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## PyTorch cheat sheet

```
— ♣ 陳建成 ① Wed, Mar 25, 2020 7:57 PM
此處整理 PyTorch 常用的 modules 和 functions 方便快速查詢。
完整且詳細的 docs 請見 PyTorch 官方文檔(ver 1.2.0)。
另外,這裡有兩個版本的 PyTorch 教學 Colaboratory Notebooks,一個和上課教學互相對應,另一
個有更詳細的解說(包含前後處理、視覺化、常用工具等),提供各位參考。
  對了,拜託各位先 copy 一份到自己雲端硬碟,或是用 Playground 模式,不要干擾到原本的版
  本,多謝各位合作 😃

    PyTorch cheat sheet

    Tensor Operations [Docs]
    Data Preparation [Docs]

    NN (Neural Network) Model Construction [Docs]

       Training
       Testing

    CNN (Convolutional Neural Networks)

    RNN (Recurrent Neural Networks)

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▶ 在我們開始前…… (表示方法說明)
```

**Tensor Operations [Docs]** 

```
torch
 — (Tensor)
     - view(*shape) # e.g. x.view(-1, 3, 12)
                        ## -1 automatically filled
     — item()
                         # get if Tensor is a scalar
 — empty(*size)
                         \# e.g. x = torch.empty(2, 3)
  — stack(tensors, dim=0)
└── cat(tensors, dim=0)
```

### torch └─ utils

**Data Preparation [Docs]** 

```
L— data
           — Dataset # A class to override
                       ## `__len__` & `__getitem__`
           – TensorDataset(data_tensor, target_tensor)
           - DataLoader(dataset, batch_size=1,
                       shuffle=False,
                       collate_fn=\
                          <function default_collate>)
                        # define `collate_fn` yourself
           sampler
             SequentialSampler(data_source)
             RandomSampler(data_source)
NN (Neural Network) Model Construction [Docs]
```

### • torch.nn

```
torch.nn.functional
• torch.nn.init
```

這是 PyTorch 最主要的 module, docs 比較複雜,分成

- torch.optim

```
• torch.autograd
Training
 torch
   — (Tensor)
        - backward()
      — cpu()
       — cuda()
     to(torch.device) \# x = x.to(device)
    cuda
     is_available()
         # if torch.cuda.is available():
         ## device = "cuda"
         ## else: device = "cpu"
    – nn as nn
      ### Models ###
      — Module
         load_state_dict(torch.load(PATH))
          --- train()
         L— eval()
       — Sequential(layers)
      ### Initializations ###
      —— init
         uniform_(w) # In-place,
                           ## w is a `torch.Tensor`.
     ### Layers ###
     Linear(in_feat, out_feat)
      — Dropout(rate)
      ### Activations ###
      Softmax(dim=None)
      —— Sigmoid()
      --- ReLU()
      —— LeakyReLU(negative_slope=0.01)
      — Tanh()
      —— GELU()
       — ReLU6() # Model Compression
       # --> Corresponding functions
      — functional as F ————
         --- softmax(input, dim=None)
          sigmoid(input)
         relu(input)
          — leaky_relu(input,
                       negative_slope=0.01)
          tanh(input)
          gelu(input)
         └─ relu6(input)
      ### Losses ###
       - MSELoss()
       — CrossEntropyLoss()
       - BCELoss()
       — NLLLoss()
       # --> Corresponding functions
       —<functional as F> <-----</pre>
          mse_loss(input, target)
          — cross_entropy(input,
                          target: torch.LongTensor)
           — binary_cross_entropy(input, target)
          — log_softmax(input)
         nll_loss(log_softmax_output, target)
            # F.nll_loss(F.log_softmax(input), target)
      ### Optimizers ###
    - optim
      — (Optimizer)
              — zero_grad()
              — step()
             state_dict()
       — SGD(model.parameters(), lr=0.1, momentum=0.9)
       — Adagrad(model.parameters(), lr=0.01,
                lr_decay=0, weight_decay=0,
                initial_accumulator_value=0,eps=1e-10)
       - RMSProp(model.parameters(), lr=0.01,
                alpha=0.99, eps=1e-08, weight_decay=0,
                momentum=0)
       — Adam(model.parameters(), lr=0.001,
              betas=(0.9, 0.999), eps=1e-08,
              weight_decay=0)
     lr_scheduler
         L— ReduceLROnPlateau(optimizer)
  — load(PATH)
  — save(model, PATH)
   — autograd
     backward(tensors)
Testing
 torch
   L— Module
         load_state_dict(torch.load(PATH))
```

## — no\_grad()

- optim

— eval()

state\_dict()

└─ (Optimizer)

### Layers ###

— Conv2d(in\_channels, out\_channels,

output\_padding=0)

kernel\_size, stride=1, padding=0)

kernel\_size, stride=1, padding=0,

— ConvTranspose2d(in\_channels, out\_channels,

```
CNN (Convolutional Neural Networks)

    Convolutional Layers

    Pooling Layers

 torchvision docs
 torch
  - (Tensor)
     view(*shape)
    – nn
```

# with torch.no\_grad(): ...

```
— MaxPool2d(kernel_size, stride=None,
                   padding=0, dilation=1)
                   # stride default: kernel_size
      — BatchNorm2d(num_feat)
      BatchNorm1d(num_feat)
    — stack(tensors, dim=0)
  └── cat(tensors, dim=0)
 torchvision
  models as models # Useful pretrained
   — transforms as transforms
       — Compose(transforms) # Wrapper
      ToPILImage(mode=None)
        - RandomHorizontalFlip(p=0.5)
       — RandomRotation(degrees)
      — ToTensor()
       — Resize(size)
    - utils
      make_grid(tensor, nrow=8, padding=2)
      save_image(tensor, filename, nrow=8,padding=2)
RNN (Recurrent Neural Networks)

    Recurrent Layers

    Gensim Word2Vec Docs

 torch
   — nn
       — Embedding(num_embed, embed_dim)
```

```
# embedding = nn.Embedding(
                     *(w2vmodel.wv.vectors.shape))
    — Parameter(params: torch.FloatTensor)
      # embedding.weight = nn.Parameter(
      ## torch.FloatTensor(w2vmodel.wv.vectors))
    LSTM(inp_size, hid_size, num_layers)
      # input: input, (h_0, c_0)
   GRU(inp_size, hid_size, num_layers)
 — stack(tensors, dim=0)
└── cat(tensors, dim=0)
gensim
— models
   word2Vec
       —— Word2Vec(sentences) # list or words/tokens
```

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```
全部的架構太大,不方便查詢,故先隱藏起來
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