

WeAct Studio

WEACT-N002

载板/底板

使用教程



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WeAct Studio

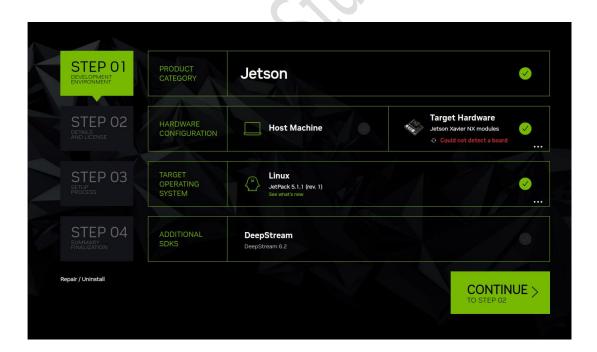
REVISION HISTORY

Draft Date	Revision	Description	
2023.07.16	V1.0	1. 初始版本	



1. 搭建烧写环境

- a) 首先,需要一台装有 **Ubuntu16.04** 以上的电脑作为 HOST 端给 Nano/NX 烧写,或者可以在 Windows 上安装 VMware 来实现。
 - VMware 上如何安装 Ubuntu18.04: https://blog.csdn.net/u012556114/article/details/82751089
- b) 在 NVIDIA 下载最新的 **SDK-Manager** 并在 ubuntu18.04 中安装 (需要注册一个 NVIDIA 账号,后面也需要用到)
 - > SDK-Manager 下载地址: https://developer.nvidia.com/nvidia-sdk-manager
- c) 选择需要 Target Hardware 以及 JetPack 版本,不勾选 HostMachine(节省主机存储空间),DeepStream 根据组件需求勾选,这里以 XavierNX(Orin 系列请看第二张图)为例选择,点击 Continue







Orin Nano/NX 请选择 OrinNX 最新 Jetpack 系统(通用)。

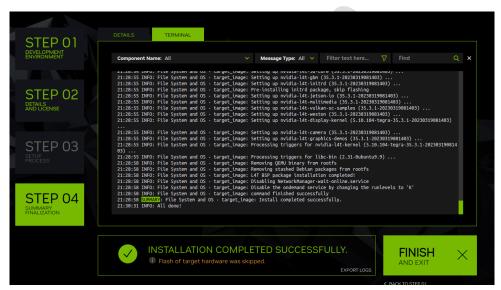
d) 这里需要勾选 I accept the terms and conditions of the license agreements, 取 消勾选 Jetson Runtime/SDK Components (后面安装组件会重新下载并一起安装), 点击 CONTINUE 进行下一步。



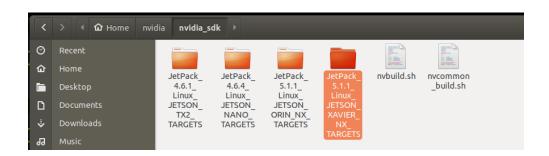
e) P.S: 请在畅通的网络环境下进行下载以及安装,下载或安装失败时,可点击 Retry 继续,直至全部状态为 Installed 并且显示绿色,安装过程中会弹出联网烧写的信息,选择 Skip。(后续步骤通过命令来烧写,可以兼容不同核心板)







f) 安装成功后,会在~/nvidia/nvidia_sdk/下有相应版本烧写所需的文件



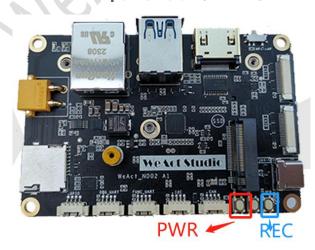
g) 在终端通过 sudo apt-get install python 安装 python 支持以便后续烧写环境。

2. 核心板烧写系统 (以 XAVIERNX 为例)

1. 使用 USB Type-C 线连接载板上的 USB OTG 接口



- 2. 将开机键**拨至 MP (手动开机)** , 两种方式进入 Recovery 模式
 - a) 按住 REC 键,再按一下 PWR 键开机,松开 REC 键进入 Recovery 模式
 - b) 按一下 PWR 开机,按住 REC 键,按一下 RST 键进入 Recovery 模式 此时 VMWare 右下角会出现 NVIDIA 的 USB 驱动标志,或者打开终端,输入 Isusb 命令,会发现 Nvidia Corp,同时风扇转速会到达最大。



```
XAVIER_NX_TARGETS/Linux_for_Tegra$ lsusb

Bus 004 Device 001: ID 1d6b:0003 Linux Foundation 3.0 root hub

Bus 003 Device 004: ID 0e0f:0002 VMware, Inc. Virtual USB Hub

Bus 003 Device 003: ID 0e0f:0002 VMware, Inc. Virtual USB Hub

Bus 003 Device 006: ID 0955:7e19 NVidia Corp.

Bus 003 Device 002: ID 0e0f:0003 VMware, Inc. Virtual Mouse

Bus 003 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub

Bus 001 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub

Bus 002 Device 002: ID 0e0f:0002 VMware, Inc. Virtual USB Hub

Bus 002 Device 001: ID 1d6b:0001 Linux Foundation 1.1 root hub
```

