

## 1.6 Inverses and Transposes

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Course Outcome: Students will have understanding about existence of inverse, Gauss-Jordan method to find the inverse of square matrices and transpose of matrices.

### Existence of Inverse:

Inverse of a square matrix  $A$  exist if it is nonsingular i.e.  $|A| \neq 0$ . It is denoted by  $A^{-1}$ .  
If a square matrix has full set of pivots, then it is <sup>also</sup> nonsingular. So, inverse of a square matrix exist if it has full set of pivots.

Ex:  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

$$|A| = 4 - 6 = -2 \neq 0$$

$\Rightarrow A^{-1}$  will exist.

$$\text{Minor of } A = M = \begin{bmatrix} 4 & 3 \\ 2 & 1 \end{bmatrix}$$

$$\text{Cofactor of } A = C = \begin{bmatrix} 4 & -3 \\ -2 & 1 \end{bmatrix}$$

$$\text{Adjoint of } A (\text{Adj. } A) = C^T = \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}$$

$$A^{-1} = \frac{\text{Adj. } A}{|A|} = \frac{C^T}{|A|} = -\frac{1}{2} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}$$

Ex:  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

$$|A| = ad - bc \neq 0$$

$\Rightarrow A^{-1}$  will exist.

$$\text{Minor of } A = M = \begin{bmatrix} d & c \\ b & a \end{bmatrix}$$

$$\text{Cofactor of } A = C = \begin{bmatrix} d & -c \\ -b & a \end{bmatrix}$$

$$\text{Adj. } A = C^T = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$A^{-1} = \frac{\text{Adj. } A}{|A|} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$



Ex:  $A = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \Rightarrow A^{-1} = \begin{bmatrix} 1/2 & 0 \\ 0 & 1/3 \end{bmatrix}$

Ex:  $A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$

$$|A| = 2(4-1) + 1(-2) = 6-2 = 4 \neq 0$$

$\Rightarrow A^{-1}$  will exist.

Minor of  $A = \begin{bmatrix} 3 & -2 & 1 \\ -2 & 4 & -2 \\ 1 & -2 & 3 \end{bmatrix}$

Cofactor of  $A = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 3 \end{bmatrix}$

Adj.  $A = \text{Transpose of cofactor} = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 3 \end{bmatrix}$

$$A^{-1} = \frac{\text{Adj. } A}{|A|} = \frac{1}{4} \begin{bmatrix} 3 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 3 \end{bmatrix}$$

Ex:  $A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} \Rightarrow A^{-1} = \begin{bmatrix} 1/2 & 0 & 0 \\ 0 & 1/3 & 0 \\ 0 & 0 & 1/4 \end{bmatrix}$

Points to remember:

1. The inverse of a square matrix, if exist, is unique and is known as both sided inverse.

2.  $AA^{-1} = I = A^{-1}A$ .

3.  $(AB)^{-1} = B^{-1}A^{-1}$ ,  $(ABC)^{-1} = C^{-1}B^{-1}A^{-1}$ .

4.  $Ax = b \Rightarrow x = A^{-1}b$ .

Gauss-Jordan Method: (The calculation of  $A^{-1}$ )

Ex: Let  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ .

$$|A| = 4-6 = -2 \neq 0$$

$\Rightarrow A^{-1}$  will exist.



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$$[A|I]$$

$$= \left[ \begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 3 & 4 & 0 & 1 \end{array} \right]$$

$$= \left[ \begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 0 & -2 & -3 & 1 \end{array} \right] \quad R_2 \leftarrow R_2 - 3R_1$$

$$= \left[ \begin{array}{cc|cc} 1 & 0 & -2 & 1 \\ 0 & -2 & -3 & 1 \end{array} \right] \quad R_1 \leftarrow R_1 + R_2$$

$$= \left[ \begin{array}{cc|cc} 1 & 0 & -2 & 1 \\ 0 & 1 & \frac{3}{2} & -\frac{1}{2} \end{array} \right] \quad R_2 \leftarrow -\frac{1}{2}R_2$$

$$= [I|A^{-1}]$$

$$\text{where } A^{-1} = \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}$$

$$\underline{\text{Ex}}: A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{bmatrix}$$

$$|A| = 1(6-2) - 1(3-2) + 1(2-2) = 4 - 1 = 1 \neq 0$$

$\Rightarrow A^{-1}$  will exist.

