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1 Basic

1.1 .vimrc

```
"This file should be placed at ~/.vimrc"
  se nu ai hls et ru ic is sc cul
  se re=1 ts=4 sts=4 sw=4 ls=2 mouse=a
  svntax on
  hi cursorline cterm=none ctermbg=89
  set bg=dark
2 inoremap {<CR> {<CR>}<Esc>ko<tab>
```

1.2 Default Bear

```
#include <bits/stdc++.h>
 using namespace std;
typedef long long ll;
 #define int ll
 typedef pair<int,int> pii;
 #define X first
 #define Y second
#define pb push back
#define All(a) a.begin(), a.end()
#define SZ(a) ((int)a.size())
#define endl '\n'
```

1.3 Default Ken

```
#include <bits/stdc++.h>
#define F first
#define S second
#define pb push_back
#define pob pop_back
#define SZ(x) (int)(x.size())
#define all(x) begin(x), end(x)
#ifdef LOCAL
#define HEHE freopen("in.txt", "r", stdin);
#define debug(...)
     {cout << #__VA_ARGS__ << " = "; dbg(__VA_ARGS__);}
#else
#define HEHE ios_base::sync_with_stdio(0), cin.tie(0);
#define debug(...) 7122;
#endif
using namespace std;
#define chmax(a, b) (a) = (a) > (b) ? (a) : (b)
#define chmin(a, b) (a) = (a) < (b) ? (a) : (b)
#define FOR(i, a, b) for (int i = (a); i <= (b); i++)
void dbg() { cerr << '\n'; }</pre>
template < typename T, typename ...U>
void dbg(T t, U \dotsu) { cerr << t << ' '; dbg(u\dots); }
#define int long long
signed main() {
  HEHE
}
```

1.4 IO Optimize

```
bool rit(auto& x) {
  x = 0; char c = cin.rdbuf()->sbumpc(); bool neg = 0;
while (!isdigit(c)) {
    if (c == EOF) return 0;
    if (c == '-') neg = 1;
    c = cin.rdbuf()->sbumpc();
  while (isdigit(c))
    x = x * 10 + c - '0', c = cin.rdbuf()->sbumpc();
  return x = neg ? -x : x, 1;
void wit(auto x) {
  if (x < 0) cout.rdbuf()->sputc('-'), x = -x;
  char s[20], len = 0;
  do s[len++] = x \% 10 + '0'; while (x /= 10);
  while (len) cout.rdbuf()->sputc(s[--len]);
```

1.5 PBDS

```
#include <ext/pb_ds/assoc_container.hpp>
                                                 #include <ext/pb_ds/tree_policy.hpp>
                                                 // #include <bits/extc++.h>
                                                 #include <bits/stdc++.h>
                                                 using namespace __gnu_pbds;
                                                 using namespace std;
8.6 XorBasis ...... 20 template <typename T>
```

```
using rbtree = tree<T, null_type, less<T</pre>
    >, rb_tree_tag, tree_order_statistics_node_update>;
  less<T> : increasing, greater<T> : decreasing
// rb_tree_tag, splay_tree_tag, ov_tree_tag
int main() {
 int x;
  rbtree<int> t, rhs, rhs2;
  t.insert(x);
  t.erase(x); // return 1 or 0
 cout << t.order_of_key(x) << '\n'; // rank</pre>
 cout << *t.find_by_order(x) << '\n'; // x-th
cout << *t.lower_bound(x) << '\n'; // iterator >= x
  cout << *t.upper_bound(x) << '\n'; // iterator > x
 t.join(rhs
      ); // merge // same type, no duplicate elements
  t.split(x, rhs2
      ); // tree : elements <= x, rhs : elements > x
```

1.6 Set Comperator

```
auto cmp = [](int a, int b) {
    return a > b;
};
set<int, decltype(cmp)> s = {1, 2, 3, 4, 5};
cout << *s.begin() << '\n';</pre>
```

1.7 Random

1.8 Python

2 Graph

2.1 2 SAT

```
struct TwoSAT {
  int n;
  Scc scc;
  void init(int _n) {
     // (0,1),(2,3),.
    n = _n; scc.init(n * 2);
  void add_disjunction(int a, int na, int b, int nb) {
  a = 2 * a ^ na, b = 2 * b ^ nb;
  scc.addEdge(a ^ 1, b);
     scc.addEdge(b ^ 1, a);
  }
  vector<int> solve() {
     scc.solve();
     vector<int> assignment(n, 0);
     for (int i = 0; i < n; i++) {</pre>
       if (scc
            .bln[2 * i] == scc.bln[2 * i ^ 1]) return {};
       assignment
            [i] = scc.bln[2 * i] > scc.bln[2 * i ^ 1];
     return assignment:
  }
};
```

2.2 Bellman Ford

```
struct edge{
  int u, v;
  int cost;
};
vector<int> d(n, inf);
bool bellman_ford(vector<edge> &ee, int n, int s){
  d[s] = 0;
```

```
auto relax = [&](edge e){
   if(d[e.v] > d[e.u] + e.cost){
      d[e.v] = d[e.u] + e.cost;
      return 1;
   }
   return 0;
}
for(int t = 1; t <= n; ++t){
   bool update = 0;
   for(auto &e: ee)
      update |= relax(e);
   if(t == n && update) return 0;
}
return 1;
}</pre>
```

2.3 Biconnected Component

```
// beware of multiple inputs
#define ep emplace
#define eb emplace_back
const int N = 2e5 + 5;
int d[N], low[N];
vector<int> g[N];
vector<vector<int>> bcc;
stack<int> st;
void dfs(int x, int p) {
 d[x] = p ? d[p] + 1 : 1, low[x] = d[x];
  st.ep(x);
  for (const auto& i : g[x]) {
    if (i == p) continue;
    if (!d[i]) {
      dfs(i, x);
      low[x] = min(low[x], low[i]);
      if (d[x] <= low[i]) {</pre>
        int tmp;
        bcc.eb();
        do tmp = st.top(), st.pop
            (), bcc.back().eb(tmp); while (tmp != x);
        st.ep(x);
      }
    low[x] = min(low[x], d[i]);
```

2.4 Bridge

```
#define eb emplace_back
using pii = pair<int, int>;
const int N = 2e5 + 5;
int d[N], low[N];
vector<int> g[N];
vector<int> ap; // articulation point
vector<pii> bridge;
void dfs(int x, int p) {
  d[x] = \neg p ? d[p] + 1 : 1, low[x] = d[x];
  int cnt = 0;
  bool isap = 0;
  for (const auto& i : g[x]) {
    if (i == p) continue;
    if (!d[i]) {
      dfs(i, x), cnt++;
if (d[x] <= low[i]) isap = 1;</pre>
      if (d[x] < low[i]) bridge.eb(x, i);</pre>
      low[x] = min(low[x], low[i]);
    low[x] = min(low[x], d[i]);
  if (p == -1 && cnt < 2) isap = 0;
  if (isap) ap.eb(x);
```

2.5 Bridge Connected Component

```
#define ep emplace
constexpr int N = 2e5 + 1;
int d[N], low[N], bcc[N], nbcc;
vector<int> g[N];
stack<int> st;
void dfs(int x, int p) {
```

```
d[x] = \neg p ? d[p] + 1 : 1, low[x] = d[x];
  st.ep(x);
  for (const auto& i : g[x]) {
    if (i == p) continue;
     if (!d[i]) {
      dfs(i, x);
       low[x] = min(low[x], low[i]);
     low[x] = min(low[x], d[i]);
  if (low[x] == d[x]) {
    nbcc++;
     int tmp;
     do tmp = st.top()
         , st.pop(), bcc[tmp] = nbcc; while (tmp != x);
}
```

2.6 Centroid Decomposition

```
const int MAXN = 1e5 + 5;
int n, q, vis[MAXN], sz[MAXN];
vector < int > adj[MAXN], pa[MAXN], mx[MAXN], dis[MAXN];
void dfs_sz(int x, int p) {
    sz[x] = 1;
    for (int i : adj[x]) {
        if (i == p or vis[i]) continue;
        dfs_sz(i, x);
        sz[x] += sz[i];
    }
int cen;
void dfs_cen(int x, int p, int all) {
   int tmp = all - sz[x];
    for (int i : adj[x]) {
        if (i == p or vis[i]) continue;
        dfs_cen(i, x, all);
        chmax(tmp, sz[i]);
    if (tmp * 2 <= all) cen = x;
void dfs(int x, int p, int d) {
    pa[x].pb(cen);
    dis[x].pb(d);
    if (d >= mx[cen].size()) mx[cen].pb(x);
    else chmax(mx[cen][d], x);
    for (int i : adj[x]) {
        if (i == p or vis[i]) continue;
        dfs(i, x, d + 1);
    }
void deco(int x, int d) {
    dfs_sz(x, x);
    dfs_cen(x, x, sz[x]);
    vis[cen] = 1;
    dfs(cen, cen, 0);
    for (int i = 1; i < mx[cen].size(); i++) {</pre>
        chmax(mx[cen][i], mx[cen][i - 1]);
    for (int i : adj[cen]) {
        if (vis[i]) continue;
        deco(i, d + 1);
    }
int get(int x, int k) {
   if (!mx[x].size() or k < 0) return 0;</pre>
    return k >= mx[x].size() ? mx[x].back() : mx[x][k];
int query(int x, int k) {
    int res = get(x, k);
for (int i = 0; i < pa[x].size(); i++) {
        int p = pa[x][i];
        int d = dis[x][i];
        chmax(res, get(p, k - d));
    return res;
}
signed main() {
    WOSHAOJI
    cin >> n >> q;
    for (int i = 1, u, v; i < n; i++) {
        cin >> u >> v;
        adj[u].pb(v);
        adj[v].pb(u);
    }
```

```
deco(1, 0);
     e (q--) {
int x, k; cin >> x >> k;
----(v k) << '\n';
while (q--) {
```

2.7 Close Vertices

```
}
#include <iostream>
#include <vector>
#include <bitset>
#include <algorithm>
#include <cstring>
 using namespace std;
 int l, w;
 vector<pair<int, short>> tree[100000];
 bitset<100000> removed;
 int current_centroid, BIT[100000];
 // Return subtree size internally
 // and
      place the discovered centroid in current_centroid
 int find_centroid
     (const int n, const int u, const int p = -1) {
   if (n == 1) { current_centroid = u; return 0; }
   int subtree_sum = 0;
   for (const auto
        &[v, w] : tree[u]) if (v != p && !removed[v]) {
       subtree_sum += find_centroid(n, v, u);
       if (current_centroid > -1) return 0;
       if (subtree_sum >=
            n >> 1) { current_centroid = u; return 0; }
     }
  return subtree_sum + 1;
void DFS(const int u, const int p, const int length,
      const int weight, vector<pair<int, int>> &record) {
   record.emplace_back(weight, length);
   for (const auto
        &[v, w] : tree[u]) if (v != p && !removed[v])
       DFS(v, u, length + 1, weight + w, record);
bool greater_size(const vector<pair</pre>
     <int, int>> &v, const vector<pair<int, int>> &w) {
   return v.size() > w.size();
long long centroid_decomposition(const int n, int u) {
   long long ans = 0;
   // Step 1: find the centroid
   current_centroid = -1; find_centroid(n, u);
   removed[u = current_centroid] = true;
   // Step 2: DFS from the centroid (again)
   // and continue the centroid decomposition
   vector<vector<pair<int, int>>> root2subtree_paths;
for (const auto &[v, w] : tree[u]) if (!removed[v]) {
       root2subtree_paths.emplace_back();
       DFS(v, u, 1, w, root2subtree_paths.back());
       // Sort mainly according to weight
       ranges::sort(root2subtree_paths.back());
       ans += centroid_decomposition
           (root2subtree_paths.back().size(), v);
   for (const auto &v : root2subtree_paths)
     for (const auto &[weight, length] : v)
       if (length <= l && weight <= w) ++ans;</pre>
   // Step 3: optimal merging
   ranges::make_heap(root2subtree_paths, greater_size);
   while (root2subtree_paths.size() > 1) {
     ranges::pop_heap(root2subtree_paths, greater_size);
     // Merge
          front() (with maybe larger size) and back()
     // Count cross-centroid paths
     memset(BIT, 0, root2subtree_paths
         .back().size() * sizeof(int));
     auto p = root2subtree_paths.front().crbegin();
     for (auto q = root2subtree_paths.back().cbegin()
         ; q != root2subtree_paths.back().cend(); ++q) {
       int L;
       while (p != root2subtree_paths.front().crend()
              && p->first + q->first > w) {
         L = min(l - p->second,
                 static cast<int>(
                      root2subtree_paths.back().size()));
         while
             (L > 0) { ans += BIT[L - 1]; L -= L & -L; }
         ++p:
       }
```

```
L = q->second;
     while (L <= static cast
          <int>(root2subtree_paths.back().size()))
       ++BIT[L - 1]; L += L & -L;
     }
   while (p != root2subtree_paths.front().crend()) {
     int L = min(l - p++->second, static_cast
         <int>(root2subtree_paths.back().size()));
     while (L > 0) { ans += BIT[L - 1]; L -= L & -L; }
   // Actually merge the lists
   vector<pair<int, int>> buffer;
   buffer.reserve(root2subtree_paths.front
       ().size() + root2subtree_paths.back().size());
   ranges::merge
        (root2subtree_paths.front(), root2subtree_paths
        .back(), back_inserter(buffer));
   root2subtree_paths.pop_back();
   ranges::pop_heap(root2subtree_paths, greater_size);
   root2subtree_paths.back() = move(buffer);
   ranges
        ::push_heap(root2subtree_paths, greater_size);
 }
 return ans;
int main() {
 ios_base::sync_with_stdio(false);
 int n; cin >> n >> l >> w;
 for (int i = 1; i < n; ++i) {</pre>
   int p; short w; cin >> p >> w;
   tree[--p].emplace_back(i, w);
   tree[i].emplace_back(p, w);
 cout << centroid_decomposition(n, 0) << endl;
```

