## COMP3421

Inverse Transformations, Shaders

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## View transform

- The world is rendered as it appears in the camera's local coordinate frame.
- The view transform converts the world coordinate frame into the camera's local coordinate frame.
- Note that this is the inverse of the transformation that would convert the camera's local coordinate frame into world coordinates.

## Transformation pipeline

We transform in 2 stages

$$P_{camera} \stackrel{view}{\longleftarrow} P_{world} \stackrel{model}{\longleftarrow} P_{local}$$

- The model transform transforms points in the local coordinate system to the world coordinate system
- The view transform transforms points in the world coordinate system to the camera's coordinate system

## View transform

Mathematically if:

$$P_{world} = Trans(Rot(Scale(P_{camera})))$$

Then the view transform is:

$$P_{camera} = Scale^{-1}(Rot^{-1}(Trans^{-1}(P_{world})))$$

## Inverse Transformations

If the local-to-global transformation is:

$$Q = \mathbf{M_T} \mathbf{M_R} \mathbf{M_S} P$$

then the global-to-local transformation is the inverse:

$$P = \mathbf{M_S^{-1}M_R^{-1}M_T^{-1}}Q$$

## Inverse Transformations

Inverses are easy to compute:

```
translation: \mathbf{M_T}^{-1}(d_x, d_y) = \mathbf{M_T}(-d_x, -d_y)
rotation: \mathbf{M_R}^{-1}(\theta) = \mathbf{M_R}(-\theta)
scale: \mathbf{M_S}^{-1}(s_x, s_y) = \mathbf{M_S}(1/s_x, 1/s_y)
shear: \mathbf{M_H}^{-1}(h) = \mathbf{M_H}(-h)
```

## Local to World Exercise

Given this local coordinate frame:

```
CoordFrame2D.identity()
   .translate(3,2)
   .rotate(-45)
   .scale(0.5,0.5);
```

• What point in the local co-ordinate frame would correspond to the world co-ordinate Q (2,-1)?

# Assignment I

- Automarking
  - -Junit 4 Unit Tests
  - -diff image files that you output with required image output
- Tutor subjective marking
  - MyCoolSceneObject
  - -Bonus Game (also course vote)

## **JUnit**

- You can run JUnit tests directly from eclipse
- For floating point equality we use an epsilon
- Demo

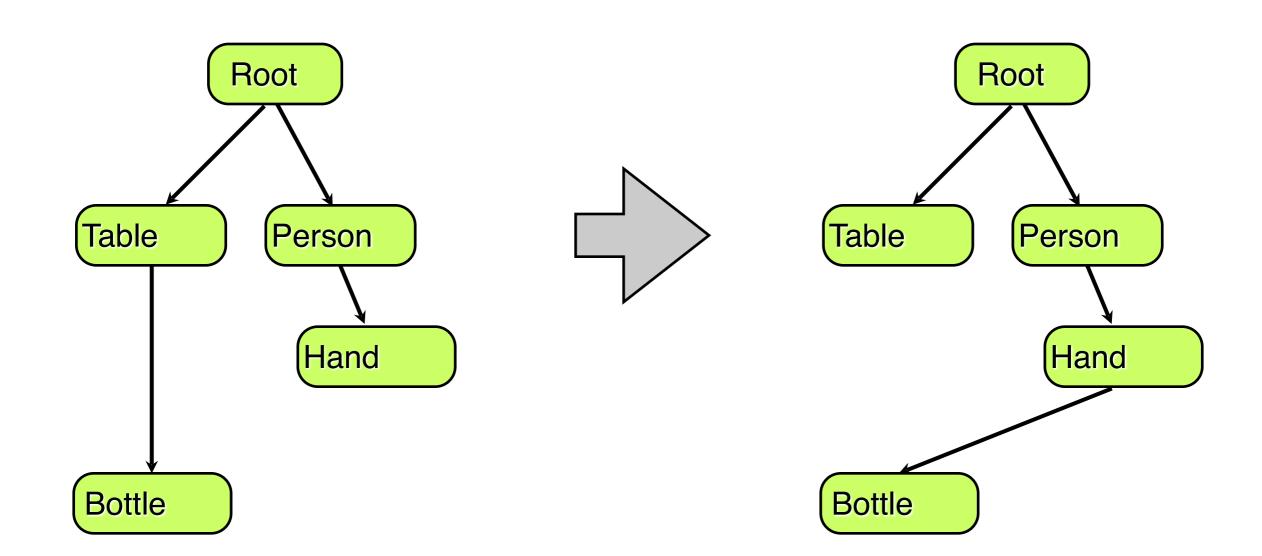
## Hints

Drawing twice: once as a fill and once as an outline.

