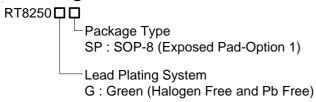


# 3A, 23V, 340kHz Synchronous Step-Down Converter

## **General Description**

The RT8250 is a high-efficiency synchronous step-down DC/DC converter that can deliver up to 3A output current from 4.5V to 23V input supply. The RT8250's current mode architecture and external compensation allow the transient response to be optimized over a wide range of loads and output capacitors. Cycle-by-cycle current limit provides protection against shorted outputs and soft-start eliminates input current surge during start-up. The RT8250 also provides output under voltage protection and thermal shutdown protection. The low current (<3 $\mu$ A) shutdown mode provides output disconnection, enabling easy power management in battery-powered systems.

## **Ordering Information**



#### Note:

Richtek products are:

- RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- ▶ Suitable for use in SnPb or Pb-free soldering processes.

## **Marking Information**



RT8250GSP: Product Number

YMDNN: Date Code

### **Features**

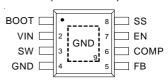
- 4.5V to 23V Input Voltage Range
- 1.5% High Accuracy Feedback Voltage
- 3A Output Current
- Integrated N-MOSFET Switches
- Current Mode Control
- Fixed Frequency Operation: 340kHz
- Output Adjustable from 0.925V to 20V
- Up to 95% Efficiency
- Programmable Soft-Start
- Stable with Low-ESR Ceramic Output Capacitors
- Cycle-by-Cycle Over Current Protection
- Input Under Voltage Lockout
- Output Under Voltage Protection
- Thermal Shutdown Protection
- Thermally Enhanced SOP-8 (Exposed Pad) Package
- RoHS Compliant and Halogen Free

## **Applications**

- Industrial and Commercial Low Power Systems
- Computer Peripherals
- LCD Monitors and TVs
- Green Electronics/Appliances
- Point of Load Regulation of High-Performance DSPs, FPGAs and ASICs.

## **Pin Configurations**

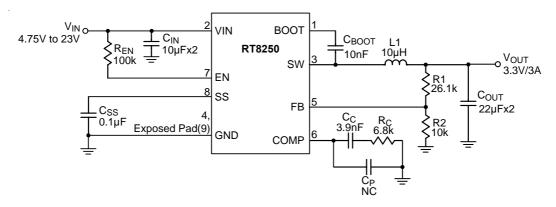




SOP-8 (Exposed Pad)



# **Typical Application Circuit**



**Table 1. Recommended Component Selection** 

Vout (V)	R1 (kΩ)	R2 (kΩ)	Rc (kΩ)	Cc (nF)	L (µH)	Соит (µF)
15	153	10	30	3.9	33	22 x 2
10	97.6	10	20	3.9	22	22 x 2
8	76.8	10	15	3.9	22	22 x 2
5	45.3	10	13	3.9	15	22 x 2
3.3	26.1	10	6.8	3.9	10	22 x 2
2.5	16.9	10	6.2	3.9	6.8	22 x 2
1.8	9.53	10	4.3	3.9	4.7	22 x 2
1.2	3	10	3	3.9	3.6	22 x 2