2.8 Disjoint Set

```
#include <bits/stdc++.h>
using namespace std;
struct disjoint_set {
  static const int maxn = (int)5e5 + 5;
  int n, fa[maxn], sz[maxn];
 vector<pair<int*, int>> h;
  vector<int> sp;
  void init(int _n) {
   n = _n;
for (int i = 0 ; i < n ; ++i)</pre>
      fa[i] = i, sz[i] = 1;
    sp.clear(); h.clear();
  void assign(int *k, int v) {
   h.push_back(\{k, *k\});
    *k = v;
  void save() { sp.push_back((int)h.size()); }
  void undo() {
    assert(!sp.empty());
    int last = sp.back(), cnt = 0; sp.pop_back();
    while (h.size() > last) {
      auto x = h.back(); h.pop_back();
      *x.first = x.second;
      cnt++;
   n += cnt / 2;
  int f(int x) {
    while (fa[x] != x) x = fa[x];
    return x;
  bool merge(int x, int y) {
   x = f(x); y = f(y);
    if (x == y) return 0;
    if (sz[x] < sz[y]) swap(x, y);
    assign(\&sz[x], sz[x] + sz[y]);
    assign(&fa[y], x);
   n - -:
    return 1;
} dis;
```

2.9 Heavy Light Decomposition

```
#include <bits/stdc++.h>
using namespace std;
const int N = 2e5 + 5;
#define eb emplace_back
int t, n, q, seg[N \ll 1]; // t := time-stamp
int sz[N], fa[N], dep[N], to[N], fr[N], dfn[N], arr[N];
// size, father, depth
     , to-heavy-child, from-head, dfs-order, a_i value
vector<int> g[N];
void upd(int x, int v) {
  for (seg[x += n] = v; x > 1; x >>= 1)
    seg[x >> 1] = max(seg[x], seg[x ^ 1]);
int qry(int l, int r) { // [l, r]
  int ret = -1e9; // -max
  for (l += n, r += n + 1; l < r; l >>= 1, r >>= 1) {
    if (l & 1) ret = max(ret, seg[l++]);
    if (r & 1) ret = max(ret, seg[--r]);
  return ret;
}
void dfs(int x, int p) {
  sz[x] = 1, fa[
      x] = p, to[x] = -1, dep[x] = -p? dep[p] + 1 : 0;
  for (auto i : g[x])
    if (i != p) {
      dfs(i, x);
      if (to[x] == -1 \mid | sz[i] > sz[to[x]]) to[x] = i;
      sz[x] += sz[i];
void dfs2(int x, int f) {
  fr[x] = f, dfn[x] = ++t, upd(dfn[x], arr[x]);
  if (to[x] != -1) dfs2(to[x], f);
  for (auto i : g[x])
    if (i != fa[x] && i != to[x]) dfs2(i, i);
int qry2(int u, int v) { // query on tree
  int fu = fr[u], fv = fr[v], ret = -1e9;
  while (fu != fv) {
    if (dep[fu] < dep[fv]) swap(fu, fv), swap(u, v);</pre>
    ret = max(ret, qry(dfn
        [fu], dfn[u])); // interval: [dfn[fu], dfn[u]]
    u = fa[fu], fu = fr[u];
  if (dep[u] > dep[v]) swap(u, v);
  // u is the LCA
  ret = max(ret, qry(dfn[u], dfn[v]));
  return ret;
int main() {
  ios::sync_with_stdio(false), cin.tie(nullptr);
  cin >> n >> q;
  for (int i = 1; i <= n; i++) cin >> arr[i];
  for (int i = 1, a, b; i < n; i++)</pre>
    cin >> a >> b, g[a].eb(b), g[b].eb(a);
  dfs(1, -1), dfs2(1, 1);
  while (q--) {
    int op; cin >> op;
    if (op == 1) {
      int x,
          v; cin >> x >> v, arr[x] = v, upd(dfn[x], v);
    else {
      int a, b; cin >> a >> b;
      cout << qry2(a, b) << '\n';</pre>
  }
}
2.10 KSP
```

```
node(ll
    _d, int _v, nd* _E) { d = _d; v = _v; E = _E; }
node(heap* _H, ll _d) { H = _H; d = _d; }
friend bool operator <(node a, node b)
    { return a.d > b.d; }
  };
  int n, k, s, t, dst[N]; nd *nxt[N];
  vector<nd*> g[N], rg[N]; heap *nullNd, *head[N];
  void init(int _n, int _k, int _s, int _t) {
  n = _n; k = _k; s = _s; t = _t;
  for (int i = 1; i <= n; i++) {
    g[i].clear(); rg[i].clear();
}</pre>
      nxt[i] = NULL; head[i] = NULL; dst[i] = -1;
  void addEdge(int ui, int vi, ll di) {
  nd* e = new nd(ui, vi, di);
    g[ui].push_back(e); rg[vi].push_back(e);
  queue<int> dfsQ;
  void dijkstra() {
    while (dfsQ.size()) dfsQ.pop();
    priority_queue<node> Q; Q.push(node(0, t, NULL));
    while (!Q.empty()) {
      node p = Q
           .top(); Q.pop(); if (dst[p.v] != -1)continue;
      dst[p.v] = p.d; nxt[p.v] = p.E; dfsQ.push(p.v);
           : rg[p.v]) Q.push(node(p.d + e->d, e->u, e));
    }
  heap* merge(heap* curNd, heap* newNd) {
    if (curNd == nullNd) return newNd;
    heap* root
          = new heap; memcpy(root, curNd, sizeof(heap));
    if (newNd->edge->d < curNd->edge->d) {
      root->edge = newNd->edge;
      root->chd[2] = newNd->chd[2];
      root ->chd[3] = newNd ->chd[3];
      newNd->edge = curNd->edge;
      newNd->chd[2] = curNd->chd[2];
      newNd->chd[3] = curNd->chd[3];
    if (root->chd[0]->dep < root->chd[1]->dep)
      root->chd[0] = merge(root->chd[0], newNd);
    else root->chd[1] = merge(root->chd[1], newNd);
    root->dep = max(root->chd[0]->dep,
                      root->chd[1]->dep) + 1;
    return root;
  }
  vector<heap*> V;
  void build() {
    nullNd = new
          heap; nullNd->dep = 0; nullNd->edge = new nd;
    fill(nullNd->chd, nullNd->chd + 4, nullNd);
    while (not dfsQ.empty()) {
      int u = dfsQ.front(); dfsQ.pop();
      if (!nxt[u]) head[u] = nullNd;
      else head[u] = head[nxt[u]->v];
      V.clear();
      for (auto && e : g[u]) {
         int v = e->v;
         if (dst[v] == -1) continue;
        e->d += dst[v] - dst[u];
        if (nxt[u] != e) {
           heap*p = new
                heap; fill(p->chd, p->chd + 4, nullNd);
           p->dep = 1; p->edge = e; V.push_back(p);
        }
      if (V.empty()) continue;
      make_heap(V.begin(), V.end(), cmp);
#define L(X) ((X<<1)+1)</pre>
#define R(X) ((X<<1)+2)
      for (size_t i = 0; i < V.size(); i++) {</pre>
        if (L(i) < V.size()) V[i]->chd[2] = V[L(i)];
         else V[i]->chd[2] = nullNd;
         if (R(i) < V.size()) V[i]->chd[3] = V[R(i)];
        else V[i]->chd[3] = nullNd;
      head[u] = merge(head[u], V.front());
    }
  vector<ll> ans;
  void first_K() {
    ans.clear(); priority_queue<node> Q;
```

```
if (dst[s] == -1) return;
     ans.push_back(dst[s]);
     if (head[s] != nullNd)
       Q.push(node(head[s], dst[s] + head[s]->edge->d));
     for (int _ = 1; _ < k and not Q.empty(); _++) {
       node p = Q.top(), q; Q.pop(); ans.push_back(p.d);
if (head[p.H->edge->v] != nullNd) {
          q.H = head
             [p.H->edge->v]; q.d = p.d + q.H->edge->d;
          Q.push(q);
       for (int i = 0; i < 4; i++)</pre>
          if (p.H->chd[i] != nullNd) {
            q.H = p.H->chd[i];
            q.d = p
                .d - p.H->edge->d + p.H->chd[i]->edge->d;
            Q.push(q);
    }
  }
   void
       solve() \ \{ \ // \ ans[i] \ stores \ the i-th \ shortest \ path
     dijkstra(); build();
     first_K(); // ans.size() might less than k
} solver;
 2.11 LCA
#define eb emplace_back
 const int N = 2e5 + 5, logN = __lg(N) + 1, inf = 1e9;
 int n, q, logn;
 int dep[N], fa[N][logN];
 vector<int> g[N];
 void dfs(int x, int p) {
  dep[x] = ~p ? dep[p] + 1 : 0;
   fa[x][0] = p;
   for (int i = 1; (1 << i) <= dep[x]; i++)</pre>
     fa[x][i] = fa[fa[x][i - 1]][i - 1];
   for (const auto& u : g[x])
     if (u != p) dfs(u, x);
```

2.12 Maximum Clique

query -> LCA(u, v)

if (u == v) return u;

return fa[u][0];

// logn =

// g[a].eb(b)

// dfs(root, -1)

```
struct Maximum_Clique {
  typedef bitset < MAXN > bst;
 bst N[MAXN], empty;
int p[MAXN], n, ans;
  void BronKerbosch2(bst R, bst P, bst X) {
    if (P == empty && X == empty)
      return ans = max(ans, (int)R.count()), void();
    bst tmp = P \mid X;
    int u:
    if ((R | P | X).count() <= ans) return;</pre>
    for (int uu = 0; uu < n; ++uu) {</pre>
      u = p[uu];
      if (tmp[u] == 1) break;
    // if (double(clock())/CLOCKS_PER_SEC > .999)
    // return;
    bst now2 = P \& \sim N[u];
    for (int vv = 0; vv < n; ++vv) {
      int v = p[vv];
      if (now2[v] == 1) {
        R[v] = 1:
        BronKerbosch2(R, P & N[v], X & N[v]);
        R[v] = 0, P[v] = 0, X[v] = 1;
```

of (u, v) = dep[u] + dep[v] - 2 * dep[LCA(u, v)]

int LCA(int u, int v) {
 if (dep[u] > dep[v]) swap(u, v);
 for (int i = 0; i < logn; i++)
 if ((dep[v] - dep[u]) >> i & 1) v = fa[v][i];
}

for (int i = logn - 1; i >= 0; i--)

u = fa[u][i], v = fa[v][i];

if (fa[u][i] != fa[v][i])

 $_{lg(n)} + 1$

```
}

void init(int _n) {
    n = _n;
    for (int i = 0; i < n; ++i) N[i].reset();
}

void add_edge(int u, int v) {
    N[u][v] = N[v][u] = 1;
}
int solve() { // remember srand
    bst R, P, X;
    ans = 0, P.flip();
    for (int i = 0; i < n; ++i) p[i] = i;
        random_shuffle(p, p + n), BronKerbosch2(R, P, X);
    return ans;
}

};
</pre>
```

2.13 SCC Kosaraju

```
#define eb emplace_back
const int N = 2e5 +
vector<int> g[N], rg[N], ord;
int scc[N];
bool v[N];
void rdfs(int x) {
  v[x] = 1;
   for (const auto& i : rg[x])
     if (!v[i]) rdfs(i);
  ord.eb(x);
void dfs(int x, int nscc) {
  scc[x] = nscc;
  for (const auto& i : g[x])
  if (scc[i] == -1) dfs(i, nscc);
void kosaraju(int n) {
  memset(v, 0, sizeof(v));
memset(scc, -1, sizeof(scc));
for (int i = 0; i < n; i++)</pre>
     if (!v[i]) rdfs(i);
   int nscc = 0;
  for (int i = n - 1; i >= 0; i--) {
     int x = ord[i];
if (scc[x] == -1)
       dfs(x, nscc++);
}
```

2.14 SCC Tarian

2.15 Tree Centroid

2.16 Virtual Tree

```
vector<int> vG[N];
int top, st[N];
void insert(int u) {
  if (top == -1) return st[++top] = u, void();
  int p = LCA(st[top], u);
  if (p == st[top]) return st[++top] = u, void();
  while (top >= 1 && dep[st[top - 1]] >= dep[p])
  vG[st[top - 1]].pb(st[top]), --top;
  if (st[top] != p)
    vG[p].pb(st[top]), --top, st[++top] = p;
  st[++top] = u;
void reset(int u) {
  for (int i : vG[u]) reset(i);
  vG[u].clear();
}
void solve(vector<int> &v) {
  top = -1
  sort(ALL(v),
    [&](int a, int b) { return dfn[a] < dfn[b]; });</pre>
  for (int i : v) insert(i);
  while (top > 0) vG[st[top - 1]].pb(st[top]), --top;
  // do something
  reset(v[0]);
}
```

3 Data Structure

3.1 2D BIT

```
const int N = 1000 + 5;
int a[N][N];
struct BIT { // 1-based
  ll bit[N][N];
  int n, m;
  void init(int _n, int _m) { // O(nm)
    n = _n, m = _m;
     for (int i = 1; i <= n; i++)
       for (int j = 1; j <= m; j++)
         bit[i][j] = a[i][j];
    for (int b = 1; b << 1 <= max(n, m); b <<= 1) {
  for (int i = b; i + b <= n; i += b << 1)
          for (int j = 1; j <= m; j++)</pre>
           bit[i + b][j] += bit[i][j];
       for (int i = 1; i <= n; i++)</pre>
          for (int j = b; j + b \le m; j += b \le 1)
            bit[i][j + b] += bit[i][j];
  void upd(int x, int y, int v) {
    for (int i = x; i <= n; i += i & -i)
for (int j = y; j <= m; j += j & -j)
         bit[i][j] += v;
  ll qry(int x, int y) {
     ll ret = 0;
     for (int i = x; i; i -= i & -i)
       for (int j = y; j; j -= j & -j)
         ret += bit[i][j];
     return ret;
  ll qry(int
     x1, int y1, int x2, int y2) { // closed-interval return qry(x2, y2) - qry(x1 -
          1, y2) - qry(x2, y1 - 1) + qry(x1 - 1, y1 - 1);
} tree;
// tree.init(n, m)
```

