

## Spanning a Subspace :

Let us know what is the meaning of a set of vectors to span a space.

### Vector Space $\mathbb{R}^2$ :

Minimum two linearly independent vectors are required to span the vector space  $\mathbb{R}^2$  i.e. the linear combination of two linearly independent vectors of  $\mathbb{R}^2$  can form the whole plane  $\mathbb{R}^2$ .

More than two vectors of  $\mathbb{R}^2$  can also span the whole plane  $\mathbb{R}^2$  provided among the vectors two are linearly independent. But one vector of  $\mathbb{R}^2$  can not span the whole plane  $\mathbb{R}^2$ .

### Vector Space $\mathbb{R}^3$ :

Minimum three linearly independent vectors are required for the spanning of the space  $\mathbb{R}^3$  i.e. the linear combination of 03 linearly independent vectors of  $\mathbb{R}^3$  can form the whole space  $\mathbb{R}^3$ .

More than three vectors of  $\mathbb{R}^3$  can also span the whole space  $\mathbb{R}^3$  provided among the given vectors three are linearly independent. But two linearly independent vectors of  $\mathbb{R}^3$  can not span the whole plane  $\mathbb{R}^3$ .

Notes : 1. The column space of a matrix is spanned by its columns.



2. The row space of a matrix is spanned by its rows.

Ex : Describe the subspace of  $\mathbb{R}^2$  spanned by

- (a) the vectors  $(1, 2)$  and  $(2, 4)$ .
- (b) the vectors  $(1, 2)$  and  $(3, 4)$ .
- (c) the vector  $(1, 2)$ .
- (d) the vectors  $(1, 2)$ ,  $(3, 4)$  and  $(1, 1)$ .

Soln : (a) Given : the vectors  $(1, 2)$  and  $(2, 4)$ .

$$\begin{aligned} \text{Let } A &= \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}, \quad R_2 \leftarrow R_2 - 2R_1 \\ &\quad \text{, echelon form} \end{aligned}$$

Rank of  $A = 1$

The required subspace of  $\mathbb{R}^2$  spanned by the given two vectors is a line passing through origin.

(b) Given : the vectors  $(1, 2)$  and  $(3, 4)$ .

$$\begin{aligned} \text{Let } A &= \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 3 \\ 0 & -2 \end{bmatrix}, \quad R_2 \leftarrow R_2 - 2R_1 \\ &\quad \text{, echelon form} \end{aligned}$$

Rank of  $A = 2$ .

The required subspace of  $\mathbb{R}^2$  spanned by the two given vectors is the whole plane  $\mathbb{R}^2$  itself.



© Given: the vector  $(1, 2)$ .

$$\text{Let } A = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0 \end{bmatrix}, R_2 \leftarrow R_2 - 2R_1$$

, echelon form

Rank of  $A = 1$ .

The required subspace of  $\mathbb{R}^2$  spanned by the given vector is a line passing through origin.

② Given: the vectors  $(1, 2)$ ,  $(3, 4)$  and  $(1, 1)$ .

$$\text{Let } A = \begin{bmatrix} 1 & 3 & 1 \\ 2 & 4 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 3 & 1 \\ 0 & -2 & -1 \end{bmatrix}, R_2 \leftarrow R_2 + 2R_1$$

, echelon form

Rank of  $A = 2$ .

The required subspace of  $\mathbb{R}^2$  spanned by the three given vectors is the whole plane  $\mathbb{R}^2$ .

### Basis for a Vector Space:

A basis for a vector space  $V$  is a subset with a sequence of vectors having two properties at once:

1. The vectors are linearly independent.  
(not too many vectors)
2. They span the space  $V$ . (not too few vectors)

### Points to remember:

1. A basis of a vector space is the maximal independent set.
2. A basis of a vector space is also a minimal spanning set.



3. Spanning involves the column space and independence involves the nullspace.

4. No elements of a basis will be wasted.

Ex  $\div$  Check whether the following sets are bases of  $\mathbb{R}^3$  or not.

(a)  $B_1 = \{(1, 2, 2), (-1, 2, 1), (0, 8, 0)\}$

(b)  $B_2 = \{(1, 2, 2), (-1, 2, 1), (0, 8, 6)\}$

(c)  $B_3 = \{(1, 2, 2), (-1, 2, 1)\}$

(d)  $B_4 = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$

(e)  $B_5 = \{(1, 1, -1), (2, 3, 4), (4, 1, -1), (0, 1, -1)\}$

Soln  $\div$  (a)

Let  $A = \begin{bmatrix} 1 & -1 & 0 \\ 2 & 2 & 8 \\ 2 & 1 & 0 \end{bmatrix}$

$$|A| = 1(0-8) + 1(-16) = -24 \neq 0$$

The vectors  $(1, 2, 2)$ ,  $(-1, 2, 1)$  and  $(0, 8, 0)$  are linearly independent.