- Draw fill first
- -Then outline over the top

## Reparenting

- What if the person picks up the bottle?
- What's the new transformation?



# Lerping

· We can add affine combinations of points:

$$\frac{1}{2}(p_1, p_2, 1)^{\top} + \frac{1}{2}(q_1, q_2, 1)^{\top} = (\frac{p_1 + q_1}{2}, \frac{p_2 + q_2}{2}, \mathbf{1})^{\top}$$

We often use this to do linear interpolation between points:

$$lerp(P,Q,t) = P + t(Q - P)$$

$$lerp(P,Q,t) = P(1-t) + tQ$$

$$lerp(P,Q,0.3)$$

# Lerping Exercise

• Using linear interpolation, what is the midpoint between A=(4,9) and B=(3,7)?

## Lines

#### Parametric form:

$$L(t) = P + t\mathbf{v}$$

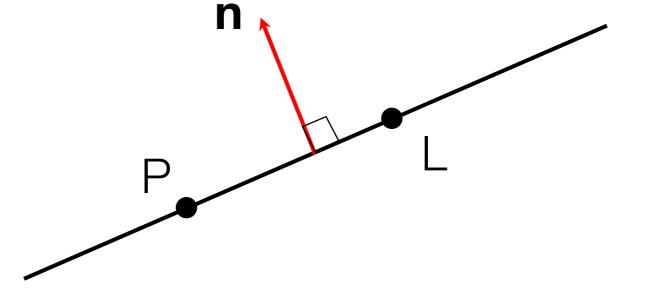
$$\mathbf{v} = Q - P$$

$$L(t) = P + t(Q - P)$$

 $\begin{array}{c} L(t) & Q & t > 1 \\ \hline 0 < t < 1 & \\ \hline t < 0 & \end{array}$ 

Point-normal form in 2D:

$$\mathbf{n} \cdot (P - L) = 0$$



## Line intersection

#### Two lines

$$L_{AB}(t) = A + (B - A)t$$
$$L_{CD}(u) = C + (D - C)u$$

Solve simultaneous equations:

$$(B-A)t = (C-A) + (D-C)u$$

## Line Intersection Example

A = (0,3) B = (12,7) 
$$L_{AB}(t) = A + (B-A)t$$
 C = (2,0) D = (7,20) 
$$L_{CD}(u) = C + (D-C)u$$

## Line Intersection Example 2

Find where the line L(t) = A + ct intersects with the line n.(P-B) = 0 where

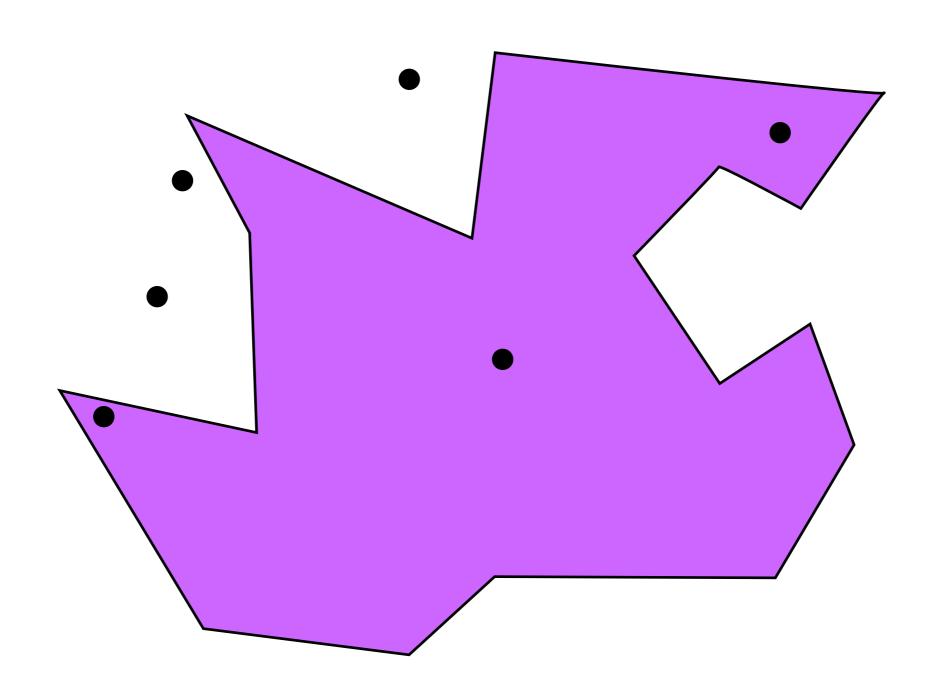
$$A=(2,3)$$
,  $c=(4,-4)$ ,  $n=(6,8)$ ,  $B=(7,7)$ 

NOT DONE IN LECTURE DUE TO TIME. Left as an exercise for the reader.