3.2 2D Segment Tree

```
const int inf = 1e9;
#define lc(x) (x << 1)
#define rc(x) (x << 1 | 1)
int N, M; // N : row max, M : col max
struct seg {
  vector <int > st;
  void pull(int);
  void merge(const seg&, const seg&, int, int);
  void upd(int, int, int);
  void upd(int, int, int, int);
```

return ret;

```
int qry(int, int, int, int, int);
seg(int size): st(size << 2 | 1) {}</pre>
                                                                 void upd(ll* bit, int x, ll v) {
                                                                    for (; x <= n; x += x & -x) bit[x] += v;
void seg::pull(int id) {
  st[id] = max(st[lc(id)], st[rc(id)]);
                                                                  ll qry(int x) {
                                                                   return (x + 1) * sum(bit1, x) - sum(bit2, x);
void seg::merge(const seg& a
       const seg& b, int id = 1, int l = 1, int r = M) \{
                                                                 ll qry(int l, int r) { // [l, r]
  st[id] = max(a.st[id], b.st[id]);
                                                                    return qry(r) - qry(l - 1);
  if (l == r) return;
  int m = (l + r) >> 1;
                                                                 void upd(int l, int r, ll v) { // [l, r]
  upd(bit1, l, v), upd(bit2, l, l * v);
  merge(a,
        b, lc(id), l, m), merge(a, b, rc(id), m + 1, r);
                                                                    upd(bit1
                                                                        , r + 1, -v), upd(bit2, r + 1, (r + 1) * -v);
void seg::build(int id = 1, int l = 1, int r = M) {
  if (l == r) {cin >> st[id]; return;}
                                                                 BIT() {
  int m = (l + r) >> 1;
                                                                   fill_n(bit1, N, 0), fill_n(bit2, N, 0);
  build(lc(id), l, m), build(rc(id), m + 1, r);
                                                                 BIT(int* a) { // O(n) build
  pull(id);
                                                                    fill_n(bit1, N, 0), fill_n(bit2, N, 0);
                                                                    for (int i = 1;
void seg::upd
    (int x, int v, int id = 1, int l = 1, int r = M) {
                                                                         i \ll n; i++) bit1[i] = a[i] - a[i - (i \& -i)];
  if (l == r) {st[id] = v; return;}
                                                                    for (int i = n; i; i--) a[i] -= a[i - 1];
  int m = (l + r) >> 1;
if (x <= m) upd(x, v, lc(id), l, m);</pre>
                                                                    for (int
                                                                        i = 1; i <= n; i++) a[i] = a[i - 1] + a[i] * i;
  else upd(x, v, rc(id), m + 1, r);
                                                                    for (int i = 1;
  pull(id);
                                                                         i <= n; i++) bit2[i] = a[i] - a[i - (i & -i)];
                                                                 }
int seg::qry(
                                                               };
  int ql, int qr, int id = 1, int l = 1, int r = M) {
if (ql <= l && r <= qr) return st[id];</pre>
                                                               3.4 chtholly tree
  int m = (l + r) \gg 1, ret = -inf;
                                                               // 存 {x, v} , 從 x 開始到下一個位置前都是v
  if (ql
                                                               map<int, int> s;
        <= m) ret = max(ret, qry(ql, qr, lc(id), l, m));
                                                               // [l, r)
  if (qr >
                                                               void ins(int l, int r, int i) {
       m) ret = max(ret, qry(ql, qr, rc(id), m + 1, r));
                                                                    auto it1 = s.find(l);
  return ret;
                                                                    auto it2 = s.find(r);
}
                                                                    for (auto it = it1; it != it2; it++) {
struct segseg {
  vector<seg> st;
                                                                    s.erase(it1, it2); // [it`, it2)
  void pull(int, int);
                                                                    s[l] = ;
  void build(int, int, int);
  void upd(int, int, int, int, int, int);
int qry(int, int, int, int, int, int, int);
                                                               void split(int pos) {
                                                                   auto it = s.lower_bound(pos);
  segseg(int n, int m): st(n \ll 2 \mid 1, seg(m)) {}
                                                                    if (it == s.end() or it->F != pos) {
                                                                        s[pos] = prev(it)->S;
void segseg::pull(int id, int x) {
  st[id].upd(x,
       \max(st[lc(id)].qry(x, x), st[rc(id)].qry(x, x)));
                                                               3.5 LiChaoST
void segseg::build(int id = 1, int l = 1, int r = N) {
  if (l == r) {st[id].build(); return;}
                                                               struct LiChao_min {
  int m = (l + r) >> 1;
build(lc(id), l, m), build(rc(id), m + 1, r);
                                                                 struct line {
                                                                    LL m. c:
  st[id].merge(st[lc(id)], st[rc(id)]);
                                                                    line(LL _m = 0, LL _c = 0) {
                                                                      m = _m;
void segseg::upd(int y
                                                                      c = _c;
       int x, int v, int id = 1, int l = 1, int r = N) {
  if (l == r) {st[id].upd(x, v); return;}
                                                                   LL eval(LL x) { return m * x + c; }
  int m = (l + r) >> 1;
  if (y <= m) upd(y, x, v, lc(id), l, m);</pre>
                                                                 struct node {
  else upd(y, x, v, rc(id), m + 1, r);
                                                                    node *1, *r;
  pull(id, x);
                                                                    line f;
                                                                    node(line v) {
int segseg::qry(int y1, int y2,
                                                                      f = v;
     int x1, int x2, int id = 1, int l = 1, int r = N) {
                                                                      l = r = NULL;
  if (y1 <= l && r <= y2) return st[id].qry(x1, x2);</pre>
                                                                   }
  int m = (l + r) \gg 1, ret = -inf;
                                                                 };
  if (y1 <= m) ret
                                                                 typedef node *pnode;
        = max(ret, qry(y1, y2, x1, x2, lc(id), l, m));
                                                                 pnode root;
  if (y2 > m) ret =
                                                                  int sz;
        max(ret, qry(y1, y2, x1, x2, rc(id), m + 1, r));
                                                               #define mid ((l + r) >> 1)
  return ret;
                                                                 void insert(line &v, int l, int r, pnode &nd) {
}
                                                                    if (!nd) {
                                                                      nd = new node(v);
3.3 BIT
                                                                      return;
const int N = 2e5 + 5;
int n, a[N];
                                                                   LL trl = nd->f.eval(l), trr = nd->f.eval(r);
                                                                   LL vl = v.eval(l), vr = v.eval(r);
                                                                    if (trl <= vl && trr <= vr) return;</pre>
struct BIT { // 1-based
  ll bit1[N], bit2[N];
ll sum(ll* bit, int x) {
                                                                    if (trl > vl && trr > vr) {
                                                                      nd - > f = v;
    ll ret = 0;
                                                                      return;
    for (; x; x -= x & -x) ret += bit[x];
```

if (trl > vl) swap(nd->f, v);

```
National Tsing Hua University Kenapsack
    if (nd->f.eval(mid) < v.eval(mid))</pre>
     insert(v, mid + 1, r, nd->r);
    else swap(nd->f, v), insert(v, l, mid, nd->l);
 LL query(int x, int l, int r, pnode &nd) {
    if (!nd) return LLONG_MAX;
    if (l == r) return nd->f.eval(x);
    if (mid >= x)
     return min(
       nd->f.eval(x), query(x, l, mid, nd->l));
    return min(
     nd->f.eval(x), query(x, mid + 1, r, nd->r));
  /* -sz <= query_x <= sz */
 void init(int _sz) {
   sz = _sz + 1;
    root = NULL;
  void add_line(LL m, LL c) {
    line v(m, c);
    insert(v, -sz, sz, root);
 LL query(LL x) { return query(x, -sz, sz, root); }
3.6 persistent
const int MAXN = 2e5 + 5;
int a[MAXN];
int sum[MAXN * 25], lc[MAXN * 25], rc[MAXN * 25];
int add_node() {
    static int now = 0;
    return ++now;
void pull(int x) {
```

```
sum[x] = sum[lc[x]] + sum[rc[x]];
void init(int &x, int lx, int rx) {
    if (!x) x = add_node();
    if (lx + 1 == rx) return;
    int mid = (lx + rx) / 2;
    init(lc[x], lx, mid);
init(rc[x], mid, rx);
void update(int fa, int &x, int lx, int rx, int i) {
    if (!x) x = add_node();
    if (lx + 1 == rx) return sum[x]++, void();
    int mid = (lx + rx) / 2;
    if (i < mid) {</pre>
        rc[x] = rc[fa];
        update(lc[fa], lc[x], lx, mid, i);
    else {
        lc[x] = lc[fa];
        update(rc[fa], rc[x], mid, rx, i);
    pull(x);
int query(int x, int lx, int rx, int l, int r) {
    if (lx >= r or rx <= l) return 0;
    if (lx >= l and rx <= r) return sum[x];</pre>
    int mid = (lx + rx) / 2;
    return query(lc[x],
         lx, mid, l, r) + query(rc[x], mid, rx, l, r);
}
```

3.7 Sparse Table

```
const int N = 5e5 + 5, logN = __lg(N) + 1;
int a[N];
struct sparse_table { // 0-based
  int st[logN][N];
  void init(int n) {
    copy(a, a + n, st[0]);
    for (int i = 1; (1 << i) <= n; i++)
      for (int j = 0; j + (1 << i) - 1 <= n; <math>j++)
        st[i][j] = max(st
            [i - 1][j], st[i - 1][j + (1 << (i - 1))]);
  int qry(int l, int r) {
    int k = __lg(r - l + 1);
    return max(st[k][l], st[k][r - (1 << k) + 1]);</pre>
  }
} st;
// st.init(n)
// st.qry(l - 1, r - 1)
```

3.8 Treap

```
#include <bits/stdc++.h>
using namespace std;
mt19937 rng;
struct node {
  node *1, *r;
  int v, p, s; bool t; // val, pri, size, tag
  void pull() {
    s = 1;
    for (auto x : \{l, r\})
      if (x) s += x->s;
  void push() {
    if (t) {
      swap(l, r), t = 0;
      for (auto& x : \{l, r\})
         if (x) x->t ^= 1;
    }
  }
  node(int _v
       = 0): v(_v), p(rng()), s(1), t(0), l(0), r(0) {}
int sz(node* o) {return o ? o->s : 0;}
node* merge(node* a, node* b) {
  if (!a || !b) return a ? : b;
  if (a->p < b->p) return
       a \rightarrow push(), a \rightarrow r = merge(a \rightarrow r, b), a \rightarrow pull(), a;
  else return
       b->push(), b->l = merge(a, b->l), b->pull(), b;
void split(node
    * o, node*& a, node*& b, int k) { // a < k, b >= k
  if (!o) return a = b = nullptr, void();
  o->push();
  if (o->v < k) a = o, split(o->r, a->r, b, k);
  else b = o, split(o -> l, a, b -> l, k);
  o->pull();
void insert(node*& o, int k) {
  node *a, *b;
  split(
      o, a, b, k), o = merge(a, merge(new node(k), b));
void ssplit(node* o, node
    *& a, node*& b, int k) { // split first k things
  if (!o) return a = b = nullptr, void();
  o->push();
  if (sz(o->l) + 1 \le k
      ) a = o, ssplit(o->r, a->r, b, k - sz(o->l) - 1);
  else b = o, ssplit(o->l, a, b->l, k);
  o->pull();
void reverse(node* o, int l, int r) { // [l, r]
  node *a, *b, *c;
ssplit(o, a, b, l - 1), ssplit(b, b, c, r - l + 1);
  b->t ^= 1, o = merge(a, merge(b, c));
}
/*
node* root = nullptr;
for (int i = 0; i < n; i++)
  root = merge(root, new node(x));
```

3.9 ZKW Segment Tree

```
const int N = 5e5 + 5:
int a[N];
struct seg_tree { // 0-based
  int seg[N << 1], n;
void upd(int x, int v) {</pre>
    for (seg[x += n] = v; x > 1; x >= 1)
      seg[x \gg 1] = max(seg[x], seg[x ^ 1]);
  int qry(int l, int r) { // [ql, qr]
    int ret = -1e9;
    for (l += n, r += n + 1; l < r; l >>= 1, r >>= 1) {
      if (l & 1) ret = max(ret, seg[l++]);
      if (r & 1) ret = max(ret, seg[--r]);
    return ret;
  void init(int _n) {
    n = _n;
    copy(a, a + n, seg + n);
    for (int i = n - 1; i >= 0; i--)
```

```
seg[i] = max(seg[i << 1], seg[i << 1 | 1]);
} tree;
// tree.init(n)
// tree.qry(l - 1, r - 1)</pre>
```

