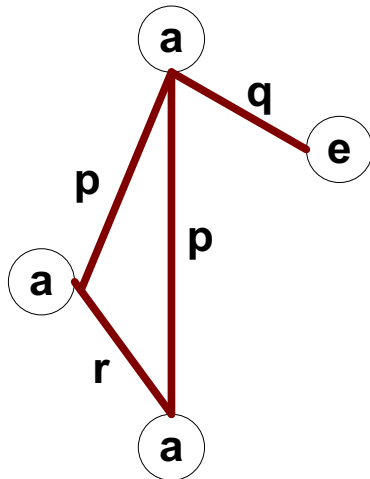


Apriori-like approach

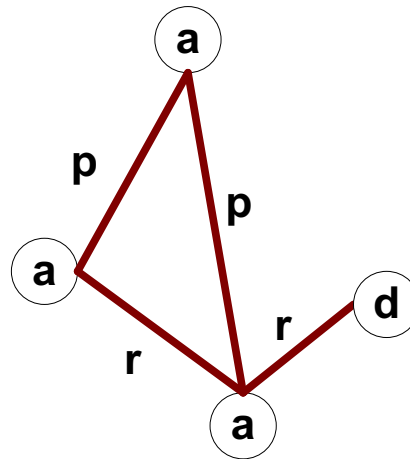
- Level-wise (Apriori-like) approach:
 - Vertex growing:
 - ◆ k is the number of vertices
 - Edge growing:
 - ◆ k is the number of edges

Vertex Growing

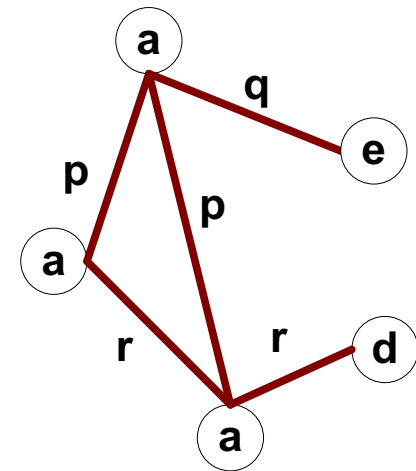
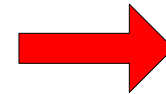


G1

+



G2



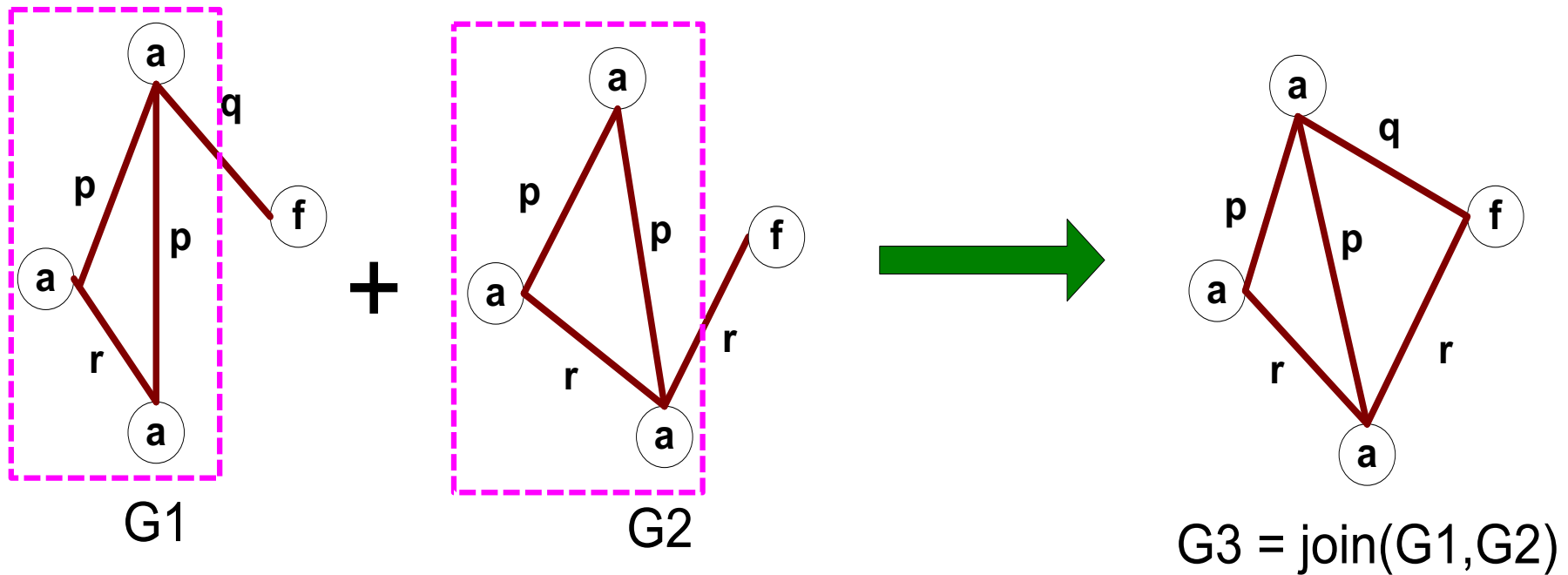
G3 = join(G1, G2)

$$M_{G1} = \begin{pmatrix} 0 & p & p & q \\ p & 0 & r & 0 \\ p & r & 0 & 0 \\ q & 0 & 0 & 0 \end{pmatrix}$$

$$M_{G2} = \begin{pmatrix} 0 & p & p & 0 \\ p & 0 & r & 0 \\ p & r & 0 & r \\ 0 & 0 & r & 0 \end{pmatrix}$$

$$M_{G3} = \begin{pmatrix} 0 & p & p & q & 0 \\ p & 0 & r & 0 & 0 \\ p & r & 0 & 0 & r \\ q & 0 & 0 & 0 & ? \\ 0 & 0 & r & ? & 0 \end{pmatrix}$$