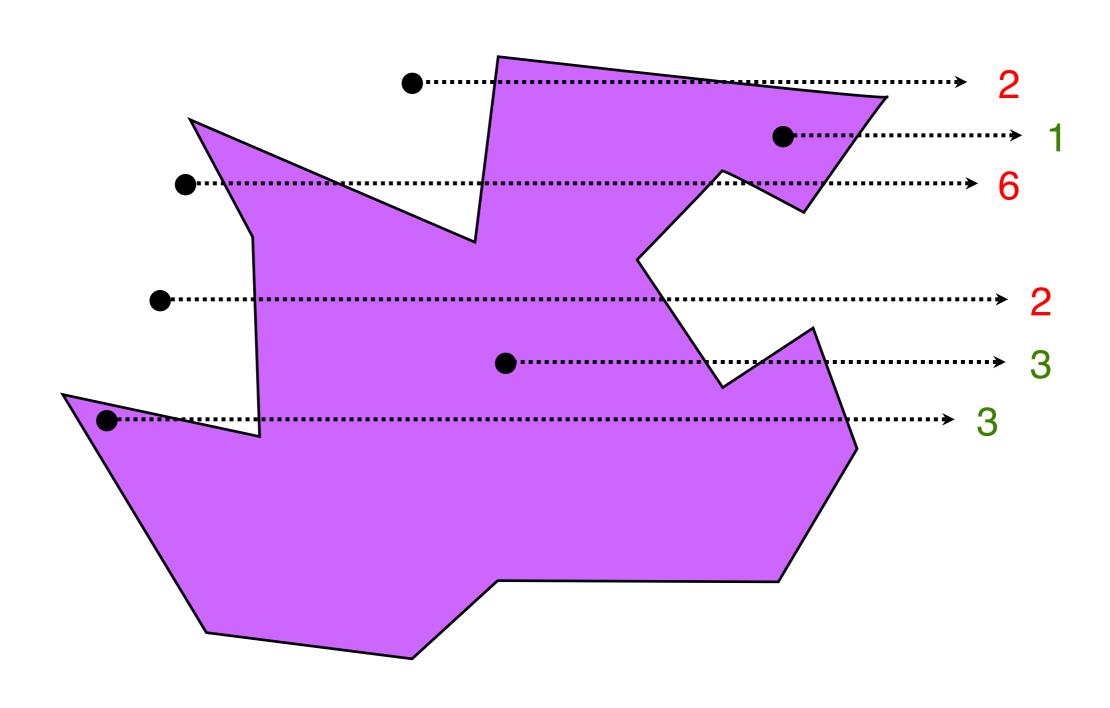
# Point in Polygon

- For any ray from the point
- Count the number of crossings with the polygon
- If there is an odd number of crossings the point is inside