4 Flow

4.1 Bipartite Matching

```
// 0(E * sqrt(V))
struct Bipartite_Matching { // 0-base
  int l, r;
  int mp[MAXN], mq[MAXN];
  int dis[MAXN], cur[MAXN];
  vector<int> G[MAXN];
  bool dfs(int u) {
    for (int &i = cur[u]; i < SZ(G[u]); ++i) {</pre>
       int e = G[u][i];
       if (!~mq[e]
            || (dis[mq[e]] == dis[u] + 1 && dfs(mq[e])))
         return mp[mq[e] = u] = e, 1;
    dis[u] = -1;
    return 0;
  bool bfs() {
    int rt = 0;
    queue<int> q;
    fill_n(dis, i, -1);
for (int i = 0; i < l; ++i)
       if (!~mp[i])
        q.push(i), dis[i] = 0;
    while (!q.empty()) {
       int u = q.front();
       q.pop();
       for (int e : G[u])
        if (!~mq[e])
           rt = 1;
         else if (!~dis[mq[e]]) {
           q.push(mq[e]);
           dis[mq[e]] = dis[u] + 1;
    return rt;
  int matching() {
    int rt = 0;
    fill_n(mp, l, -1);
    fill_n(mq, r, -1);
    while (bfs()) {
       fill_n(cur, l, 0);
for (int i = 0; i < l; ++i)
         if (!~mp[i] && dfs(i))
           ++rt;
    }
    return rt;
  void add_edge(int s, int t) {
    G[s].pb(t);
  void init(int _l, int _r) {
    l = _l, r = _r;
for (int i = 0; i < l; ++i)</pre>
      G[i].clear();
  }
};
4.2 Dinic
```

```
// O(V^2 * E)
// O(min(V^(2/3)
    , E^(1/2)) * E) for unit graph (all cap are same)
// O(E * sqrt(V)) for bipartite matching
struct MaxFlow { // O-base
    struct edge {
        int to, cap, flow, rev;
    };
    vector<edge> G[MAXN];
    int s, t, dis[MAXN], cur[MAXN], n;
    int dfs(int u, int cap) {
        if (u == t || !cap) return cap;
        for (int &i = cur[u]; i < (int)G[u].size(); ++i) {
            edge &e = G[u][i];
            if (dis[e.to] == dis[u] + 1 && e.flow != e.cap) {
                 int df = dfs(e.to, min(e.cap - e.flow, cap));
                 if (df) {</pre>
```

```
e.flow += df:
            G[e.to][e.rev].flow -= df;
            return df;
       }
     dis[u] = -1;
     return 0;
   bool bfs() {
     fill_n(dis, n, -1);
     queue<int> q;
     q.push(s), dis[s] = 0;
     while (!q.empty()) {
       int tmp = q.front();
        q.pop();
        for (auto &u : G[tmp])
          if (!~dis[u.to] && u.flow != u.cap) {
            q.push(u.to);
            dis[u.to] = dis[tmp] + 1;
     }
     return dis[t] != -1;
   int maxflow(int _s, int _t) {
     s = _s, t = _t;
int flow = 0, df;
     while (bfs()) {
       fill_n(cur, n, 0);
while ((df = dfs(s, INF))) flow += df;
     return flow;
   void init(int _n) {
     for (int i = 0; i < n; ++i) G[i].clear();</pre>
   void reset() {
     for (int i = 0; i < n; ++i)
       for (auto &j : G[i]) j.flow = 0;
   void add_edge(int u, int v, int cap) {
     G[u].pb(edge{v, cap, 0, (int)G[v].size()});
G[v].pb(edge{u, 0, 0, (int)G[u].size() - 1});
   }
};
```

4.3 KM

```
// O(n^3), where n is the number
      of vertices on one side of the bipartite graph
// Finds
      the maximum weight matching in a bipartite graph
struct KM { // 0-base
  int w[MAXN][MAXN], hl[MAXN], hr[MAXN], slk[MAXN], n;
  int fl[MAXN], fr[MAXN], pre[MAXN], qu[MAXN], ql, qr;
bool vl[MAXN], vr[MAXN];
  void init(int _n) {
    n = _n;
for (int i = 0; i < n; ++i)</pre>
      for (int j = 0; j < n; ++j) w[i][j] = -INF;
  void add_edge(int a, int b, int wei) {
    w[a][b] = wei;
  bool Check(int x) {
   if (vl[x] = 1, ~fl[x])
      return vr[qu[qr++] = fl[x]] = 1;
     while (\sim x) swap(x, fr[fl[x] = pre[x]]);
    return 0;
  void Bfs(int s) {
    fill(slk, slk + n, INF);
fill(vl, vl + n, 0), fill(vr, vr + n, 0);
    ql = qr = 0, qu[qr++] = s, vr[s] = 1;
    while (1) {
      int d;
      while (ql < qr)
for (int x = 0, y = qu[ql++]; x < n; ++x)</pre>
           if (!vl[x] &&
                slk[x] >= (d = hl[x] + hr[y] - w[x][y]))
             if (pre[x] = y, d) slk[x] = d;
             else if (!Check(x)) return;
       d = INF:
      for (int x = 0; x < n; ++x)
        if (!vl[x] && d > slk[x]) d = slk[x];
       for (int x = 0; x < n; ++x) {
```

```
if (vl[x]) hl[x] += d;
        else slk[x] -= d;
        if (vr[x]) hr[x] -= d;
      for (int x = 0; x < n; ++x)
        if (!vl[x] && !slk[x] && !Check(x)) return;
   }
  int Solve() {
    fill(fl, fl + n, -1), fill(fr, fr + n, -1),
         fill(hr, hr + n, 0);
    for (int i = 0; i < n; ++i)
      hl[i] = *max_element(w[i], w[i] + n);
    for (int i = 0; i < n; ++i) Bfs(i);</pre>
    int res = 0;
    for (int i = 0; i < n; ++i) res += w[i][fl[i]];</pre>
    return res;
 }
};
```

Maximum Simple Graph Matching // O(V^3) , where V is the number of vertices

```
struct Matching { // 0-base
  queue < int > q; int n;
  vector<int> fa, s, vis, pre, match;
  vector<vector<int>> G;
  int Find(int u)
  { return u == fa[u] ? u : fa[u] = Find(fa[u]); }
  int LCA(int x, int y) {
    static int tk = 0; tk++; x = Find(x); y = Find(y);
    for (;; swap(x, y)) if (x != n) {
        if (vis[x] == tk) return x;
        vis[x] = tk;
        x = Find(pre[match[x]]);
  void Blossom(int x, int y, int l) {
    for (; Find(x) != l; x = pre[y]) {
      pre[x] = y, y = match[x];
if (s[y] == 1) q.push(y), s[y] = 0;
      for (int z : \{x, y\}) if (fa[z] == z) fa[z] = l;
    }
  bool Bfs(int r) {
  iota(ALL(fa), 0); fill(ALL(s), -1);
    q = queue < int > (); q.push(r); s[r] = 0;
    for (; !q.empty(); q.pop()) {
      for (int x = q.front(); int u : G[x])
        if (s[u] == -1) {
          if (pre[u] = x, s[u] = 1, match[u] == n) {
             for (int a = u, b = x, last;
                  b != n; a = last, b = pre[a])
                   match[b], match[b] = a, match[a] = b;
             return true;
           q.push(match[u]); s[match[u]] = 0;
        } else if (!s[u] && Find(u) != Find(x)) {
           int l = LCA(u, x);
          Blossom(x, u, l); Blossom(u, x, l);
    return false;
  \label{eq:matching} \textit{Matching(int \_n)} \; : \; \textit{n(\_n), fa(n + 1), s(n + 1), vis}
  (n + 1), pre(n + 1, n), match(n + 1, n), G(n) {} void add_edge(int u, int v)
  { G[u].pb(v), G[v].pb(u); }
  int solve() {
    int ans = 0:
    for (int x = 0; x < n; ++x)
      if (match[x] == n) ans += Bfs(x);
    return ans:
 } // match[x] == n means not matched
```

4.5 MCMF

```
// O(FE * logV), where F is
      the maximum flow, \mbox{\ensuremath{E}} is edges, and \mbox{\ensuremath{V}} is vertices.
struct MinCostMaxFlow { // 0-base
  struct Edge {
    ll from, to, cap, flow, cost, rev;
  } *past[N];
  vector<Edge> G[N];
  int inq[N], n, s, t;
```

```
ll dis[N], up[N], pot[N];
   bool BellmanFord() {
     fill_n(dis, n, INF), fill_n(inq, n, 0);
     queue<int> q;
     auto relax = [&](int u, ll d, ll cap, Edge * e) {
       if (cap > 0 && dis[u] > d) {
         dis[u] = d, up[u] = cap, past[u] = e;
         if (!inq[u]) inq[u] = 1, q.push(u);
     };
     relax(s, 0, INF, 0);
     while (!q.empty()) {
       int u = q.front();
       q.pop(), inq[u] = 0;
       for (auto &e : G[u]) {
         ll d2 = dis[u] + e.cost + pot[u] - pot[e.to];
         relax
             (e.to, d2, min(up[u], e.cap - e.flow), &e);
     return dis[t] != INF;
   }
   void solve(int _s
     , int _t, ll &flow, ll &cost, bool neg = true) { s = \_s, t = \_t, flow = 0, cost = 0:
     if (neg) BellmanFord(), copy_n(dis, n, pot);
     for (; BellmanFord(); copy_n(dis, n, pot)) {
       for (int
           i = 0; i < n; ++i) dis[i] += pot[i] - pot[s];
       flow += up[t], cost += up[t] * dis[t];
       for (int i = t; past[i]; i = past[i]->from) {
        auto &e = *past[i];
         e.flow += up[t], G[e.to][e.rev].flow -= up[t];
    }
   }
   void init(int _n) {
     n = _n, fill_n(pot, n, 0);
     for (int i = 0; i < n; ++i) G[i].clear();</pre>
   void add_edge(ll a, ll b, ll cap, ll cost) {
     G[a].pb(Edge{a, b, cap, 0, cost, SZ(G[b])});
     G[b].pb(Edge{b, a, 0, 0, -cost, SZ(G[a]) - 1});
};
```