$$[A|I]$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 2 & 2 & 0 & 1 & 0 \\ 1 & 2 & 3 & 0 & 0 & 1 \end{array} \right]$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & -1 & 1 & 0 \\ 0 & 1 & 2 & -1 & 0 & 1 \end{array} \right] \quad \begin{array}{l} R_2 \leftarrow R_2 - R_1 \\ R_3 \leftarrow R_3 - R_1 \end{array}$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 0 & -1 & 1 \end{array} \right] \quad R_3 \leftarrow R_3 - R_2$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 1 & 0 & 1 & 2 & -1 \\ 0 & 1 & 0 & -1 & 2 & -1 \\ 0 & 0 & 1 & 0 & -1 & 1 \end{array} \right] \quad \begin{array}{l} R_1 \leftarrow R_1 - R_3 \\ R_2 \leftarrow R_2 - R_3 \end{array}$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 2 & 0 & 0 \\ 0 & 1 & 0 & -1 & 2 & -1 \\ 0 & 0 & 1 & 0 & -1 & 1 \end{array} \right] \quad R_1 \leftarrow R_1 - R_2$$

$$= [I|A^{-1}]$$

$$\text{where } A^{-1} = \begin{bmatrix} 2 & 0 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$



## Transpose :

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \Rightarrow A^T = \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix}.$$

Symmetric matrix: A square matrix  $A$  is said to be symmetric if  $A^T = A$ .

Skew-symmetric matrix: A square matrix  $A$  is said to be skew-symmetric if  $A^T = -A$ .

If  $A$  is any real square matrix, then  $A + A^T$  is always symmetric and  $A - A^T$  is always skew-symmetric.

Let  $B = A + A^T$ . Then

$$B^T = (A + A^T)^T = A^T + (A^T)^T = A^T + A = B$$

$\Rightarrow B$  is symmetric.

Let  $C = A - A^T$ . Then

$$C^T = (A - A^T)^T = A^T - (A^T)^T = A^T - A = -(A - A^T) = -C$$

$\Rightarrow C$  is skew-symmetric.

$$A = \frac{A + A^T}{2} + \frac{A - A^T}{2}$$

$\downarrow$   
symmetric

$\downarrow$   
skew-symmetric

$\Rightarrow$  Any real square matrix can be expressed as a sum of symmetric and skew-symmetric matrix.



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Ex: Express the matrix  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$  as sum of symmetric and skew-symmetric matrix.

Soln:  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, A^T = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$

$$A = \frac{A + A^T}{2} + \frac{A - A^T}{2}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 5/2 \\ 5/2 & 4 \end{bmatrix} + \begin{bmatrix} 0 & -1/2 \\ 1/2 & 0 \end{bmatrix}$$

↓  
symmetric

↓  
skew-symmetric

Ex:  $A = \begin{bmatrix} \textcircled{1} & 3 & 5 \\ 3 & 12 & 18 \\ 5 & 18 & 30 \end{bmatrix}$

$$= \begin{bmatrix} 1 & 3 & 5 \\ 0 & \textcircled{2} & 3 \\ 0 & 3 & 5 \end{bmatrix}$$

$$R_2 \leftarrow R_2 - 3R_1 \quad (3)$$

$$R_3 \leftarrow R_3 - 5R_1 \quad (5)$$

$$= \begin{bmatrix} 1 & 3 & 5 \\ 0 & 3 & 3 \\ 0 & 0 & \textcircled{2} \end{bmatrix}$$

$$R_3 \leftarrow R_3 - R_2 \quad (1)$$

$$= U$$

LU-factorization:

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 5 & 1 & 1 \end{bmatrix}, U = \begin{bmatrix} 1 & 3 & 5 \\ 0 & 3 & 3 \\ 0 & 0 & 2 \end{bmatrix}$$

$$LU = A$$

LDU-factorization:

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 5 & 1 & 1 \end{bmatrix}, D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix}, U = \begin{bmatrix} 1 & 3 & 5 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$LDU = A$$

Here  $U = L^T$ . So,  $LDL^T = A$ .



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In this example since  $A^T = A$ , so  $LDU = A$  is  
 $LDL^T = A$ .

Note: If  $A = A^T$  can be factored into  $A = LDU$  without row exchanges, then  $U$  is the transpose of  $L$  and  $A = LDL^T$ .