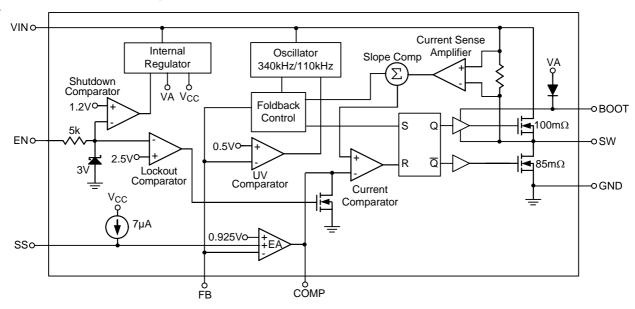
# **Functional Pin Description**

Pin No.	Pin Name	Pin Function
1	воот	Bootstrap for High Side Gate Driver. Connect a 10nF or greater ceramic capacitor from the BOOT pin to SW pin.
2	VIN	Voltage Supply Input. The input voltage range is from 4.5V to 23V. A suitable large capacitor must be bypassed with this pin.
3	SW	Switching Node. Connect the output LC filter between the SW pin and output load.
4, 9 (Exposed Pad)	GND	Ground. The exposed pad must be soldered to a large PCB and connected to GND for maximum power dissipation.
5	FB	Output Voltage Feedback Input. The feedback reference voltage is 0.925V typically.
6	COMP	Compensation Node. This pin is used for compensating the regulation control loop. A series RC network is required to be connected from COMP to GND. If it is needed, an additional capacitor should be connected from COMP to GND.
7	EN	Enable Input. A logic high enables the converter, a logic low forces the converter into shutdown mode reducing the supply current to less than $3\mu A$ . For automatic startup, connect this pin to VIN with a $100k\Omega$ pull up resistor.
8	SS	Soft-Start Control Input. The soft-start period can be set by connecting a capacitor from the SS to GND. A $0.1\mu F$ capacitor sets the soft-start period to 13ms typically.

www.richtek.com DS8250-05 March 2011



# **Function Block Diagram**



# Absolute Maximum Ratings (Note 1)

• Supply Voltage, V <sub>IN</sub>	-0.3V to 24V
Switching Voltage, SW	$-0.3V$ to $(V_{IN} + 0.3V)$
<20ns	$-0.3V$ to $(V_{IN} + 3V)$
• BOOT Voltage	$(V_{SW} - 0.3V)$ to $(V_{SW} + 6V)$
• The Other Pins	-0.3V to 6V
<ul> <li>Power Dissipation, P<sub>D</sub> @ T<sub>A</sub> = 25°C</li> </ul>	
SOP-8 (Exposed Pad)	· 1.333W
Package Thermal Resistance (Note 2)	
SOP-8 (Exposed Pad), $\theta_{JA}$	· 75°C/W
SOP-8 (Exposed Pad), $\theta_{JC}$	· 15°C/W
Junction Temperature	· 150°C
• Lead Temperature (Soldering, 10 sec.)	- 260°C
Storage Temperature Range	- −65°C to 150°C
ESD Susceptibility (Note 3)	
HBM (Human Body Mode)	· 2kV
MM (Machine Mode)	· 200V
Recommended Operating Conditions (Note 4)	
• Supply Voltage, V <sub>IN</sub>	4.5V to 23V
• Enable Voltage, V <sub>EN</sub>	0V to 5.5V
Junction Temperature Range	- −40°C to 125°C
Ambient Temperature Range	-40°C to 85°C



### **Electrical Characteristics**

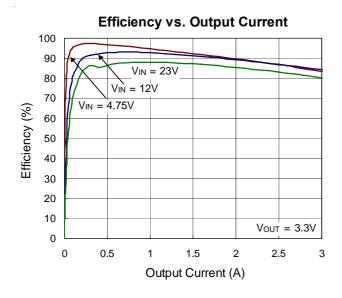
 $(V_{IN} = 12V, T_A = 25^{\circ}C \text{ unless otherwise specified})$ 

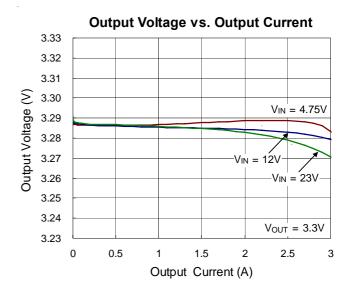
Parameter		Symbol	Test Conditions	Min	Тур	Max	Unit	
Shutdown Supply Current			V <sub>EN</sub> = 0V		0.3	3	μΑ	
Supply Current			V <sub>EN</sub> = 3 V, V <sub>FB</sub> = 1V		0.7	1.2	mA	
Feedback Voltage		V <sub>FB</sub>	$4.75 V \leq V_{IN} \leq 23 V$	0.911	0.925	0.939	V	
Error Amplifier Tra	nsconductance	GEA	$\Delta IC = \pm 10 \mu A$		1250		μΑΛ	
High-Side Switch	On-Resistance	R <sub>DS(ON)1</sub>			100		mΩ	
Low-Side Switch C	On-Resistance	R <sub>DS(ON)2</sub>			85		mΩ	
High-Side Switch	Leakage Current		$V_{EN} = 0V, V_{SW} = 0V$		0	10	μΑ	
Upper Switch Current Limit			Min. Duty Cycle V <sub>BOOT</sub> – V <sub>SW</sub> = 4.8V		5.5	-	Α	
Lower Switch Curi	rent Limit		From Drain to Source		1.4	-	Α	
COMP to Current Sense Transconductance		G <sub>CS</sub>			5.2	-	ΑN	
Oscillation Frequency		f <sub>OSC1</sub>		300	340	380	kHz	
Short Circuit Oscillation Frequency		f <sub>OSC2</sub>	$V_{FB} = 0V$		110		kHz	
Maximum Duty Cy	<i>r</i> cle	D <sub>MAX</sub>	$V_{FB} = 0.8V$		90	-	%	
Minimum On Time		t <sub>ON</sub>			200	-	ns	
EN Threshold	Logic-High	V <sub>IH</sub>		2.7			V	
Voltage	Logic-Low	VIL				0.4	]	
Input Under Voltage Lockout Threshold			V <sub>IN</sub> Rising	3.8	4.2	4.4	٧	
Input Under Voltage Lockout Threshold Hysterisis					200		mV	
Soft-Start Current			V <sub>SS</sub> = 0V		7	-	μΑ	
Soft-Start Period			$C_{SS} = 0.1 \mu F$		13	-	ms	
Thermal Shutdown		T <sub>SD</sub>			150		°C	