5 Geometry 5.1 Basic 2D

```
// Courtesy of Jinkela
const double PI = atan2(0.0, -1.0);
template < typename T>
struct point {
 T x, y;
  point() {}
  point(const T&x, const T&y): x(x), y(y) {}
  point operator+(const point &b)const {
    return point(x + b.x, y + b.y);
  point operator-(const point &b)const {
   return point(x - b.x, y - b.y);
  point operator*(const T &b)const {
    return point(x * b, y * b);
  point operator/(const T &b)const {
    return point(x / b, y / b);
  bool operator==(const point &b)const {
    return x == b.x && y == b.y;
  T dot(const
       point &b)const { return x * b.x + y * b.y; }
  T cross(const
       point &b)const { return x * b.y - y * b.x; }
  point normal()const { //求法向量
    return point(-y, x);
  T abs2()const { return dot(*this); }
 Trad(const point &b)const { //兩向量的弧度
    return fabs(atan2(fabs(cross(b)), dot(b)));
  T getA()const { //對x軸的弧度
    T A = atan2(y, x); //超過180度會變負的
if (A <= -PI / 2)A += PI * 2;
```

```
if ((p[i].y > t.y) != (p[j].y > t.y)) {
  T L = (t.x - p[i].x) * (p[j].y - p[i].y);
  T R = (p[j].x - p[i].x) * (t.y - p[i].y);
    return A:
 }
template<typename T>
                                                                    if (p[j].y < p[i].y) \{L = -L; R = -R;\}
struct line {
                                                                    if (L < R)c = !c;
                                                                  }
 line() {}
  point<T> p1, p2;
                                                                } return c;
  T a, b, c; //ax+by+c=0
                                                              int point_in_convex(const point<T>&x)const {
  line(const
       point<T>&x, const point<T>&y): p1(x), p2(y) {}
                                                                int l = 1, r = (int)p.size() - 2;
  void pton() { //轉成一般式
                                                                while (l <= r) { //點是否在凸
    a = p1.y - p2
                                                                  多邊形\mathbf{P}, 是的話回傳1、在邊上回傳-1、否則回傳0 int mid = (l + r) / 2;
        .y; b = p2.x - p1.x; c = -a * p1.x - b * p1.y;
                                                                  T a1 = (p[mid] - p[0]).cross(x - p[0]);
  T ori(const point<T> &p)const
                                                                  T a2 = (p[mid + 1] - p[0]).cross(x - p[0]);
       { //點和有向直ID的關ID, >0左邊、=0在ID上<0右邊
                                                                  if (a1 >= 0 && a2 <= 0) {
    return (p2 - p1).cross(p - p1);
                                                                    Tres
 }
                                                                         = (p[mid + 1] - p[mid]).cross(x - p[mid]);
                                                                    return res > 0 ? 1 : (res >= 0 ? -1 : 0);
 T btw(const point<T> &p)const { //點投影落在 E 段上<=0
    return (p1 - p).dot(p2 - p);
                                                                  if (a1 < 0)r = mid - 1; else l = mid + 1;
                                                                } return 0;
  bool point_on_segment(const point<T>&p)const {
                                                              }
    return ori(p) == 0 && btw(p) <= 0;
                                                              vector<T> getA()const { //凸包邊對x軸的夾角
  T dis2(const point<T> &p, bool
                                                                vector <T>res;//一定是遞增的
                                                                for (size_t i = 0; i < p.size(); ++i)</pre>
       is_segment = 0)const { //點跟直匠/匠段的距離平方
    point < T > v = p2 - p1, v1 = p - p1;
                                                                  res.push_back
                                                                      ((p[(i + 1) % p.size()] - p[i]).getA());
    if (is_segment) {
                                                                return res;
      point < T > v2 = p - p2;
      if (v.dot(v1) <= 0)return v1.abs2();</pre>
                                                              bool line_intersect(const
      if (v.dot(v2) >= 0)return v2.abs2();
                                                                   vector<T>&A, const line<T> &l)const { //O(logN)
                                                                int f1 = upper_bound(A.begin
    T tmp = v.cross(v1); return tmp * tmp / v.abs2();
                                                                    (), A.end(), (l.p1 - l.p2).getA()) - A.begin();
 }
                                                                int f2 = upper_bound(A.begin
 T seg_dis2(const line<T> &l)const { //兩  段 距離 平方
                                                                    (), A.end(), (l.p2 - l.p1).getA()) - A.begin();
    return min({dis2(l.p1, 1),
                                                                return l.cross_seg(line<T>(p[f1], p[f2]));
         dis2(l.p2, 1), l.dis2(p1, 1), l.dis2(p2, 1)});
                                                              T diam() {
 point<T> projection
                                                                int n = p.size(), t = 1;
      (const point <T> &p) const { //點對直图的投影
                                                                T ans = 0; p.push_back(p[0]);
    point < T > n = (p2 - p1).normal();
                                                                for (int i = 0; i < n; i++) {
    return p - n * (p - p1).dot(n) / n.abs2();
                                                                  point < T > now = p[i + 1] - p[i];
                                                                  while (now.cross(p[t + 1] - p[
    i]) > now.cross(p[t] - p[i]))t = (t + 1) % n;
 point<T> mirror(const point<T> &p)const {
    //點對直I的鏡射,要先呼叫pton轉成一般式
                                                                  ans = max(ans, (p[i] - p[t]).abs2());
    point < T > R; T d = a * a + b * b;
                                                                } return p.pop_back(), ans;
    R.x = (b * b * p.x -
        a * a * p.x - 2 * a * b * p.y - 2 * a * c) / d;
                                                              T min_cover_rectangle() {
    R.y = (a * a * p.y
                                                                int n = p.size(), t = 1, r = 1, l;
        b * b * p.y - 2 * a * b * p.x - 2 * b * c) / d;
                                                                if (n < 3)return 0; //也可以做最小周長矩形
    return R:
                                                                T ans = 1e99; p.push_back(p[0]);
                                                                for (int i = 0; i < n; i++) {
 bool parallel(const line &l)const {
                                                                  point < T > now = p[i + 1] - p[i];
   return (p1 - p2).cross(l.p1 - l.p2) == 0;
                                                                  while (now.cross(p[t + 1] - p[
 }
                                                                       i]) > now.cross(p[t] - p[i]))t = (t + 1) % n;
};
                                                                  while (now.dot(p[r + 1] -
template < typename T>
                                                                      p[i]) > now.dot(p[r] - p[i]))r = (r + 1) % n;
struct polygon {
                                                                  if (!i)l = r;
 polygon() {}
                                                                  while (now.dot(p[l + 1] - p
  vector<point<T> > p;//逆時針順序
                                                                      [i] <= now.dot(p[l] - p[i]))l = (l + 1) % n;
  T double_signed_area()const {
                                                                  T d = now.abs2();
    T ans = 0;
                                                                  T tmp = now.cross(p[t] - p[i]) * (now.
    for (int i = p
    .size() - 1, j = 0; j < (int)p.size(); i = j++)</pre>
                                                                  dot(p[r] - p[i]) - now.dot(p[l] - p[i])) / d;
ans = min(ans, tmp);
      ans += p[i].cross(p[j]);
                                                                } return p.pop_back(), ans;
    return ans;
 }
                                                              T dis2(polygon &pl) { //凸包最近距離平方
  point<T> center_of_mass()const {
                                                                vector<point<T> > &P = p, &Q = pl.p;
    T cx = 0, cy = 0, w = 0;
                                                                int n = P.size(), m = Q.size(), l = 0, r = 0;
    for (int i = p.size
                                                                for (int
        () - 1, j = 0; j < (int)p.size(); i = j++) {
                                                                     i = 0; i < n; ++i)if (P[i].y < P[l].y)l = i;
      T a = p[i].cross(p[j]);
                                                                for (int
      cx += (p[i].
                                                                     i = 0; i < m; ++i)if (Q[i].y < Q[r].y)r = i;
         x + p[j].x) * a; cy += (p[i].y + p[j].y) * a;
                                                                P.push_back(P[0]), Q.push_back(Q[0]);
      w += a;
                                                                T ans = 1e99;
   } return point<T>(cx / 3 / w, cy / 3 / w);
                                                                for (int i = 0; i < n; ++i) {
 }
                                                                  while ((P[l] - P[l + 1])
.cross(Q[r + 1] - Q[r]) < 0)r = (r + 1) % m;
  int ahas(const point<T>& t)const { //點是否在簡
      單多邊形匠,是的話回傳1、在邊上回傳-1、否則回傳0
                                                                  ans = min(ans, line<T>(P[l],
    int c = 0; //Works for clockwise input as well
                                                                      P[l + 1]).seg_dis2(line<T>(Q[r], Q[r + 1])));
    for (int i
                                                                  l = (l + 1) \% n;
         0, j = p.size() - 1; i < p.size(); j = i++) {
                                                                } return P.pop_back(), Q.pop_back(), ans;
      if (line<</pre>
          T>(p[i], p[j]).point_on_segment(t))return -1;
                                                              static int sign(const point<T>&t) {
```

```
return (t.y ? t.y : t.x) < 0;
}
static bool
     angle_cmp(const line<T>& A, const line<T>& B) {
  point <T > a = A.p2 - A.p1, b = B.p2 - B.p1;
  return sign(a) < sign</pre>
      (b) || (sign(a) == sign(b) && a.cross(b) > 0);
int halfplane_intersection(vector<line<T> > &s) {
  sort(s.begin()
      , s.end(), angle_cmp); // E段左側匠該匠段半平面
  int L, R, n = s.size();
  vector<point<T> > px(n);
  vector < line < T > q(n);
  q[L = R = 0] = s[0];
  for (int i = 1; i < n; ++i) {</pre>
    while (L < R \&\& s[i].ori(px[R - 1]) <= 0)--R;
    while (L < R \&\& s[i].ori(px[L]) <= 0)++L;
    q[++R] = s[i];
    if (q[R].parallel(q[R
         - 1]) && q[--R].ori(s[i].p1) > 0)q[R] = s[i];
    if (L < R)
        px[R - 1] = q[R - 1].line_intersection(q[R]);
  while (L < R \&\& q[L].ori(px[R - 1]) <= 0)--R;
  p.clear();
  if (R - L <= 1)return 0;
  px[R] = q[R].line_intersection(q[L]);
  for (int i = L; i <= R; ++i)p.push_back(px[i]);</pre>
  return R - L + 1;
```

5.2 Convex Hull

```
#define f first
#define s second
#define ALL(x) (x).begin(), (x).end()
template <typename T>
pair<T, T> operator
    -(const pair<T, T>& a, const pair<T, T>& b) {
  return {a.f - b.f, a.s - b.s};
template <typename T>
int cross(const pair<T,</pre>
     T>& o, const pair<T, T>& a, const pair<T, T>& b) {
  auto p = a - o, q = b - o;
  return p.f * q.s - q.f * p.s;
template <typename T>
vector
    <pair<T, T>> convex_hull(vector<pair<T, T>> hull) {
  if (hull.size() <= 2) return hull;</pre>
 sort(ALL(hull));
  vector<pair<T, T>> stk;
  int n = hull.size();
  for (int i = 0; i < n; i++) {</pre>
    while (stk.size() >= 2 && cross
        (stk.end()[-2], stk.end()[-1], hull[i]) <= 0)
      stk.pop_back();
    stk.push_back(hull[i]);
      int i = n - 2, t = stk.size() + 1; i >= 0; i--) {
    while ((int)stk.size() >= t && cross
        (stk.end()[-2], stk.end()[-1], hull[i]) <= 0)
      stk.pop_back();
    stk.push_back(hull[i]);
  return stk.pop back(), stk;
```

5.3 Dynamic Convex Hull

```
struct Line {
  ll a, b, l = MIN, r = MAX;
Line(ll a, ll b): a(a), b(b) {}
   ll operator()(ll x) const {
     return a * x + b;
  bool operator<(Line b) const {</pre>
     return a < b.a;</pre>
  bool operator<(ll b) const {</pre>
     return r < b;
  }
};
```

```
ll iceil(ll a, ll b) {
  if (b < 0) a *= -1, b *= -1;
if (a > 0) return (a + b - 1) / b;
  else return a / b;
ll intersect(Line a, Line b) {
  return iceil(a.b - b.b, b.a - a.a);
struct DynamicConvexHull {
  multiset<Line, less<>> ch;
  void add(Line ln) {
    auto it = ch.lower_bound(ln);
    while (it != ch.end()) {
      Line tl = *it;
       if (tl(tl.r) <= ln(tl.r)) {</pre>
        it = ch.erase(it);
      else break;
    auto it2 = ch.lower_bound(ln);
    while (it2 != ch.begin()) {
      Line tl = *prev(it2);
      if (tl(tl.l) <= ln(tl.l)) {</pre>
        it2 = ch.erase(prev(it2));
      else break;
    it = ch.lower_bound(ln);
    if (it != ch.end()) {
      Line tl = *it;
      if (tl(tl.l) >= ln(tl.l)) ln.r = tl.l - 1;
      else {
        ll pos = intersect(ln, tl);
         tl.l = pos;
        ln.r = pos - 1;
        ch.erase(it);
        ch.insert(tl);
      }
    it2 = ch.lower_bound(ln);
    if (it2 != ch.begin()) {
      Line tl = *prev(it2);
      if (tl(tl.r) >= ln(tl.r)) ln.l = tl.r + 1;
         ll pos = intersect(tl, ln);
         tl.r = pos - 1;
         ln.l = pos;
         ch.erase(prev(it2));
        ch.insert(tl);
    if (ln.l <= ln.r) ch.insert(ln);</pre>
  ll query(ll pos) {
    auto it = ch.lower_bound(pos);
    if (it == ch.end()) return 0;
    return (*it)(pos);
};
5.4 Segmentation Intersection
```

```
int sign(ll x) {
  return (x > 0 ? 1 : (x < 0 ? -1 : 0));
ll cross
  (pair<ll, ll> o, pair<ll, ll> a, pair<ll, ll> b) {
return (a.first - o.first) * (b.second - o.second
      ) - (a.second - o.second) * (b.first - o.first);
}
bool intersect1D(ll a, ll b, ll c, ll d) {
  if (a > b) swap(a, b);
  if (c > d) swap(c, d);
  return max(a, c) <= min(b, d);</pre>
bool intersect2D(pair<ll, ll> a
     , pair<ll, ll> b, pair<ll, ll> c, pair<ll, ll> d) {
  return
        intersect1D(a.first, b.first, c.first, d.first)
```