Points to remember:

1.  $(A+B)^T = A^T + B^T$
2.  $(AB)^T = B^T A^T$ ,  $(ABC)^T = C^T B^T A^T$ .
3.  $(A^T)^T = A$
4.  $(A^{-1})^T = (A^T)^{-1}$

### Problem Set 1.6

No. 6. (a) If  $A$  is invertible and  $AB = AC$ , prove that  $B = C$ .

Proof: Let  $A$  be invertible and  $AB = AC$ .

$$AB = AC$$

$$\Rightarrow A^{-1}(AB) = A^{-1}(AC)$$

$$\Rightarrow (A^{-1}A)B = (A^{-1}A)C \quad (\text{by associative law})$$

$$\Rightarrow IB = IC$$

$$\Rightarrow B = C.$$

(b) If  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ , find an example with  $AB = AC$  but  $B \neq C$ .

Soln: Let  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ ,  $B = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}$ ,  $C = \begin{bmatrix} 2 & 3 \\ 6 & 7 \end{bmatrix}$ .

$$AB = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 0 & 0 \end{bmatrix}$$

$$AC = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 6 & 7 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 0 & 0 \end{bmatrix}.$$

$$AB = AC \text{ but } B \neq C.$$



Q.10.  $A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

$[A_1 | I]$

$= \begin{bmatrix} 1 & 0 & 0 & | & 1 & 0 & 0 \\ 1 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix}$

$= \begin{bmatrix} 1 & 0 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & -1 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix} \quad R_2 \leftarrow R_2 - R_1$

$= \begin{bmatrix} 1 & 0 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & -1 & 1 & -1 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix} \quad R_2 \leftarrow R_2 - R_3$

$= [I | A^{-1}]$

$\therefore A^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$

$A_2 = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$

$[A_2 | I]$

$= \begin{bmatrix} 2 & -1 & 0 & | & 1 & 0 & 0 \\ -1 & 2 & -1 & | & 0 & 1 & 0 \\ 0 & -1 & 2 & | & 0 & 0 & 1 \end{bmatrix}$

$= \begin{bmatrix} 2 & -1 & 0 & | & 1 & 0 & 0 \\ 0 & \frac{3}{2} & -1 & | & \frac{1}{2} & 1 & 0 \\ 0 & -1 & 2 & | & 0 & 0 & 1 \end{bmatrix} \quad R_2 \leftarrow R_2 + \frac{1}{2} R_1$

$= \begin{bmatrix} 2 & -1 & 0 & | & 1 & 0 & 0 \\ 0 & \frac{3}{2} & -1 & | & \frac{1}{2} & 1 & 0 \\ 0 & 0 & \frac{4}{3} & | & \frac{1}{3} & \frac{2}{3} & 1 \end{bmatrix} \quad R_3 \leftarrow R_3 + \frac{2}{3} R_2$

$= \begin{bmatrix} 2 & -1 & 0 & | & 1 & 0 & 0 \\ 0 & \frac{3}{2} & 0 & | & \frac{3}{4} & \frac{3}{2} & \frac{3}{4} \\ 0 & 0 & \frac{4}{3} & | & \frac{1}{3} & \frac{2}{3} & 1 \end{bmatrix} \quad R_2 \leftarrow R_2 + \frac{3}{4} R_3$

$A_3 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

$[A_3 | I]$

$= \begin{bmatrix} 0 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 1 & 1 & 1 & | & 0 & 0 & 1 \end{bmatrix}$

$= \begin{bmatrix} 1 & 1 & 1 & | & 0 & 0 & 1 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 1 & 0 & 0 \end{bmatrix} \quad R_1 \leftrightarrow R_3$

$= \begin{bmatrix} 1 & 1 & 0 & | & -1 & 0 & 1 \\ 0 & 1 & 0 & | & -1 & 1 & 0 \\ 0 & 0 & 1 & | & 1 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} R_1 \leftarrow R_1 - R_2 \\ R_2 \leftarrow R_2 - R_3 \end{array}$

$= \begin{bmatrix} 1 & 0 & 0 & | & 0 & -1 & 1 \\ 0 & 1 & 0 & | & -1 & 1 & 0 \\ 0 & 0 & 1 & | & 1 & 0 & 0 \end{bmatrix} \quad R_1 \leftarrow R_1 - R_2$