3. Orin 系列核心板需要修改该项,并且需要插入 SSD

- a) 修改该文件 Linux_for_Tegra/bootloader/t186ref/BCT/tegra234-mb2-bct-misc-p3767-0000.dts
- b)—删除: cvb_eeprom_read_size = <0x100> 增加: cvb_eeprom_read_size = <0x0>
- 4. 进入~/nvidia/nvidia_sdk/JetPack_5.1.1_Linux_JETSON_XAVIER_NX_TARGE TS/Linux_for_Tegra, 打开终端:
 - a) sudo ./flash.sh jetson-xavier-nx-devkit-emmc mmcblk0p1

等烧录成功就可以使用了,其他设备命令请参考下面表格。

各设备刷机命令

设备	刷机命令
Nano-SD (核心板带 SD 卡槽)	sudo ./flash.sh jetson-nano-qspi-sd mmcblk0p1
Nano-EMMC	sudo ./flash.sh jetson-nano-emmc mmcblk0p1
TX2-NX	sudo ./flash.sh jetson-xavier-nx-devkit-tx2-nx mmcblk0p1
Xavier-SD (核心板带 SD 卡槽)	sudo ./flash.sh jetson-xavier-nx-devkit-qspi mmcblk0p1
Xavier-EMMC	sudo ./flash.sh jetson-xavier-nx-devkit-emmc mmcblk0p1
Orin Nano 4GB	1. sudo BOARDID=3767 BOARDSKU=0004 ./tools/kernel_flash/l4t_initrd_flash.shno-flashexternal-device nvme0n1p1 -p "-c bootloader/t186ref/cfg/flash_t234_qspi.xmlno- systemimg" - c ./tools/kernel_flash/flash_l4t_external.xmlmassflash 5showlogsnetwork usb0 p3768-0000+p3767-0000 nvme0n1p1

	2. sudo ./tools/kernel_flash/l4t_initrd_flash.shflash-onlynetwork usb0massflash 5showlogs
Orin Nano 8GB	 sudo BOARDID=3767 BOARDSKU=0003 ./tools/kernel_flash/l4t_initrd_flash.shno-flashexternal-device nvme0n1p1 -p "-c bootloader/t186ref/cfg/flash_t234_qspi.xmlno- systemimg" - c ./tools/kernel_flash/flash_l4t_external.xmlmassflash 5showlogsnetwork usb0 p3768-0000+p3767-0000 nvme0n1p1 sudo ./tools/kernel_flash/l4t_initrd_flash.shflash-onlynetwork usb0massflash 5showlogs
Orin NX 8GB	 sudo BOARDID=3767 BOARDSKU=0001 ./tools/kernel_flash/l4t_initrd_flash.shno-flashexternal-device nvme0n1p1 -p "-c bootloader/t186ref/cfg/flash_t234_qspi.xmlno- systemimg" - c ./tools/kernel_flash/flash_l4t_external.xmlmassflash 5showlogsnetwork usb0 p3768-0000+p3767-0000 nvme0n1p1 sudo ./tools/kernel_flash/l4t_initrd_flash.shflash-onlynetwork usb0massflash 5showlogs
Orin NX 16GB	 sudo BOARDID=3767 BOARDSKU=0000 ./tools/kernel_flash/l4t_initrd_flash.shno-flashexternal-device nvme0n1p1 -p "-c bootloader/t186ref/cfg/flash_t234_qspi.xmlno- systemimg" - c ./tools/kernel_flash/flash_l4t_external.xmlmassflash

- 5 --showlogs --network usb0 p3768-0000+p3767-0000 nvme0n1p1
- sudo ./tools/kernel_flash/l4t_initrd_flash.sh --flash-only
 --network usb0 --massflash 5 --showlogs

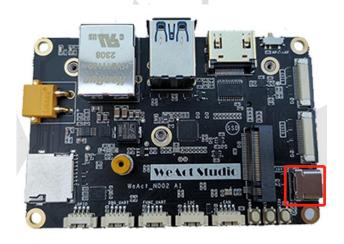
烧写系统成功后会有 Successfully!显示,如下图所示。

3. 核心板更新设备树 (以 XAVIERNX 为例)

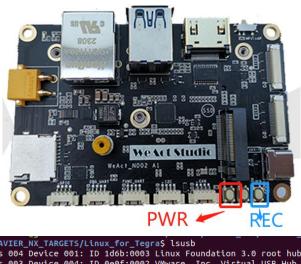
WeAct 设备树可开启的功能

	WeAct Studio
Nano-SD	无需更新
Nano-EMMC	可以使用 SD 卡
TX2NX	可以使用 SD 卡
XavierNX	可以使用 SD 卡
Orin Nano/NX	无需更新