6 Math 6.1 Big Int

```
#include <bits/stdc++.h>
using namespace std;
template<typename T>
inline string to_string(const T& x) {
  stringstream ss;
  return ss << x, ss.str();</pre>
using ll = long long;
struct bigN: vector<ll> {
  const static
       int base = 10000000000, width = log10(base);
  bool negative;
 bigN(const iterator
       a, const_iterator b): vector<ll>(a, b) {}
  bigN(string s) {
    if (s.empty()) return;
if (s[0] == '-')negative = 1, s = s.substr(1);
    else negative = 0;
    for (int
         i = int(s.size()) - 1; i >= 0; i -= width) {
      ll t = 0;
      for (int j = max(0, i - width + 1); j <= i; ++j)
  t = t * 10 + s[j] - '0';</pre>
      push_back(t);
    trim();
  template < typename T>
bigN(const T &x): bigN(to_string(x)) {}
  bigN(): negative(0) {}
  void trim() {
    while (size() && !back())pop_back();
    if (empty()) negative = 0;
  void carry(int _base = base) {
  for (size_t i = 0; i < size(); ++i) {</pre>
      if (at(i) >= 0 && at(i) < _base) continue;</pre>
      if (i + 1u == size())push_back(0);
      int r = at(i) % _base;
      if (r < 0)r += _base;</pre>
      at(i + 1) += (at(i) - r) / _base;
      at(i) = r;
    }
  }
  int abscmp(const bigN &b) const {
    if (size() > b.size()) return 1;
    if (size() < b.size()) return -1;</pre>
    for (int i = int(size()) - 1; i >= 0; --i) {
      if (at(i) > b[i]) return 1;
      if (at(i) < b[i]) return -1;</pre>
    return 0;
  int cmp(const bigN &b) const {
    if (negative
         != b.negative) return negative ? -1 : 1;
    return negative ? -abscmp(b) : abscmp(b);
  bool operator
      <(const bigN&b) const {return cmp(b) < 0;}
  bool operator
      >(const bigN&b) const {return cmp(b) > 0;}
  bool operator
      <=(const bigN&b) const {return cmp(b) <= 0;}
  bool operator
       >=(const bigN&b) const {return cmp(b) >= 0;}
  bool operator == (const bigN&b) const {return !cmp(b);}
  bool operator
      !=(const bigN&b) const {return cmp(b) != 0;}
  bigN abs() const {
    bigN res = *this;
    return res.negative = 0, res;
  bigN operator-() const {
```

```
biaN res = *this:
  return res.negative = !negative, res.trim(), res;
bigN operator+(const bigN &b) const {
  if (negative) return -(-(*this) + (-b));
  if (b.negative) return *this - (-b);
  bigN res = *this;
  if (b.size() > size()) res.resize(b.size());
  for (size_t
       i = 0; i < b.size(); ++i) res[i] += b[i];
 return res.carry(), res.trim(), res;
bigN operator-(const bigN &b) const {
  if (negative) return -(-(*this) - (-b));
  if (b.negative) return *this + (-b);
  if (abscmp(b) < 0) return -(b - (*this));</pre>
  bigN res = *this;
  if (b.size() > size()) res.resize(b.size());
  for (size_t
       i = 0; i < b.size(); ++i) res[i] -= b[i];
 return res.carry(), res.trim(), res;
bigN convert_base
    (int old_width, int new_width) const {
  vector<
      long long> p(max(old_width, new_width) + 1, 1);
  for (size_t
       i = 1; i < p.size(); ++i)p[i] = p[i - 1] * 10;
  bigN ans;
  long long cur = 0;
  int cur_id = 0;
  for (size_t i = 0; i < size(); ++i) {</pre>
    cur += at(i) * p[cur_id];
    cur_id += old_width;
    while (cur_id >= new_width) {
      ans.push_back(cur % p[new_width]);
      cur /= p[new_width];
      cur_id -= new_width;
  return ans.push_back(cur), ans.trim(), ans;
bigN karatsuba(const bigN &b) const {
  bigN res; res.resize(size() * 2);
  if (size() <= 32) {
    for (size_t i = 0; i < size(); ++i)</pre>
      for (size_t j = 0; j < size(); ++j)</pre>
        res[i + j] += at(i) * b[j];
    return res;
  size_t k = size() / 2;
  bigN a1(begin(), begin() + k);
  bigN a2(begin() + k, end());
  bigN b1(b.begin(), b.begin() + k);
  bigN b2(b.begin() + k, b.end());
  bigN a1b1 = a1.karatsuba(b1);
  bigN a2b2 = a2.karatsuba(b2);
  for (size_t i = 0; i < k; ++i)a2[i] += a1[i];
for (size_t i = 0; i < k; ++i)b2[i] += b1[i];</pre>
  bigN r = a2.karatsuba(b2);
  for (size_t
       i = 0; i < a1b1.size(); ++i)r[i] -= a1b1[i];
  for (size_t
       i = 0; i < a2b2.size(); ++i)r[i] -= a2b2[i];
  for (size t
       i = 0; i < r.size(); ++i)res[i + k] += r[i];
  for (size_t
       i = 0; i < a1b1.size(); ++i)res[i] += a1b1[i];
  for (size_t i = 0; i
       < a2b2.size(); ++i)res[i + size()] += a2b2[i];
  return res;
bigN operator*(const bigN &b) const {
  const static int mul_base
       = 1000000, mul_width = log10(mul_base);
  bigN A = convert_base(width, mul_width);
  bigN B = b.convert_base(width, mul_width);
  int n = max(A.size(), B.size());
  while (n & (n - 1))++n;
  A.resize(n), B.resize(n);
  bigN res = A.karatsuba(B);
  res.negative = negative != b.negative;
  res.carry(mul_base);
  res = res.convert_base(mul_width, width);
  return res.trim(), res;
```

```
bigN operator*(long long b) const {
    bigN res = *this;
    if (b < 0) res.negative = !negative, b = -b;
    for (size_t
         i = 0, is = 0; i < res.size() || is; ++i) {
      if (i == res.size()) res.push_back(0);
      long long a = res[i] * b + is;
      is = a / base;
      res[i] = a % base;
    return res.trim(), res;
  bigN operator/(const bigN &b) const {
    int norm = base / (b.back() + 1);
    bigN x = abs() * norm;
    bigN y = b.abs() * norm;
    bigN q, r;
    q.resize(x.size());
    for (int i = int(x.size()) - 1; i >= 0; --i) {
      r = r * base + x[i];
      int s1 = r.size() <= y.size() ? 0 : r[y.size()];
      int s2
           = r.size() < y.size() ? 0 : r[y.size() - 1];
      int d = (ll(base) * s1 + s2) / y.back();
      r = r - y * d;
      while (r.negative) r = r + y, --d;
      q[i] = d;
    q.negative = negative != b.negative;
    return q.trim(), q;
  bigN operator%(const bigN &b) const {
    return *this - (*this / b) * b;
  friend istream& operator>>(istream &ss, bigN &b) {
    string s;
    return ss >> s, b = s, ss;
      ostream& operator << (ostream &ss, const bigN &b) {
    if (b.negative) ss <<</pre>
    ss << (b.empty() ? 0 : b.back());
    for (int i = int(b.size()) - 2; i >= 0; --i)
      ss << setw(width) << setfill('0') << b[i];</pre>
    return ss;
  template < typename T>
  operator T() {
    stringstream ss;
    ss << *this;
    T res;
    return ss >> res, res;
};
```

6.2 Chinese Remainder

```
int solve(int n, vector<int> &a, vector<int> &m){
     int M = 1;
     for(auto i : m) M *= i;
     int ans = 0;
     for(int i = 0; i < n; i++){</pre>
         int m1 = M / m[i], m2 = extgcd(m1, m[i]).X;
ans += (a[i] * m1 * m2) % M;
     ans = ans % M + M;
     ans %= M;
     return ans;
}
```

6.3 Extgcd

```
pair<ll, ll> extgcd(ll a, ll b) {
  if (b == 0) return {1, 0};
  auto [xp, yp] = extgcd(b, a % b);
  return {yp, xp - a / b * yp};
```

6.4 FFT

```
// Remember not to output -0
   polynomial multiply:
   DFT(a, len); DFT(b, len);
   for(int i=0;i<len;i++) c[i] = a[i]*b[i];</pre>
   iDFT(c, len);
   (len must be 2^k and = 2^m(max(a, b)))
```

```
Hand written Cplx would be 2x faster
Cplx omega[2][N];
void init_omega(int n) {
  static constexpr llf PI = acos(-1);
  const llf arg = (PI + PI) / n;
  for (int i = 0; i < n; ++i)</pre>
    omega[0][i] = {cos(arg * i), sin(arg * i)};
  for (int i = 0; i < n; ++i)
    omega[1][i] = conj(omega[0][i]);
void tran(Cplx arr[], int n, Cplx omg[]) {
  for (int i = 0, j = 0; i < n; ++i) {
    if (i > j)swap(arr[i], arr[j]);
    for (int l = n >> 1; (j ^= l) < l; l >>= 1);
  for (int l = 2; l <= n; l <<= 1) {
    int m = l >> 1;
    for (auto p = arr; p != arr + n; p += l) {
      for (int i = 0; i < m; ++i) {
        Cplx t = omg[n / l * i] * p[m + i];
p[m + i] = p[i] - t; p[i] += t;
      }
  }
}
void DFT(Cplx arr[], int n) {tran(arr, n, omega[0]);}
void iDFT(Cplx arr[], int n) {
  tran(arr, n, omega[1]);
for (int i = 0; i < n; ++i) arr[i] /= n;</pre>
```

6.5 Gauss Elimination

```
#include <bits/stdc++.h>
std::bitset<1000> a[500];
int main() {
  int n; std::cin >> n;
  for (int i = 0; i < n; ++i) {</pre>
    for (int j = 0, t; j < n; ++j)
       std::cin >> t, a[i][j] = t;
     a[i][i + n] = 1;
  for (int i = 0; i < n; ++i) {</pre>
    int t;
     for (t = i; t < n; ++t) if (a[t][i]) break;</pre>
     if (t == n) return std::cout << "-1\n", 0;</pre>
     std::swap(a[i], a[t]);
    for (int i
         = i + 1; j < n; ++j) if (a[j][i]) a[j] ^= a[i];
  for (int i = n - 1; i >= 0; --i)
    for (int j = i - 1; j >= 0; --j)
if (a[j][i]) a[j] ^= a[i];
  for (int i = 0; i < n; ++i) {
     std::vector<int> ans;
     for (int j = n; j < 2 *
          n; ++j) if (a[i][j]) ans.push_back(j - n + 1);
    for (size_t j = 0; j < ans.size(); ++j)
std::cout << ans[j] << " \n"[j == ans.size()];</pre>
  return 0;
}
```

6.6 Gauss Elimination 2

```
using ll = long long;
const ll mod = 998244353;
ll fp(ll a, ll b) {
  ll ret = 1;
  for (; b; b >>= 1, a = a * a % mod)
    if (b & 1) ret = ret * a % mod;
 return ret;
}
vector<ll> gauss_elimination
    (vector<vector<ll>>% a) { // n * (n+1)
  // if a[i][j] < 0, a[i][j] += mod
  int n = a.size();
  bool swp = 0;
  for (int i = 0; i < n; i++) {
    for (int k = i; k < n; k++)</pre>
      if (a[i][i] == 0 && a[k][i] != 0) {
        swap(a[i], a[k]), swp ^= 1; // det = -det
        break;
      }
```

```
if (a[i][i] == 0) return {}; // 0
  ll inv = fp(a[i][i], mod - 2);
  for (int j = 0; j < n; j++) {
    if (i != j) {
      ll tmp = a[j][i] * inv % mod;
      for (int k = i; k <= n; k++)</pre>
        a[j][k] = (a[
             j][k] - tmp * a[i][k] % mod + mod) % mod;
    }
 }
// general solution
vector<ll> ans(n);
for (int i = 0; i < n; i++)
     ans[i] = a[i][n] * fp(a[i][i], mod - 2) % mod;
return ans;
// det
// ll ret = 1;
// for (
int i = 0; i < n; i++) ret = ret * a[i][i] % mod;
// return swp ? mod - ret : ret;
```

6.7 Karatsuba

```
const ll base = 10000000;
void karatsuba(const vector<ll</pre>
    >& f, const vector<ll>& g, vector<ll>& c, int n) {
  if (n <= 32) {
    for (int i = 0; i < n; i++)</pre>
       for (int j = 0; j < n; j++)
        c[i + j] += f[i] * g[j];
    return;
  }
  vector
       <ll> f1(n / 2), f2(n / 2), g1(n / 2), g2(n / 2);
  copy(f.begin(), f.begin() + n / 2, f1.begin()
       ), copy(f.begin() + n / 2, f.end(), f2.begin());
  copy(g.begin(), g.begin() + n / 2, g1.begin()
), copy(g.begin() + n / 2, g.end(), g2.begin());
  vector<ll> t1(n), t2(n), t3(n);
  karatsuba(
       f1, g1, t1, n / 2), karatsuba(f2, g2, t2, n / 2);
  for (int i = 0; i < n / 2; i++) f1[i] += f2[i];
for (int i = 0; i < n / 2; i++) g1[i] += g2[i];
  karatsuba(f1, g1, t3, n / 2);
  for (int i = 0; i < n; i++) t3[i] -= t1[i] + t2[i];
  for (int i = 0; i < n; i++)</pre>
    c[i] += t1
         [i], c[i + n] += t2[i], c[i + n / 2] += t3[i];
void mul(const vector
    <ll>& a, const vector<ll>& b, vector<ll>& c) {
  int n = a.size(), m = b.size(), t = max(n, m), p = 1;
  while (p < t) p <<= 1;
  vector<ll> aa(p), bb(p);
  copy(a.begin(), a.end(), aa
   .begin()), copy(b.begin(), b.end(), bb.begin());
  c.assign(p << 1, 0), karatsuba(aa, bb, c, p);</pre>
  for (int i = 0; i < p; i++)</pre>
    c[i + 1] += c[i] / base, c[i] %= base;
  if (c[p]) p++;
  c.resize(p);
}
```

6.8 Linear Sieve

```
vector < bool > isp;
vector < int > p;
void sieve(int n) {
  p.clear(), isp.assign(n + 1, 1);
  isp[0] = isp[1] = 0;
  for (int i = 2; i <= n; i++) {
    if (isp[i]) p.eb(i);
    for (const auto& x : p) {
      if (1LL * i * x > n) break;
      isp[i * x] = 0;
      if (i % x == 0) break;
    }
}
```

6.9 Matrix

```
template <typename T> using vec = vector<T>;
```

6.10 Miller Rabin

```
using ll = ll;
ll mod_mul(ll a, ll b, ll m) {
  a \%= m, b \%= m;
  ll y = (ll)((
  double)a * b / m + 0.5); /* fast for m < 2^5  */ ll r = (a * b - y * m) % m;
  return r < 0 ? r + m : r;
template < typename T>
T pow(T a, T b, T mod) \{ //a^b \mod 
  T ans = 1;
  for (; b; a = mod_mul(a, a, mod), b >>= 1)
    if (b & 1) ans = mod_mul(ans, a, mod);
  return ans;
int sprp[3] = \{2, 7, 61\}; // range of int
int llsprp[7] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022}; // range of unsigned ll
template < typename T>
bool isprime(T n, int *sprp, int num) {
  if (n == 2)return 1;
  if (n < 2 || n % 2 == 0) return 0;
  int t = 0;
  T u = n - 1:
  for (; u % 2 == 0; ++t)u >>= 1;
  for (int i = 0; i < num; ++i) {
    T a = sprp[i] % n;
    if (a == 0 || a == 1 || a == n - 1) continue;
    T x = pow(a, u, n);
    if (x == 1 || x == n - 1) continue;
    for (int j = 1; j < t; ++j) {
      x = mod_mul(x, x, n);
      if (x == 1) return 0;
if (x == n - 1) break;
    if (x == n - 1) continue;
    return 0;
  return 1:
```

6.11 NTT

```
const int G = 3, P = 998244353;
const int sval = 100, split = log10(sval);
int fpow(int x, int y) {
  int ret = 1;
  for (; y; y >>= 1, x = 1LL * x * x % P)
  if (y & 1) ret = 1LL * ret * x % P;
  return ret;
void ntt(vector<int>& x, int lim, int opt) {
 if (i < j) swap(x[i], x[j]);</pre>
  for (int m = 2; m <= lim; m <<= 1) {
    int k = m >> 1;
    int gn = fpow(G, (P - 1) / m);
    for (int i = 0; i < lim; i += m) {</pre>
      int g = 1;
      for (int
           j = 0; j < k; ++j, g = 1LL * g * gn % P) {
        int tmp = 1LL * x[i + j + k] * g % P;
x[i + j + k] = (x[i + j] - tmp + P) % P;
        x[i + j] = (x[i + j] + tmp) % P;
    }
  if (opt == -1) {
```

void tran(int n, LL a[], bool inv_ntt = false) {

int basic = MAXN / n , theta = basic;

