

Computer Organization and Architecture (EET2211)

LAB I: Examine & Analyze Different Addressing Modes of 8086 Microprocessor

Siksha 'O' Anusandhan Deemed to be University, Bhubaneswar

Branch: Computer Science and Engineering			Section: 'D'
S. No.	Name	Registration No.	Signature
1	Saswat Mohanty	1941012407	<i>Saswat Mohanty</i>

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Remarks:

Teacher's Signature

I. OBJECTIVE:

1. Addition of two 16bit numbers using immediate addressing mode.
2. Addition of two 16bit numbers using direct addressing mode.
3. Addition of two 16bit numbers using indirect addressing mode.
4. Addition of two 16bit numbers using index addressing mode.
5. Addition of two 16bit numbers using base index addressing mode.

II. PRE-LAB

For Obj. 1:

a) Explain immediate addressing mode briefly.

The addressing mode in which the data operand is a part of the instruction itself is known as immediate addressing mode.

b) Examine & analyze the output obtained from addition of two 16 bit numbers.

MOV AX,2000H

MOV BX,9000H

ADD AX,BX

Output = B000h

c) Write the assembly code.

```
org 100h
MOV AX,2000H
MOV BX,9000H
ADD AX,BX
HLT
ret
```

For Obj. 2:

a) Explain direct addressing mode briefly.

The addressing mode in which the effective address of the memory location is written directly in the instruction

b) Examine & analyze the output obtained from addition of two 16 bit numbers.

```
mov ax,[2000h]
mov bx,[9000h]
add ax,bx
```

[2000h] = 1111h

[9000h] = 2222h

Output: [3004h] = 3333h

c) Write the assembly code.

```
org 100h
MOV AX,0000H
MOV DS,AX
ADD AX,[2000H]
MOV BX,[2100H]
ADD AX,BX
MOV [3004H],AX
hlt
```

For Obj. 3:

a) Explain indirect addressing mode briefly.

This addressing mode allows data to be addressed at any memory location through an offset address held in any of following registers BP, BX, DI and SI

b) Examine & analyze the output obtained from addition of two 16 bit numbers.

mov ax,[si]

mov bx,[si]

add ax,bx

[20400h] = 1111h

[20402h] = 2222h

Output : [20404] = 3333h

c) Write the assembly code.

```
org 100h
MOV AX,2000H
MOV DS,AX
MOV SI,0400H
MOV AX,[SI]
INC SI
INC SI
MOV BX,[SI]
ADD AX,BX
INC SI
INC SI
MOV [SI],AX
hlt
```

For Obj. 4:

a) Explain index addressing mode briefly.

In this addressing mode, the operands offset address is found by adding the contents of SI or DI register and 8 bit/ 16 bit displacements

b) Examine & analyze the output obtained from addition of two 16 bit numbers.

```
mov ax,[si]
mov bx,[si+2]
add ax,bx
```

[20700h] = 1111h

[20702h] = 2222h

Output: [20704] = 3333h

c) Write the assembly code.

```
org 100h
MOV AX,2000H
MOV DS,AX
MOV SI,0700H
MOV AX,[SI+0]
MOV BX,[SI+2]
ADD AX,BX
MOV [SI+4],AX
HLT
```

For Obj. 5:

a) Explain base index addressing mode briefly.

In this addressing mode, the offset address of the operand is computed by summing the base register to the contents of an Index register.

b) Examine & analyze the output obtained from addition of two 16 bit numbers.

```
mov ax,[bx+si]
mov cx,[bx+si]
add ax,cx
```

[0000h] = 1111h

[3500h] = 2222h

[3502h] = 3333h

Output: [3504] = 5555h

c) Write the assembly code.

```
org 100h
MOV AX,0000H
MOV DS,AX
MOV BX,3000H
MOV SI,0500H
MOV CX,[BX+SI]
MOV DX,[BX+SI+02]
MOV AX,CX
ADD AX,DX
HLT
```

III. LAB:

Assembly Program:

For Obj. 1

```
; SASWAT MOHANTY
; 1941012407

; Addition of two 16bit numbers using immediate addressing mode

org 100h

MOV AX,2000H
MOV BX,9000H
ADD AX,BX
HLT
```

```
ret
```