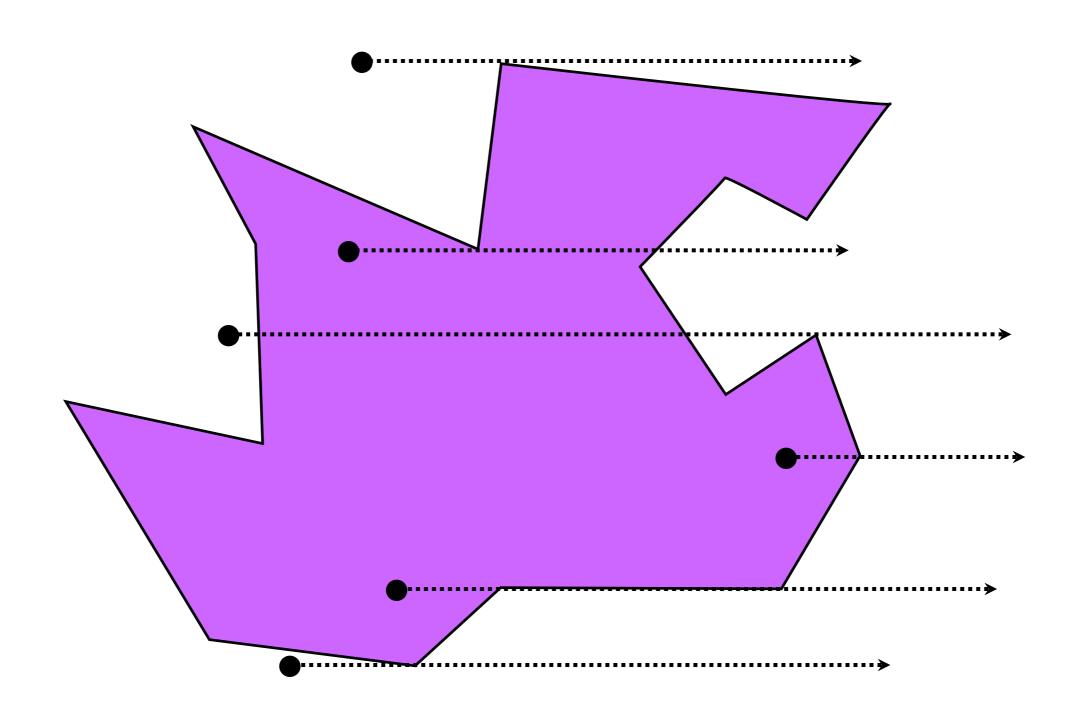
# Point in polygon



# Point in polygon

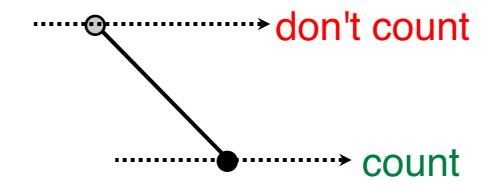


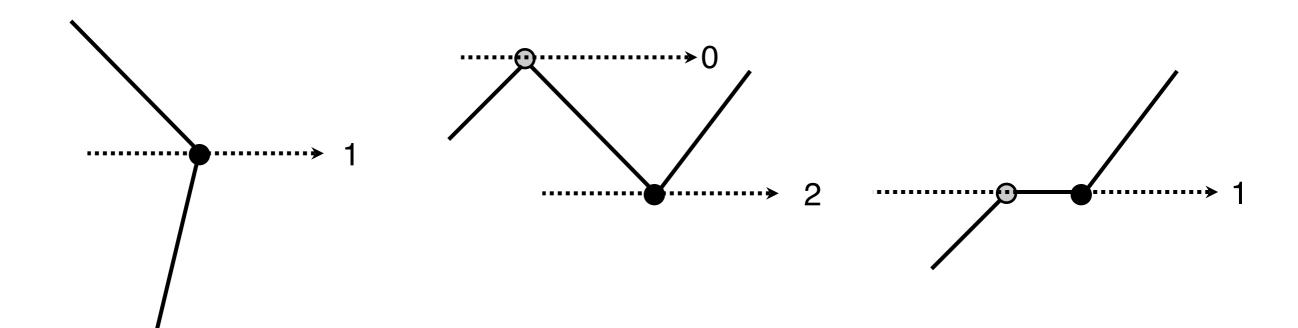
# Difficult points



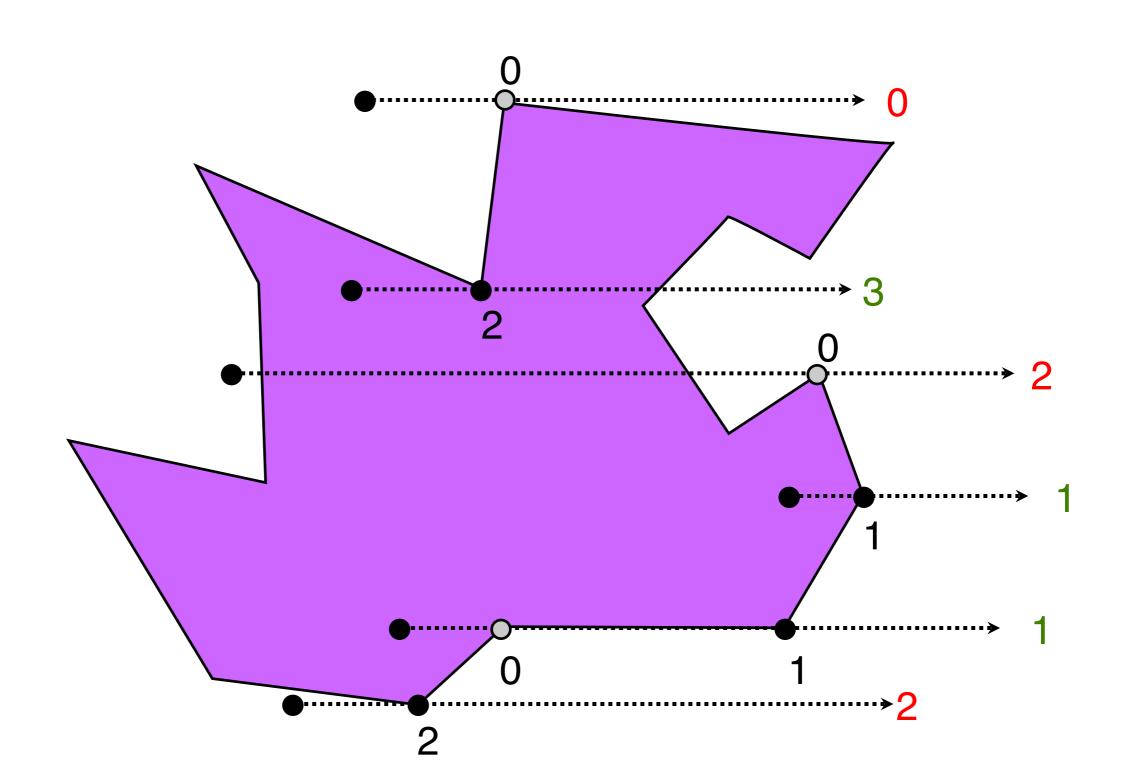
## Solution

Only count crossings at the lower vertex of an edge.





# Point in polygon



# Computational Geometry

- Computational Geometry in C, O'Rourke
- http://cs.smith.edu/~orourke/books/ compgeom.html
- CGAL
   Computational Geometry Algorithms Library
- http://cgal.org/

## Shaders

- Shaders are programs executed on the GPU for the purpose of rendering graphics.
- They are written in a special language called GLSL (GL Shader Language).

# GLSL Syntax

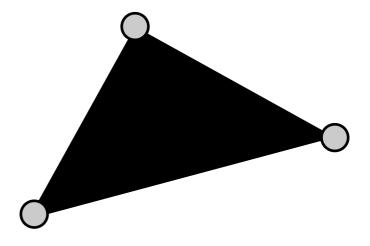
- C like language with
  - -No pointers!
  - -Basic types: float int bool
  - -Standard C/C++ arithmetic and logic operators and overloaded ones to work on vectors and matrices
  - if statements, loops

# GLSL Syntax

- No characters, strings or printf
  - Hard to debug
- No recursion
- No double (limited support in later versions)

## Vertex Shaders

- The GPU will execute the vertex shader for every vertex we supply it.
- e.g. if we're drawing a triangle, the vertex shader will execute three times.



## Basic Vertex Shader

Takes the input position and returns it as is.

