

1 `rot_to_Rotator(rot)`

Takes a `rot` object (`CowBot`) and returns a `Rotator` object (framework).

2 `setState(game_info, ball_state, current_state, teammates_state, opponents_state, boosts_state, game_info_state)`

This will set the game state as specified. Most of the code is translating between different state objects. `game_info` (`GameState` (`CowBot`)) is passed solely for the indices of each car, because I have no way of knowing that a priori. Seeing as it's unlikely I'll want to mess with boost pads anytime soon, I'm skipping that for now. I believe they're also broken since RLBot 1.15.0.

`ball_state` (`BallState` (`CowBot`)) and `current_state` (`CarState` (`CowBot`)) are the states of the ball and our car, respectively. `teammates_state` and `opponents_state` (lists of `CarState` (`CowBot`)) hold the states of our teammates' and opponents' cars, respectively. `boosts_state` and `game_info_state` are currently skipped and should always be `None`.

3 `state_to_physics(state)`

Takes a partial `CarState` or `BallState` and returns the corresponding `Physics` object (framework).