For Obj. 2

```
; SASWAT MOHANTY
; 1941012407

; Addition of two 16bit numbers using direct addressing mode

org 100h

MOV AX,0000H
MOV DS,AX
ADD AX,[2000H]    ; value stored at 2000 = 1111
MOV BX,[2100H]    ; value stored at 2100 = 2222
ADD AX,BX
MOV [3004H],AX

hlt

ret
```

For Obj. 3

```
; SASWAT MOHANTY
; 1941012407

; Addition of two 16bit numbers using indirect addressing mode

org 100h

MOV AX,2000H
MOV DS,AX
MOV SI,0400H
MOV AX,[SI]       ; value stored at 20400 = 1111
INC SI            ; value stored at 20402 = 2222
INC SI
MOV BX,[SI]
ADD AX,BX
INC SI
INC SI
MOV [SI],AX
```

```
hlt
```

```
ret
```

For Obj. 4

```
; SASWAT MOHANTY  
; 1941012407  
  
; Addition of two 16bit numbers using index addressing mode  
  
org 100h  
  
MOV AX,2000H  
MOV DS,AX  
MOV SI,0700H      ;VALUES STORED AT 20700 = 1111  
MOV AX,[SI+0]      ;VALUES STORED AT 20702 = 2222  
MOV BX,[SI+2]  
ADD AX,BX  
MOV [SI+4],AX  
  
HLT  
  
ret
```

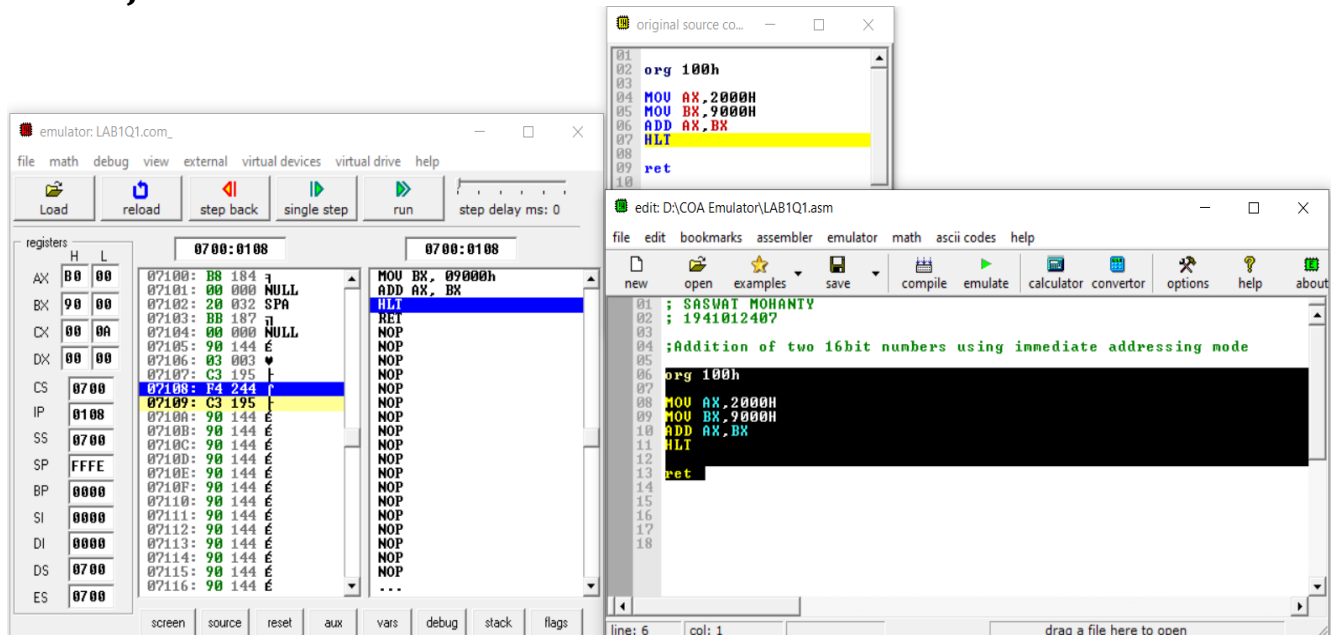
For Obj. 5

```
; SASWAT MOHANTY  
; 1941012407  
  
; Addition of two 16bit numbers using base index addressing mode  
  
org 100h  
  
MOV AX,0000H      ;value stored at 0000 = 1111  
MOV DS,AX  
MOV BX,3000H  
MOV SI,0500H      ;value stored at 3500 = 2222  
MOV CX,[BX+SI]     ;value stored at 3502 = 3333  
MOV DX,[BX+SI+02]  
MOV AX,CX  
ADD AX,DX  
  
HLT
```