Edge Growing

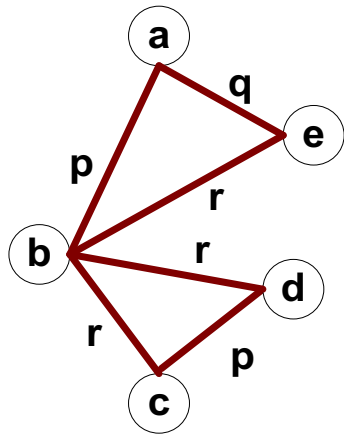


Apriori-like Algorithm

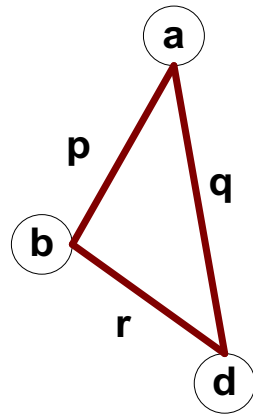
- Find frequent 1-subgraphs
- Repeat
 - Candidate generation
 - ◆ Use frequent $(k-1)$ -subgraphs to generate candidate k -subgraph
 - Candidate pruning
 - ◆ Prune candidate subgraphs that contain infrequent $(k-1)$ -subgraphs
 - Support counting
 - ◆ Count the support of each remaining candidate
 - Eliminate candidate k -subgraphs that are infrequent

In practice, it is not as easy. There are many other issues

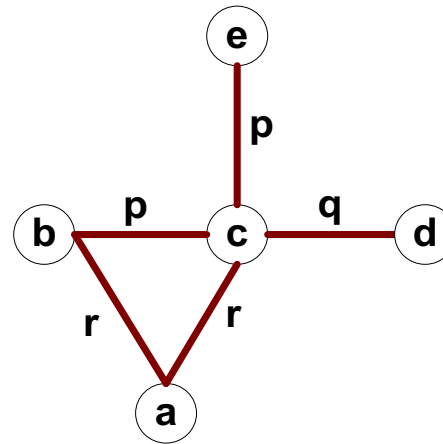
Example: Dataset



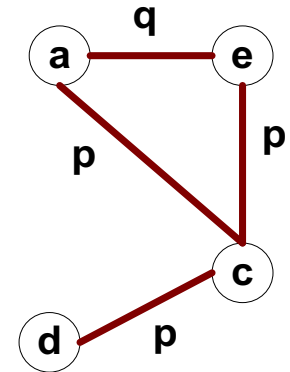
G1



G2



G3



G4

	(a,b,p)	(a,b,q)	(a,b,r)	(b,c,p)	(b,c,q)	(b,c,r)	...	(d,e,r)
G1	1	0	0	0	0	1	...	0
G2	1	0	0	0	0	0	...	0
G3	0	0	1	1	0	0	...	0
G4	0	0	0	0	0	0	...	0

Example

Minimum support count = 2

k=1

Frequent
Subgraphs

a

b

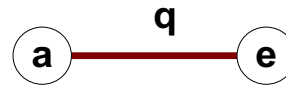
c

d

e

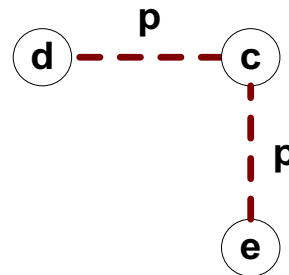
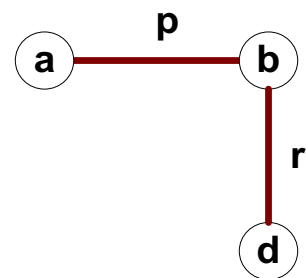
k=2

Frequent
Subgraphs



k=3

Candidate
Subgraphs

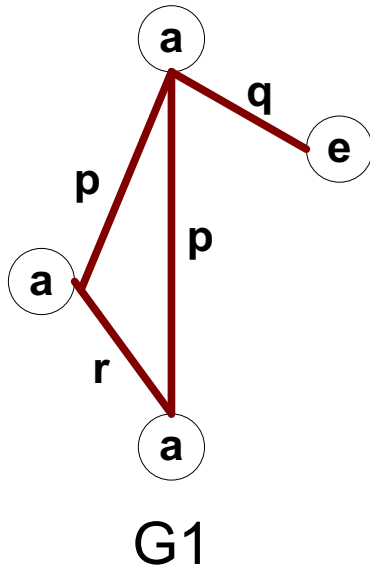


(Pruned candidate
due to low support)

