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On a Yang-Baxter map and the Dehornoy ordering

I. A. Dynnikov

A map $f \colon X \times X \to X \times X$ is called a Yang–Baxter map on a set X if it satisfies the relation

$$(f \times \mathrm{id}_X) \circ (\mathrm{id}_X \times f) \circ (f \times \mathrm{id}_X) = (\mathrm{id}_X \times f) \circ (f \times \mathrm{id}_X) \circ (\mathrm{id}_X \times f). \tag{1}$$

The study of these maps was proposed in [1], and we have borrowed the term "Yang-Baxter map" from [2]. Various approaches to the construction of Yang-Baxter maps and several examples can be found in [2]-[4].

Proposition 1. The map $f: \mathbb{R}^4 \to \mathbb{R}^4$ given by f(a,b,c,d) = (a',b',c',d'), where

$$a' = \max(a, a + b, b + c), \qquad b' = d - \max(0, a - b - c + \max(0, b) + \max(0, d)),$$

$$c' = a + c + d - \max(a, c, a + d), \quad d' = \max(b, a - c + \max(0, b) + \max(0, d)),$$
(2)

is a non-degenerate (that is, bijective) Yang-Baxter map on \mathbb{R}^2 . The inverse map is given by the formula $f^{-1} = \tau \circ f \circ \tau$, where $\tau(a, b, c, d) = (-a, b, -c, d)$.

Proof. By explicit substitution it is easy to verify that the map

$$f^{r}(a,b,c,d) = \left(a + ab + bc, \frac{bcd}{bc + a(1+b)(1+d)}, \frac{acd}{a+c+ad}, \frac{bc + a(1+b)(1+d)}{c}\right)$$
(3)

obtained from f by replacing the operators +, -, max by \cdot , /, +, respectively, is a Yang–Baxter map on \mathbb{R}^2_+ . In this calculation we use only the commutative and distributive properties of the operators \cdot , /, +, which are also possessed by +, -, max.

The maps f and f^r define actions ρ and ρ^r of the braid group B_n on \mathbb{R}^{2n} and \mathbb{R}^{+n}_+ , respectively, in the standard way. Let us clarify the geometric meaning of the actions ρ and ρ^r .

The braid group B_n can be embedded in the group $MCG^{0,n+3}$ of diffeomorphism classes of the sphere S^2 with n+3 distinguished points $P_0, P_1, \ldots, P_{n+2}$. Here a Dehn semitwist around the points P_i , P_{i+1} corresponds to the generator σ_i . The group $MCG^{0,n+3}$ acts in the standard way on the space $L^{0,n+3}$ of laminations and on the Teichmüller space $T^{0,n+3}$ of the surface $S^2 - \{P_0, \ldots, P_{n+2}\}$. The action ρ (ρ^r) is just the description in a special system of coordinates of the restriction to the subgroup B_n of the standard action of the group $MCG^{0,n+3}$ on the space $L^{0,n+3}$ (respectively, $T^{0,n+3}$).

We realize the sphere S^2 as $\mathbb{R}^2 \cup \{\infty\}$, and put $P_k = (k,0)$ for $k = 0, \ldots, n+1$, $P_{n+2} = \infty$, $e_0 = \{(x,0) \mid x < 0\}$, $e_{3k+1} = \{(k+1/2,y)\}$ for $k = 0, \ldots, n$, $e_{3k-1} = \{(k,y) \mid y > 0\}$, $e_{3k} = \{(k,y) \mid y < 0\}$ for $k = 1, \ldots, n$, $e_{3n+2} = \{(x,0) \mid x > n+1\}$. The vertices P_k and the edges e_k define a singular triangulation of S^2 .

The action of the group B_n on $T^{0,n+3}$ coincides with ρ^r if as coordinates (a_1,b_1,\ldots,a_n,b_n) on $T^{0,n+3}$ we take $a_k=\lambda_{3k-1}/\lambda_{3k},\ b_k=\lambda_{3k-2}/\lambda_{3k+1}$, where λ_i is the λ -length of the edge e_i defined in [5].

