

TODO: Clean up `__init__` so it's not as much a wall of code.

1 class ArcLineArc

1.1 waypoints

List of `Vec3`. The list of waypoints we want to follow. `waypoints[0]` is the point we are going to head to next.

1.2 current_state

`CarState`. The `current_state` of our car.

1.3 self.piece

`PathPiece`. The data to tell `follow_path()` what it should do.