1. 使用 USB Type-C 线连接载板上的 USB OTG 接口



- 2. 将开机键**拨至 MP (手动开机)** , 两种方式进入 Recovery 模式
 - a) 按住 REC 键,再按一下 PWR 键开机,松开 REC 键进入 Recovery 模式
 - b) 按一下 PWR 开机,按住 REC 键,按一下 RST 键进入 Recovery 模式 此时 VMWare 右下角会出现 NVIDIA 的 USB 驱动标志,或者打开终端,输入 Isusb 命令,会发现 Nvidia Corp,同时风扇转速会到达最大。



```
_XAVIER_NX_TARGETS/Linux_for_Tegra$ lsusb

Bus 004 Device 001: ID 1d6b:0003 Linux Foundation 3.0 root hub

Bus 003 Device 004: ID 0e0f:0002 VMware, Inc. Virtual USB Hub

Bus 003 Device 003: ID 0e0f:0002 VMware, Inc. Virtual USB Hub

3us 003 Device 006: ID 0955:7e19 NVidia Corp.

Bus 003 Device 002: ID 0e0f:0003 VMware, Inc. Virtual Mouse

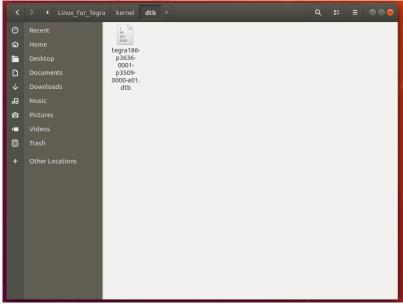
Bus 003 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub

Bus 001 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub

Bus 002 Device 002: ID 0e0f:0002 VMware, Inc. Virtual USB Hub

Bus 002 Device 001: ID 1d6b:0001 Linux Foundation 1.1 root hub
```

- 3. Jetpack 4.x 版本更新设备树(Jetson Nano/TX2NX),以 TX2NX 为例
- a) 找到相应版本的设备树
- b) 进入~/nvidia/nvidia_sdk/JetPack_4.6_Linux_JETSON_TX2_TARGETS/Linux_for_Tegra/kernel/dtb, 复制提供的设备树 tegra186-p3636-0001-p35 09-0000-a01.dtb 至该目录



- c) 进入~/nvidia/nvidia_sdk/JetPack_4.6_Linux_JETSON_TX2_TARGETS/Linux_for Tegra, 打开终端:
- d) 命令 **sudo** ./**flash.sh** -**r** -**k** kernel-dtb jetson-xavier-nx-devkit-tx2-nx mmcblk0p1,其他核心板请参考下图表格:

各设备更新设备树命令

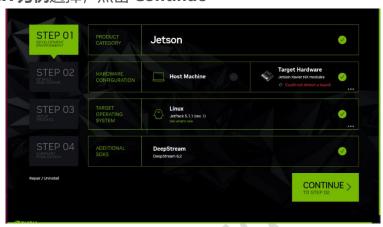
设备	设备树更新命令
Nano- SD	sudo ./flash.sh -r -k DTB jetson-nano-qspi-sd mmcblk0p1
Nano- EMMC	sudo ./flash.sh -r -k DTB jetson-nano-emmc mmcblk0p1
TX2- NX	sudo ./flash.sh -r -k kernel-dtb jetson-xavier-nx-devkit-tx2-nx mmcblk0p1

4. Jetpack 5.x 版本更新设备树 (Jetson XavierNX)

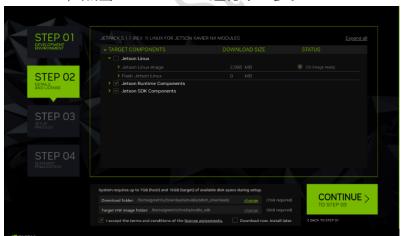
- e) 按一下 PWR 直接开机
- f) 将 git 对应的设备树拷入设备系统桌面(kernel_tegra194-p3668-0001-p3509-0000.dtb)
- g) 在桌面右键, 打开终端
- h) 输入命令: sudo rm /boot/dtb/kernel_tegra194-p3668-0001-p3509-0000.dtb
- i) 输入命令: sudo cp kernel_tegra194-p3668-0001-p3509-0000.dtb /boot/dtb
- j) 重启系统即可