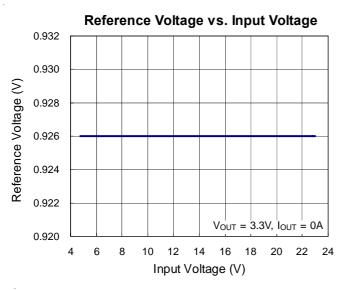
- **Note 1.** Stresses listed as the above "Absolute Maximum Ratings" may cause permanent damage to the device. These are for stress ratings. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may remain possibility to affect device reliability.
- Note 2.  $\theta_{JA}$  is measured in the natural convection at  $T_A = 25^{\circ}C$  on a high effective thermal conductivity four-layer test board of JEDEC 51-7 thermal measurement standard. The case position of  $\theta_{JC}$  is on the exposed pad of the package.
- Note 3. Devices are ESD sensitive. Handling precaution is recommended.
- Note 4. The device is not guaranteed to function outside its operating conditions.

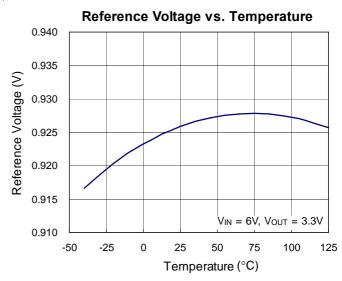


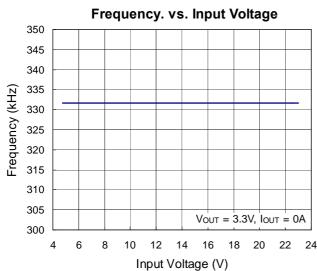
## **Typical Operating Characteristics**