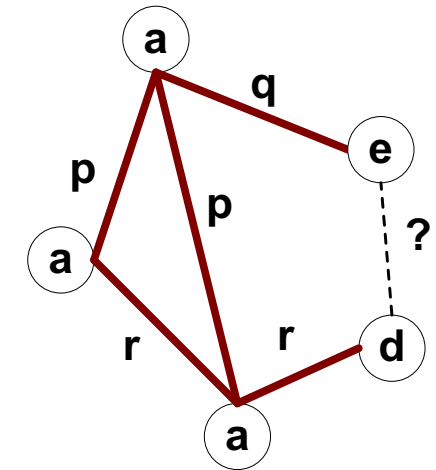
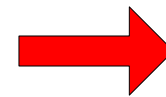
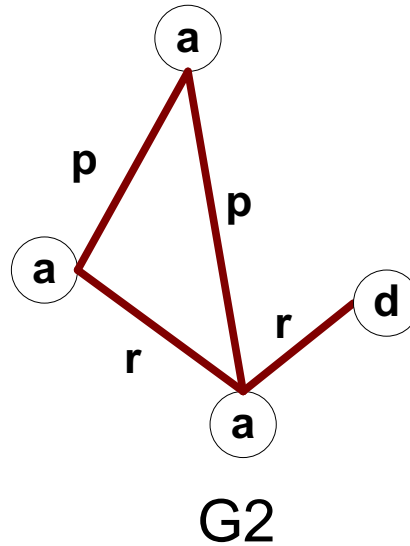
Candidate Generation

- In Apriori:
 - Merging two frequent k -itemsets will produce a candidate $(k+1)$ -itemset
- In frequent subgraph mining (vertex/edge growing)
 - Merging two frequent k -subgraphs may produce **more than one** candidate $(k+1)$ -subgraph

Multiplicity of Candidates (Vertex Growing)



+



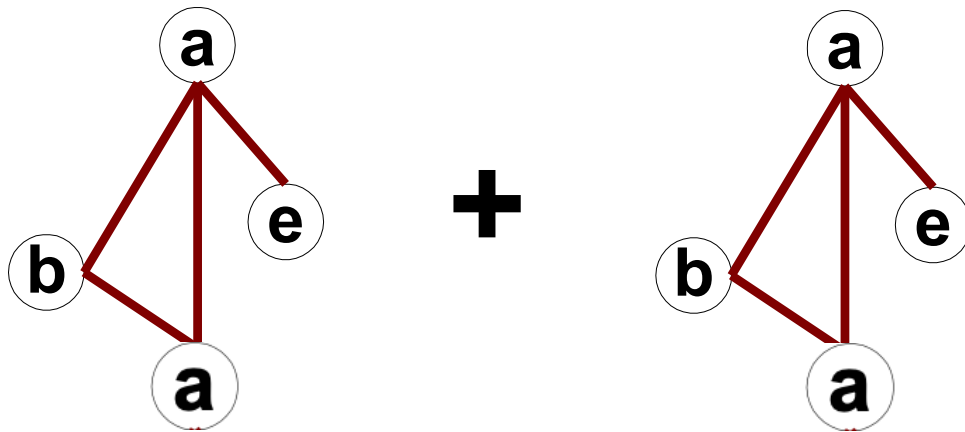
$$M_{G_1} = \begin{pmatrix} 0 & p & p & q \\ p & 0 & r & 0 \\ p & r & 0 & 0 \\ q & 0 & 0 & 0 \end{pmatrix}$$

$$M_{G_2} = \begin{pmatrix} 0 & p & p & 0 \\ p & 0 & r & 0 \\ p & r & 0 & r \\ 0 & 0 & r & 0 \end{pmatrix}$$

$$M_{G_3} = \begin{pmatrix} 0 & p & p & 0 & q \\ p & 0 & r & 0 & 0 \\ p & r & 0 & r & 0 \\ 0 & 0 & r & 0 & ? \\ q & 0 & 0 & ? & 0 \end{pmatrix}$$