$= [I | A^{-1}]$

$\therefore A^{-1} = \begin{bmatrix} 0 & -1 & 1 \\ -1 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$

$= \begin{bmatrix} 2 & 0 & 0 & | & \frac{3}{2} & \frac{1}{2} \\ 0 & \frac{3}{2} & 0 & | & \frac{3}{4} & \frac{3}{2} & \frac{3}{4} \\ 0 & 0 & \frac{4}{3} & | & \frac{1}{3} & \frac{2}{3} & 1 \end{bmatrix} \quad R_1 \leftarrow R_1 + \frac{2}{3} R_2$

$= \begin{bmatrix} 1 & 0 & 0 & | & \frac{3}{4} & \frac{1}{2} & \frac{1}{4} \\ 0 & 1 & 0 & | & \frac{1}{2} & 1 & \frac{1}{2} \\ 0 & 0 & 1 & | & \frac{1}{4} & \frac{1}{2} & \frac{3}{4} \end{bmatrix} \quad \begin{array}{l} R_1 \leftarrow \frac{1}{2} R_1 \\ R_2 \leftarrow \frac{2}{3} R_2 \\ R_3 \leftarrow \frac{3}{4} R_3 \end{array}$

$= [I | A^{-1}]$

$\therefore A^{-1} = \begin{bmatrix} \frac{3}{4} & \frac{1}{2} & \frac{1}{4} \\ \frac{1}{2} & 1 & \frac{1}{2} \\ \frac{1}{4} & \frac{1}{2} & \frac{3}{4} \end{bmatrix}$



No. 11. Let  $B$  be a square matrix.

Let  $A = B + B^T$  and  $K = B - B^T$ .

$$A^T = (B + B^T)^T = B^T + (B^T)^T = B^T + B = A$$

$\Rightarrow A$  is symmetric.

$$\text{Again, } K^T = (B - B^T)^T = B^T - (B^T)^T = B^T - B = -(B - B^T) = -K$$

$\Rightarrow K$  is skew-symmetric.

$$A = B + B^T = \begin{bmatrix} 1 & 3 \\ 1 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 1 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 4 \\ 4 & 2 \end{bmatrix}$$

$$K = B - B^T = \begin{bmatrix} 1 & 3 \\ 1 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 1 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ -2 & 0 \end{bmatrix}$$

$$B = \frac{B + B^T}{2} + \frac{B - B^T}{2}$$

$$\Rightarrow \begin{bmatrix} 1 & 3 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$\downarrow$   
symmetric

$\downarrow$   
skew-symmetric.

No. 15.  $A = \begin{bmatrix} a & b & c \\ d & e & 0 \\ f & 0 & 0 \end{bmatrix}$

$$|A| = c(0 - ef) = -cef$$

$A$  is singular if  $|A| \neq 0$

$$\Rightarrow -cef \neq 0$$

$$\Rightarrow cef \neq 0.$$

The required conditions for  $A$  to be invertible

are  $a, b, c, d, e, f \in \mathbb{R}$  such that  $cef \neq 0$ .

$$B = \begin{bmatrix} a & b & 0 \\ c & d & 0 \\ 0 & 0 & e \end{bmatrix}$$

$$|B| = a(de - 0) - b(ce) = e(ad - bc)$$

$B$  is invertible  $\Rightarrow |B| \neq 0$

$$\Rightarrow \boxed{e(ad - bc) \neq 0}, a, b, c, d, e \in \mathbb{R}.$$



No. 17. (a)  $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ ,  $B = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

$$A+B = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$A+B$  is not invertible although  $A$  and  $B$  are invertible.

(b)  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ ,  $B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$

$$A+B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$A+B$  is invertible although  $A$  and  $B$  are not invertible.

(c)  $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ ,  $B = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$ ,  $C = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix}$

All of  $A$ ,  $B$  and  $A+B$  are invertible.

No. 42.

$$A = \begin{bmatrix} 2 & c & c \\ c & c & c \\ 8 & 7 & c \end{bmatrix}$$

For  $c = 0, 2, 7$ , the matrix is not invertible, as for these three values of  $c$  the determinant of the matrix is zero.

$c = 0 \Rightarrow$  zero column (or zero ~~row~~ row).

$c = 2 \Rightarrow$  identical rows

$c = 7 \Rightarrow$  identical columns.