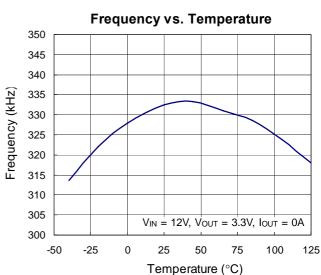




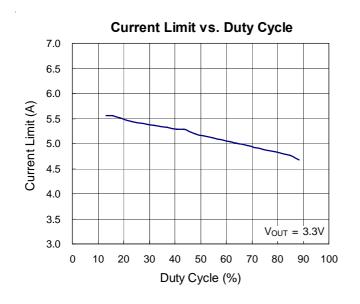


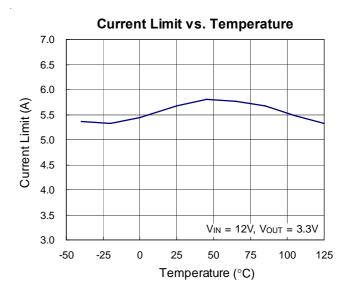


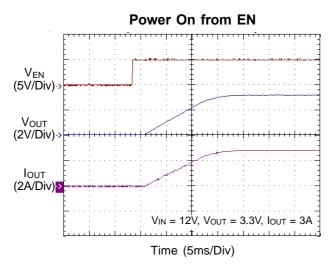


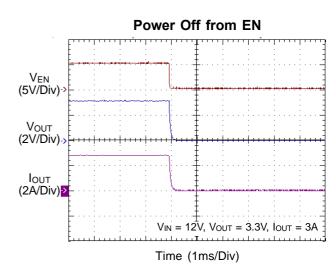


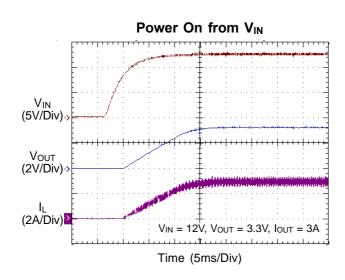


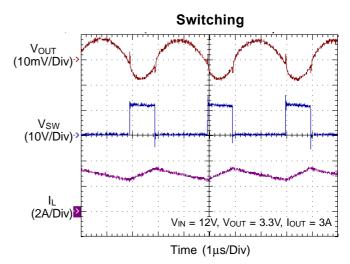




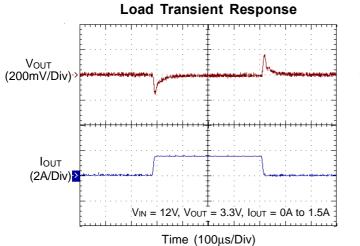


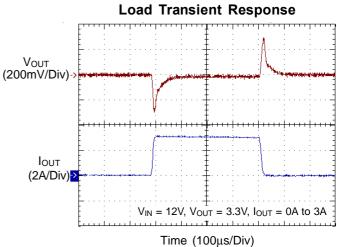














## **Application Information**

The RT8250 is a synchronous high voltage buck converter that can support the input voltage range from 4.5V to 23V and the output current can be up to 3A.

### **Output Voltage Setting**

The resistive divider allows the FB pin to sense the output voltage as shown in Figure 1.

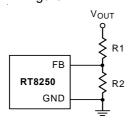


Figure 1. Output Voltage Setting

The output voltage is set by an external resistive divider according to the following equation:

$$V_{OUT} = V_{FB} \left( 1 + \frac{R1}{R2} \right)$$

Where  $V_{FB}$  is the feedback reference voltage (0.925V typ.).

#### **External Bootstrap Diode**

Connect a 10nF low ESR ceramic capacitor between the BOOT pin and SW pin. This capacitor provides the gate driver voltage for the high side MOSFET.

It is recommended to add an external bootstrap diode between an external 5V and the BOOT pin for efficiency improvement when input voltage is lower than 5.5V or duty ratio is higher than 65%. The bootstrap diode can be a low cost one such as 1N4148 or BAT54.

The external 5V can be a 5V fixed input from system or a 5V output of the RT8250. Note that the external boot voltage must be lower than 5.5V.

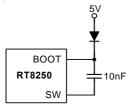


Figure 2. External Bootstrap Diode

### Soft-Start

The RT8250 contains an external soft-start clamp that gradually raises the output voltage. The soft-start timming

can be programed by the external capacitor between SS pin and GND. The chip provides a  $7\mu$ A charge current for the external capacitor. If a  $0.1\mu$ F capacitor is used to set the soft-start and its period will be 13ms(typ.).

#### **Inductor Selection**

The inductor value and operating frequency determine the ripple current according to a specific input and output voltage. The ripple current  $\Delta I_L$  increases with higher  $V_{IN}$  and decreases with higher inductance.

$$\Delta I_{L} = \left[ \frac{V_{OUT}}{f \times L} \right] \times \left[ 1 - \frac{V_{OUT}}{V_{IN}} \right]$$

Having a lower ripple current reduces not only the ESR losses in the output capacitors but also the output voltage ripple. High frequency with small ripple current can achieve highest efficiency operation. However, it requires a large inductor to achieve this goal.

For the ripple current selection, the value of  $\Delta I_L = 0.2375(I_{MAX})$  will be a reasonable starting point. The largest ripple current occurs at the highest  $V_{IN}$ . To guarantee that the ripple current stays below the specified maximum, the inductor value should be chosen according to the following equation :

$$L = \left[\frac{V_{OUT}}{f \times \Delta I_{L(MAX)}}\right] \times \left[1 - \frac{V_{OUT}}{V_{IN(MAX)}}\right]$$

### **Inductor Core Selection**

The inductor type must be selected once the value for L is known. Generally speaking, high efficiency converters can not afford the core loss found in low cost powdered iron cores. So, the more expensive ferrite or mollypermalloy cores will be a better choice.

The selected inductance rather than the core size for a fixed inductor value is the key for actual core loss. As the inductance increases, core losses decrease. Unfortunately, increase of the inductance requires more turns of wire and therefore the copper losses will increase.

