Section 1: OS Concepts and x86

CS 162

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1 Vocabulary

With credit to the Anderson & Dahlin textbook (A&D):

- stack The stack is the memory set aside as scratch space for a thread of execution. When a function is called, a block is reserved on the top of the stack for local variables and some book-keeping data. When that function returns, the block becomes unused and can be used the next time a function is called. The stack is always reserved in a LIFO (last in first out) order; the most recently reserved block is always the next block to be freed.
- heap The heap is memory set aside for dynamic allocation. Unlike the stack, there is no enforced pattern to the allocation and deallocation of blocks from the heap; you can allocate a block at any time and free it at any time.
- **process** A process is an instance of a computer program that is being executed, typically with restricted rights. It consists of an address space and one or more threads of control. It is the main abstraction for protection provided by the operating system kernel.
- address space The address space for a process is the set of memory addresses that it can use and the state associated with them. The memory corresponding to each process' address space is private and cannot be accessed by other processes, unless it is explicitly shared.
- C A high-level programming language. In order to run it, C will be compiled to low level machine instructions like x86_64 or RISC-V. Note that it is often times easier to express high level ideas in C, but C cannot be used to express many details (such as register allocation).
- x86 A very popular family of instruction sets (which includes i386 and x86_64). Unlike MIPS or RISC-V, x86 is primarily based on CISC (Complex Instruction Set Computing) architecture. Virtually all servers, desktops, and most laptops (with Intel or AMD) natively execute x86.

2 C Review

2.1 Pointer and C Programming Practice

Write a function that places source inside of dest, starting at the offset position of dest. This is effectively swapping the tail-end of dest with the string contained in source (including the null terminator). Assume both are null-terminated and the programmer will never overflow dest. As an exercise in using pointers, implement it without using libraries.

```
void replace(char *dest, char *source, int offset)
{
     while (*((dest++)+offset) = *source++);
}

There are many equivalent ways to write C code. The code above is functionally equivalent to
     void replace(char *dest, char *source, int offset)
{
        dest += offset;
        while (*source) {
           *dest = *source;
           source++;
           dest++;
        }
        *dest = *source; // to copy the null terminator
}

However, the first one is much harder to read and offers no clear advantage other than looking cool.

Note:
Focus on each step and why it's important rather than fancy syntax.
dest + offset: incrementing the char pointer, which is just an address.
dest = *source: need to dereference char pointers to place character.
```

3 Fundamental Operating System Concepts

source++, dest++: bump pointers when moving along the string.

1. What are the 3 roles the OS plays?

Referee: The OS manages the sharing of resources, isolation and protect from other processes. Illusionist: The OS provides a clean and easy to use abstraction of the underlying hardware resources.

Glue: The OS provides common services between processes to facilitate sharing, community, and user level uniformity.

2. How is a process different from a thread?

A thread is an independent execution context, with its own registers, program counter, and stack. A thread is defined by an OS object called the Thread Control Block (TCB) which stores all of this information.

A process is comprised of one or more threads and enjoys OS level isolation from other operation systems, this includes having its own address space. The process is defined by an OS object called the Process Control Block (PCB) which stores process level information like a pointer to a page table, a list of open files, and process metadata.

Different threads in the same process may each have their own stacks, but all share the process' address space and so can access each other's memory. Threads encapsulate concurrency (modern OS schedule by threads not processes) while processes encapsulate isolation.

3. What is the process address space and address translation? Why are they important?

A process works with virtual memory and address translation is used to map the process virtual memory to the machine's physical memory. This is important because

- (a) Virtual memory provides an isolation abstraction that gives the illusion of the process being the sole user of the address space.
- (b) Gives the illusion of a large address space without having to actually allocate that much physical memory.
- (c) Provides isolation between processes because virtual memory between processes do not (usually) translate to the same physical memory, so different processes will not be able to access each other's memory.
- 4. What is dual mode operation and what are the three forms of control transfer from user to kernel mode?

Dual mode helps provide isolation between processes by restricting the use of certain resources and actions to just the system in "kernel mode."

The three forms of transfer are:

- (1) If a process wants to use those resources, like the filesystem, it can perform a control transfer called **a system call or syscall** from user space to kernel space. The kernel then validates the arguments of the syscall and accesses the resource on the behalf of the process.
- (2) An interrupt is an external asynchronous event independent of the user process that requires the attention of the operating system. The kernel switches from the process to the kernel in order to respond to this interrupt, which can be something like an OS timer going off or incoming bits on an I/O device.
- (3) **A trap** is an internal synchronous event such as a fault in the execution of the user process that forces the process to transfer control to the kernel. It is caused by instructions in the user process such as dividing by zero or accessing invalid memory.
- 5. Why does a thread in kernel mode have a separate kernel stack? What can happen if the kernel stack was in the user address space?

