Total # of points = 100.

Project description. Write a program to compute the *HOG* (*Histograms of Oriented Gradients*) feature from an input image and then classify the HOG feature vector into *human* or *no-human* by using a *3-nearest neighbor* (*NN*) *classifier*. In the 3-NN classifier, the distance between the input image and a training image is computed by taking the histogram intersection of their HOG feature vectors:

$$\frac{\sum_{j=1}^n min(I_j, M_j)}{\sum_{j=1}^n M_j}$$

where I is the HOG feature of the input image and M is the HOG feature of the training image; the subscript j indicates the jth component of the feature vector and n is the dimension of the HOG feature vector. The distance between the input image and each of the training images is computed and the classification of the input image is taken to be the majority classification of the three nearest neighbors.

Conversion to grayscale: The inputs to your program are color images cut out from a larger image. First, convert the color images into grayscale using the formula I = Round(0.299R + 0.587G + 0.114B) where R, G and B are the pixel values from the red, green and blue channels of the color image, respectively, and Round is the round off operator.

Gradient operator: Use the **Prewitt's operator** for the computation of horizontal and vertical gradients. Use the formula $M(i,j) = \sqrt{G_x^2 + G_y^2}$ to compute gradient magnitude, where G_x and G_y are the horizontal and vertical gradients. Normalize and round off the gradient magnitude to integers within the range [0, 255]. Next, compute the gradient angle. For image locations where the templates go outside of the borders of the image, assign a value of 0 to both the gradient magnitude and gradient angle. Also, if both G_x and G_y are 0, assign a value of 0 to both gradient magnitude and gradient angle.

HOG feature: Refer to the lecture slides for the computation of the HOG feature. Use the unsigned representation and quantize the gradient angle into one of the 9 bins as shown in the table below. If the gradient angle is within the range [180, 360), simply subtract the angle by 180 first. Use the following parameter values in your implementation: $cell\ size = 8 \times 8$ pixels, $block\ size = 16 \times 16$ pixels (or 2 x 2 cells), $block\ overlap$ or $step\ size = 8$ pixels (or 1 cell.) Use L2 norm for block normalization. Leave the histogram and final feature values as floating point numbers (Do not round off to integers.)

Histogram Bins						
Bin#	Angle in degrees	Bin center				
1	[0,20)	10				
2	[20,40)	30				
3	[40,60)	50				
4	[60,80)	70				
5	[80,100)	90				
6	[100,120)	110				
7	[120,140)	130				
8	[140,160)	150				
9	[160,180)	170				

Training and test images: A set of 20 training images and a set of 10 test images in *.bmp* format will be provided. The training set contains 10 positive (human) and 10 negative (no human) samples and the test set contains 5 positive and 5 negative samples. All images are of size 160 (height) X 96 (width). With the given image size and the parameters given above for computing the HOG feature, there are 20 X 12 cells and 19 X 11 blocks in the detection window. The dimension of the HOG feature vector is 7,524.

Implementation: You can use Python, C++/C, Java or Matlab to implement your program. If you would like to use a different language, send me an email first. You are not allowed to use any built-in library functions for any of the tasks you are required to implement, including the Prewitt's operator and the computation of HOG features and histogram intersections. The only library functions you are allowed to use are those for the reading and writing of image files, matrix and vector arithmetic, and other commonly used mathematical functions.

Hand-in: Hand in the following files on BrightSpace by the due date. Please submit as separate files, do not ZIP.

- Your source code file. Put comments in your source code to make it easier for someone
 else to read your program. Points will be taken off if you do not have comments in your
 source code.
- The ASCII (.txt) files containing the HOG feature values for three of the training images and three of the test images (one file per image.) I will let you know which images to provide HOG feature values later. The feature values should be separated by line breaks. You should have 7,524 lines in each file.
- A PDF report that contains the following:
 - o Instruction on how to run your program and instruction on how to compile your program if your program requires compilation.
 - o Normalized gradient magnitude images for the 10 test images.
 - o The source code of your program (Copy-and-paste from source code file. This is in addition to the source code file that you need to hand in.)
 - o Use the table below to report the classification results. Distance is computed by using the histogram intersection formula above.

Test image	Correct Classification	File name of 1 st NN, distance &	File name of 2 nd NN, distance &	File name of 3 rd NN, distance &	Classification from 3-NN
		classification	classification	classification	
crop001034b	Human				
crop001070a	Human				
crop001278a	Human				
crop001500b	Human				
person_and_bike_151a	Human				
00000003a_cut	No-human				
00000090a_cut	No-human				
00000118a_cut	No-human				
no_person_no_bike_258_	No-human				
cut					
no_person_no_bike_264_	No-human				
cut					