Ferrite designs are preferred at high switching frequency due to the characteristics of very low core losses. So, design goals can focus on the reduction of copper loss and the saturation prevention. Ferrite core material saturates "hard", which means that inductance collapses abruptly when the peak design current is exceeded. The previous situation results in an abrupt increase in inductor ripple current and consequent output voltage ripple.

Do not allow the core to saturate!

Different core materials and shapes will change the size/ current and price/current relationship of an inductor.

Toroid or shielded pot cores in ferrite or permalloy materials are small and do not radiate energy. However, they are usually more expensive than the similar powdered iron inductors. The rule for inductor choice mainly depends on the price vs. size requirement and any radiated field/ EMI requirements.

### CIN and COUT Selection

The input capacitance,  $C_{IN}$ , is needed to filter the trapezoidal current at the source of the high side MOSFET. To prevent large ripple current, a low ESR input capacitor sized for the maximum RMS current should be used. The RMS current is given by:

$$I_{RMS} = I_{OUT(MAX)} \frac{V_{OUT}}{V_{IN}} \sqrt{\frac{V_{IN}}{V_{OUT}}} - 1$$

This formula has a maximum at  $V_{IN} = 2V_{OUT}$ , where  $I_{RMS} = I_{OUT}/2$ . This simple worst-case condition is commonly used for design because even significant deviations do not offer much relief.

Choose a capacitor rated at a higher temperature than required. Several capacitors may also be paralleled to meet size or height requirements in the design.

For the input capacitor, a  $10\mu F$  x 2 low ESR ceramic capacitor is recommended. For the recommended capacitor, please refer to table 3 for more detail.

The selection of  $C_{\text{OUT}}$  is determined by the required ESR to minimize voltage ripple.

Moreover, the amount of bulk capacitance is also a key for  $C_{\text{OUT}}$  selection to ensure that the control loop is stable. Loop stability can be checked by viewing the load transient response as described in a later section.

The output ripple,  $\Delta V_{OUT}$ , is determined by :

$$\Delta V_{OUT} \le \Delta I_L \left[ ESR + \frac{1}{8fC_{OUT}} \right]$$

The output ripple will be highest at the maximum input voltage since ΔI<sub>L</sub> increases with input voltage. Multiple capacitors placed in parallel may be needed to meet the ESR and RMS current handling requirement. Dry tantalum, special polymer, aluminum electrolytic and ceramic capacitors are all available in surface mount packages. Special polymer capacitors offer very low ESR value. However, it provides lower capacitance density than other types. Although Tantalum capacitors have the highest capacitance density, it is important to only use types that pass the surge test for use in switching power supplies. Aluminum electrolytic capacitors have significantly higher ESR. However, it can be used in cost-sensitive applications for ripple current rating and long term reliability considerations. Ceramic capacitors have excellent low ESR characteristics but can have a high voltage coefficient and audible piezoelectric effects. The high Q of ceramic capacitors with trace inductance can also lead to significant ringing.

Higher values, lower cost ceramic capacitors are now becoming available in smaller case sizes. Their high ripple current, high voltage rating and low ESR make them ideal for switching regulator applications. However, care must be taken when these capacitors are used at input and output. When a ceramic capacitor is used at the input and the power is supplied by a wall adapter through long wires, a load step at the output can induce ringing at the input,  $V_{\text{IN}}$ . At best, this ringing can couple to the output and be mistaken as loop instability. At worst, a sudden inrush of current through the long wires can potentially cause a voltage spike at  $V_{\text{IN}}$  large enough to damage the part.

#### **Checking Transient Response**

The regulator loop response can be checked by looking at the load transient response. Switching regulators take several cycles to respond to a step in load current. When a load step occurs,  $V_{OUT}$  immediately shifts by an amount equal to  $\Delta I_{LOAD}$  (ESR) also begins to charge or discharge  $C_{OUT}$  generating a feedback error signal for the regulator to return  $V_{OUT}$  to its steady-state value. During this recovery time,  $V_{OUT}$  can be monitored for overshoot or ringing that would indicate a stability problem.



#### **Thermal Considerations**

For continuous operation, do not exceed the maximum operation junction temperature 125°C. The maximum power dissipation depends on the thermal resistance of IC package, PCB layout, the rate of surroundings airflow and temperature difference between junction to ambient. The maximum power dissipation can be calculated by following formula:

$$P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$$

Where  $T_{J(MAX)}$  is the maximum operation junction temperature,  $T_A$  is the ambient temperature and the  $\theta_{JA}$  is the junction to ambient thermal resistance.