Each OS thread has a kernel stack (located in kernel memory) plus an user stack (located in user memory). This kernel stack is memory that is only accessible by the thread in privileged kernel mode and thus provides protection for the kernel from the user.

If the user process had write permission to the kernel stack, it could corrupt the kernel in the event that the user purposely or accidentally overwrite the kernel stack. Some OSes keep the PCB in the kernel stack, which if the user had access to can allow for permissions changes, information leakage, and breaking of process isolation.

- 6. How does the syscall handler protect the kernel from corrupt or malicious user code?
 - The syscall number is used to index into a vector mapping number of fixed syscall handlers
 this prevents the user from getting the kernel to run user code in kernel mode.
 - The handler copies the user arguments from the user registers or stack onto the kernel stack this protects the kernel from malicious code on the user stack from evading

checks.

- All of the arguments are validated before the syscall is executed this protects the kernel from errors in the user arguments like invalid or null pointers.
- Results from the syscall are copied back into user memory so the caller has access to them.

4 x86 Assembly

In the projects for this class, you will write an operating system for a 32-bit x86 machine. The class VM (and probably your laptop) use a 64-bit x86 processor (i.e., an x86-64 processor) that is capable of executing 32-bit x86 instructions. There are significant differences between the 64-bit and 32-bit versions of x86. For this worksheet, we will focus on the 32-bit x86 ISA because that is the ISA you will have to read when working on the projects. Remember that if you compile programs on your local machine or directly in the class VM (not in Pintos), the result will be in x86-64 assembly.

4.1 Registers

The 32-bit x86 ISA has 8 main registers: eax, ebx, ecx, edx, esi, edi, esp, and ebp. You can omit the "e" to reference the bottom half of each register. For example, ax refers to the bottom half of eax. esp is the stack pointer and ebp is the base pointer. Additionally, eip is the instruction pointer, similar to the program counter in MIPS or RISC-V.

x86 also has segment registers (cs, ds, es, fs, gs, and ss) and control registers (e.g., cr0). You can think of segment registers as offsets when accessing memory in certain ways (e.g., cs is for instruction fetches, ss is for stack memory), and control registers as configuring what features of the processor are enabled (e.g., protected mode, floating point unit, cache, paging). We won't focus on them in this worksheet, but you should know that they exist. In particular, Pintos sets these up carefully upon startup in pintos/src/threads/start.S, so look there if you are interested. Keep in mind that there are special restrictions as to how these registers are used as operands to instructions.

4.2 Syntax

Although the x86 ISA specifies the registers and instructions, there are two different syntaxes for writing them out: Intel and AT&T. Instruction operands are written in a different order in each syntax, which can make it confusing to read one syntax if you are used to the other. For this worksheet, we will focus on the AT&T syntax because it is the version used by the toolchain we are using (gcc, as).

In the AT&T syntax:

- Registers are preceded by a percent sign (e.g., %eax for the register eax)
- Immediates are preceded by a dollar sign (e.g., \$4 for the constant 4)
- For many (but not all!) instructions, use parentheses to dereference memory addresses (e.g., (%eax) reads from the memory address in eax)
- You can add a constant offset by prefixing the parentheses (e.g., 8(%eax) reads from the memory address eax + 8)
- Source operands typically precede destination operands, for instructions with two operands.

Instructions are often suffixed by a letter to specify the size of operands. Use the suffix b to work with 8-bit bytes. Use the suffix w to work with 16-bit words. Use the suffix 1 to work with 32-bit longwords (or doublewords). (Analogously, on the x86-64 ISA, append q to work with 64-bit quadwords). If you omit the suffix, the assembler will add it for you.

Some examples:

- addw %ax, %bx: Add the word in ax to the word in bx, and store the result in bx.
- addl %eax, %ebx: Add the longword in eax to the longword in ebx, and store the result in ebx.
- addl (%eax), %ebx: Add the longword in memory at the address in eax to the longword in ebx, and store the result in ebx.
- addl 12(%eax), %ebx: Add the longword in memory at the address eax + 12 to the longword in ebx, and store the result in ebx.
- subl \$12, %esp: Subtract the constant 12 from the longword in esp, and store the result in esp.