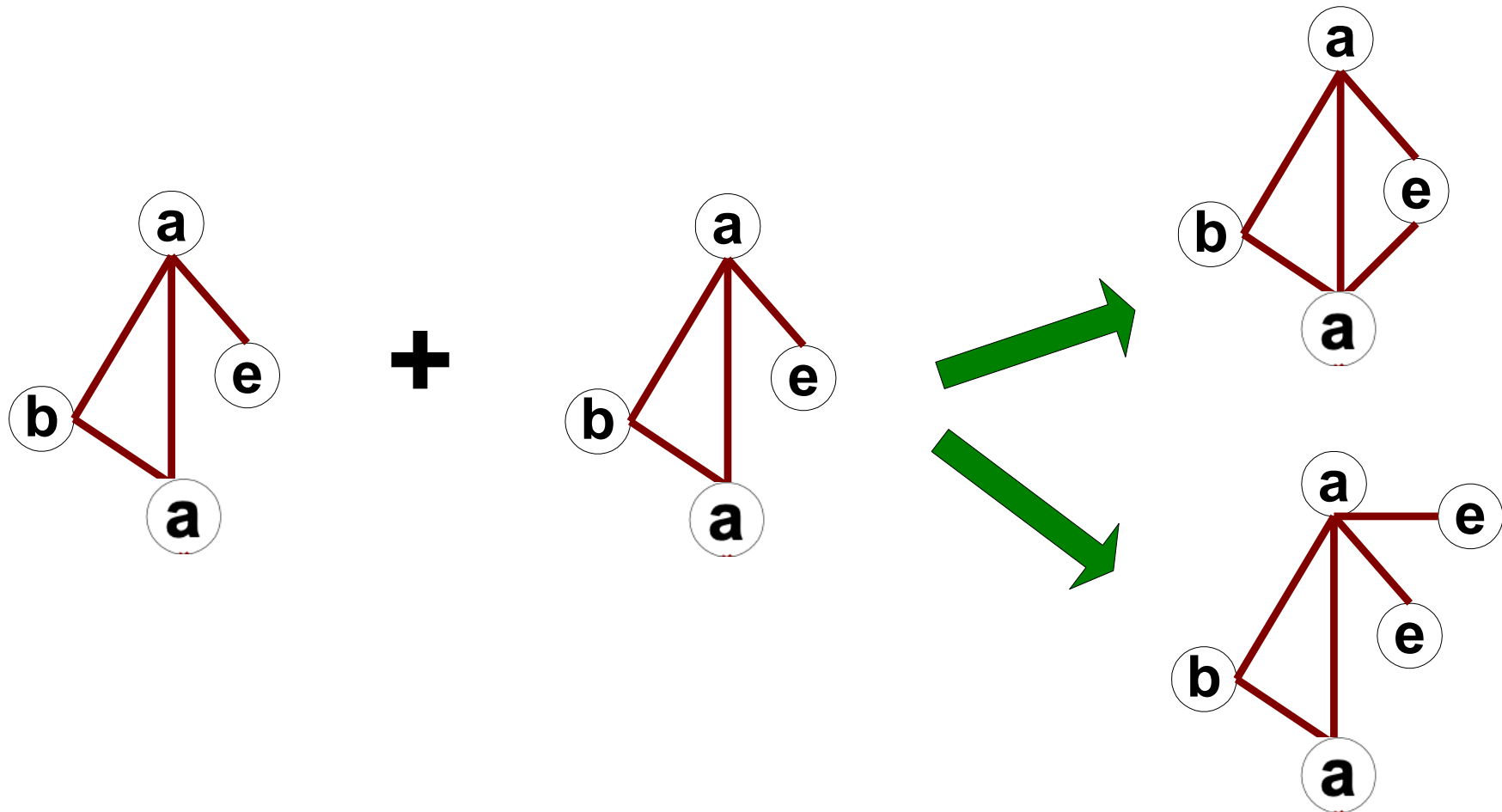
Multiplicity of Candidates (Edge growing)

- Case 1: identical vertex labels



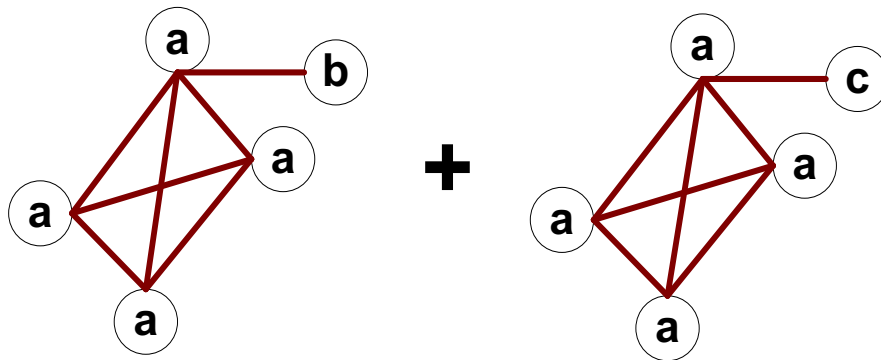
Multiplicity of Candidates (Edge growing)

- Case 1: identical vertex labels



Multiplicity of Candidates (Edge growing)