For recommended operating conditions specification of RT8250, the maximum junction temperature is 125°C. The junction to ambient thermal resistance  $\theta_{JA}$  is layout dependent. For PSOP-8 package, the thermal resistance  $\theta_{JA}$  is 75°C/W on the standard JEDEC 51-7 four-layers thermal test board. The maximum power dissipation at  $T_A$  = 25°C can be calculated by following formula:

$$P_{D(MAX)} = (125^{\circ}C - 25^{\circ}C) / (75^{\circ}C/W) = 1.333W$$
 for PSOP-8 package

The maximum power dissipation depends on operating ambient temperature for fixed  $T_{J(MAX)}$  and thermal resistance  $\theta_{JA}$ . For RT8250 package, the Figure 3 of derating curve allows the designer to see the effect of rising ambient temperature on the maximum power dissipation allowed.

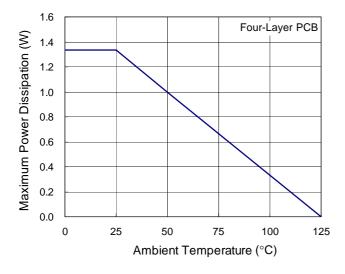


Figure 3. Derating Curve for RT8250 Package

### **Layout Consideration**

Follow the PCB layout guidelines for optimal performance of the RT8250.

- Keep the traces of the main current paths as short and wide as possible.
- Put the input capacitor as close as possible to the device pins (VIN and GND).
- SW node is with high frequency voltage swing and should be kept at small area. Keep sensitive components away from the SW node to prevent stray capacitive noise pick-up.
- Place the feedback components to the FB pin and COMP pin as close as possible.
- The GND pin and Exposed Pad should be connected to a strong ground plane for heat sinking and noise protection.

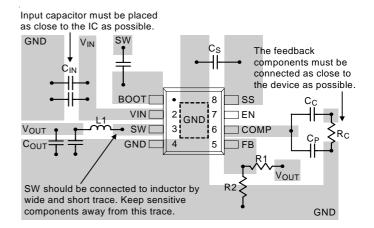


Figure 4. PCB Layout Guide



**Table 2. Suggested Inductors for Typical Application Circuit** 

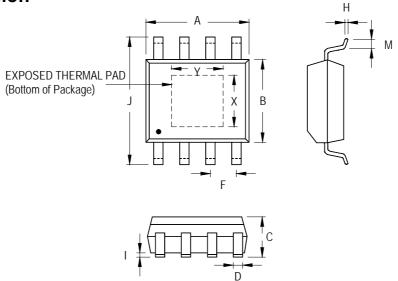
Component Supplier	Series	Dimensions (mm)		
TDK	VLF10045	10 x 9.7 x 4.5		
TAIYO YUDEN	NR8040	8x8x4		

Table 3. Suggested Capacitors for  $C_{\text{IN}}$  and  $C_{\text{OUT}}$ 

Component Supplier	Part No.	Capacitance (µF)	Case Size	
MURATA	GRM31CR61E106K	10	1206	
TDK	C3225X5R1E106K	10	1206	
TAIYO YUDEN	TMK316BJ106ML	10	1206	
MURATA	GRM31CR60J476M 47		1206	
TDK	C3225X5R0J476M 47		1210	
TAIYO YUDEN	EMK325BJ476MM	47	1210	
MURATA	GRM32ER71C226M	22	1210	
TDK	C3225X5R1C226M	22	1210	



### **Outline Dimension**



Symbol		Dimensions In Millimeters		Dimensions In Inches		
		Min	Max	Min	Max	
А		4.801	5.004	0.189	0.197	
В		3.810	4.000	0.150	0.157	
С		1.346	1.753	0.053	0.069	
D		0.330	0.510	0.013	0.020	
F		1.194	1.346	0.047	0.053	
Н		0.170	0.254	0.007	0.010	
I		0.000	0.152	0.000	0.006	
J		5.791	6.200	0.228	0.244	
М		0.406	1.270	0.016	0.050	
Ontion 1	Χ	2.000	2.300	0.079	0.091	
Option 1	Υ	2.000	2.300	0.079	0.091	
Option 2	Χ	2.100	2.500	0.083	0.098	
	Υ	3.000	3.500	0.118	0.138	

8-Lead SOP (Exposed Pad) Plastic Package

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