LL w = omega[i * theta % MAXN];
for (int j = i; j < n; j += m) {</pre>

for (int m = n; m >= 2; m >>= 1) {

for (int i = 0; i < mh; i++) {</pre>

int mh = m >> 1;

int k = j + mh;

```
reverse(x.begin() + 1, x.begin() + lim);
int inv = fpow(lim, P - 2);
for (int in part);
                                                                           LL x = a[j] - a[k];
                                                                           if (x < 0) x += P;
    for (int i = 0; i < lim; ++i)</pre>
                                                                           a[j] += a[k];
      x[i] = 1LL * x[i] * inv % P;
                                                                           if (a[j] > P) a[j] -= P;
                                                                           a[k] = (w * x) % P;
                                                                        }
                                                                      }
vector<int> mul(vector<int> a, vector<int> b) {
  int lim = 1, n = a.size(), m = b.size();
                                                                      theta = (theta * 2) % MAXN;
  while (lim < (n + m - 1)) lim <<= 1;
  a.resize(lim + 1), b.resize(lim + 1);
                                                                    for (int j = 1; j < n - 1; j++) {
  for (int k = n >> 1; k > (i ^= k); k >>= 1);
  ntt(a, lim, 1), ntt(b, lim, 1);
for (int i = 0; i < lim; ++i)</pre>
    a[i] = 1LL * a[i] * b[i] % P;
                                                                      if (j < i) swap(a[i], a[j]);</pre>
  ntt(a, lim, -1);
                                                                    if (inv_ntt) {
  int len = 0;
  for (int i = 0; i < lim; ++i) {</pre>
                                                                      LL ni = inv(n, P);
                                                                      reverse( a + 1 , a + n );
for (i = 0; i < n; i++)
    if (a[i] >= sval) len
        = i + 1, a[i + 1] += a[i] / sval, a[i] %= sval;
    if (a[i]) len = max(len, i);
                                                                        a[i] = (a[i] * ni) % P;
                                                                  }
  while (a[len] >= sval) a[
      len + 1] += a[len] / sval, a[len] %= sval, len++;
                                                               };
  return a.resize(len + 1), a;
                                                                const LL P = 2013265921, root = 31;
                                                                const int MAXN = 4194304;
void print(const vector<int>& v) {
                                                               NTT<P, root, MAXN> ntt;
  if (!v.size()) return;
                                                                6.13 Pollard Rho
  cout << v.back();</pre>
  for (int i = v.size() - 2; ~i; --i)
                                                                // does not work when n is prime
    cout << setfill('0') << setw(split) << v[i];</pre>
                                                                ll add(ll
  cout << '\n';
                                                                        ll b, ll m) {return (a += b) > m ? a - m : a;}
                                                                     а.
                                                                ll mul(ll a, ll b, ll m) {
int main() {
                                                                  a \%= m, b \%= m;
 ios::sync_with_stdio(false), cin.tie(nullptr);
                                                                  ll y = (ll)((
  string stra, strb;
                                                                      double)a * b / m + 0.5); /* fast for m < 2^58 */</pre>
  while (cin >> stra >> strb) {
                                                                  ll r = (a * b - y * m) % m;
    vector < int > a((stra.size() + split - 1) / split);
vector < int > b((strb.size() + split - 1) / split);
                                                                  return r < 0 ? r + m : r;
    int tmp = stra.size();
                                                                ll f(ll
    for (auto& i : a)
                                                                     x, ll mod) { return add(mul(x, x, mod), 1, mod); }
      tmp -= split, i = atoi(stra.substr(max
                                                                ll pollard_rho(ll n) {
          (0, tmp), min(split, split + tmp)).data());
                                                                  if (!(n & 1)) return 2;
    tmp = strb.size();
                                                                  while (true) {
    for (auto& i : b)
                                                                    ll y =
      tmp -= split, i = atoi(strb.substr(max
                                                                          2, x = rand() % (n - 1) + 1, res = 1, tmp = 1;
           (0, tmp), min(split, split + tmp)).data());
                                                                    for (int sz = 2; res == 1; sz *= 2, y = x) {
    print(mul(a, b));
                                                                      for (int
                                                                           i = 0, t = 0; i < sz && res <= 1; i++, t++) {
  return 0;
                                                                         x = f(x, n); tmp = mul(tmp, abs(x - y), n);
                                                                         if (!(t & 31) ||
6.12 NTT2
                                                                              i + 1 == sz) res = __gcd(tmp, n), tmp = 1;
// Remember coefficient are mod P
  p=a*2^n+1
                                                                    if (res != 0 && res != n) return res;
       2^n
                                        root
   n
                                                                  }
        65536
                      65537
                                        3
   16
                                                               }
   20
        1048576
                      7340033
                                       3 */
   23
        8388608
                      998244353
                                                               6.14 Primes
// (must be 2^k)
template < LL P, LL root, int MAXN >
                                                               /* 12721 13331 14341 75577 123457 222557
struct NTT {
                                                                      556679 999983 1097774749 1076767633 100102021
  static LL bigmod(LL a, LL b) {
                                                                     999997771 1001010013 1000512343 987654361 999991231
    LL res = 1;
                                                                     999888733 98789101 987777733 999991921 1010101333
    for (LL bs = a; b; b >>= 1, bs = (bs * bs) % P)
                                                                      1010102101 1000000000039 100000000000037
      if (b & 1) res = (res * bs) % P;
                                                                      2305843009213693951 \quad 4611686018427387847
    return res:
                                                                      9223372036854775783 18446744073709551557 */
  static LL inv(LL a, LL b) {
                                                                     String
    if (a == 1)return 1;
    return (((LL)(a - inv(b % a, a)) * b + 1) / a) % b;
                                                               7.1 AC
                                                                struct ACautomata {
  LL omega[MAXN + 1];
  NTT() {
                                                                  struct Node {
    omega[0] = 1;
                                                                    int cnt;
    LL r = bigmod(root, (P - 1) / MAXN);
                                                                    Node *go[26], *fail, *dic;
    for (int i = 1; i <= MAXN; i++)
  omega[i] = (omega[i - 1] * r) % P;</pre>
                                                                    Node () {
   cnt = 0, fail = 0, dic = 0;
                                                                      memset(go, 0, sizeof(go));
```

} pool[1048576], *root;

pool[nMem] = Node();

return &pool[nMem++];

void init() { nMem = 0, root = new_Node(); }

void add(const string &str) { insert(root, str, 0); }

Node* new_Node() {

int nMem;

```
National Tsing Hua University Kenapsack
  void insert(Node *cur, const string &str, int pos) {
  for (int i = pos; i < str.size(); i++) {</pre>
       if (!cur->go[str[i] - 'a'])
  cur->go[str[i] - 'a'] = new_Node();
cur = cur->go[str[i] - 'a'];
     cur->cnt++;
  void make_fail() {
     queue < Node *> que;
     que.push(root);
     while (!que.empty()) {
       Node* fr = que.front(); que.pop();
       for (int i = 0; i < 26; i++) {
          if (fr->go[i]) {
            Node *ptr = fr->fail;
            while (ptr && !ptr->go[i]) ptr = ptr->fail;
            fr->go[i]->
                 fail = ptr = (ptr ? ptr->go[i] : root);
            fr->go[i]->dic = (ptr->cnt ? ptr : ptr->dic);
            que.push(fr->go[i]);
       }
    }
  }
} AC;
7.2 Hash
struct Hash {
  vector<ll> h;
```

7.3 KMP

```
#define pb push_back
const int N = 1e6 + 5;
int F[N]:
vector<int> match(string A, string B) {
  vector<int> ans;
  F[0] = -1, F[1] = 0;
  for (int
       i = 1, j = 0; i < (int)B.size(); F[++i] = ++j) {
    if (B[i] == B[j]) F[i] = F[j]; // optimize
    while (j != -1 && B[i] != B[j]) j = F[j];
  for (int i = 0, j = 0; i < (int)A.size(); ++i) {</pre>
   while (j != -1 && A[i] != B[j]) j = F[j];
    if (++j
         == (int)B.size()) ans.pb(i + 1 - j), j = F[j];
 }
  return ans:
}
```

7.4 Manacher

```
R < s.size() && s[L - 1] == s[R]) {--L; ++R;}
      P.push_back(R - L);
  return P;
}
7.5 SA
const int N = 2e5 + 5;
string s;
int sa[N], tmp[2][N], c[N], rk[N], h[N];
// lcp(sa[i], sa[j]) = min\{h[k]\} where i <= k <= j
void suffix_array() {
  int *x = tmp[0], *y = tmp[1], m = 256, n = s.size();
  fill(c, c + m, 0);
  for (int i = 0; i < n; i++) c[x[i] = s[i]]++;
  partial_sum(c, c + m, c);
  for (int i = n - 1; i \ge 0; i--) sa[--c[x[i]]] = i;
  for (int k = 1; k < n; k <<= 1) {
    fill(c, c + m, 0);
    for (int i = 0; i < n; i++) c[x[i]]++;
    partial_sum(c, c + m, c);
    int p = 0;
    for (int i = n - k; i < n; i++) y[p++] = i;
    for (int i = 0; i < n; i++)</pre>
      if (sa[i] >= k) y[p++] = sa[i] - k;
    for (int i
          = n - 1; i \ge 0; i - - c[x[y[i]]]] = y[i];
    y[sa[0]] = p = 0;
     for (int i = 1; i < n; i++) {
       int a = sa[i], b = sa[i - 1];
      if (x[a] != x[b] || a + k >=
           n \mid | b + k >= n \mid | x[a + k] != x[b + k]) p++;
      y[sa[i]] = p;
    if (n == p + 1) break;
    swap(x, y), m = p + 1;
  }
}
void LCP() {
  int n = s.size(), val = 0;
  for (int i = 0; i < n; i++) rk[sa[i]] = i;
for (int i = 0; i < n; i++) {</pre>
    if (rk[i] == 0) h[rk[i]] = 0;
    else {
      if (val) val--;
      int p = sa[rk[i] - 1];
       while (val + i < n && val
            + p < n && s[val + i] == s[val + p]) val++;
      h[rk[i]] = val;
  }
// cin >> s, suffix_array(), LCP();
```

else R = (L = i) + j; while (L > 0 &&

7.6 SA2

```
void counting_sort
    (vector<int> &dest, const vector<int> &src
     int bucket_count, function<int(const int&)> f) {
  int *bucket_begin = new
       int[bucket_count], *buf = new int[src.size()];
  fill(bucket_begin, bucket_begin + bucket_count, 0);
  for (int i = 0; i < src.size(); ++i)</pre>
    if ((buf[i] = f(src[i])) + 1 < bucket_count)</pre>
      ++bucket begin[buf[i] + 1];
  partial_sum(bucket_begin
      , bucket_begin + bucket_count, bucket_begin);
  dest.resize(src.size());
  for (int i = 0; i < src.size(); ++i)</pre>
    dest[bucket_begin[buf[i]]++] = src[i];
  delete[] bucket_begin; delete[] buf;
#define
     a 'a'
            // The smallest character in the alphabet
#define sz 26 // The
     size of the alphabet. The alphabet is [a, a + sz)
vector<int> suffix_array(const string &s) {
  vector<int> SA, sa(s.size());
  SA.reserve(s.size()); iota(sa.begin(), sa.end(), 0);
  counting_sort(SA,
       sa, sz, [&](const int &i) { return s[i] - a; });
```

```
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  int *R = new int[SA.size()], *r = new int[SA.size()];
  R[SA[0]]
             // R = 0 is reserved for the empty string
  for (int i = 1; i < SA.size(); ++i)</pre>
    R[SA[i]] = s
        [SA[i]] == s[SA[i - 1]] ? R[SA[i - 1]] : i + 1;
  int L = 1;
  while (L < s.size()) {</pre>
    auto R2 = [&](const int &i) {
      if (i + L < SA.size()) return R[i + L];</pre>
      return 0; // so
           that when L = 1, "a" is ordered before "aa"
    counting_sort(sa, SA, SA.size() + 1, R2);
    counting_sort(SA, sa, SA.size
        (), [&](const int &i) { return R[i] - 1; });
    r[SA[0]] = 1;
    for (int i = 1; i < SA.size(); ++i)</pre>
      if (R[SA[i]] ==
           R[SA[i - 1]] \&\& R2(SA[i]) == R2(SA[i - 1]))
        r[SA[i]] = r[SA[i - 1]];
      else r[SA[i]] = i + 1;
    swap(R, г); L <<= 1;
  delete[] R; delete[] r; return SA;
#undef a
#undef sz
7.7
     SAIS
const int N = 300010:
struct SA {
#define REP(i,n) for(int i=0;i<int(n);i++)</pre>
#define REP1(i,a,b) for(int i=(a);i<=int(b);i++)</pre>
```

```
bool _t[N * 2]; int _s[N * 2], _sa[N * 2];
int _c[N * 2], x[N], _p[N], _q[N * 2], hei[N], r[N];
int operator [](int i) { return _sa[i]; }
  void build(int *s, int n, int m) {
    memcpy(_s, s, sizeof(int)*n);
    sais(_s, _sa, _p, _q, _t, _c, n, m); mkhei(n);
  void mkhei(int n) {
    REP(i, n) r[_sa[i]] = i;
    hei[0] = 0;
    REP(i, n) if (r[i]) {
      int ans = i > 0 ? max(hei[r[i - 1]] - 1, 0) : 0;
           [i + ans] == _s[_sa[r[i] - 1] + ans]) ans++;
      hei[r[i]] = ans;
    }
  }
  void sais(int *s, int *sa,
    int *p, int *q, bool *t, int *c, int n, int z) {
    bool uniq = t[n - 1] = true, neq;
    int nn = 0, nmxz
= -1, *nsa = sa + n, *ns = s + n, lst = -1;
#define MSO(x,n) memset((x),0,n*sizeof(*(x)))
#define MAGIC(XD) MS0(sa,n);\
memcpy(x,c,sizeof(int)*z); XD;\
memcpy(x+1,c,sizeof(int)*(z-1));\
REP(i,n) if
    (sa[i]\&\&!t[sa[i]-1]) sa[x[s[sa[i]-1]]++]=sa[i]-1;
memcpy(x,c,sizeof(int)*z);\
for(int i=n-1;i>=0;i--)
     if(sa[i]&&t[sa[i]-1]) sa[--x[s[sa[i]-1]]]=sa[i]-1;
    MSO(c, z); REP(i, n) uniq &= ++c[s[i]] < 2;
    REP(i, z - 1) c[i + 1] += c[i];
    if (uniq) { REP(i, n) sa[--c[s[i]]] = i; return; }
    for (int i = n - 2; i >= 0; i--)
      t[i] = (s[
           i] == s[i + 1] ? t[i + 1] : s[i] < s[i + 1]);
    MAGIC(REP1(i, 1, n - 1) if (t[i] &&
         t[i - 1] sa[--x[s[i]]] = p[q[i] = nn++] = i);
    REP(i, n) if (sa[i] && t[sa[i]] && !t[sa[i] - 1]) {
      ns[q[lst = sa[i]]] = nmxz += neq;
    sais(ns, nsa
    , p + nn, q + n, t + n, c + z, nn, nmxz + 1);  \label{eq:magnetic}  \mbox{MAGIC(for (int i = nn - 1; i)} 
          >= 0; i--) sa[--x[s[p[nsa[i]]]]] = p[nsa[i]]);
  }
} sa;
int H[N], SA[N], RA[N];
void suffix_array(int* ip, int len) {
```

```
// should padding a zero in the back
// ip is int array, len is array length
// ip[0..n-1] != 0, and ip[len]=0
ip[len++] = 0; sa.build(ip, len, 128);
memcpy(H, sa.hei
+ 1, len << 2); memcpy(SA, sa._sa + 1, len << 2); for (int i = 0; i < len; i++) RA[i] = sa.r[i] - 1;
// resulting height, sa array \in [0,len)
```

