{n-k}}$$



Theorem[Y. 2017]

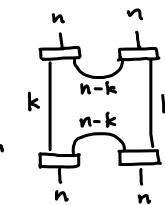
$$\begin{array}{c}
 \text{Diagram: } \begin{array}{c} n \\ | \\ \square \\ | \\ m \\ | \\ n \end{array} \quad \begin{array}{c} n \\ | \\ \square \\ | \\ n \end{array} \\
 \text{Red annotations: } m \left\{ \begin{array}{c} \diagup \\ \vdots \\ \diagdown \end{array} \right. \quad \rightarrow \quad \begin{array}{c} n \\ | \\ \square \\ | \\ m \\ | \\ n \end{array}
 \end{array}
 = (-1)^{n-k_m} q^{\frac{n-k_m}{2}} \sum_{\substack{n \geq k_1 \geq k_2 \geq \dots \geq k_m \geq 0}} (-1)^{\sum_{i=1}^m k_i} q^{\frac{1}{2} \sum_{i=1}^m (k_i^2 + k_i)}$$

$$\times \frac{(q)_n}{(q)_{n-k_1} (q)_{k_1-k_2} \cdots (q)_{k_{m-1}-k_m} (q)_{k_m}}$$



$$\begin{array}{c}
 \text{Diagram: } \begin{array}{c} n \\ | \\ \square \\ | \\ 2m \\ | \\ n \end{array} \quad \begin{array}{c} n \\ | \\ \square \\ | \\ n \end{array}
 \end{array}
 = q^{-\frac{m}{2}(n^2+2n)} \sum_{\substack{n \geq k_1 \geq k_2 \geq \dots \geq k_m \geq 0}} (-1)^{n-k_m} q^{\frac{n-k_m}{2}} q^{\sum_{i=1}^m (k_i^2 + k_i)}$$

$$\times \frac{(q)_n^2}{(q)_{n-k_1} (q)_{k_1-k_2} \cdots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$

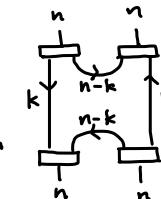


④ Twist formulas for $(n,0)$ coloring of \mathfrak{sl}_3

Theorem[Y. 2017] (anti-parallel case)

$$\begin{array}{c} n \\ \square \\ \downarrow \\ \square \\ \downarrow \\ \boxed{2m} \\ \uparrow \\ \square \\ \uparrow \\ n \end{array} = q^{-\frac{2m}{3}(n^2+3n)} \sum_{n \geq k_1 \geq k_2 \geq \dots \geq k_m \geq 0} q^{n-k_m} q^{\sum_{i=1}^m (k_i^2 + 2k_i)}$$

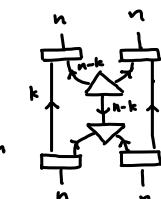
$$x \frac{(q)_n^2}{(q)_{n-k_1} (q)_{k_1-k_2} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$



Theorem[Y. 2020]

$$\begin{array}{c} n \\ \square \\ \uparrow \\ \square \\ \uparrow \\ \boxed{2m} \\ \uparrow \\ \square \\ \uparrow \\ n \end{array} = q^{-\frac{m}{3}(n^2+3n)} \sum_{n \geq k_1 \geq k_2 \geq \dots \geq k_m \geq 0} q^{\frac{n-k_m}{2}} q^{\sum_{i=1}^m (k_i^2 + k_i)}$$

$$x \frac{(q)_n^2}{(q)_{n-k_1} (q)_{k_1-k_2} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$