3. 安装 NVIDIA 组件

选择需要 Target Hardware 以及 JetPack 版本,不勾选 HostMachine,这里以 XavierNX 为例选择,点击 Continue



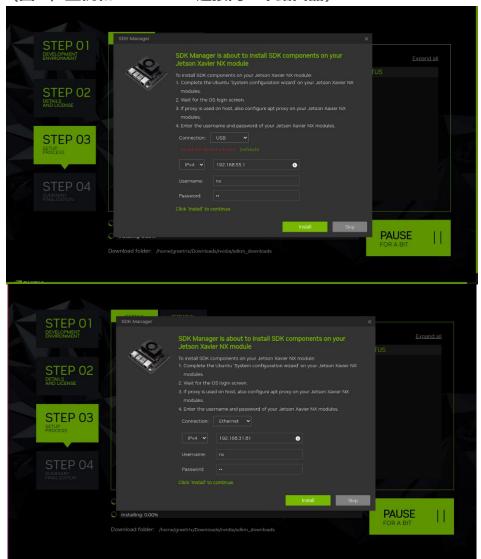
2. 勾选所需要 SDK 组件,勾选 I accept the terms and conditions of the license agreements,点击 CONTINUE 进行下一步。



3. 使用 USB Type-C 线连接载板上的 USB OTG 接口。



- 4. 将开机键**拨至 MP(手动开机)**,按一下 **PWR** 键开机,此时 VMWare 右下角会出现 **NVIDIA 的 USB 驱动标志**,或者打开终端,输入 **Isusb** 命令,会发现 **Nvidia Corp**。
- 5. 输入 XavierNX 账号密码,XavierNX 端请保持联网状态,也可以用同局域网下的 IP (图 2, 主机和 XavierNX 连接同一个路由器)



6. 等待安装完成即可。

4. 环境备份及镜像烧写

1. 系统安装在 EMMC, 以 TX2NX 为例

- a) 参考**第2章**,无论备份还是镜像烧写,进入 Recovery 模式,注意镜像较大,请保证 Ubuntu 有充足的空间(>40G)。
- b) **备份**: 这里以 TX2NX 为例(其他设备参考上章内容修改 jetson 名称),对核心板现有环境进行备份。进入~/nvidia/nvidia_sdk/JetPack_4.6_Linux_JETSON_TX 2 TARGETS/Linux for Tegra,打开终端:

使用镜像备份命令: sudo ./flash.sh -r -k APP -G backup.img jetson-xavier-nx -devkit-tx2-nx mmcblk0p1,等待备份完成即可,此时目录下会有 backup.img 的镜像(建议复制一份至其他位置备份),此时**备份已经成功**。

greetrix@greetrix-virtual-machine:~/nvidia/nvidia_sdk/JetPack_4.6_Linux_JETSON_T
X2_TARGETS/Linux_for_Tegra\$ sudo ./flash.sh -r -k APP -G backup.img jetson-xavie
r-nx-devkit-tx2-nx mmcblk0p1

```
tegrarcm v2 --boot recovery
    9.1920
               Applet version 01.00.0000
    9.1966
    9.3692
   10.3763
               tegrarcm v2 --isapplet
   10.3793
             USB communication failed.Check if device is in recovery
   10.5068
   10.8536 ] tegradevflash_v2 --iscpubl
   10.8565 ] Cannot Open USB
   11.3572 ]
   12.3617 ] tegrarcm_v2 --isapplet
   12.5109
   12.5142 ] tegradevflash_v2 --iscpubl
   12.5163 ] Bootloader version 01.00.0000
   12.6843 ] Bootloader version 01.00.0000
   12.7463
  12.7464 ] Reading partition
12.7492 ] tegradevflash_v2 --read APP /home/greetrix/nvidia/nvidia_sdk/JetPac
4.6_Linux_JETSON_TX2_TARGETS/Linux_for_Tegra/backup.img
12.7511 ] Bootloader version 01.00.0000
   12.9183 ] [.....
[ 2216.5426 ]
*** The [APP] has been read successfully. ***
         Converting RAW image_to Sparse image... greetrix@greetrix-virtual-machin
X2 TARGETS/Linux_for_TegraS 🖟 4.6 Linux_JETSON_TX
```

c) **镜像烧写**: 进入~/nvidia/nvidia_sdk/JetPack_4.6_Linux_JETSON_TX2_TAR GETS/Linux_for_Tegra, 将备份好的 backup.img 拷入 Liunx_for_Tegra/bootloade r/下, 并重命名为 system.img, 回到 Linux_for_Tegra 目录下, 打开终端:

使用已有镜像烧写命令: sudo ./flash.sh -r jetson-xavier-nx-devkit-tx2-nx mmcb lk0p1, 等待烧写完成即可。

```
18.0000 ] Writing partition spe-fw_b with spe_sigheader.bin.encrypt
 18.0790 ] Writing partition mb2 with nvtboot_sigheader.bin.encrypt
 18.1596 ] Writing partition mb2_b with nvtboot_sigheader.bin.encrypt
 18.1895 ] [.....] 100%
 18.2416 ] Writing partition mts-preboot with preboot_d15_prod_cr_sigheader.bi
n.encrypt
 18.2710 ] [.....] 100%
 18.6760 ] Writing partition mts-preboot b with preboot d15 prod cr sigheader.
bin.encrypt
 18.7053 ] [......] 100%
18.7467 ] Writing partition SMD with slot_metadata.bin
 18.9037 ] Writing partition SMD_b with slot_metadata.bin
 18.9658 ] Writing partition VER_b with emmc_bootblob_ver.txt
 18.9922 ] [.....] 100%
 19.0322 ] Writing partition VER with emmc_bootblob_ver.txt
 19.0966 ] Writing partition master_boot_record with mbr_1_3.bin
 19.1194 ] [......] 100%
19.1525 ] Writing partition APP with system.img
 19.1800 ] [......
```

```
ct.encrypt
1888.6372 | Bootloader version 01.00.0000
 1888.8013 Writing partition MB1_BCT with mb1_cold_boot_bct_MB1_sigheader.bd
.encrvpt
1888.8706
 1888.8837 ] tegradevflash_v2 --write MB1_BCT_b mb1_cold_boot_bct_MB1_sighead
.bct.encrypt
1888.8849 ] Bootloader version 01.00.0000
 1889.0452 Writing partition MB1_BCT_b with mb1_cold_boot_bct_MB1_sigheader
ct.encrypt
1889.1180
 1889.1181 ] Flashing completed
1889.1181 ] Coldbooting the device
 1889.1436 ] tegradevflash_v2 --reboot coldboot
 1889.1449 ] Bootloader version 01.00.0000
1889.3379 ]
** The target t186ref has been flashed successfully. ***
Reset the board to boot from internal eMMC.
```

2. 系统安装在 SD 卡或者 SSD 的设备,直接通过主机拷贝 SD 卡或者 SSD 到其他存储介质即可



5. 系统迁移至 NVME 固态硬盘

P.S: 该迁移仅用于 Nano/TX2NX/XavierNX, Orin 系列插上 SSD, 直接通过第二章命令 烧录即可

- a) WeAct-N002 载板支持 PCIE3.0 X 4 插槽 , 支持 2242 NVME SSD M.2 接口固态硬盘,
- b) NVME 固态硬盘配置:
 - ▶ 1. 配置前确保系统能识别到 NVME 固态硬盘,终端命令: sudo fdisk -lu

Disk /dev/nvme0n1: 119.2 GiB, 128035676160 bytes, 250069680 sectors
Units: sectors of 1 * 512 = 512 bytes
Sector size (logical/physical): 512 bytes / 512 bytes
I/O size (minimum/optimal): 512 bytes / 512 bytes
Disklabel type: gpt

- 2. 将 NVME 设置成 GPT 格式:
 - i. 终端命令: sudo parted /dev/nvme0n1 进入 parted

tx2nx@tx2nx:~\$ sudo parted /dev/nvme0n1
[sudo] password for tx2nx:
GNU Parted 3.2
Using /dev/nvme0n1
Welcome to GNU Parted! Type 'help' to view a list of commands.
(parted)

ii. 终端命令: mklabel gpt 将磁盘 label 设置为 gpt 格式

(parted) mklabel gpt
Warning: The existing disk label on /dev/nvme0n1 will be destroyed and all data on this disk will be lost. Do you want to
Yes/No? Yes□

iii. 终端命令: mkpart logical 0 -1 将磁盘 part 设置为 gpt 格式

iv. 终端命令: print 查看分区结果

(parted) print Model: KBG40ZNS128G NVMe TOSHIBA 128GB (nvme) Disk /dev/nvme0n1: 128GB Sector size (logical/physical): 512B/512B Partition Table: gpt Disk Flags: Number Start End Size File system Name Flags 17.4kB 128GB 128GB logic

- v. 终端命令: **quit** 退出
- vi. 终端命令: sudo fdisk /dev/nvme0n1

```
(parted) quit
Information: You may need to update /etc/fstab.

tx2nx@tx2nx:~$ sudo fdisk /dev/nvme0n1

Welcome to fdisk (util-linux 2.31.1).
Changes will remain in memory only, until you decide to write them.
Be careful before using the write command.
Command (m for help): []
```

vii. Command (m for help): 输入 N,选择增加新分区,后面回车默认即可

```
Command (m for help): n
Partition number (2-128, default 2): 2
First sector (250067728-250069646, default 250068992):
Last sector, +sectors or +size{K,M,G,T,P} (250068992-250069646, default 250069646):
Created a new partition 2 of type 'Linux filesystem' and of size 327.5 KiB.
```

viii. Command (m for help): 输入 P, 查看分区结果

```
        Device
        Start
        End
        Sectors
        Size Type

        /dev/nvme0n1p1
        34 250067727
        250067694
        119.2G Linux filesystem

        /dev/nvme0n1p2
        250068992
        250069646
        655 327.5K Linux filesystem
```

- ix. 终端命令: quit 退出
- x. 终端命令: sudo mke2fs -t ext4 /dev/nvme0n1p1,格式化分区

xi. 终端命令: **sudo mount /dev/nvme0n1p1 /mnt**, 成功 mount 则 NVME 配 置成功

```
tx2nx@tx2nx:~$ sudo mount /dev/nvme0n1p1 /mnt
tx2nx@tx2nx:~$ [
```