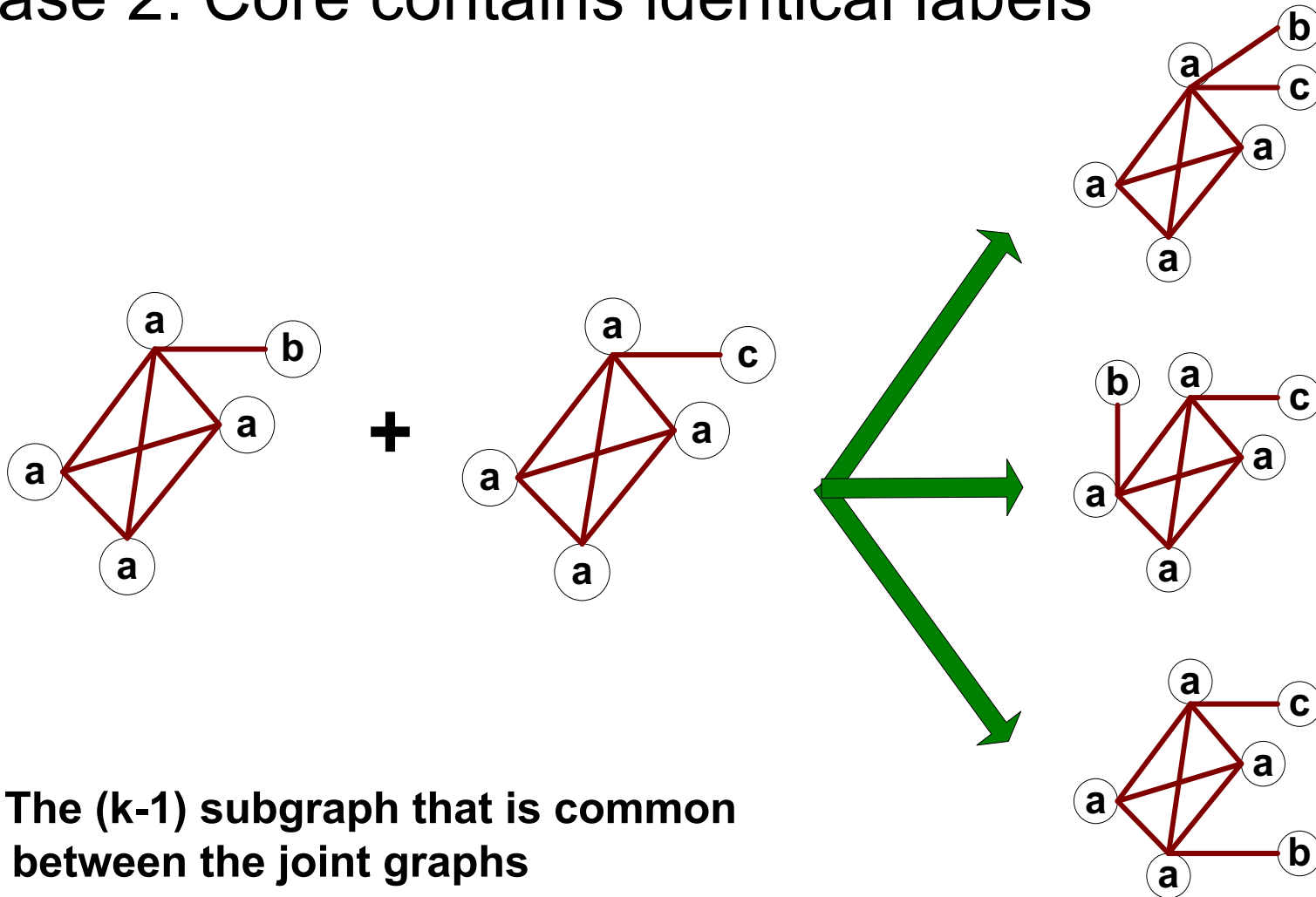
- Case 2: Core contains identical labels



Core: The $(k-1)$ subgraph that is common between the joint graphs

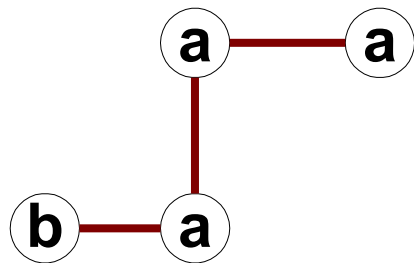
Multiplicity of Candidates (Edge growing)

- Case 2: Core contains identical labels

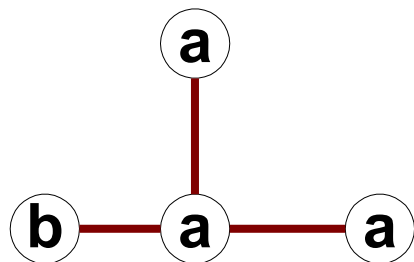


Multiplicity of Candidates (Edge growing)