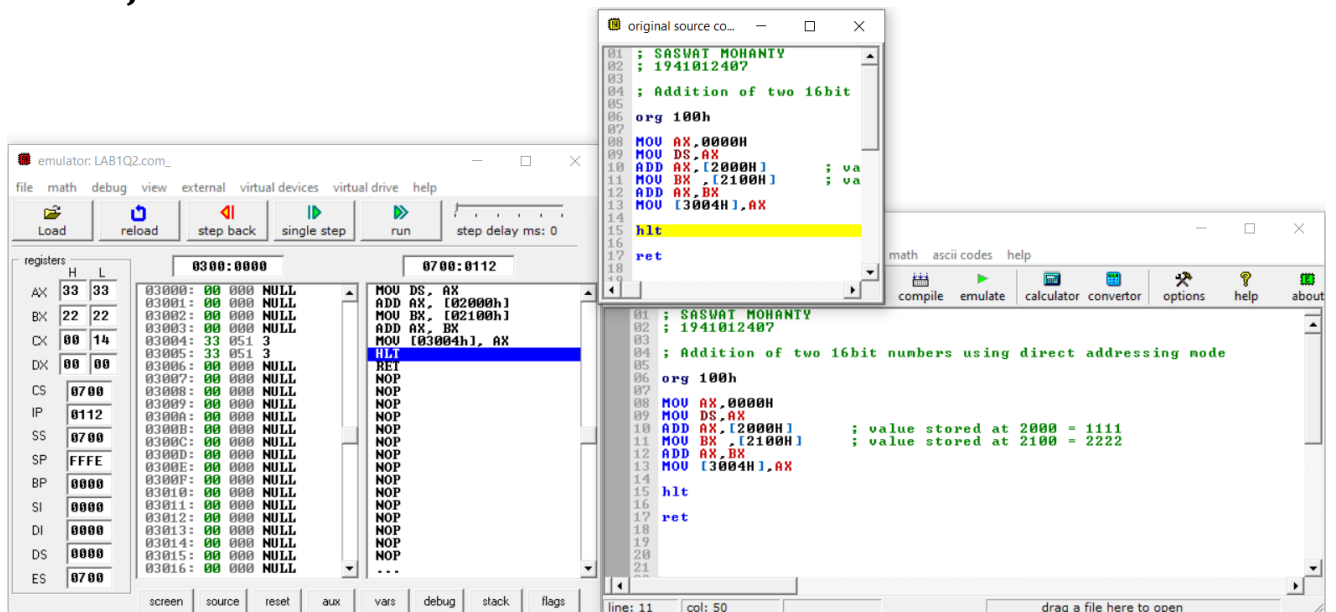

ret

Observations (with screen shots):

For Obj. 1



For Obj. 2



For Obj.3

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Load reload step back single step run step delay ms: 0

registers H L

Register	H	L
AX	33	33
BX	22	22
CX	00	16
DX	00	00
CS	0700	
IP	0114	
SS	0700	
SP	FFFE	
BP	0000	
SI	0404	
DI	0000	
DS	2000	
ES	0700	

2000:0400 0700:0114

20400: 11 017 1111
20401: 11 017 1111
20402: 22 034 2222
20403: 22 034 2222
20404: 33 051 3
20405: 33 051 3
20406: 00 000 NULL
20407: 00 000 NULL
20408: 00 000 NULL
20409: 00 000 NULL
2040A: 00 000 NULL
2040B: 00 000 NULL
2040C: 00 000 NULL
2040D: 00 000 NULL
2040E: 00 000 NULL
2040F: 00 000 NULL
20410: 00 000 NULL
20411: 00 000 NULL
20412: 00 000 NULL
20413: 00 000 NULL
20414: 00 000 NULL
20415: 00 000 NULL
20416: 00 000 NULL