- c) NVIDIA Jetson 系统迁移 (!!!迁移前建议参考第 3 章进行系统备份):
 - ✓ 下面以 TX2NX 为例,其他设备替换命令中间的设备名称即可,设备名称可参考上面命令
 - ▶ 1. 终端命令: git clone https://github.com/jetsonhacks/rootOnNVMe 下载脚本

2. 进入 rootOnNVMe 文件夹,终端命令: ./copy-rootfs-ssd.sh,复制系统文件 至 NVME SSD

```
tx2nx@tx2nx:/home/script/rootOnNVMe-master$ ./copy-rootfs-ssd.sh mount: /mnt: /dev/nvme0n1p1 already mounted on /mnt. 17,380,838 0% 2.40MB/s 0:00:06 (xfr#39, ir-chk=1015/44887)
```

🕨 3. 终端命令: ./setup-service.sh 配置启动项

```
tx2nx@tx2nx:/home/script/rootOnNVMe-master$ ./setup-service.sh
==== AUTHENTICATING FOR org.freedesktop.systemd1.reload-daemon ===
Authentication is required to reload the systemd state.
Authenticating as: tx2nx,, (tx2nx)
Password: Failed to reload daemon: Method call timed out
polkit-agent-helper-1: pam_authenticate failed: Authentication failure
Created symlink /etc/systemd/system/default.target.wants/setssdroot.service → /etc/systemd/system/setssdroot.service.
Service to set the rootfs to the SSD installed.
Make sure that you have copied the rootfs to SSD.
Reboot for changes to take effect.
```

- 4. 参考第2章,进入 Recovery 模式。
- 5. (烧录环境的 Ubuntu,参考前面章节)进入~/nvidia/nvidia_sdk/JetPack_
 4.6_Linux_JETSON_TX2_TARGETS/Linux_for_Tegra, 打开终端: sudo ./flas
 h.sh jetson-xavier-nx-devkit-tx2-nx nvme0n1p1 更新 EMMC 内部引导

```
greetrix@greetrix-virtual-machine:~/nvidia/nvidia_sdk/JetPack_4.6_Linux_JETSON_T
X2_TARGETS/Linux_for_Tegra$ sudo ./flash.sh jetson-xavier-nx-devkit-tx2-nx nvme0
n1p1
```

```
[ 37.3739 ] Coldbooting the device
[ 37.3775 ] tegradevflash_v2 --reboot coldboot
[ 37.3788 ] Bootloader version 01.00.0000
[ 37.5711 ]
*** The target t186ref has been flashed successfully. ***
Make the target filesystem available to the device and reset the board to boot f
rom external nvme0n1p1.
```

▶ 6. 重启 TX2NX,终端命令: df -I,此时系统盘已经变为 NVME SSD,并且原有 EMMC 上系统已经成功迁移。

```
tx2nx@tx2nx:~$ df -l
                              Used Available Use% Mounted on
Filesystem
               1K-blocks
/dev/nvme0n1p1 122547172 11949920 104329176 11% /
                                                0% /dev
                  1578060
                                 0
                                     1578060
tmpfs
                  1962748
                                52
                                     1962696
                                                1% /dev/shm
tmpfs
                  1962748
                             20764
                                     1941984
                                                2% /run
tmpfs
                     5120
                                 4
                                         5116
                                                1% /run/lock
                  1962748
                                 0
                                     1962748
                                                0% /sys/fs/cgroup
tmpfs
                  392548
                                12
                                       392536
                                                1% /run/user/120
tmpfs
                  392548
                                       392548
                                 0
                                                0% /run/user/1000
tmpfs
```

6. 系统迁移至 SD 卡

a) SD 卡配置:

1. 配置前确保系统能识别到 SD 卡,终端命令: sudo fdisk -lu

```
Disk /dev/mmcblk1: 59.5 GiB, 63864569856 bytes, 124735488 sectors
Units: sectors of 1 * 512 = 512 bytes
Sector size (logical/physical): 512 bytes / 512 bytes
I/O size (minimum/optimal): 512 bytes / 512 bytes
```