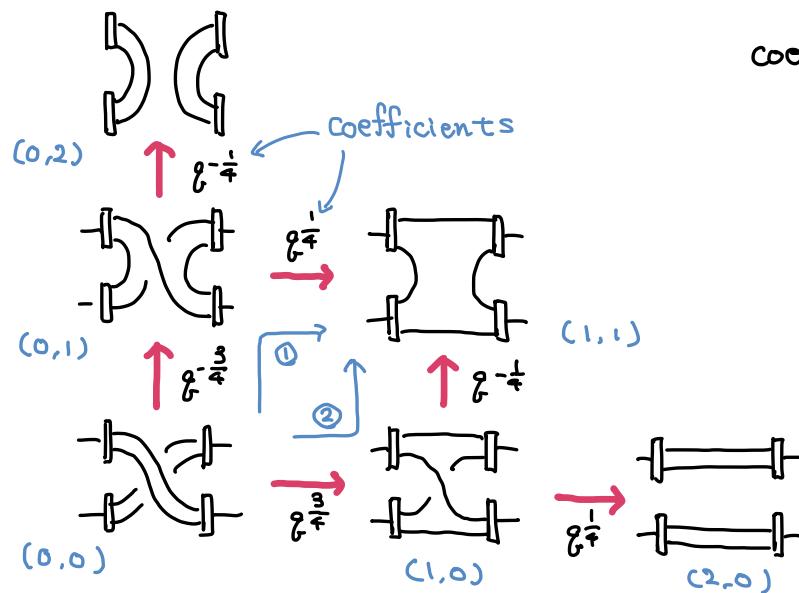
$$\left(\begin{array}{c} \xrightarrow{q} \xrightarrow{q} \\ \downarrow \quad \uparrow \\ \triangle \end{array} \right) = \left(\begin{array}{c} \xleftarrow{q} \xleftarrow{q} \\ \vdots \\ \xleftarrow{q} \xleftarrow{q} \end{array} \right)$$

How to derive twist formulas (Y. 2017)

e.g.

$$\begin{aligned}
 & \text{Diagram 1} = q^{\frac{3}{4}} \text{Diagram 2} + q^{-\frac{3}{4}} \text{Diagram 3} \\
 & = q^{\frac{3}{4}} \left(q^{\frac{1}{4}} \text{Diagram 4} + q^{-\frac{1}{4}} \text{Diagram 5} \right) + q^{-\frac{3}{4}} \left(q^{\frac{1}{4}} \text{Diagram 6} + q^{-\frac{1}{4}} \text{Diagram 7} \right)
 \end{aligned}$$

by skein tree

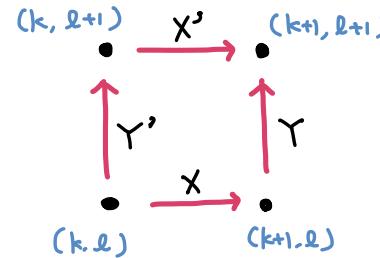
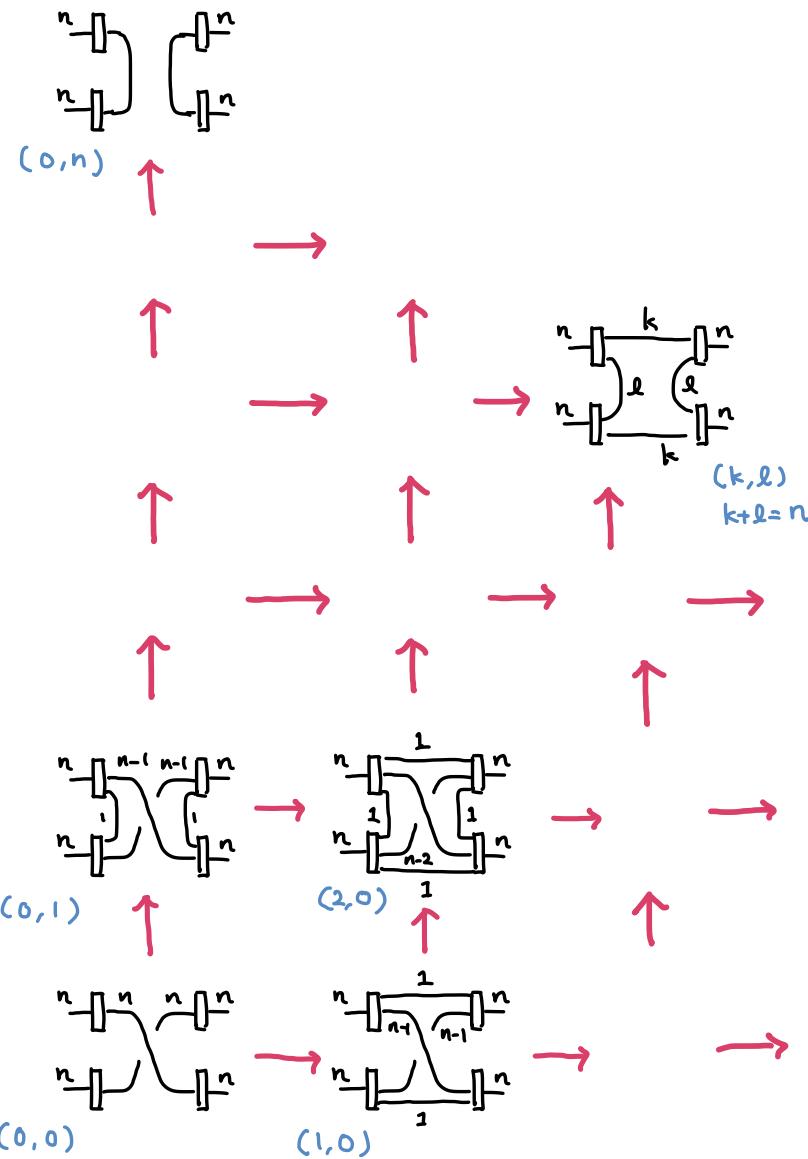