So,  $B_1$  is a basis of  $\mathbb{R}^3$ .

(b) Let  $A = \begin{bmatrix} 1 & -1 & 0 \\ 2 & 2 & 8 \\ 2 & 1 & 6 \end{bmatrix}$

$$|A| = 1(12-8) + 1(12-16) = 4-4 = 0$$

The vectors of  $B_2$  are linearly dependent.

So,  $B_2$  is not a basis of  $\mathbb{R}^3$ .

(c)  $B_3$  is not a basis of  $\mathbb{R}^3$  as it does not contain the maximum number of linearly independent vectors of  $\mathbb{R}^3$ .



(d) Let  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ .

$$|A| = 1 \neq 0$$

The vectors of  $B_4$  are linearly independent.  
So,  $B_4$  is a basis of  $\mathbb{R}^3$  and is known as standard basis of  $\mathbb{R}^3$ .

(e) The elements of  $B_5$  are linearly dependent as four or more vectors in  $\mathbb{R}^3$  are always linearly dependent.

So,  $B_5$  is not a basis of  $\mathbb{R}^3$ .

### Dimension of Vector Spaces:

Dimension of a vector space is the maximum no. of linearly independent vectors of the vector space.

OR

The no. of elements present in the basis of a vector space is known as dimension of the vector space.

$$\dim. \mathbb{R} = 1, \dim. \mathbb{R}^2 = 2, \dim. \mathbb{R}^3 = 3, \dots$$

$$\dim. \mathbb{R}^n = n.$$

Dimension of the vector space  $\mathbb{R}^3 = 3$ .

Any plane passing through origin are 2-dimensional subspaces of  $\mathbb{R}^3$ .

Any line passing through origin are 1-dimensional subspace of  $\mathbb{R}^3$ .



The origin  $\{(0,0,0)\}$  is a 0-dimensional subspace of  $\mathbb{R}^3$ .

Note : A vector space has multiple bases.

### Problem Set 2.3

No. 3. (a) Given: vectors  $(1, 3, 2)$ ,  $(2, 1, 3)$  and  $(3, 2, 1)$ .

$$\text{Let } A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix}$$

$$\begin{aligned} |A| &= 1(1-6) - 2(3-4) + 3(9-2) \\ &= -5 + 2 + 21 \\ &= 18 \neq 0 \end{aligned}$$

So, the given vectors are linearly independent.

(b) Given: vectors  $(1, -3, 2)$ ,  $(2, 1, -3)$  and  $(-3, 2, 1)$ .

$$\text{Let } A = \begin{bmatrix} 1 & 2 & -3 \\ -3 & 1 & 2 \\ 2 & -3 & 1 \end{bmatrix}$$

$$\begin{aligned} |A| &= 1(1+6) - 2(-3-4) - 3(9-2) \\ &= 7 + 14 - 21 \\ &= 21 - 21 = 0 \end{aligned}$$

So, the given vectors are linearly dependent.

No. 5. Let  $\omega_1, \omega_2, \omega_3$  are linearly independent vectors.

Let  $v_1 = \omega_2 - \omega_3$ ,  $v_2 = \omega_1 - \omega_3$  and  $v_3 = \omega_1 - \omega_2$ .

$$\begin{aligned} v_1 - v_2 + v_3 &= \omega_2 - \omega_3 - \omega_1 + \omega_3 + \omega_1 - \omega_2 \\ &= 0 \end{aligned}$$

$\Rightarrow v_1, v_2$  and  $v_3$  are linearly dependent.



No. 8. Let  $v_1, v_2, v_3, v_4$  be vectors in  $\mathbb{R}^3$

- (a) These four vectors are dependent because four or more vectors in  $\mathbb{R}^3$  are always dependent
- (b) The two vectors  $v_1$  and  $v_2$  will be dependent if one is a multiple of other.
- (c) The vectors  $v_1$  and  $(0,0,0)$  are dependent because  $0 \cdot v_1 + c(0,0,0) = 0$  has a nonzero solution for any  $c \neq 0$ .

No. 9. Given: Plane:  $x + 2y - 3z - t = 0$  in  $\mathbb{R}^4$ .

(i)  $x = -2y + 3z + t$

$y=0, z=0, t=1 \Rightarrow x=1$

$y=0, z=1, t=0 \Rightarrow x=3$

So,  $(1, 0, 0, 1)$  and  $(3, 0, 1, 0)$  are two independent vectors.

(ii)  $y=1, z=0, t=0 \Rightarrow x=-2$

So,  $(1, 0, 0, 1)$ ,  $(3, 0, 1, 0)$  and  $(-2, 1, 0, 0)$  are three independent vectors.

(iii) Since there are 3 free variables, so there will be not four independent vectors on the plane.

(iv) The plane is the nullspace of the matrix  $A = \begin{bmatrix} 1 & 2 & -3 & -1 \end{bmatrix}$ .