7.8 Suffix Automaton

```
#include <bits/stdc++.h>
class SuffixAutomaton {
public:
  static const int MAXN = 500 << 1;</pre>
  static const int MAXC = 26;
  struct Node {
    Node *next[MAXC], *pre;
    int step;
    Node() {
      pre = NULL, step = 0;
      memset(next, 0, sizeof(next));
  } _mem[MAXN];
  int size;
  Node *root. *tail:
  void init() {
    size = 0;
    root = tail = newNode();
  Node* newNode() {
    Node *p = \&_mem[size++];
    *p = Node();
    return p;
  int toIndex(char c) { return c - 'A'; }
  char toChar(int c) { return c + 'A'; }
  void add(char c, int len) {
    c = toIndex(c);
    Node *p, *q, *np, *nq;
p = tail, np = newNode();
    np->step = len;
    for (; p && p->next[c] == NULL; p = p->pre)
      p->next[c] = np;
    tail = np;
    if (p == NULL) {
      np->pre = root;
    } else {
      if (p->next[c]->step == p->step + 1) {
        np->pre = p->next[c];
      } else {
        q = p->next[c], nq = newNode();
        *nq = *q;
        nq->step = p->step + 1;
        a->pre = np->pre = na:
        for (; p && p->next[c] == q; p = p->pre)
          p->next[c] = nq;
    }
  void build(const char *s) {
    init();
    for (int i = 0; s[i]; i++)
      add(s[i], i + 1);
  void dfs(Node *u, int idx, char path[]) {
    for (int i = 0; i < MAXC; i++) {</pre>
      if (u->next[i]) {
        path[idx] = toChar(i);
        path[idx + 1] = '\0';
        puts(path);
        dfs(u->next[i], idx + 1, path);
    }
  void print() {
    char s[1024];
    dfs(root, 0, s);
} SAM:
int main() {
  char s[1024];
  while (scanf("%s", s) == 1) {
    SAM.build(s);
    SAM.print();
```

```
return 0:
7.9 Trie
int trie[MAXN * 31][2], node;
int tag[MAXN * 31];
void add(int x) {
    int now = 0;
    for (int i = 30; i >= 0; i--) {
        if (!trie[now][x
             >> i & 1]) trie[now][x >> i & 1] = ++node;
        now = trie[now][x >> i & 1];
        tag[now]++;
    }
void del(int x) {
    int now = 0;
    for (int i = 30; i >= 0; i--) {
        now = trie[now][x >> i & 1];
        tag[now]--;
int qry(int x) {
    int now = 0, res = 0;
    for (int i = 30; i >= 0; i--) {
        int id = (x >> i & 1) ^ 1;
        if (!tag[trie[now][id]]) id ^= 1;
        now = trie[now][id];
        res = res * 2 + id;
    return res;
}
7.10 Z
void z_value(const char *s, int len, int *z) {
```

8 Others 8.1 Aliens

}

```
實際上如果這邊根本是平的, 那我們只要讓二分艘找到最
小的P讓他的切點不超過K,那就保證了這條配會貼在上面
ll mid = (l+r < 0 ? (l + r) / 2: (l + r + 1) / 2)
while(l < r){
    int m = (l + r) / 2;
    if(calc(m) \ll K) r = m;
    else l = m + 1;
#include <bits/stdc++.h>
#define F first
#define S second
#define int long long
using namespace std;
bool operator < (
    const pair<int, int> &a, const pair<int, int> &b) {
    return a.F < b.F or (a.F == b.F and a.S > b.S);
#define chmax(a, b) a = (a) < (b)? (b) : (a)
int n, k;
int a[1000005];
pair<int, int> dp[1000005];
vector<int> last(100005, 0);
pair<int, int> DP(int penalty) {
   last.assign(100005, 0);
    pair<int, int> ans = \{0, 0\};
    int l = 0;
    for (int i = 1; i <= n; i++) {
        while (l < last[a[i]]) {</pre>
            chmax(ans, dp[l]);
```

```
dp[i] = {ans.F + i - l - penalty, ans.S + 1};
        last[a[i]] = i;
    while (l < n) {
        1++;
        chmax(ans, dp[l]);
    return ans;
}
signed main() {
    ios_base::sync_with_stdio(0), cin.tie(0);
    cin >> n >> k;
    for (int i = 1; i <= n; i++) cin >> a[i];
    int l = -1, r = 2000000;
    while (l < r - 1) {
        int m = (l + r) / 2;
        pair<int, int> res = DP(m);
        if (res.S <= k) {</pre>
            r = m;
        } else
            l = m;
    auto res = DP(r);
    cout << res.F + k * r << '\n';
}
```

8.2 Knapsack on Tree

```
#include <bits/stdc++.h>
#define F first
#define S second
#define pb push_back
#define all(x) begin(x), end(x)
#ifdef LOCAL
#define HEHE freopen("in.txt", "r", stdin);
#else
#define HEHE ios_base::sync_with_stdio(0), cin.tie(0);
#endif
using namespace std;
#define chmax(a, b) (a) = (a) < (b) ? (b) : (a)
#define chmin(a, b) (a) = (a) < (b) ? (a) : (b)
#define ll long long
#define FOR(i, a, b) for (int i = a; i <= b; i++)</pre>
int N, W, cur;
vector<int> w, v, sz;
vector<vector<int>> adj, dp;
void dfs(int x) {
    sz[x] = 1;
    for (int i : adj[x]) dfs(i), sz[x] += sz[i];
    cur++:
    // choose x
    FOR (i, w[x], W) {
        dp[cur][i] = dp[cur - 1][i - w[x]] + v[x];
    // not choose x
    FOR (i, 0, W) {
        chmax(dp[cur][i], dp[cur - sz[x]][i]);
}
signed main() {
    HEHE
    cin >> N >> W;
    adj.resize(N + 1);
    w.assign(N + 1, 0);
    v.assign(N + 1, 0);
    sz.assign(N + 1, 0);
    dp.assign(N + 2, vector<int>(W + 1, \theta));
    FOR (i, 1, N) {
   int p; cin >> p;
        adj[p].pb(i);
    FOR (i, 1, N) cin >> w[i];
    FOR (i, 1, N) cin >> v[i];
    dfs(0):
    cout << dp[N + 1][W] << '\n';
}
```

8.3 Mo

#include <bits/stdc++.h>

```
using namespace std:
const int N = 2e5 + 5, sqN = sqrt(N) + 5;
int a[N], ans[N], n, q, sz; // maybe need blk[sqN];
struct Query {
  int ql, qr, id;
  bool operator<(const Query& b) const {</pre>
    int aa = ql / sz, bb = b.ql / sz;
    if (aa != bb) return aa < bb;</pre>
    else return qr < b.qr;</pre>
} Q[N];
void add(int x) {}
void sub(int x) {}
int qry(int k) {}
int main() {
 ios::sync_with_stdio(false), cin.tie(nullptr);
  cin >> n >> q, sz = sqrt(n);
  for (int i = 0; i < n; i++) cin >> a[i];
  for (int i = 0, ql, qr; i < q; i++)</pre>
    cin >> ql >> qr, Q[i] = \{ql - 1, qr - 1, i\};
  // Mo's algorithm
  sort(Q, Q + q); /* remember initialize arrays */
  int l = 0, r = -1;
  for (int i = 0; i < q; i++) {
    auto [ql, qr, k, id] = Q[i];
    while (r < qr) add(a[++r]);</pre>
    while (r > qr) sub(a[r--]);
    while (l < ql) sub(a[l++]);
    while (l > ql) add(a[--l]);
    ans[id] = qry(k);
  for (int i = 0; i < q; i++) cout << ans[i] << '\n';</pre>
8.4 Mono Slope
```

```
struct Line{
  ll a, b;
  ll l = MIN, r = MAX;
  Line(ll a, ll b): a(a), b(b) {}
  ll operator()(ll x){
    return a * x + b;
deque < Line > dq;
ll iceil(ll a, ll b){
  if(b < 0) a *= -1, b *= -1;</pre>
  if(a > 0) return (a + b - 1) / b;
  else return a / b;
ll intersect(Line a, Line b){
  return iceil(a.b - b.b, b.a - a.a);
void add(Line ln){
  while(!dq.empty
      () && ln(dq.back().l) >= dq.back()(dq.back().l)){
    dq.pob;
  if(dq.empty()){
    dq.eb(ln);
    return;
  ll pos = intersect(ln, dq.back());
  if(pos > dq.back().r){
    if(dq.back().r != MAX){
       ln.l = dq.back().r + 1;
      dq.eb(ln);
    }
    return;
  dq.back().r = pos - 1;
  ln.l = pos;
  dq.eb(ln);
ll query(ll x){
  while(dq.front().r < x) dq.pof;</pre>
  return dq.front()(x);
```

8.5 Partial Ordering

```
// O(n log^2 n)
#include <bits/stdc++.h>
using namespace std;
using ll = long long;
 const int N = 1e5 + 5, M = 2e5 + 5;
 int n, K, cnt, ans[N];
struct node {
  int x, y, z, v, ans, tag, id;
node() { ans = tag = v = x = y = z = 0; }
   friend
         bool operator==(const node &a, const node &b) {
     return
           (a.x == b.x) && (a.y == b.y) && (a.z == b.z);
  }
} a[N], t[N];
 bool cmp1(const node &a, const node &b) {
   if (a.x != b.x) return a.x < b.x;
   if (a.y != b.y) return a.y < b.y;</pre>
   return a.z < b.z;</pre>
bool cmp2(const node &a, const node &b) {
  if (a.y != b.y) return a.y < b.y;</pre>
   if (a.tag != b.tag) return a.tag < b.tag;</pre>
   return a.id < b.id;</pre>
 #define lowbit(x) (x & -x)
int bit[M];
 void add(int p, int x) {
  for (; p <= K; p += lowbit(p)) bit[p] += x;</pre>
 int query(int p) {
   int ret = 0:
   for (; p; p -= lowbit(p)) ret += bit[p];
   return ret;
void CDQ(int l, int r) {
   if (l == r) return;
   int mid = (l + r) \gg 1;
   CDQ(l, mid); CDQ(mid + 1, r);
   for (int i = l; i <= r; ++i) a[i].id = i;
for (int i = l; i <= mid; ++i) a[i].tag = 0;</pre>
   for (int i = mid + 1; i <= r; ++i) a[i].tag = 1;</pre>
   sort(a + l, a + r + 1, cmp2);
   for (int i = l; i <= r; ++i) {</pre>
     if (!a[i].tag) add(a[i].z, a[i].v);
     else a[i].ans += query(a[i].z);
   for (int i = l; i <= r; ++i)</pre>
     if (!a[i].tag) add(a[i].z, -a[i].v);
 int main() {
   cin >> n >> K;
   for (int i = 1; i <= n; ++
       i) cin >> a[i].x >> a[i].y >> a[i].z, a[i].v = 1;
   sort(a + 1, a + n + 1, cmp1);
   cnt = 1;
   for (int i = 2; i <= n; ++i) {
     if (a[i] == a[cnt]) ++a[cnt].v;
     else a[++cnt] = a[i];
   CDQ(1, cnt);
// let ans[i] denote that the
       number of (aj<=ai && bj<=bi && cj<=ci) for i != j
   for (int i = 1; i <=
        cnt; ++i) ans[a[i].ans + a[i].v - 1] += a[i].v;
   for (int i = 0; i < n; ++i) cout << ans[i] << '\n';</pre>
   return 0:
}
```

8.6 Xor Basis

```
int basis[20]
bool add(int x) {
    for (int i = 19; i >= 0; i--) {
        if (!(x >> i & 1)) continue;
        if (!basis[i]) {
            basis[i] = x;
            return true;
        }
        else x ^= basis[i];
    }
    return false;
}
// 維持 basis[i] 的最高配是 i
```

