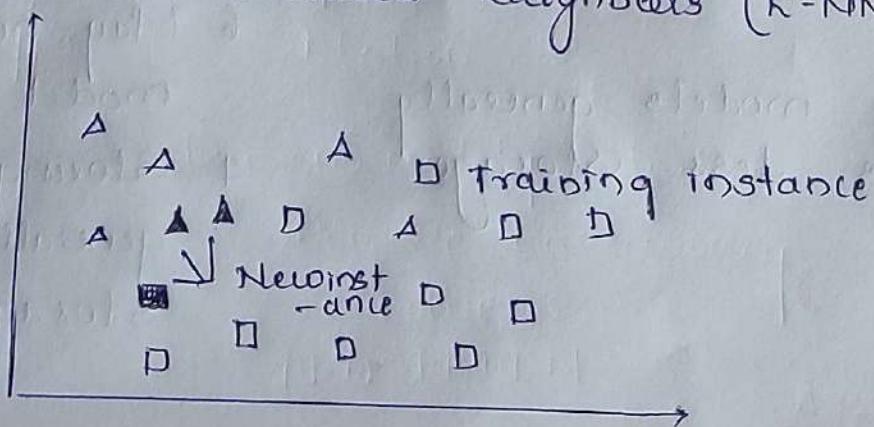


* Instance Based Model Based learning

I. Instance based learning: →
(Memorizing)

It stores training examples & uses them to compare new data points

It follows K-Nearest Neighbors (K-NN)



- Model Based learning →
Builds a generalized model from the data to make predictions.



* Difference -

Model

1. prepare the data for model training
2. Train model from training data to estimate model parameters i.e. discover patterns
3. Store the model in suitable form
4. Generalize the rules in form of model even before scoring instance using model
5. predict for unseen scoring instance using model
6. Requires a known model form
7. Storing models generally requires less storage.

Instance

1. prepare the data for model training. No difference here.
2. Do not train model. patterns discovered postponed until scoring query received.
3. There is no model to store.
4. No generalization before scoring. Only generalize for each scoring instance individually as & when seen
5. predict for unseen scoring instance using training data directly
6. May not have explicit model form
7. Storing training data generally requires more storage.

* challenges in Machine learning:-

1. Data Collection
2. Insufficient data / labelled data
3. Non-representative data
 - Sampling Noise
 - Sampling Bias
4. poor Quality data
5. Irrelevant features
6. Overfitting
7. Underfitting
8. Software Integration
9. offline learning
10. Cost involved

* Machine learning Development lifecycle:-

1. Framing the problem
Data collection, Algorithm
2. Gathering data
Kaggle, CSV, API
3. Data preprocessing
Clean the data
4. Exploratory data Analysis (EDA)
univariate / Bivariate
5. Feature Engineering & Selection
6. Model training Evaluation & Selection
7. Model deployment
8. Testing
9. Optimize

* Tensor

- It is a container that stores number in multiple dimensions

0D Tensor / Scalar →

Holds one number, no dimensions
Scalar size is always = 1

2. 1D Tensor / Vector →

$[1, 2, 3, 4]$ → vector / 1D array / array / 1D tensor

3. 2D Tensor / Matrices →

$[1, 2, 3] \ [4, 5, 6] \ [7, 8, 9]$

$\downarrow \begin{bmatrix} [1, 2, 3] \\ [4, 5, 6] \\ [7, 8, 9] \end{bmatrix}$ → 2D

Rank = 2 = ndim

mat = np.array([$[1, 2, 3]$, $[4, 5, 6]$, $[7, 8, 9]$])
mat

O/P = array($\begin{bmatrix} [1, 2, 3], \\ [4, 5, 6], \\ [7, 8, 9] \end{bmatrix}$)

mat.ndim

0D => import numpy as np

arr = np.array([1])

arr

O/P array([1])

arr.ndim

1

1D =>

arr = np.array([$[1, 2, 3]$,
 $[4, 5, 6]$, $[7, 8, 9]$])

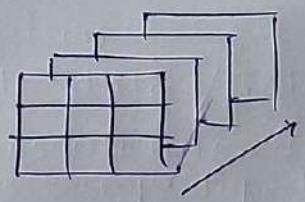
arr

O/P = array($\begin{bmatrix} [1, 2, 3], \\ [4, 5, 6], \\ [7, 8, 9] \end{bmatrix}$)

arr.ndim

2

4) ND tensors : →



$4 \times 3 \times 3$

• 1D-tensor

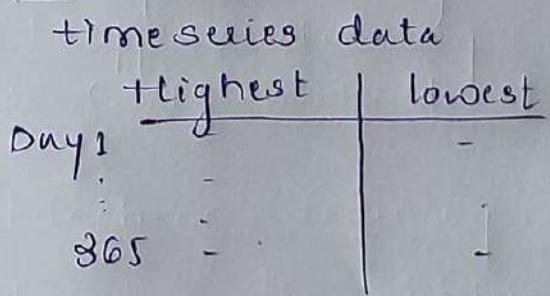
$$[81, 91, 0] \rightarrow 1D$$

↳ Vector

• 2D-tensor

$$\left[\begin{array}{ccc} - & - & - \\ - & - & - \\ \dots & \dots & \dots \end{array} \right] \left[\begin{array}{c} \\ \\ \end{array} \right] \rightarrow 1D$$

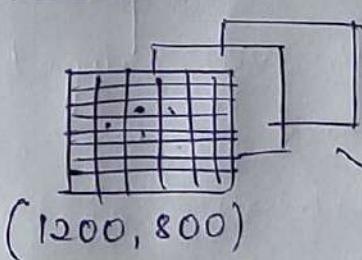
• 3D-tensor



+ radius.
[365, 2]

↳ 10 yrs = [10, 365, 2]
↳ 3D

• 4D-tensor



(3, 1200, 800) \curvearrowright 3D

If I require 50 color images
(50, 3, 1200, 800)

• 5D-tensor

Videos

60 sec \rightarrow 4 videos



30 fps

↳ 480p \rightarrow 480 x 720 (3 channels)

(4, 1800, 480, 720, 3)

↳ 5D