coefficient of basis web on (1,1)

$$\begin{aligned}
 & = \sum_{\gamma: \text{paths from } (0,0) \text{ to } (1,1)} \prod_{\delta} w_{\delta} \\
 & \quad w: \text{coeff. on } \delta \\
 & = \frac{q^{-\frac{3}{4}} q^{\frac{1}{4}}}{①} + \frac{q^{\frac{3}{4}} q^{-\frac{1}{4}}}{②} \\
 & \quad \times q
 \end{aligned}$$

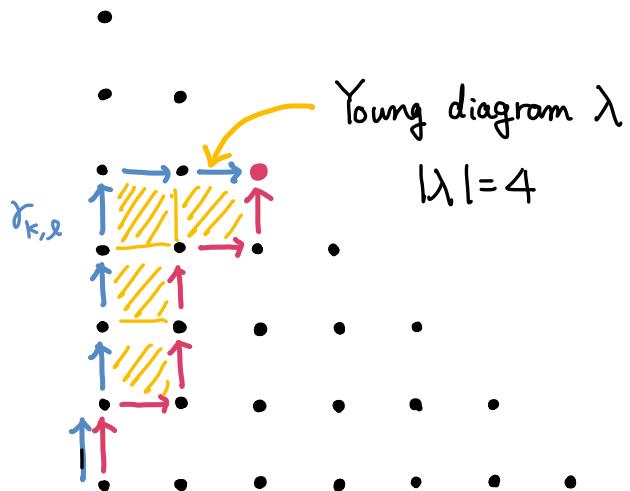
(half twist formula)

Lemma



$$\text{then } XY = g Y'X'$$

④ coefficient of (k, l) ($k+l=n$)



$$= \sum_{\gamma: \text{path from } (0,0) \text{ to } (k,l)} \prod w$$

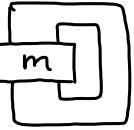
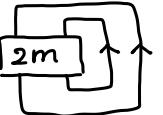
w: weight on γ

$$= \left(\prod_{w: \text{weight on } \gamma_{k,l}} w \right) \left(\sum_{\substack{\lambda: \text{Young diagram} \\ \# \text{row} \leq k \\ \# \text{column} \leq l}} q^{|\lambda|} \right)$$

$$\text{coeff}_r \left(\begin{array}{c} \text{red path} \end{array} \right) = q^4 \left(\begin{array}{c} \text{blue path} \end{array} \right)$$