- Case 3: Core multiplicity

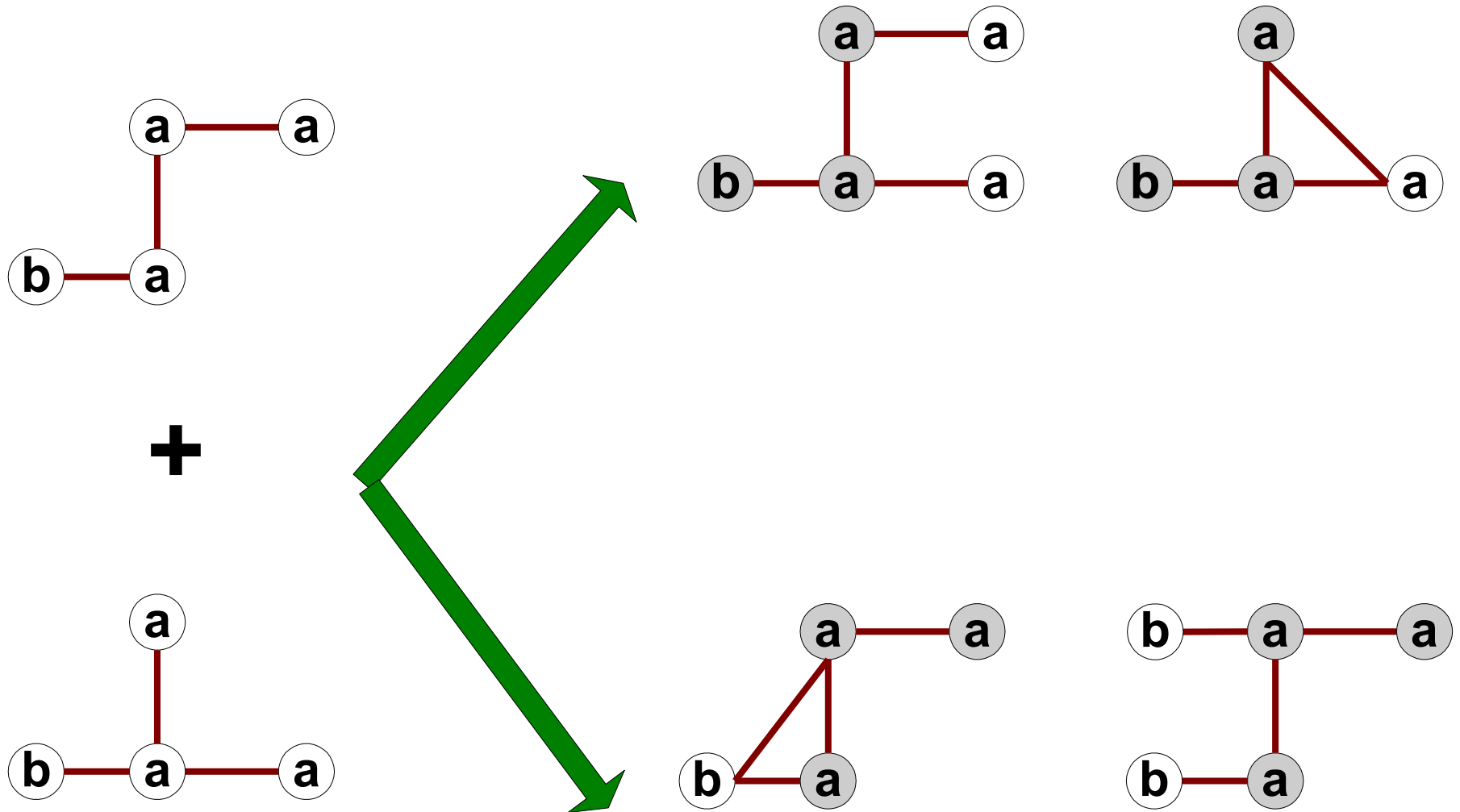


+

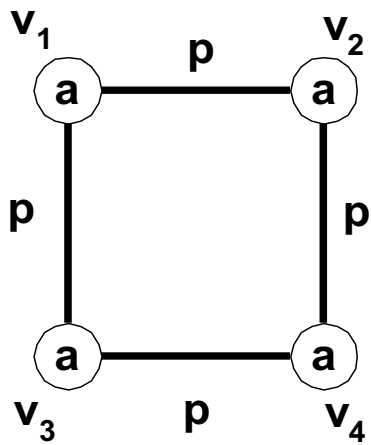


Multiplicity of Candidates (Edge growing)

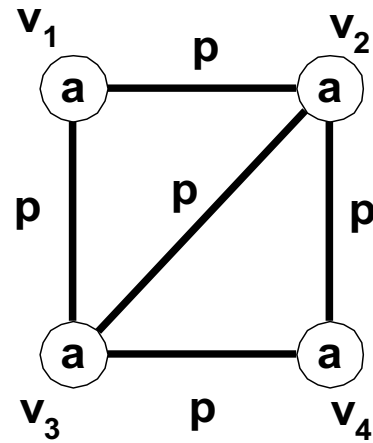
- Case 3: Core multiplicity



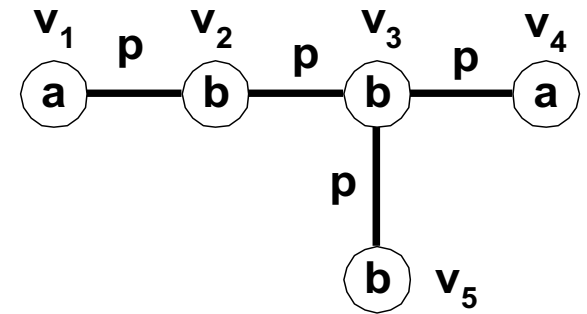
Topological Equivalence



G1



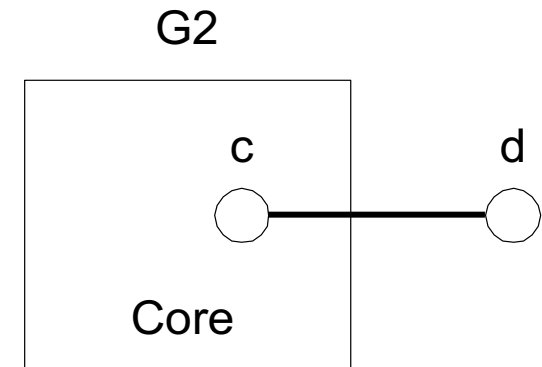
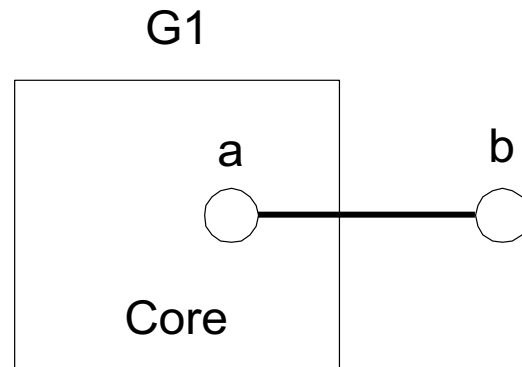
G2