- 2. 将 SD 卡设置成 GPT 格式:
 - i. 终端命令: sudo fdisk /dev/mmcblk1, 进入 sd 卡配置

```
tx2nx@tx2nx:~/Desktop$ sudo fdisk /dev/mmcblk1
Welcome to fdisk (util-linux 2.31.1).
Changes will remain in memory only, until you decide to write them.
Be careful before using the write command.
```

ii. 终端命令: q, 新建 gpt 分区表

```
Command (m for help): g
Created a new GPT disklabel (GUID: E39DF30E-48FE-B041-A6FA-5EFAEC223CEA).
```

iii. 终端命令: n, 新建分区, 其他输入回车按默认值

```
Command (m for help): n
Partition number (1-128, default 1):
First sector (2048-124735454, default 2048):
Last sector, +sectors or +size{K,M,G,T,P} (2048-124735454, default 124735454):
```

iv. 终端命令: w, 保存分区信息

```
Command (m for help): w
The partition table has been altered.
Calling ioctl() to re-read partition table.
Syncing disks.
```

v. 终端命令: sudo mke2fs -t ext4 /dev/mmcblk1p1, 格式化分区

vi. 终端命令: **sudo mount /dev/mmcblk1p1 /mnt**, 成功 mount 则 SD 卡配置成功

tx2nx@tx2nx:~/Desktop\$ sudo mount /dev/mmcblk1p1 /mnt

- b) NVIDIA Jetson 系统迁移 (!!!迁移前建议参考第 3 章进行系统备份):
 - ✓ 下面以 TX2NX 为例,其他设备替换命令中间的设备名称即可,设备名称可参考上面命令
 - 1. 终端命令: git clone https://github.com/jetsonhacks/rootOnNVMe 下载脚本
 - 2. 修改 copy-rootfs-ssd.sh 文件, 注释掉 mount 命令

```
#1/bin/bash
# Mount the SSD as /mnt
# Sudo mount /dev/nvme0nlp1 /mnt
# Copy over the rootfs from the SD card to the SSD
sudo rsync -axHAWX --numeric-ids --info=progress2 --exclude={"/dev/","/proc/","/sys/","/tmp/"
,"/run/","/mmt/","/media/*","/lost+found") / /mnt
# We want to keep the SSD mounted for further operations
# So we do not unmount the SSD
```

3. 进入 rootOnNVMe 文件夹,终端命令: ./copy-rootfs-ssd.sh,复制系统文件至 SD 卡

```
nx@nx-desktop:~/rootOnNVMe$ sudo bash ./copy-rootfs-ssd.sh
276,613,277 37% 50.12MB/s 0:00:05 (xfr#2089, ir-chk=1622/4960)
```

- 4. 参考第2章, 进入 Recovery 模式。
- > 5. (**烧录环境的 Ubuntu**, 参考**前面章节**) 进入
 - ~/nvidia/nvidia_sdk/JetPack_4.6_Linux_JETSON_TX2_TARGETS/Linux_for_ Tegra, 打开终端:

将前面章节对应的刷机命令 mmcblk0p1 换成 mmcblk1p1 更新 EMMC 内部引导

◆ 如 TX2NX-EMMC: sudo ./flash.sh jetson-xavier-nx-devkit-tx2-nx mm cblk1p1

greetrix@greetrix-virtual-machine:~/nvidia/nvidia_sdk/JetPack_4.6_Linux_JETSON_T
X2_TARGETS/Linux_for_Tegra\$ sudo ./flash.sh jetson-xavier-nx-devkit-tx2-nx mmcbl
k1p1

```
[ 30.4511 ] Coldbooting the device
[ 30.4521 ] tegradevflash_v2 --reboot coldboot
[ 30.4531 ] Bootloader version 01.00.0000
[ 30.6253 ]
*** The target t186ref has been flashed successfully. ***
Make the target filesystem available to the device and reset the board to boot f
rom external mmcblk1p1.
```

▶ 6. 重启 TX2NX,终端命令: df -l,此时系统盘已经变为 SD 卡,并且原有 EMMC 上系统已经成功迁移。

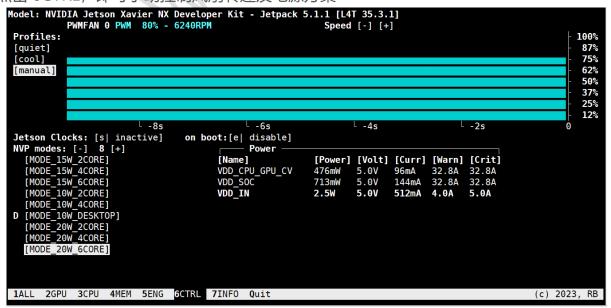
```
tx2nx@tx2nx:~$ df -h
Filesystem Size
                        Used Avail Use% Mounted on
/dev/mmcblk1p1
                   59G
                          12G
                                44G
                                      21% /
                  1.6G
devtmpfs
                            0
                               1.6G
                                       0% /dev
tmpfs
                  1.9G
                               1.9G
                         52K
                                       1% /dev/shm
tmpfs
                  1.9G
                         21M
                               1.9G
                                       2% /run
tmpfs
                  5.0M
                        4.0K
                               5.0M
                                       1% /run/lock
tmpfs
                  1.9G
                            0
                               1.9G
                                       0% /sys/fs/cgroup
tmpfs
                  384M
                         12K
                               384M
                                       1% /run/user/120
                               384M
tmpfs
                  384M
                            0
                                       0% /run/user/1000
```

7. 安装 JTOP (控制风扇, 查看系统信息)