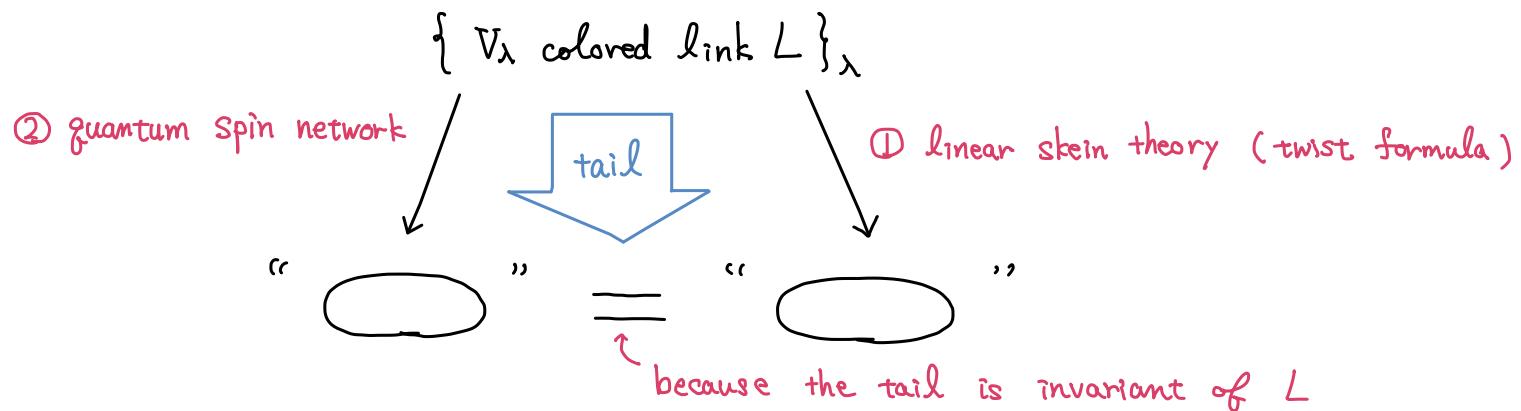
$$= \left(\prod_{w: \text{weight on } \gamma_{k,l}} w \right) \frac{(q)_n}{(q)_k (q)_{n-k}}$$

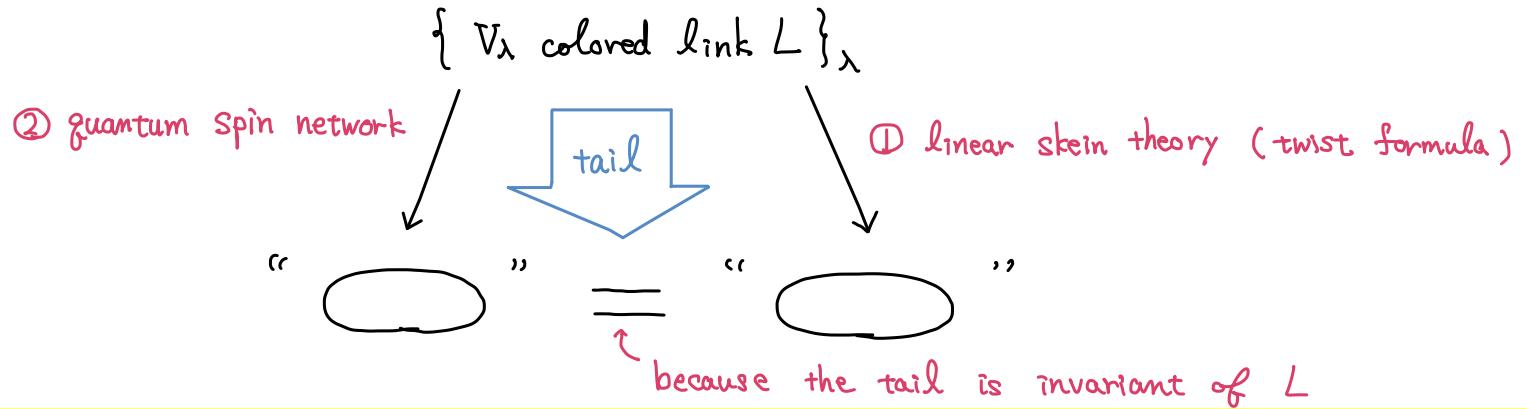
④ Andrews - Gordon type identities from the tail of $T_{(2,m)}$