G3

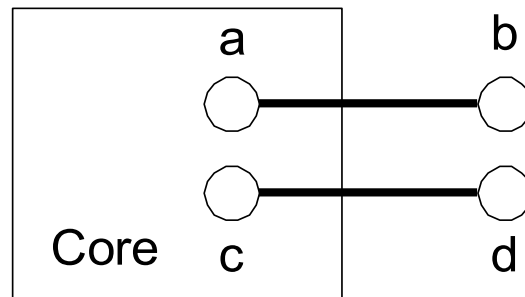
Candidate Generation by Edge Growing

- Given:



- Case 1: $a \neq c$ and $b \neq d$

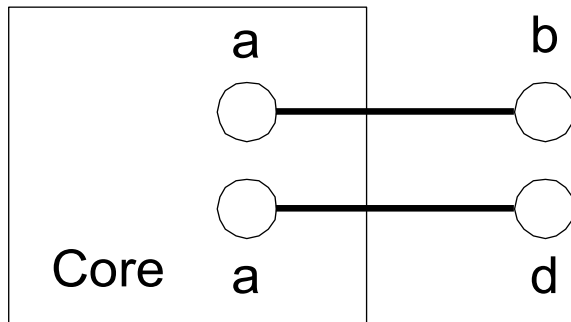
$G3 = \text{Merge}(G1, G2)$



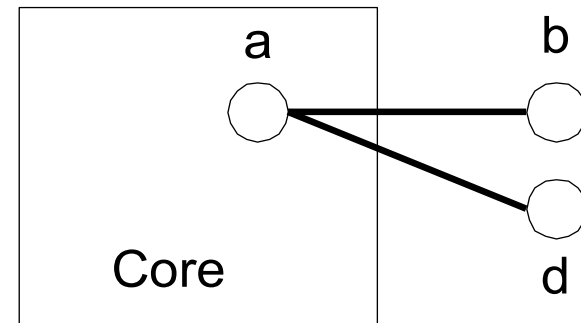
Candidate Generation by Edge Growing

- Case 2: $a = c$ and $b \neq d$

$G3 = \text{Merge}(G1, G2)$



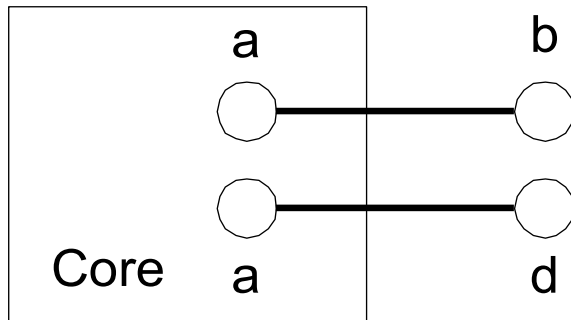
$G3 = \text{Merge}(G1, G2)$



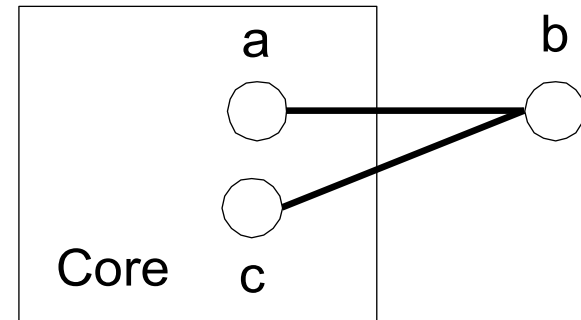
Candidate Generation by Edge Growing

- Case 3: $a \neq c$ and $b = d$

$G3 = \text{Merge}(G1, G2)$



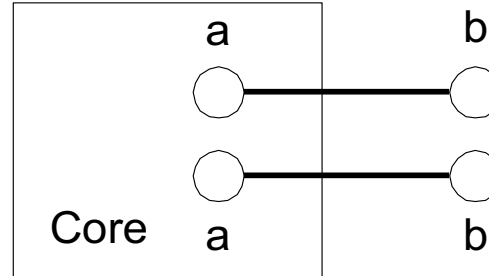
$G3 = \text{Merge}(G1, G2)$



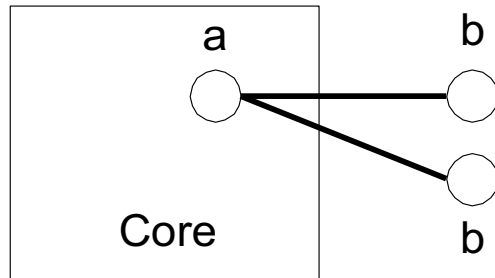
Candidate Generation by Edge Growing

- Case 4: $a = c$ and $b = d$

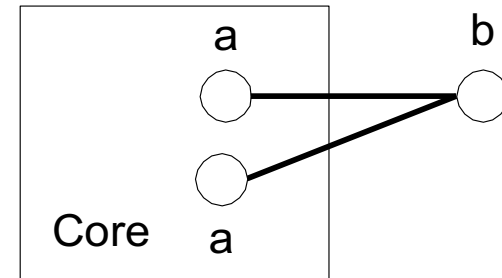
$G3 = \text{Merge}(G1, G2)$



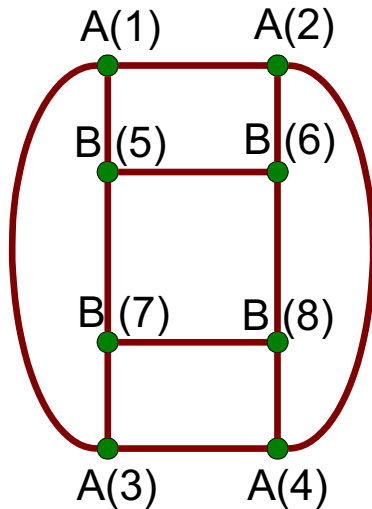
$G3 = \text{Merge}(G1, G2)$



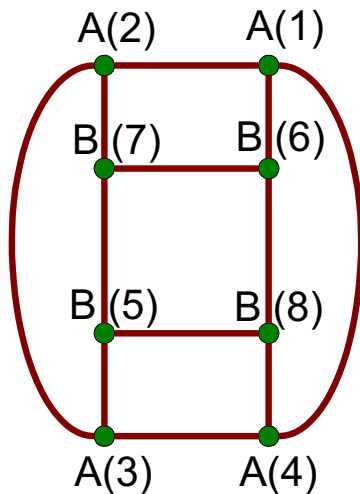
$G3 = \text{Merge}(G1, G2)$



Adjacency Matrix Representation



	A(1)	A(2)	A(3)	A(4)	B(5)	B(6)	B(7)	B(8)
A(1)	1	1	1	0	1	0	0	0
A(2)	1	1	0	1	0	1	0	0
A(3)	1	0	1	1	0	0	1	0
A(4)	0	1	1	1	0	0	0	1