MOV DS, AX
MOV SI, 00400h
INC SI
MOV BX, [SI]
ADD AX, BX
INC SI
MOV [SI], AX
HLT
RET

original source co...

```

05
06 org 100h
07
08 MOV AX,2000H
09 MOV DS,AX
10 MOV SI,0400H
11 MOV AX,[SI]
12 INC SI
13 INC SI
14 MOV BX,[SI]
15 ADD AX,BX
16 INC SI
17 INC SI
18 MOV [SI],AX
19
20 hlt
21
22 ret
23

```

01 ; SASVAT MOHANTY
02 ; 1941012407
03
04 ; Addition of two 16bit numbers using indirect addressing mode
05
06 org 100h
07
08 MOV AX,2000H
09 MOV DS,AX
10 MOV SI,0400H
11 MOV AX,[SI] ; value stored at 20400 = 1111
12 INC SI ; value stored at 20402 = 2222
13 INC SI
14 MOV BX,[SI]
15 ADD AX,BX
16 INC SI
17 INC SI
18 MOV [SI],AX
19
20 hlt
21
22 ret

line: 12 col: 52

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For Obj.4

emulator: LAB1Q4.com

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Load reload step back single step run step delay ms: 0

registers H L

Register	H	L
AX	33	33
BX	22	22
CX	00	14
DX	00	00
CS	0700	
IP	0112	
SS	0700	
SP	FFFE	
BP	0000	
SI	0700	
DI	0000	
DS	2000	
ES	0700	

2000:0700 0700:0112

20700: 11 017 1111
20701: 11 017 1111
20702: 22 034 2222
20703: 22 034 2222
20704: 33 051 3
20705: 33 051 3
20706: 00 000 NULL
20707: 00 000 NULL
20708: 00 000 NULL
20709: 00 000 NULL
2070A: 00 000 NULL
2070B: 00 000 NULL
2070C: 00 000 NULL
2070D: 00 000 NULL
2070E: 00 000 NULL
2070F: 00 000 NULL
20710: 00 000 NULL
20711: 00 000 NULL
20712: 00 000 NULL
20713: 00 000 NULL
20714: 00 000 NULL
20715: 00 000 NULL
20716: 00 000 NULL

MOV DS, AX
MOV SI, 00700h
MOV BX, [SI] + 02h
ADD AX, BX
MOV [SI] + 04h, AX
HLT
RET

original source co...

```

01 ; SASVAT MOHANTY
02 ; 1941012407
03
04 ; Addition of two 16bit
05
06 org 100h
07
08 MOV AX,2000H
09 MOV DS,AX
10 MOV SI,0700H
11 MOV AX,[SI+0]
12 MOV BX,[SI+2]
13 ADD AX,BX
14 MOV [SI+4],AX
15
16 HLT
17
18 ret
19
20
21

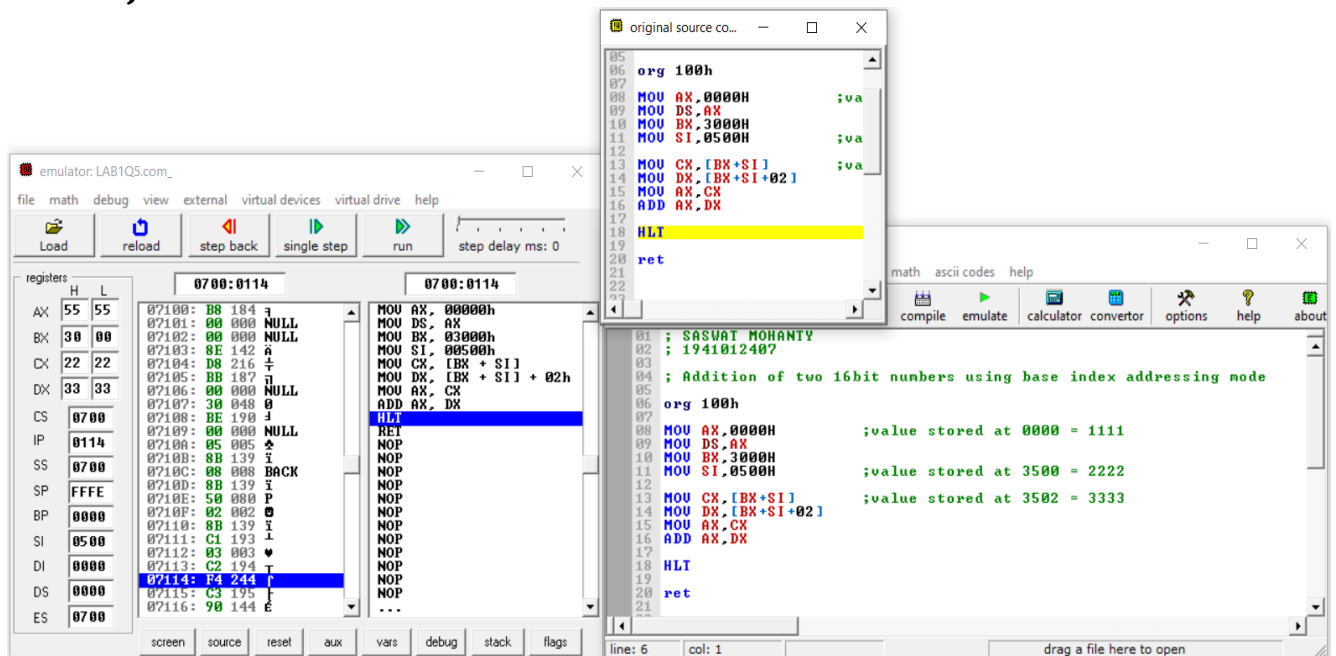
```