```
// Incoming vertex position
in vec2 position;

void main() {
    gl_Position = vec4(position, 0, 1);
}
```

## **GLSL**

#### Variables declared:

- 'in' are inputs to the shader and are different for each vertex.
- 'uniform' are inputs to the shader that are the same for every vertex
- 'out' are what the shader outputs
- Variables starting with 'gl\_' are built-in and have special meaning.

# GLSL Syntax

- Has support for 2D, 3D, 4D vectors (array like list like containers) of different types
  - -vec2, vec3, vec4 are float vectors
- Operators are overloaded for vector operations.
- · Can be constructed in many ways. e.g.

vec4 vec4(vec2 xy, float z, float w);

## **GLSL**

• gl\_Position is a homogenous point in 3D (i.e. a vector of rank 4)

```
// Incoming vertex position
in vec2 position;

void main() {
    gl_Position = vec4(position, 0, 1);
}
```

## **GLSL**

 This shader applies no transformation to the vertex at all (equivalent to UNSWgraph v0.2 and earlier)

```
// Incoming vertex position
in vec2 position;

void main() {
    gl_Position = vec4(position, 0, 1);
}
```

# Fragment Shaders

 The GPU will execute the fragment shader for every pixel it draws into the framebuffer

• e.g. if we're drawing a triangle, the fragment shader will execute for every pixel that gets filled in.