B(5)	1	0	0	0	1	1	1	0
B(6)	0	1	0	0	1	1	0	1
B(7)	0	0	1	0	1	0	1	1
B(8)	0	0	0	1	0	1	1	1

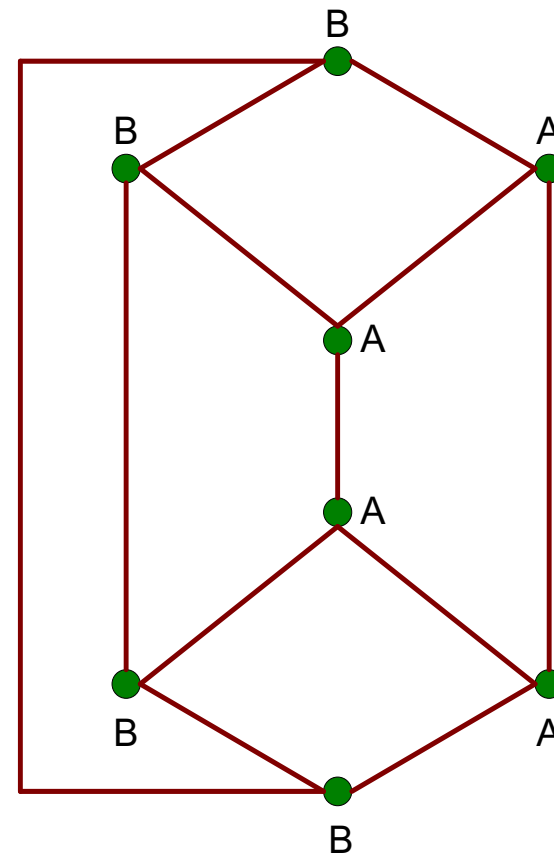
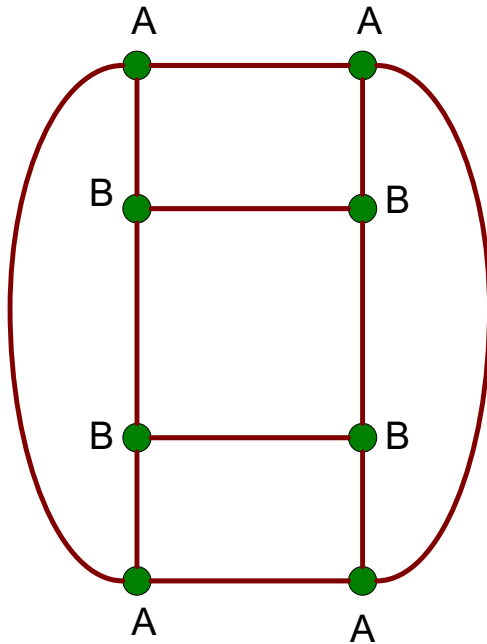


	A(1)	A(2)	A(3)	A(4)	B(5)	B(6)	B(7)	B(8)
A(1)	1	1	0	1	0	1	0	0
A(2)	1	1	1	0	0	0	1	0
A(3)	0	1	1	1	1	0	0	0
A(4)	1	0	1	1	0	0	0	1
B(5)	0	0	1	0	1	0	1	1
B(6)	1	0	0	0	0	1	1	1
B(7)	0	1	0	0	1	1	1	0
B(8)	0	0	0	1	1	1	0	1

- The same graph can be represented in many ways

Graph Isomorphism

- A graph is isomorphic if it is topologically equivalent to another graph



Graph Isomorphism

- Test for graph isomorphism is needed:
 - During candidate generation step, to determine whether a candidate has been generated
 - During candidate pruning step, to check whether its $(k-1)$ -subgraphs are frequent
 - During candidate counting, to check whether a candidate is contained within another graph

Graph Isomorphism

- Use canonical labeling to handle isomorphism
 - Map each graph into **an ordered string representation** (known as its code) such that two isomorphic graphs will be mapped to the same canonical encoding
 - Example:
 - ◆ Lexicographically largest adjacency matrix