01 ; SASVAT MOHANTY
02 ; 1941012407
03
04 ; Addition of two 16bit numbers using index addressing mode
05
06 org 100h
07
08 MOV AX,2000H
09 MOV DS,AX
10 MOV SI,0700H ; VALUES STORED AT 20700 = 1111
11 MOV AX,[SI+0] ; VALUES STORED AT 20702 = 2222
12 MOV BX,[SI+2]
13 ADD AX,BX
14 MOV [SI+4],AX
15
16 HLT
17
18 ret
19
20
21

line: 11 col: 47

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For Obj. 5



Conclusion:

For Obj. 1:

It can be concluded that for immediate addressing the operand is specified in the instruction itself.

For Obj. 2:

It can be concluded that for direct addressing the operands offset is given in the instruction as a 16-bit displacement element.

For Obj. 3:

It can be concluded that for indirect addressing the operands offset is placed SI register as specified in the instruction.

For Obj. 4:

It can be concluded that for index addressing the offset is the sum of the content of SI register and a 16-bit displacement element.

For Obj. 5:

It can be concluded that for base index addressing the offset is the sum of the content of BX and SI register.

IV. POST LAB:

1. Discuss different general-purpose registers used in 8086 microprocessor.

EU has 8 general purpose registers; two registers can also be combined to form 16-bit registers. The valid register pairs are

- **AX (AL, AH):** Word multiply, word divide, word I/O
- **BX (BL, BH):** Store address information
- **CX (CL, CH):** String operation, loops
- **DX (DL, DH):** Word multiply, word divide, indirect I/O (used to hold I/O address during I/O instructions. If the result is more than 16 bits, the lower order 16 bits are stored in accumulator and higher order 6 bits are stored in DX register)

2. Explain the concept of segmented memory. What are its advantages?

Segmentation is the process in which the main memory of the computer is divided into different segments and each segment has its own base address. It is basically used to enhance the speed of execution of the computer system, so that processor is able to fetch and execute the data from the memory easily and fast.

The main advantages of segmentation memory are as follows:

- 1) It provides a powerful memory management mechanism.
- 2) Data related or stack related operations can be performed in different segments.
- 3) Code related operation can be done in separate code segments.
- 4) It allows to processes to easily share data.
- 5) It allows extending the address ability of the processor, i.e., segmentation allows the use of 16-bit registers to give an addressing capability of 1 Megabytes. Without segmentation, it would require 20-bit registers.

- 6) It is possible to enhance the memory size of code data or stack segments beyond 64 KB by allotting more than one segment for each area.

3. Explain the physical address formation in 8086.

Physical Address = Base Address * 10H + Offset

4. Write a program to add two 16 bit numbers 12H and 08H, and store the sum.

```
org 100h  
mov ax,0012h  
mov bx,0008h  
add ax,bx  
hlt
```