- 1. 打开终端,通过下面命令安装 Jtop
 - a) sudo apt-get install python3-pip python3-dev -y
 - b) sudo -H pip3 install jetson-stats
 - c) sudo systemctl restart jtop.service
 - d) sudo jtop

```
10.0%] 1.2GHz
                                                                                                              1.2GHz
                                                                                                              1.2GHz
                                                                                                     51.0%] 4103RPM
                                ::::::1.6GHz] 1.6GHz
                                                         0% NV Power[5]: MODE_10W_DESKTOP
                                                            Uptime: 0 days 0:8:46
                                                                                                        0.0%] 114MHz
5.7G/13.7G]
GPU
TYPE
                             PRI
                                       CPU%
                                              MEM
                                                       [GPU MEM]
                                                                    Command
1584
1717
1998
                                       0.2
1.2
0.0
                                              9.7M
35.2M
8.1M
                                                       17.5M
5.8M
0k
        root
                       G
                             20
                                                                    Xorg
                                  SSS
                      G
                             20
                                                                    gnome-shell
        root
                      G
                             20
                                                                    goa-daemon
       nx
gdm
                                       0.0
                       G
                                                       0k
1647
                             20
                                              8.1M
                                                                    goa-daemon
                                                                    nvargus-daemon
                                                                                                           [Avg]
             [HW engines]
                                                 [Sensor] -
                                                                [Temp]
                                                                                       [Power] —
                                                                                                   [Inst]
      APE: [OFF] CVNAS: [OFF]
DLA0c: [OFF] DLA1c: [OFF]
NVENC: [OFF] NVDEC: [OFF]
NVJPG: [OFF] PVA0a: [OFF]
                                                                45.00C
44.50C
                                                                                      CPU GPU CV
                                                                                                    476mW
                                                                                                            495mW
                                                  AUX
                                                                                                    752mW
                                                                                                            751mW
                                                                45.50C
44.50C
                                                  CPU
                                                                                      VDD_IN
                                                                                                    2.6W
                                                                                                            2.6W
                                                  GPU
                                                                55.00C
       SE: [OFF]
                     VIC: [OFF]
                                                  iwlwifi
                                                  thermal
                                                                44.850
1ALL 2GPU 3CPU 4MEM 5ENG 6CTRL 7INFO Quit
                                                                                                          (c) 2023, RB
```

2. 点击 6CTRL,即可手动控制风扇转速及电源方案



8. 使用 CAN 进行通信

- 3. Tx2-NX/XavierNX/OrinNX/OrinNano 上集成了 1 个 CAN 控制器 CAN0,另外 WeAct Studio 的载板上设计了 1 个 CAN 收发器(CAN0),可直接挂载 CAN 物理总线使用。
- 4. Tx2-NX/XavierNOrinNX/OrinNanoX 自带 canbus 的驱动并集成到了镜像中,已经支持 canbus 无需多做处理。我们需要安装 canbus 模块。(在终端输入下面命令或者放入rc.local 里面开启自启)

```
modprobe can // 插入 can 总线子系统 modprobe can-raw //插入 can 协议模块 modprobe can-bcm modprobe can-gw modprobe can_dev //真正的 can 口支持
```

5. 通过 Ismod 检查是否安装成功。

```
nvidia@localhost:~$ lsmod
Module
                                Used by
                          Size
fuse
                        103841
                                2
mttcan
can dev
                         13306
                                1 mttcan
can_gw
                         10919
                                0
can bcm
                         16471
                                0
can raw
                         46600
                                3 can raw, can bcm, can gw
can
zram
                         26166
                                6
overlay
                         48691
                                0
                                0
bcmdhd
                        934274
cfg80211
                                1 bcmdhd
                        589351
spidev
                                0
                         13282
nvgpu
                       1575721
                                20
                         13912
                                0
bluedroid_pm
ip tables
                         19441
  tables
                         28951
                                1 ip_tables
```

6. 配置 canbus 属性,和串口的波特率设置类似。

sudo ip link set can0 type can bitrate 500000 sudo ip link set up can0

7. 通过 ifconfig 查看是否配置成功。

```
nvidia@localhost:~$ ifconfig
can0: flags=193<UP,RUNNING,NOARP> mtu 16
    unspec 00-00-00-00-00-00-00-00-00-00-00-00-00 txqueuelen 10 (UNSPEC)
    RX packets 0 bytes 0 (0.0 B)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 0 bytes 0 (0.0 B)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
    device interrupt 131
```

8. 在一个终端通过 cansend can0(can1) ×××命令来发送数据, 另一个终端通过 candump can1(can0)完成实际信号收发测试

```
nvidia@localhost:~$ cansend can0 555#112233445566
```

联系我们

1. Github: https://github.com/WeActTC

2. 码云: https://gitee.com/WeAct-TC

3. 网站: https://www.weact-tc.cn/

4. 淘宝: https://weactstudio.taobao.com/



WeAct Studio 官方淘宝店