# Contents

[摘要 I](#_Toc3740966)

[Abstract II](#_Toc3740967)

[Acknowledgements IV](#_Toc3740968)

[Contents V](#_Toc3740969)

[List of Tables VIII](#_Toc3740970)

[List of Figures IX](#_Toc3740971)

[Chapter 1 Introduction 1](#_Toc3740972)

[1.1 Motivation and Objectives 1](#_Toc3740973)

[1.2 Literature Review 3](#_Toc3740974)

[1.2.1 Autonomous Driving Vehicle 4](#_Toc3740975)

[1.2.2 Perception Module 6](#_Toc3740976)

[Chapter 2 Autonomous Vehicle System 11](#_Toc3740978)

[2.1 Vechicle Introduction 11](#_Toc3740979)

[2.2 Sensor Configuration 16](#_Toc3740983)

[2.3 Computing and Connecting Hardware 16](#_Toc3740983)

[2.4 Coordinate Systems and Transformations 16](#_Toc3740983)

[Chapter 3 Peception and Data Fusion Algorithm 23](#_Toc3740987)

[3.1 Single Shot MultiBox Detector 23](#_Toc3740988)

[3.2 Kanade–Lucas–Tomasi 30](#_Toc3740992)

[3.3 Lidar-Camera Calibration 34](#_Toc3740997)

[3.4 Kalman Filter 34](#_Toc3740997)

[Chapter 4 System Development and Experimence 39](#_Toc3741001)

[4.1 Robot Operating System 39](#_Toc3741002)

[4.2 Single Sensor Processing 47](#_Toc3741007)

[4.2.1 Image Object Detection 47](#_Toc3741008)

[4.2.2 Lidar Clustering 48](#_Toc3741009)

[4.2.2 Radar Tracking 48](#_Toc3741009)

[4.3 Detection Level Data Fusion 61](#_Toc3741013)

[4.4 Track Level Data Fusion 61](#_Toc3741013)

[4.5 Simulation and Real-Time Experimence 65](#_Toc3741014)

[4.5.1 Simulator 65](#_Toc3741015)

[4.5.2 Real Test Environment 70](#_Toc3741017)

[Chapter 5 Conclusions and Future Works 76](#_Toc3741020)

[5.1 Discussions 76](#_Toc3741021)

[5.2 Future Works 78](#_Toc3741022)

[References 81](#_Toc3741023)