- $T_{(2,m)} :=$ 
- e.g. $m=2$  $m=3$ 
- $T_{\neq}(2,2m) :=$ 
- $T_{\neq}(2,2m) :=$ 

- $f(a,b) := \sum_{i=0}^{\infty} a^{\frac{i(i+1)}{2}} b^{\frac{i(i-1)}{2}} + \sum_{i=1}^{\infty} a^{\frac{i(i-1)}{2}} b^{\frac{i(i+1)}{2}}$: the theta series

$$\psi(a,b) := \sum_{i=0}^{\infty} a^{\frac{i(i+1)}{2}} b^{\frac{i(i-1)}{2}} - \sum_{i=1}^{\infty} a^{\frac{i(i-1)}{2}} b^{\frac{i(i+1)}{2}}$$
 : the false theta series





Theorem[Armond-Dasbach, 2011]

$$f(-q^{2m}, -q) / (1-q) = J_{T(2, 2m+1)}^{\mathfrak{sl}_2}(q) = \frac{(q)_\infty}{1-q} \sum_{k_1 \geq k_2 \geq \dots \geq k_{m-1} \geq 0} q^{\sum_{i=1}^{m-1} k_i^2 + k_i} \frac{q}{(q)_{k_1-k_2} (q)_{k_2-k_3} \dots (q)_{k_{m-2}-k_{m-1}} (q)_{k_{m-1}}}.$$

Theorem[Hajij, 2015]

$$J_{\mathbb{H}}(q^{2m-1}, q) / (1-q) = J_{T(2, 2m)}^{\mathfrak{sl}_2}(q) = \frac{(q)_\infty}{1-q} \sum_{k_1 \geq k_2 \geq \dots \geq k_m \geq 0} q^{-k_m} q^{\sum_{i=1}^m k_i^2 + k_i} \frac{q}{(q)_{k_1-k_2} (q)_{k_2-k_3} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$

Theorem[Y. 2018]

$$\sum_{i=0}^{\infty} q^{-2i} q^{m(i^2+2i)} \frac{(1-q^{i+1})^3 (1+q^{i+1})}{(1-q)^2 (1-q^2)} = \mathcal{J}_{T \not\supset (2,2m)}^{\text{sl}_3}(q)$$

[

a "diagonal summand"
of the sl_3 false theta function
in Bringmann - Kaszian - Milas

$$= \frac{(q)_{\infty}}{(1-q)(1-q^2)} \sum_{k_1 \geq k_2 \geq \dots \geq k_m \geq 0} \frac{q^{-2km} q^{\sum_{i=1}^m k_i^2 + 2k_i}}{(q)_{k_1-k_2} (q)_{k_2-k_3} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$

Theorem[Y. 2020]

$$\mathcal{J}_{T \not\supset (2,2m+1)}^{\text{sl}_3}(q) = \frac{f(-q^{2m}, -q)}{(1-q)^2 (1-q^2)}$$

$$\mathcal{J}_{T \not\supset (2,2m)}^{\text{sl}_3}(q) = \frac{\Psi(q^{2m-1}, q)}{(1-q)^2 (1-q^2)}$$

→ $\mathcal{J}_{T \not\supset (2,m)}^{\text{sl}_3}(q) = \frac{1}{(1-q)(1-q^2)} \mathcal{J}_{T \supset (2,m)}^{\text{sl}_2}(q)$

Thank you for listening 