Notice that you don't need special instructions to load from/store to memory. Some other useful instructions are and, or, and xor. An especially common instruction is mov:

- movl %eax, %ebx: Copy the longword in eax into ebx.
- movl \$4, %ecx: Set the longword in ecx to 4.
- movl 4, %ecx: Read the longword in memory at address 4 and store the result in ecx.
- movl %edx, -8(%ecx): Write the longword in edx to memory at the address ecx 8.

For the instructions lea and leal, which you will find in Pintos, the parenthesis notation for memory works differently. They calculate an absolute memory address given a register and offset.

• leal 8(%eax), %ebx: Sets ebx to eax + 8. You can think of this as setting ebx to the memory address that movl 8(%eax), %ebx would read from.

4.3 Practice: Clearing a Register

Write an instruction that clears register eax (i.e., stores zero in eax).

```
There are various possibilities:

xorl %eax, %eax
subl %eax, %eax
movl $0, %eax
```

4.4 Calling Convention

The **caller** does the following:

- 1. Push the arguments onto the stack, in reverse order. After this step, the top of the stack must be 16-byte aligned add padding before pushing arguments, if necessary, so that this is true.
- 2. Push the return address and jump to the function you are trying to call.
- 3. When the callee returns, the return address is gone but the arguments are still on the stack.

The callee does the following, and must preserve ebx, esi, edi, and ebp:

- 1. (Typical, but not required) Push ebp onto the stack, and store current esp into ebp.
- 2. Compute the return value and store it in eax.
- 3. Restore esp to its value at the time the callee began executing.
- 4. Pop the return address off of the stack and jump to it.

4.5 Instructions Supporting the Calling Convention

• push1 %eax is equivalent to:

```
subl $4, %esp
movl %eax, (%esp)
```

• popl %eax is equivalent to:

```
movl (%esp), %eax
addl $4, %esp
```

- \bullet call \$0x1234: push the return address (address of the next instruction of the caller) onto the stack and jump to the specified address (address of the callee).
- leave is equivalent to:

```
movl %ebp, %esp
popl %ebp
```

• ret pops a longword off of the stack (typically a return address) and jumps to it.

pushal pushes eax, ecx, edx, ebx, esp, ebp, esi, and edi to the stack, and popal pops values off of the stack and stores them in those registers. They are useful to switch context or handle interrupts.

4.6 Practice: Reading Disassembly

file.c:

```
int global = 0;
int callee(int x, int y) {
  int local = x + y;
  return local + 1;
}

void caller(void) {
  global = callee(3, 4);
}
```

When gcc compiles this file, with optimizations off, it outputs:

file.s:

```
callee:
                 %ebp
        pushl
                 %esp, %ebp
        movl
                 $16, %esp
        subl
        movl
                 8(%ebp), %edx
        movl
                 12(%ebp), %eax
                 %edx, %eax
        addl
                \%eax, -4(\%ebp)
        movl
                 -4(%ebp), %eax
        movl
                 $1, %eax
        addl
        leave
        ret
caller:
        pushl
                 %ebp
        movl
                 %esp, %ebp
        pushl
                 $4
                 $3
        pushl
        call
                 callee
                 $8, %esp
        addl
                 %eax, global
        movl
        nop
```

```
leave
ret
```

What does each instruction do? Mark the prologue(s), epilogue(s), and call sequence(s).

- First three instructions of callee are the prologue: save esp and allocate space for locals.
- The next two movl instructions read the function arguments off of the stack into registers.
- The addl instruction computes x + y.
- The next mov1 instruction stores the result at ebp 4, the stack memory allocated for the local variable.
- The next movl reads the value of local into a register, and the following addl instruction adds one to it. Now the return value is in eax.
- The final two instructions are the epilogue: restore **esp**, pop the return address off the stack, and jump to it.
- The first two lines of caller are the prologue: save esp.
- The next four lines are the call sequence for calling callee: set up stack, call function, and clean up stack.
- The next mov1 instruction stores the return value into the address of the global variable.
- The nop appears to be an artifact of gcc—we're compiling with optimizations off, so the compiler doesn't optimize this out (although it would on any other optimization level)
- The last two instructions are the epilogue: restore **esp**, pop the return address of the stack and jump to it.

4.7 Practice: x86 Calling Convention

Sketch the stack frame of helper before it returns.

```
void helper(char* str, int len) {
  char word[len];
  strncpy(word, str, len);
  printf("%s", word);
  return;
}
int main(int argc, char *argv[]) {
  char* str = "Hello World!";
  helper(str, 13);
}
```

```
13
str
return address
saved EBP
\0
!
```

d
1
...
1
e
H