# Basic Fragment Shader

 In OpenGL if the fragment shader only has one declared output, then that is what gets written to the framebuffer.

```
out vec4 outputColor;

void main() {
    // Output black
    outputColor = vec4(0,0,0,0);
}
```

# Basic Fragment Shader

 For reasons we will cover later, the output is a rank 4 vector. The first 3 components are the RGB values.

```
out vec4 outputColor;

void main() {
    // Output black
    outputColor = vec4(0,0,0,0);
}
```

## Setting up Shaders

- OpenGL support a full compiler pipeline for GLSL.
- Shaders can be loaded from text files, compiled, linked and loaded (transferred to the GPU).
- See Shader.java in unsw.graphics

## Using Shaders

- After your shaders have been set up you need to tell OpenGL what shaders to use.
- To set the current shader use:
- gl.glUseProgram(shaderProgramID);
- UNSWgraph has Shader.use() that does this

# Color Fragment Shader

This shader allows us to draw in colour

```
out vec4 outputColor;
uniform vec3 input_color;

void main()
{
    // Output whatever was input outputColor = vec4(input_color, 0);
}
```

### Uniform Variables

- Uniforms are read-only input variables
- Defined in your JOGL program and input into your vertex or fragment shader.
- Can't be changed for a given primitive.

### User Defined Uniforms

 To pass in your own uniforms into your shaders from the application program

```
int loc =
gl.glGetUniformLocation(shaderProgram,"myVal");
gl.glUniform1f(loc,0.5);
```

 Your vertex and/or fragment shader will need a matching declaration like:

```
uniform float myVal;
```

# Color Fragment Shader

See Shader.setPenColor()

```
out vec4 outputColor;
uniform vec3 input_color;

void main()
{
    // Output whatever was input outputColor = vec4(input_color, 0);
}
```

# Transforming Vertex Shader

```
// Incoming vertex position
in vec2 position;
uniform mat3 model_matrix;
uniform mat3 view_matrix;
void main() {
   // The global position is in homogenous coordinates
    vec3 globalPosition = model_matrix * vec3(position, 1);
    // The position in camera coordinates
    vec3 viewPosition = view_matrix * globalPosition;
    // We must convert from a homogenous coordinate in 2D to a homogenous
    // coordinate in 3D.
    gl_Position = vec4(viewPosition.xy, 0, 1);
```

# Transforming Vertex Shader

- See shaders/vertex\_2d.glsl
- This is how we apply the model and view transforms.
- See Shader.setModelMatrix() and Shader.setViewMatrix()

### Matrix Components

Matrices are in column major order

### GLSL Functions

- Standard Maths functions: sqrt, pow, abs, floor, ceiling, clamp etc
- Trigonometric functions in radians: cos sin tan degrees etc.
- Vector functions: dot, cross, normalize, reflect etc
- Can create user defined functions, syntax similar to C

### Exercise

 Write a fragment shader to generate a visualisation of the Mandelbrot set.

See Mandelbrot.java in unsw.graphics.example.

### Revision: Complex numbers

 Have both a real component and an imaginary component.

$$c = a + bi$$

Where:

$$i = \sqrt{-1}$$

### Revision: Complex numbers

Can be added

$$c_1 = a_1 + b_1 i$$

$$c_2 = a_2 + b_2 i$$

$$c_1 + c_2 = (a_1 + b_1 i) + (a_2 + b_2 i)$$

$$= (a_1 + a_2) + (b_1 + b_2) i$$

and multiplied

$$c_1c_2 = (a_1 + b_1i)(a_2 + b_2i)$$

$$= a_1a_2 + a_1b_2i + b_1a_2i + b_1b_2i^2$$

$$= (a_1a_2 - b_1b_2) + (a_1b_2 + b_1a_2)i$$

• Note that  $i^2 = -1$ 

## Revision: Complex numbers

The magnitude

$$|a+bi|$$

is defined as

$$\sqrt{a^2+b^2}$$

### Mandelbrot Set

 Defined as the set of complex numbers, c, for which

$$z_{n+1} = z_n^2 + c$$

remains bounded in its magnitude. i.e if |z| in this loop remains bounded

```
while (true) {
   z = z² + c;
}
```

### Mandelbrot Set

- We can't compute it exactly as it requires infinite computation
- We have to approximate it!
- Execute the loop N times, if it doesn't diverge, assume it never will.
- if |z| > 2 then it has diverged.