To explain the geometric meaning of the action ρ more simply, we shall restrict ourselves to the integer points $\mathbb{Z}^{2n} \subset \mathbb{R}^{2n}$. By an *integer lamination* on $S^2 - \{P_0, \dots, P_{n+2}\}$ we mean any isotopy class of a union of non-intersecting simple closed curves $S^2 - \{P_0, \dots, P_{n+2}\}$, none of which is homotopic to zero nor bounds a disc containing exactly one of the point P_k . For an integer lamination l we shall denote by $\mu_k(l)$ the smallest possible number of points of intersection of a

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representative of l with the edge e_k . On the set $L^{0,n+3}_{\mathbb{Z}}$ of integer laminations we introduce the following collection of functions: $a_i(l) = (\mu_{3i-1}(l) - \mu_{3i}(l))/2$, $b_i(l) = (\mu_{3i-2}(l) - \mu_{3i+1}(l))/2$.

Lemma 1. The collection of functions (a_1,b_1,\ldots,a_n,b_n) defines a one-to-one map $L^{0,n+3}_{\mathbb{Z}} \to \mathbb{Z}^{2n}$. Under this identification the action of the group B_n on $L^{0,n+3}_{\mathbb{Z}}$ coincides with the action ρ .

The proof differs only in details from the proof of the analogous theorem in [6].

Recall that a braid $b \in B_n$ is called σ -positive (see [7]) if for some k, 0 < k < n, it can be represented by a word in the standard generators σ_i that does not contain $\sigma_1, \ldots, \sigma_{k-1}$ and contains σ_k only to a positive power. A braid that is the inverse of a σ -positive braid is called σ -negative. It was proved in [7] that every non-trivial braid is either σ -positive or σ -negative. Thus in the group B_n we may define a right-invariant ordering by putting $b_1 > b_2$ if $b_1b_2^{-1}$ is σ -positive. An algorithm was proposed in [7] for determining whether a given braid was σ -positive, σ -negative, or trivial. Although this algorithm works fast in practice, a polynomial bound for its speed has not yet been proved.

We consider a partial order $<_{\text{oddlex}}$ in \mathbb{Z}^{2n} defined as follows: $x <_{\text{oddlex}} y$ if for some $j \le n$ we have $x_{2j-1} < y_{2j-1}$ and $x_{2i-1} = y_{2i-1}$ for all 0 < i < j. Let L_0 denote the vector $(0,1,0,1,\ldots,0,1) \in \mathbb{Z}^{2n}$.

Proposition 2. A braid $b \in B_n$ is σ -positive (σ -negative) if and only if $L_0 <_{\text{oddlex}} b \cdot L_0$ (respectively, $b \cdot L_0 <_{\text{oddlex}} L_0$).

This assertion gives a simple algorithm for determining which of the inequalities b > 1 or b < 1 holds for a given braid b. To estimate its speed we introduce the following definition.

Suppose the braid b is written in the form $b = \Delta_{i_1 j_1}^{p_1} \dots \Delta_{i_m j_m}^{p_m}$, where Δ_{ij}^p is an element of Garside type: $\Delta_{ij}^p = (\sigma_i \sigma_{i+1} \dots \sigma_{j-1})(\sigma_i \sigma_{i+1} \dots \sigma_{j-2}) \dots \sigma_i$. We define the Δ -length of the word b as the quantity $|b|_{\Delta} = \sum_{s=1}^m (1 + \ln(j_s - i_s) + \ln|p_s|)$.

We note that for any word \overline{b} defining a braid we have the bound $|b|_{\Delta} \leq |b|$. We shall use the following norm in the space \mathbb{Z}^{2n} : $||x|| = \max_{i=1}^{n} |x_i|$.

Proposition 3. Any braid $b \in B_n$ satisfies the bound $\ln \|b \cdot L_0\| \le 2|b|_{\Delta}$. Hence the element $b \cdot L_0$ can be computed in const $|b|_{\Delta} \cdot |b|$ operations.

We note that a bound for the time needed to compare b with 1 in the σ -ordering depends only on the length of the word b and not on the number of strings. Until recently the best time bound among algorithms for the solution of the word problem in B_n was that for an algorithm in [9], where the bound is linear in n. An algorithm similar to ours recently appeared independently in [10], where, however, it was not noted that the action on laminations is related to a certain Yang-Baxter map.

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¹Originally the author had only noticed that the action ρ gave a fast algorithm for recognising a trivial braid. The question of the connection between this action and σ -ordering was posed by Dehornoy, and the answer conjectured by S. Orevkov, who referred the author to [8], where similar geometric ideas are used.

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